



Non-linear dynamics

Phenomenology, applications and examples

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Summary of the 1st lecture



- Hamiltonian formalism provides the natural framework to analyse (linear and non-linear) beam dynamics
- Canonical (symplectic) transformations enable to move from variables describing a distorted phase space to something simpler (ideally circles)
- The generating functions passing from the old to the new variables are bounded to diverge in the vicinity of resonances (emergence of chaos)
- Calculating this generating function with canonical perturbation theory becomes hopeless for higher orders
- Representing the accelerator (or beam line) like a composition of maps (through Lie transformations) enables derivation of the generating functions in an algorithmic way, in principle to arbitrary order





Phase space dynamics - Fixed point analysis



Phase space dynamics

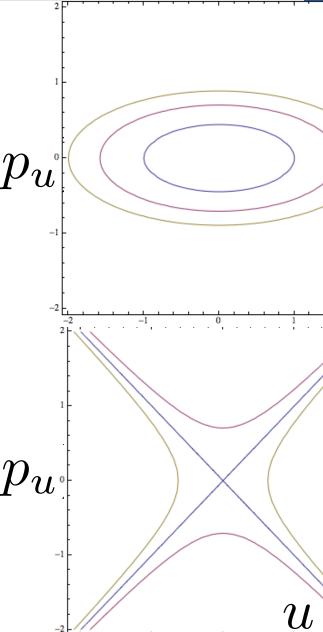


- Valuable description when examining trajectories in **phase space** (u, p_u)
- Existence of integral of motion imposes geometrical constraints on phase flow
- For the simple harmonic oscillator

$$H = \frac{1}{2} \left(p_u^2 + \omega_0^2 u^2 \right)$$

phase space curves are **ellipses** around the equilibrium point parameterized by the integral of motion Hamiltonian (energy)

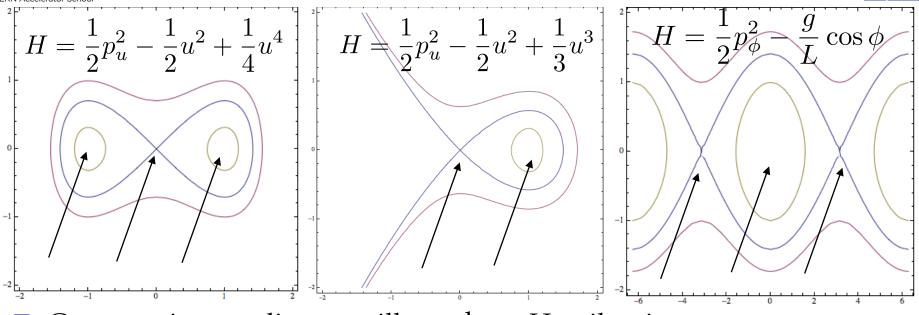
By simply **changing** the **sign** of the potential in the harmonic oscillator, the phase trajectories become **hyperbolas**, symmetric around the equilibrium point where two straight lines cross, moving towards and away from it





Non-linear oscillators





Conservative non-linear oscillators have Hamiltonian

$$H = E = \frac{1}{2}p_u^2 + V(u)$$

with the potential being a general (polynomial) function of positions

- **Equilibrium points** are associated with extrema of the potential
- Considering three non-linear oscillators
 - Quartic potential (left): two minima and one maximum
 - □ **Cubic** potential (center): one minimum and one maximum
 - Pendulum (right): periodic minima and maxima





Fixed point analysis



Consider a general second order system

$$\frac{du}{dt} = f_1(u, p_u)$$

$$\frac{dp_u}{dt} = f_2(u, p_u)$$

- **Equilibrium** or "fixed" points $f_1(u_0, p_{u0}) = f_2(u_0, p_{u0}) = 0$ are determinant for topology of trajectories at their vicinity
- The linearized equations of motion at their vicinity are

The linearized equations of motion at their vicinity are
$$\frac{d}{dt} \begin{bmatrix} \delta u \\ \delta p_u \end{bmatrix} = \mathcal{M}_J \begin{bmatrix} \delta u \\ \delta p_u \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(u_0, p_{u0})}{\partial u} & \frac{\partial f_1(u_0, p_{u0})}{\partial p_u} \\ \frac{\partial f_2(u_0, p_{u0})}{\partial u} & \frac{\partial f_2(u_0, p_{u0})}{\partial p_u} \end{bmatrix} \begin{bmatrix} \delta u \\ \delta p_u \end{bmatrix}$$

Jacobian matrix

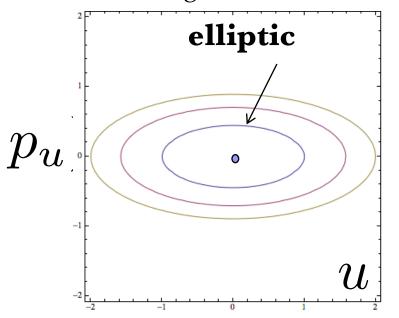
Fixed point nature is revealed by eigenvalues of \mathcal{M}_J , i.e. solutions of the characteristic polynomial $\det |\mathcal{M}_J - \lambda \mathbf{I}| = 0$

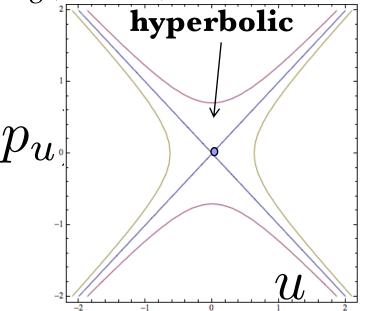


Fixed point for conservative systems



- For conservative systems of 1 degree of freedom, the second order characteristic polynomial for any fixed point has two possible solutions:
 - □ Two **complex eigenvalues** with opposite sign, corresponding to **elliptic** fixed points. Phase space flow is described by **ellipses**, with particles evolving clockwise or anti-clockwise
 - □ Two **real eigenvalues** with opposite sign, corresponding to **hyperbolic** (or saddle) fixed points. Flow described by two lines (or manifolds), incoming (stable) and outcoming (unstable)





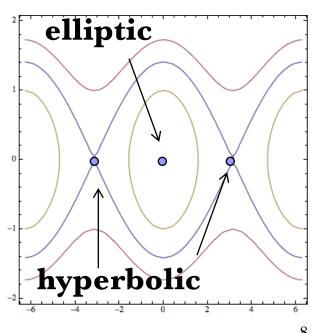


Pendulum fixed point analysis



- The "fixed" points for a pendulum can be found at $(\phi_n, p_\phi) = (\pm n\pi, 0) \;,\; n = 0, 1, 2 \ldots$
- The Jacobian matrix is $\begin{bmatrix} 0 & 1 \\ -\frac{g}{L}\cos\phi_n & 0 \end{bmatrix}$
- The eigenvalues are $\lambda_{1,2} = \pm i \sqrt{\frac{g}{L}} \cos \phi_n$
- Two cases can be distinguished:

 - The **separatrix** are the stable and unstable manifolds passing through the hyperbolic points, separating bounded **librations** and unbounded **rotations**





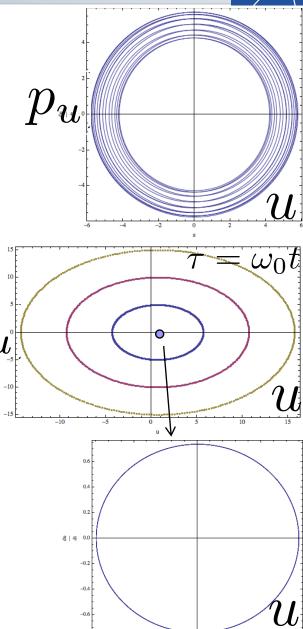
Phase space for time-dependent systems



Consider now a simple harmonic oscillator where the frequency is time-dependent

$$H = \frac{1}{2} \left(p_u^2 + \omega_0^2(t) u^2 \right)$$

- Plotting the evolution in phase space, provides trajectories that intersect each other (top)
- The phase space has time as extra dimension,
- By rescaling the time to become $au=\omega_0 t$ and considering every integer interval of the new $p_{\dot{u}}$ time variable, the phase space looks like the one of the harmonic oscillator (middle)
- This is the simplest version of a **Poincaré surface of section**, which is useful for studying geometrically phase space of multi-dimensional systems
- The fixed point in the surface of section is now a periodic orbit (bottom)



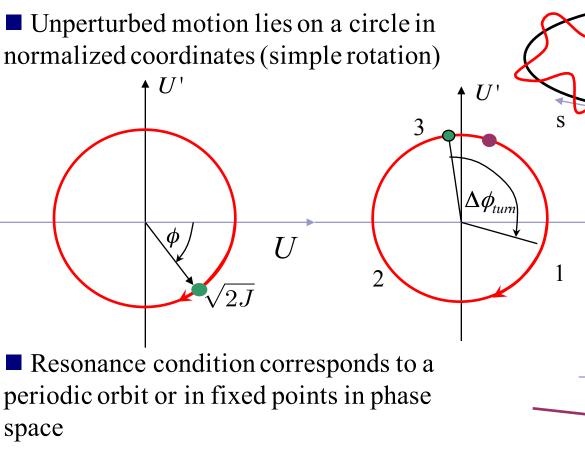


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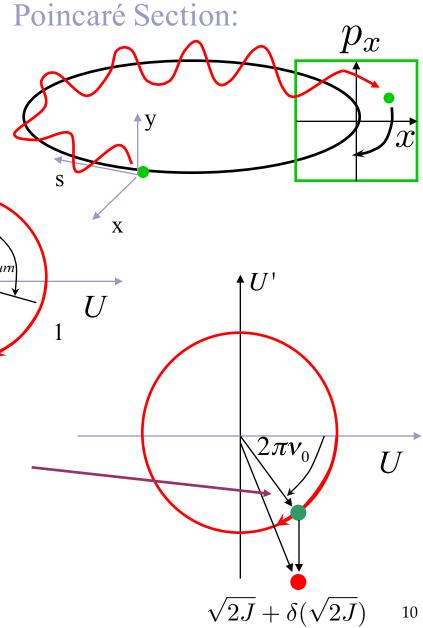
Poincaré Section in practice



■ Record the particle coordinates at one location (BPM)



- periodic orbit or in fixed points in phase space
- For a nonliner kick, the radius will change by $\delta(\sqrt{2J})$ and the particles stop lying on circles







Motion close to a resonance



Secular perturbation theory



- The vicinity of a resonance $n_1\omega_1 + n_2\omega_2 = \emptyset$ can be studied through secular perturbation theory (see appendix)
- A canonical transformation is applied such that the new variables are in a frame remaining on top of the resonance
- If one frequency is slow, one can average the motion and remain only with a 1 degree of freedom Hamiltonian
- Finding the location of the fixed points (J_{10}, ϕ_{10}) (i.e. periodic orbits) in phase space (J_1, ϕ_1) and defining a new action

$$\Delta J_1 = J_1 - J_{10}$$
, the resonant Hamiltonian is
$$H_r(\Delta J_1, \phi_1) = \frac{\partial^2 H_0(\mathbf{J})}{\partial J_1^2} \bigg|_{J_1 = J_{10}} \frac{(\Delta J_1)^2}{2} + 2\varepsilon \bar{H}_{n_1, -n_2}(\mathbf{J}) \cos \varphi_1$$

This is a pendulum where the frequency and the resonance half width are

$$\omega_{1} = \left(2\varepsilon H_{n_{1},-n_{2}}(\mathbf{J})\frac{\partial^{2} H_{0}(\mathbf{J})}{\partial J_{1}^{2}}\Big|_{J_{1}=J_{10}}\right)^{1/2} \Delta J_{1 \ max} = 2\left(\frac{2\varepsilon H_{n_{1},-n_{2}}(\mathbf{J})}{\frac{\partial^{2} H_{0}(\mathbf{J})}{\partial J_{1}^{2}}\Big|_{J_{1}=J_{10}}}\right)^{1/2}$$



Secular perturbation theory for the 3rd order resonance



We first introduce the distance to the resonance

$$\nu = \frac{p}{3} + \delta \; , \; \; \delta << 1$$

■ It is convenient then to eliminate the "time" dependence by passing on a "1-turn" frame, using the generating function

$$F_2(\phi, J_1, s) = \phi J_1 + J_1 \left(\frac{2\pi \nu s}{C} - \int_0^s \frac{ds'}{\beta(s')} \right) = (\phi + \chi(s))J_1$$
 with the new angle $\psi_1 = \phi - \chi(s)$ providing the Hamiltonian

$$H_1 = \frac{\nu}{R} J_1 + \frac{2\sqrt{2}}{3} K_s(s) (J_1 \beta)^{3/2} \cos^3(\psi_1 + \chi(s))$$

■ The perturbation can be expanded in a Fourier series, where only the resonant term is kept or,

$$\hat{H}_1 = \nu J_1 + J_1^{3/2} A_{3p} \cos(3\psi_1 - p\theta)$$

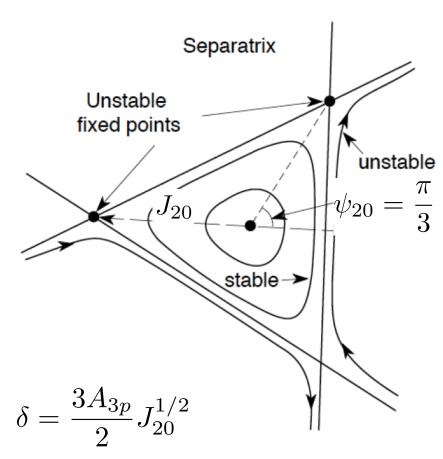
$$\hat{H}_2 = \delta J_2 + J_2^{3/2} A_{3p} \cos(3\psi_2)$$



Fixed points for 3rd order resonance



- By setting the Hamilton's equations equal to zero, three fixed points can be found at $\psi_{20} = \frac{\pi}{3}$, $\frac{3\pi}{3}$, $\frac{5\pi}{3}$, $J_{20} = \left(\frac{2\delta}{3A_{3n}}\right)^2$
- For $\frac{\delta}{A_{3p}} > 0$ all three points are unstable
- Close to the elliptic one at $\psi_{20} = 0$ the motion in phase space is described by circles that they get more and more distorted to end up in the "triangular" separatrix uniting the unstable fixed points
- The tune separation from the resonance (**stop-band width**) is $\delta = \frac{3A_{3p}}{2}J_{20}^{1/2}$





Fixed points for general multi-pole



For any polynomial perturbation of the form x^k the "resonant" Hamiltonian is written as

$$\hat{H}_2 = \delta J_2 + \alpha(J_2) + J_2^{k/2} A_{kp} \cos(k\psi_2)$$

- Note now that in contrast to the sextupole there is a non-linear detuning term $\alpha(J_2)$
- The conditions for the fixed points are $\sin(k\psi_2) = 0 \; , \; \; \delta + \frac{\partial \alpha(J_2)}{\partial J_2} + \frac{k}{2}J_2^{k/2-1}A_{kp}\cos(k\psi_2) = 0$
- There are k fixed points for which $\cos(k\psi_{20}) = -1$ and the fixed points are stable (elliptic). They are surrounded by ellipses
- There are also k fixed points for which $\cos(k\psi_{20}) = 1$ and the fixed points are unstable (hyperbolic). The trajectories are hyperbolas

Fixed points for an octupole



The resonant Hamiltonian close to the 4th order resonance is written as

$$\hat{H}_2 = \delta J_2 + cJ_2^2 + J_2^2 A_{kp} \cos(4\psi_2)$$

■ The fixed points are found by taking the derivative over the two variables and setting them to zero, i.e.

$$\sin(4\psi_2) = 0 , \quad \delta + 2cJ_2 + 2J_2A_{kp}\cos(4\psi_2) = 0$$

■ The fixed points are at

$$\psi_{20} = \left(\frac{\pi}{4}\right) \left(\frac{\pi}{2}\right), \left(\frac{3\pi}{4}\right), \left(\pi\right), \left(\frac{5\pi}{4}\right), \left(\frac{3\pi}{2}\right), \left(\frac{7\pi}{4}\right), \left(2\pi\right)$$

For half of them, there is a minimum in the potential as $\cos(4\psi_{20})=-1$ and they are elliptic and half of them they are hyperbolic as $\cos(4\psi_{20})=1$

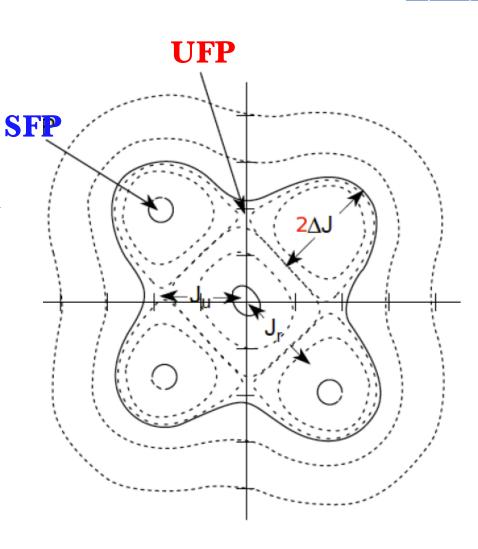




Topology of an octupole resonance



- Regular motion near the center, with curves getting more deformed towards a rectangular shape
- The separatrix passes through 4 unstable fixed points, but motion seems well contained
- Four stable fixed points exist and they are surrounded by stable motion (islands of stability)
- Question: Can the central fixed point become hyperbolic (answer in the appendix)







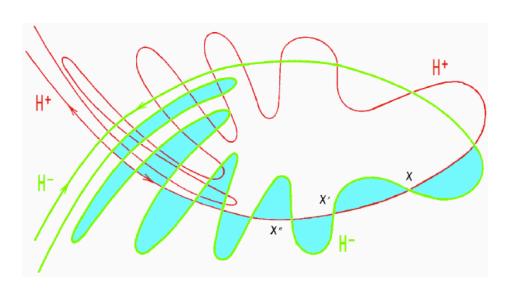
Onset of chaos

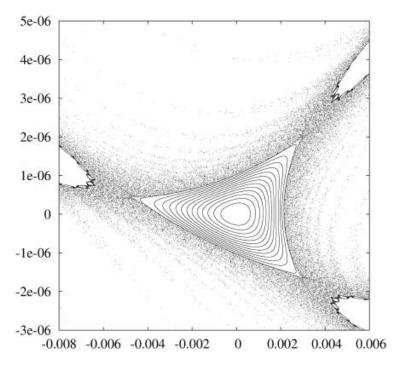


Path to chaos



- When perturbation becomes higher, motion around the separatrix becomes chaotic (producing tongues or splitting of the separatrix)
- Unstable fixed points are indeed the source of chaos when a perturbation is added



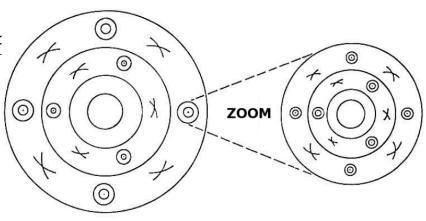


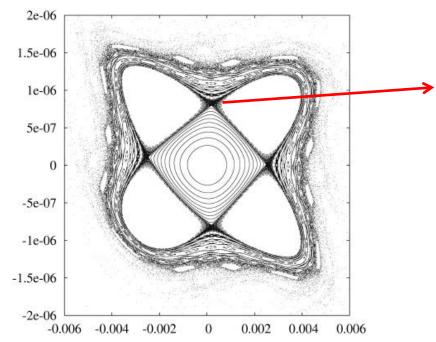


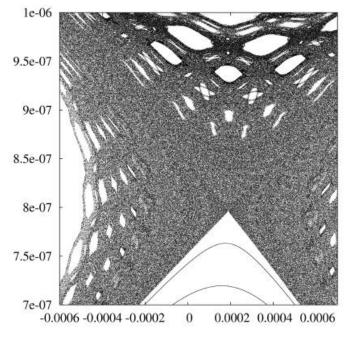
Chaotic motion



- Poincare-Birkhoff theorem states that under perturbation of a resonance only an even number of fixed points survives (half stable and the other half unstable)
- Themselves get destroyed when perturbation gets higher, etc. (self-similar fixed points)
- Resonance islands grow and resonances can overlap allowing diffusion of particles





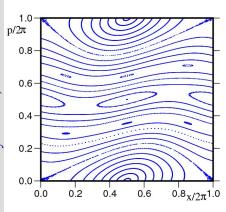


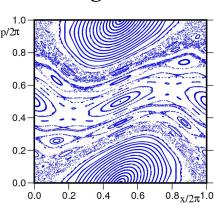


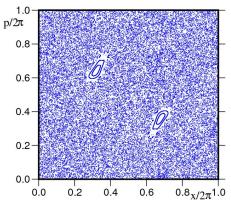
Resonance overlap criterion

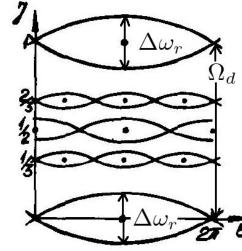


- When perturbation grows, the resonance island width grows
- Chirikov (1960, 1979) proposed a criterion for the overlap of two neighboring resonances and the onset of orbit diffusion
- The distance between two resonances is $\delta \hat{J}_{1 n, n'} = \frac{2\left(\frac{1}{n_1+n_2} \frac{1}{n'_1+n'_2}\right)}{\left|\frac{\partial^2 \bar{H}_0(\hat{\mathbf{J}})}{\partial \hat{J}_1^2}\right|_{\hat{I}_1 \hat{I}_1}}$
- $\Delta \hat{J}_{n \ max} + \Delta \hat{J}_{n' \ max} \ge \delta \hat{J}_{n,n'}$
- Considering the width of chaotic layer and secondary islands, the "two thirds" rule apply $\Delta \hat{J}_{n \ max} + \Delta \hat{J}_{n' \ max} \geq \frac{2}{3} \delta \hat{J}_{n,n'}$
- The main limitation is the geometrical nature of the criterion (difficulty to be extended for > 2 degrees of freedom)











Chaos detection methods



Computing/measuring dynamic aperture (DA) or particle survival

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A. Chao et al., PRL 61, 24, 2752, 1988;F. Willeke, PAC95, 24, 109, 1989.
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Computation of Lyapunov exponents

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F. Schmidt, F. Willeke and F. Zimmermann, PA, 35, 249, 1991; M. Giovannozi, W. Scandale and E. Todesco, PA 56, 195, 1997
```

Variance of unperturbed action (a la Chirikov)

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B. Chirikov, J. Ford and F. Vivaldi, AIP CP-57, 323, 1979J. Tennyson, SSC-155, 1988;J. Irwin, SSC-233, 1989
```

Fokker-Planck diffusion coefficient in actions

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T. Sen and J.A. Elisson, PRL 77, 1051, 1996
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Frequency map analysis





Dynamic aperture



Dynamic Aperture



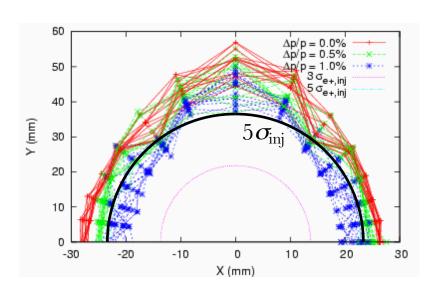
- The most direct way to evaluate the non-linear dynamics performance of a ring is the computation of **Dynamics Aperture**
- Particle motion due to multi-pole errors is generally nonbounded, so chaotic particles can escape to infinity
- This is not true for all non-linearities (e.g. the beam-beam force)
- Need a symplectic tracking code to follow particle trajectories (a lot of initial conditions) for a number of turns (depending on the given problem) until the particles start getting lost
- As multi-pole errors may not be completely known, one has to track through several machine models built by random distribution of these errors
- One could start with 4D (only transverse) tracking but certainly needs to simulate 5D (constant energy deviation) and finally 6D (synchrotron motion included)

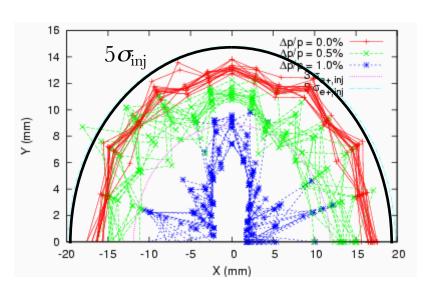


Dynamic Aperture plots



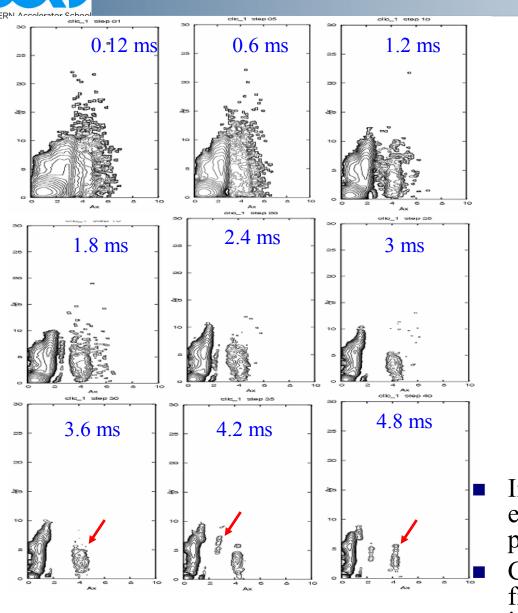
- Dynamic aperture plots show the maximum initial values of stable trajectories in x-y coordinate space at a particular point in the lattice, for a range of energy errors.
 - □ The beam size (injected or equilibrium) can be shown on the same plot.
 - □ Generally, the goal is to allow some significant margin in the design the measured dynamic aperture is often smaller than the predicted dynamic aperture.



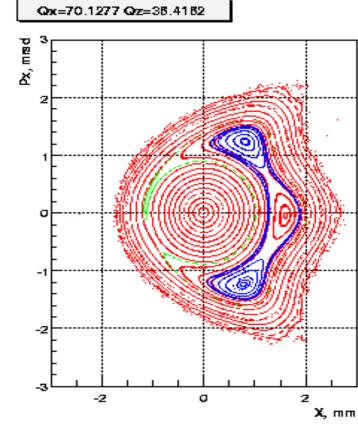


Dynamic aperture including damping





Non-linear dynamics, CERN Accelerator School, October 2015



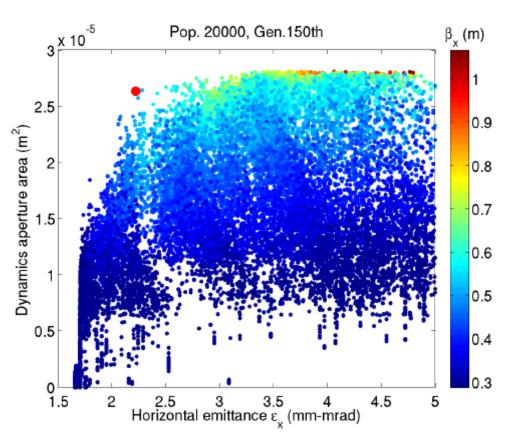
Including radiation damping and excitation shows that 0.7% of the particles are lost during the damping Certain particles seem to damp away from the beam core, on resonance islands



Genetic Algorithms for lattice optimisation



- MOGA –Multi Objective Genetic Algorithms are being recently used to optimise linear but also non-linear dynamics of electron low emittance storage rings
- Use knobs quadrupole strengths, chromaticity sextupoles and correctors with some constraints
- Target ultra-low horizontal emittance, increased lifetime and high dynamic aperture



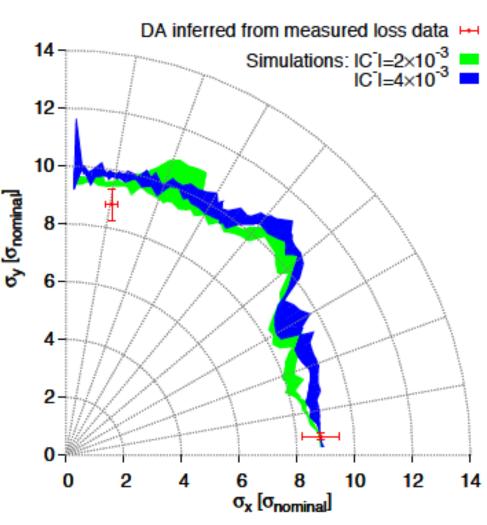
Measuring Dynamic Aperture



During LHC design phase, DA target was 2x higher than collimator position, due to statistical fluctuation, finite mesh, linear imperfections, short tracking time, multi-pole time dependence, ripple and a 20% safety margin

Better knowledge of the model led to good agreement between measurements and simulations for actual LHC

Necessity to build an accurate magnetic model (from beam based measurements)







Frequency Map Analysis



Frequency map analysis



- Frequency Map Analysis (FMA) is a numerical method which springs from the studies of J. Laskar (Paris Observatory) putting in evidence the
- chaotic motion in the Solar Systems
- FMA was successively applied to several dynamical systems
 - Stability of Earth Obliquity and climate stabilization (Laskar, Robutel, 1993)
 - 4D maps (Laskar 1993)
 - □ Galactic Dynamics (Y.P and Laskar, 1996 and 1998)
 - Accelerator beam dynamics: lepton and hadron rings (Dumas, Laskar, 1993, Laskar, Robin, 1996, Y.P, 1999, Nadolski and Laskar 2001)



Motion on torus



Consider an integrable Hamiltonian system of the usual form

$$H(\boldsymbol{J}, \boldsymbol{\varphi}, \boldsymbol{\theta}) = H_0(\boldsymbol{J})$$

Hamilton's equations give
$$\dot{\phi}_j = \frac{\partial H_0(\mathbf{J})}{\partial J_j} = \omega_j(\mathbf{J}) \Rightarrow \phi_j = \omega_j(\mathbf{J})t + \phi_{j0}$$

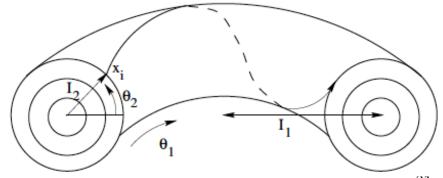
$$\dot{J}_j = -\frac{\partial H_0(\mathbf{J})}{\partial \phi_j} = 0 \Rightarrow J_j = \mathrm{const.}$$

- The actions define the surface of an invariant torus
- In complex coordinates the motion is described by

$$\zeta_j(t) = J_j(0)e^{i\omega_j t} = z_{j0}e^{i\omega_j t}$$

For a **non-degenerate** system $\det \left| \frac{\partial \omega(J)}{\partial J} \right| = \det \left| \frac{\partial^2 H_0(J)}{\partial J^2} \right| \neq 0$ there is a one-to-one correspondence between the actions and the frequency, a frequency map can be defined parameterizing the tori in the frequency space

$$F: (\mathbf{I}) \longrightarrow (\omega)$$





Quasi-periodic motion



■ If a transformation is made to some new variables

$$\zeta_j = I_j e^{i\theta_j t} = z_j + \epsilon G_j(\mathbf{z}) = z_j + \epsilon \sum_{j=1}^{n} c_{\mathbf{m}} z_1^{m_1} z_2^{m_2} \dots z_n^{m_n}$$

- The system is still integrable but the tori are distorted
- The motion is then described by

$$\zeta_j(t) = z_{j0}e^{i\omega_j t} + \sum a_{\mathbf{m}}e^{i(\mathbf{m}\cdot\omega)t}$$

i.e. a **quasi-periodic** function of time, with

$$a_{\mathbf{m}} = \epsilon \ c_{\mathbf{m}} z_{10}^{m_1} z_{20}^{m_2} \dots z_{n0}^{m_n} \text{ and } \mathbf{m} \cdot \omega = m_1 \omega_1 + m_2 \omega_2 + \dots + m_n \omega_n$$

- For a non-integrable Hamiltonian, $H(\mathbf{I}, \theta) = H_0(\mathbf{I}) + \epsilon H'(\mathbf{I}, i\theta)$ and especially if the perturbation is small, most tori persist (**KAM** theory)
- In that case, the motion is still quasi-periodic and a frequency map can be built
- The regularity (or not) of the map reveals stable (or chaotic) motion

Building the frequency map



When a quasi-periodic function f(t)=q(t)+ip(t) in the complex domain is given numerically, it is possible to recover a quasi-periodic approximation

$$f'(t) = \sum_{k=1}^{N} a'_k e^{i\omega'_k t}$$

in a very precise way over a finite time span [-T, T]several orders of magnitude more precisely than simple Fourier techniques

- This approximation is provided by the Numerical Analysis of Fundamental Frequencies – NAFF algorithm
- The frequencies ω'_k and complex amplitudes a'_k are computed through an iterative scheme.

The C

The NAFF algorithm



34

The first frequency ω'_1 is found by the location of the maximum of

$$\phi(\sigma) = \langle f(t), e^{i\sigma t} \rangle = \frac{1}{2T} \int_{-T}^{T} f(t)e^{-i\sigma t} \chi(t)dt$$

where $\chi(t)$ is a weight function

- In most of the cases the Hanning window filter is used $\chi_1(t) = 1 + \cos(\pi t/T)$
- Once the first term $e^{i\omega_1't}$ is found, its complex amplitude a_1' is obtained and the process is restarted on the remaining part of the function

$$f_1(t) = f(t) - a_1' e^{i\omega_1't}$$

■ The procedure is continued for the number of desired terms, or until a required precision is reached

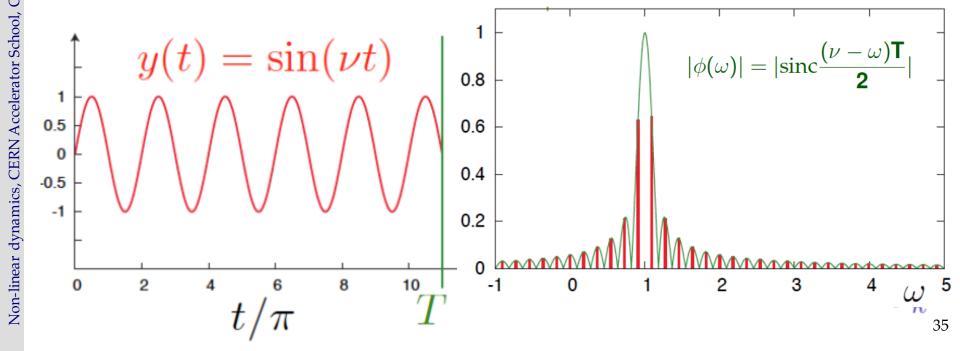


Frequency determination



- The accuracy of a simple FFT even for a simple sinusoidal signal is not better than $|\nu \nu_T| = \frac{1}{T}$
- Calculating the Fourier integral explicitly

$$\phi(\omega)=< f(t), \ e^{i\omega t}>= \frac{1}{T}\int_0^T f(t) \ e^{-i\omega t} \ dt$$
 shows that the maximum lies in between the main picks of the FFT



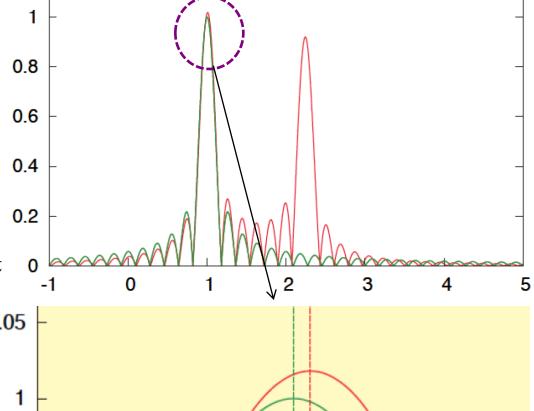


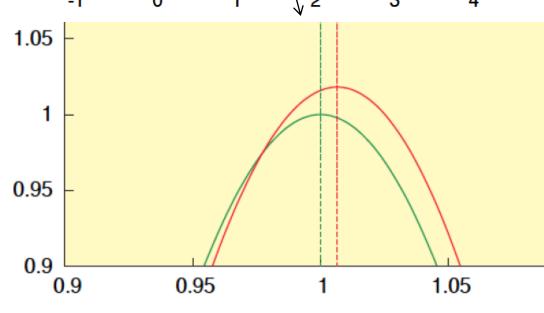
Frequency determination



A more complicated signal with two frequencies

 $f(t) = a_1 e^{i\omega_1 t} + a_2 e^{i\omega_2 t}$ shifts slightly the maximum with respect to its real location



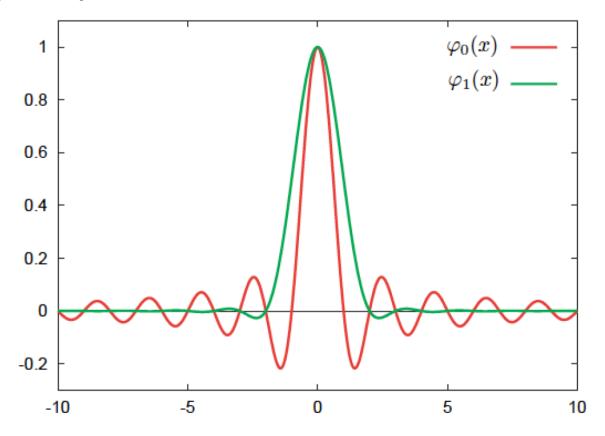




Window function



A window function like the Hanning filter $\chi_1(t) = 1 + \cos(\pi t/T)$ kills side-lobs and allows a very accurate determination of the frequency





Precision of NAFF



■ For a general window function of order

$$\chi_p(t) = \frac{2^p (p!)^2}{(2p)!} (1 + \cos \pi t)^p$$

Laskar (1996) proved a theorem stating that the solution provided by the NAFF algorithm converges asymptotically towards the real KAM quasi-periodic solution with precision

$$\nu_1 - \nu_1^T \propto \frac{1}{T^{2p+2}}$$

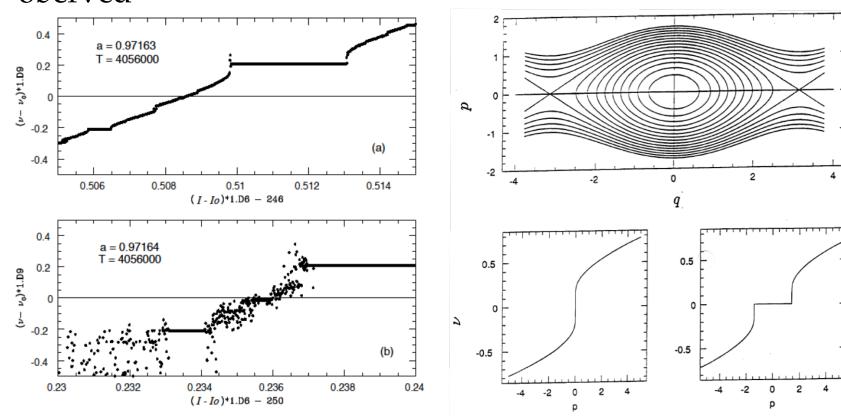
■ In particular, for no filter (i.e. p=0) the precision is $\frac{1}{\sqrt{n^2}}$, whereas for the Hanning filter (p=1), the precision is of the order of $\frac{1}{T^4}$



Aspects of the frequency map



- In the vicinity of a resonance the system behaves like a pendulum
- Passing through the elliptic point for a fixed angle, a fixed frequency (or rotation number) is observed
- Passing through the hyperbolic point, a frequency jump is oberved



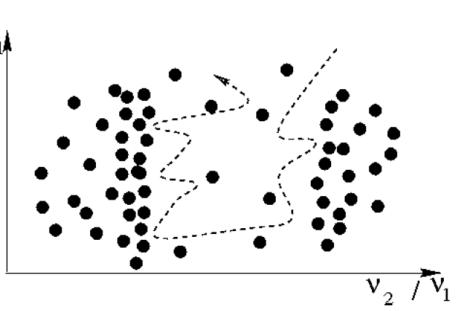


Diffusion in frequency space



- For a 2 degrees of freedom Hamiltonian system, the frequency space is a line, the tori are dots on this lines, and the chaotic zones are confined by the existing KAM tori
- For a system with 3 or more degrees of freedom, KAM tori are still represented by dots but do not prevent chaotic trajectories to diffuse
- This topological possibility v₃/v₁ of particles diffusing is called **Arnold diffusion**
- This diffusion is supposed to be extremely small in their vicinity, as tori act as effective barriers

 (Nechoroshev theory)



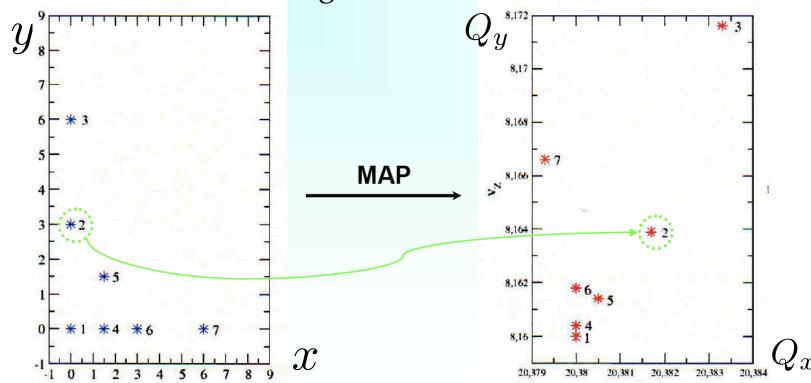


Building the frequency map



- lacksquare Choose initial conditions (x_i,y_i) with $\,(p_{x;i},p_{y;i})$
- Numerically integrate trajectories for sufficient number of turns
- Compute through NAFF $(Q_{x;i}, Q_{y;i})$ after sufficient number of turns

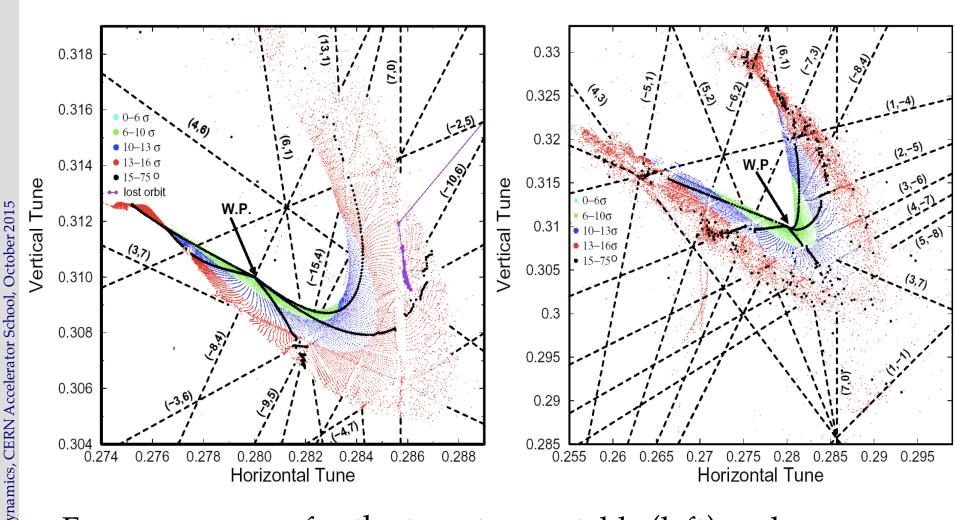
Plot them in the tune diagram





Frequency maps for the LHC





 Frequency maps for the target error table (left) and an increased random skew octupole error in the superconducting dipoles (right)



Diffusion Maps



Calculate frequencies for two equal and successive time spans and compute frequency diffusion vector:

$$D|_{t=\tau} = \nu|_{t \in (0,\tau/2]} - \nu|_{t \in (\tau/2,\tau]}$$

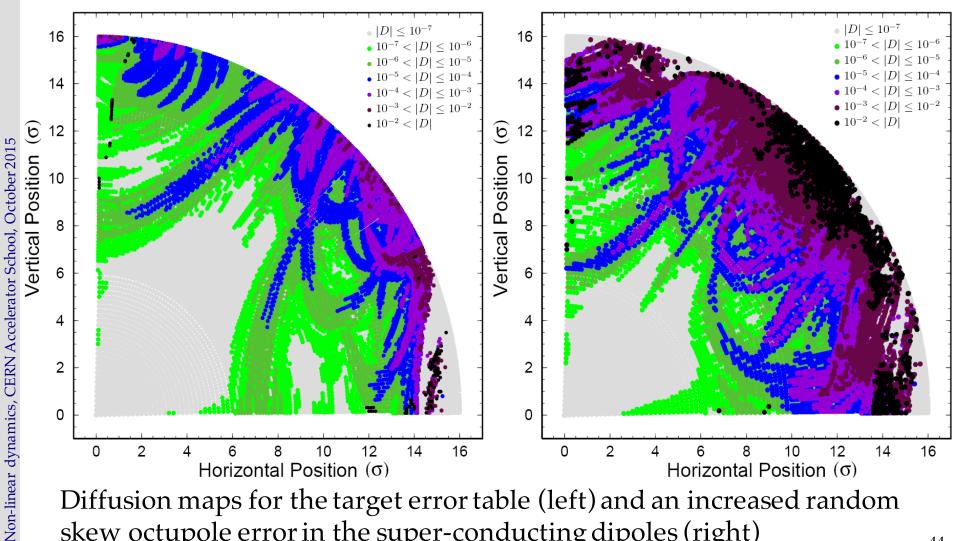
- Plot the initial condition space color-coded with the norm of the diffusion vector
- Compute a diffusion quality factor by averaging all diffusion coefficients normalized with the initial conditions radius

$$D_{QF} = \left\langle \frac{|D|}{(I_{x0}^2 + I_{y0}^2)^{1/2}} \right\rangle_R$$



Diffusion maps for the LHC





Diffusion maps for the target error table (left) and an increased random skew octupole error in the super-conducting dipoles (right)



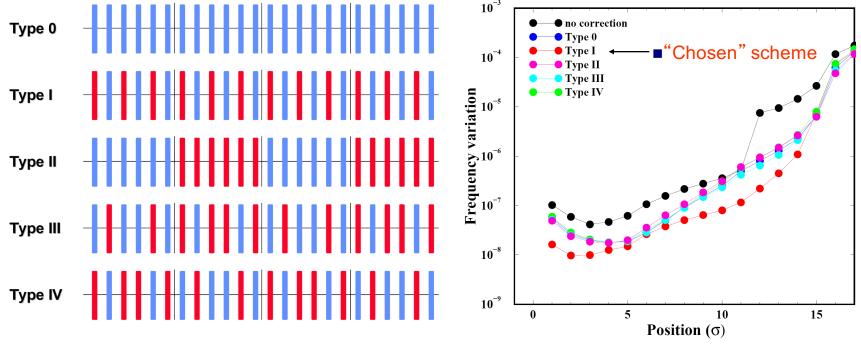


Numerical Applications



Correction schemes efficiency





- Comparison of correction schemes for b₄ and b₅ errors in the LHC dipoles
- Frequency maps, resonance analysis, tune diffusion estimates, survival plots and short term tracking, proved that only half of the correctors are needed



Beam-Beam interaction



Variable	Symbol	Value
Beam energy	E	7 TeV
Particle species		protons
Full crossing angle	$ heta_c$	$300~\mu \text{rad}$
rms beam divergence	$\sigma_{\scriptscriptstyle X}'$	31.7 μ rad
rms beam size	$\sigma_{\scriptscriptstyle X}$	$15.9~\mu\mathrm{m}$
Normalized transv.		
rms emittance	$\gamma \varepsilon$	$3.75~\mu\mathrm{m}$
IP beta function	$\boldsymbol{\beta}^*$	0.5 m
Bunch charge	N_b	$(1 \times 10^{11} - 2 \times 10^{12})$
Betatron tune	Q_0	0.31

■ Long range beam-beam interaction represented by a 4D kick-map

$$\Delta x = -n_{par} \frac{2r_p N_b}{\gamma} \left[\frac{x' + \theta_c}{\theta_t^2} \left(1 - e^{-\frac{\theta_t^2}{2\theta_{x,y}^2}} \right) - \frac{1}{\theta_c} \left(1 - e^{-\frac{\theta_c^2}{2\theta_{x,y}^2}} \right) \right]$$

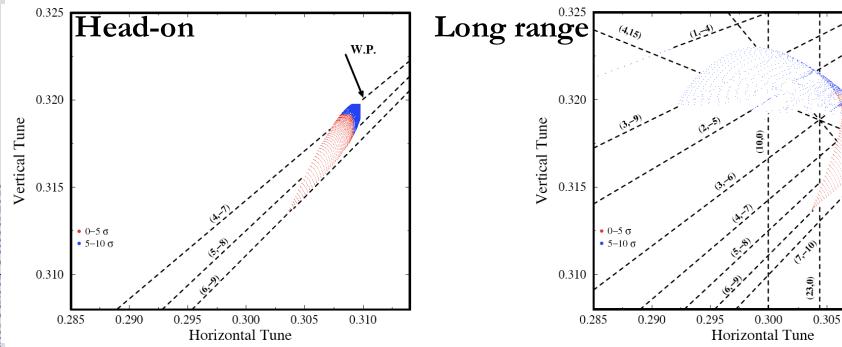
$$\Delta y = -n_{par} \frac{2r_p N_b}{\gamma} \frac{y'}{\theta_t^2} \left(1 - e^{-\frac{\theta_t^2}{2\theta_{x,y}^2}} \right)$$

with
$$\theta_t \equiv \left((x' + \theta_c)^2 + {y'}^2 \right)^{1/2}$$



Head-on vs Long range interaction





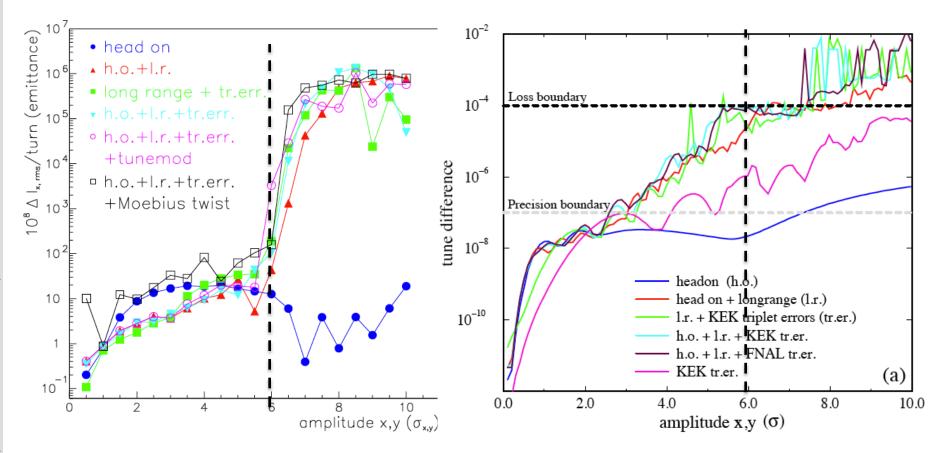
- Proved dominant effect of long range beam-beam effect
- Dynamics dominated by the 1/r part of the force, reproduced by electrical wire, which was proposed for correcting the effect
- Experimental verification in SPS and installation to the LHC IPs

0.310



Action variance vs. frequency diffusion



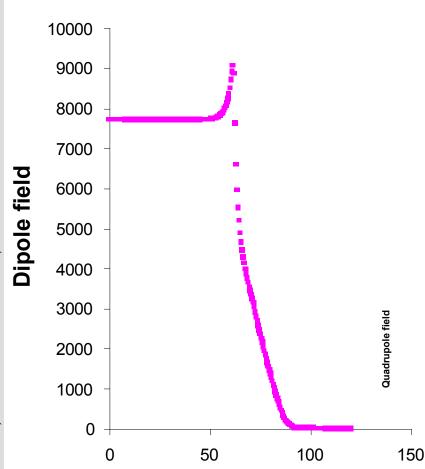


 Very good agreement of diffusive aperture boundary (action variance) with frequency variation (loss boundary corresponding to around 1 integer unit change in 10⁷ turns)



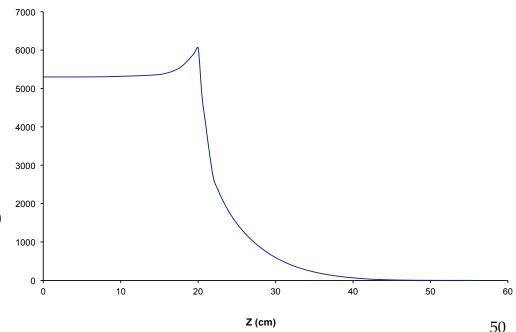
Magnet fringe fields





z (cm)

- Up to now we considered only transverse fields
- Magnet fringe field is the longitudinal dependence of the field at the magnet edges
- Important when magnet aspect ratios and/or emittances are big





Quadrupole fringe field



General field expansion for a quadrupole magnet:

$$B_x = \sum_{m,n=0}^{\infty} \sum_{l=0}^{m} \frac{(-1)^m x^{2n} y^{2m+1}}{(2n)! (2m+1)!} {m \choose l} b_{2n+2m+1-2l}^{[2l]}$$

$$B_y = \sum_{m,n=0}^{\infty} \sum_{l=0}^{m} \frac{(-1)^m x^{2n+1} y^{2m}}{(2n+1)! (2m)!} {m \choose l} b_{2n+2m+1-2l}^{[2l]}$$

$$B_z = \sum_{m,n=0}^{\infty} \sum_{l=0}^{m} \frac{(-1)^m x^{2n+1} y^{2m+1}}{(2n+1)! (2m+1)!} {m \choose l} b_{2n+2m+1-2l}^{[2l+1]}$$

and to leading order

$$B_x = y \left[b_1 - \frac{1}{12} (3x^2 + y^2) b_1^{[2]} \right] + O(5)$$

$$B_y = x \left[b_1 - \frac{1}{12} (3y^2 + x^2) b_1^{[2]} \right] + O(5)$$

$$B_z = xy b_1^{[1]} + O(4)$$

The quadrupole fringe to leading order has an octupole-like effect



Magnet fringe fields



■ From the hard-edge Hamiltonian

$$H_f = \frac{\pm Q}{12B\rho(1+\frac{\delta p}{p})} (y^3 p_y - x^3 p_x + 3x^2 y p_y - 3y^2 x p_x),$$

the first order shift of the frequencies with amplitude can be computed analytically

analytically (blue) quadrup fringe-field
$$\begin{pmatrix} \delta \nu_x \\ \delta \nu_y \end{pmatrix} = \begin{pmatrix} a_{hh} & a_{hv} \\ a_{hv} & a_{vv} \end{pmatrix} \begin{pmatrix} 2J_x \\ 2J_y \end{pmatrix},$$
 Realistic Hard-edge

with the "anharmonicity" coefficients (torsion)

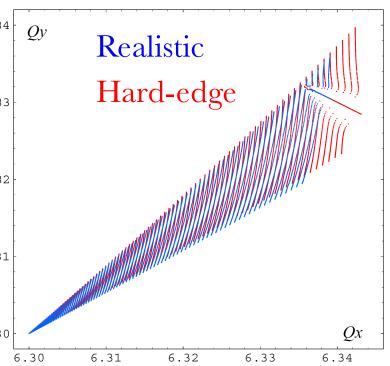
$$a_{hh} = \frac{-1}{16\pi B\rho} \sum_{i} \pm Q_{i} \beta_{xi} \alpha_{xi}$$

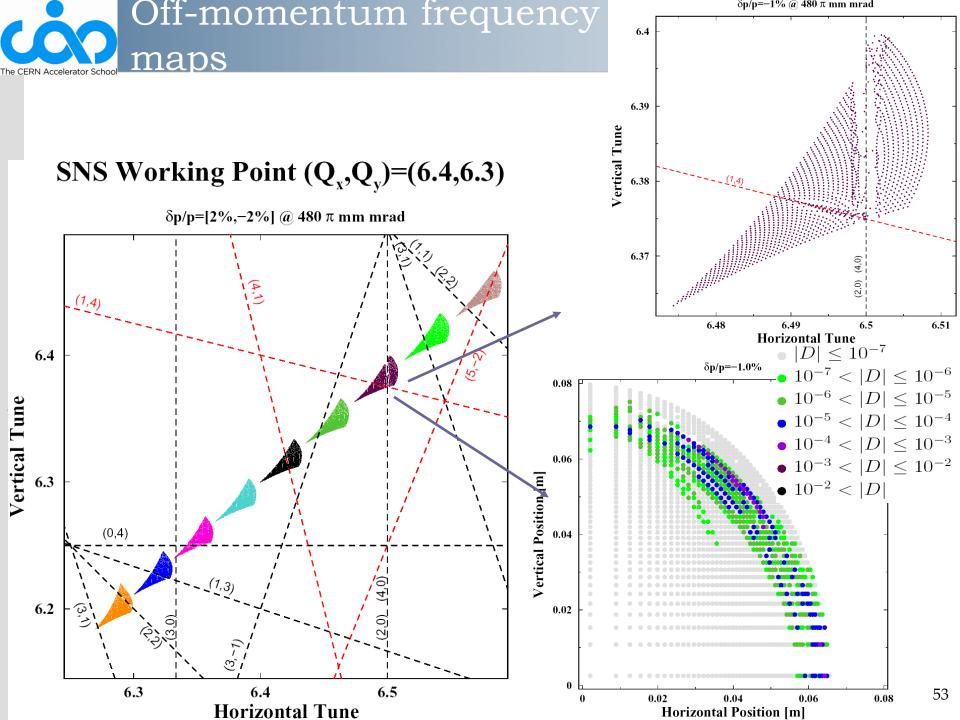
$$a_{hv} = \frac{1}{16\pi B\rho} \sum_{i} \pm Q_{i} (\beta_{xi} \alpha_{yi} - \beta_{yi} \alpha_{xi})^{5.81}$$

$$a_{vv} = \frac{1}{16\pi B\rho} \sum_{i} \pm Q_{i} \beta_{yi} \alpha_{yi}$$

$$5.80$$

Tune footprint for the SNS based on hard-edge (red) and realistic (blue) quadrupole fringe-field



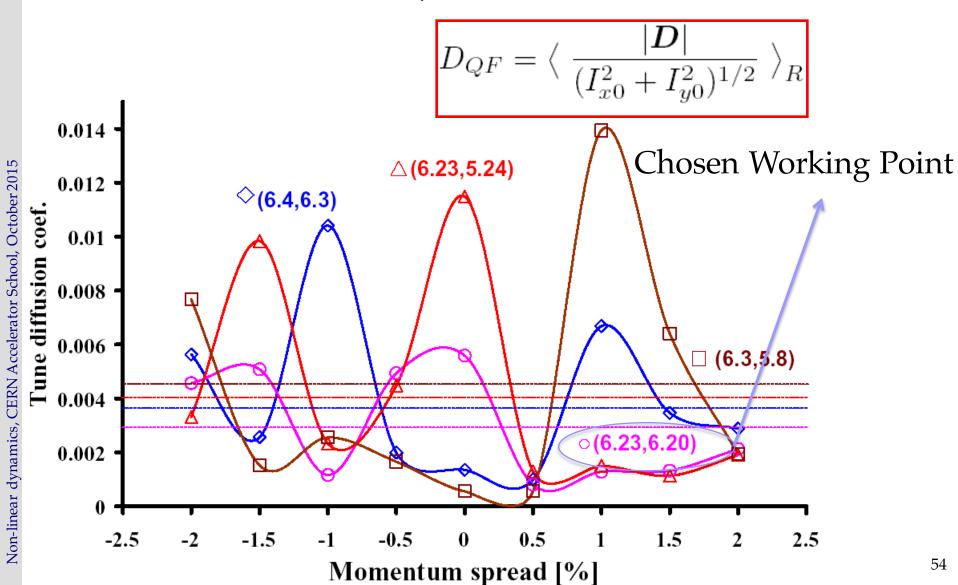




Choice of the SNS ring working poin



Tune Diffusion quality factor



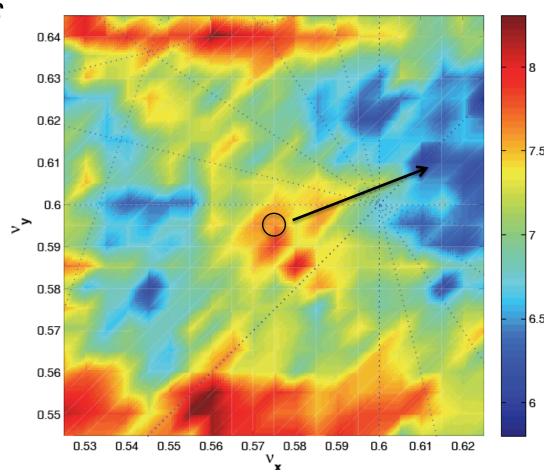


Global Working point choice



- Figure of merit for choosing best working point is sum of diffusior rates with a constant added for every lost particle
- Each point is produced after tracking 100 particles
- Nominal working point had to be moved towards "blue" area

$$e^D = \sqrt{\frac{(\nu_{x,1} - \nu_{x,2})^2 + (\nu_{y,1} - \nu_{y,2})^2}{N/2}}$$



$$WPS = 0.1N_{lost} + \sum e^{D}$$



Advanced symplectic integration schemes



- Symplectic integrators with **positive** steps for Hamiltonian systems $H = A + \epsilon B$ with both A and B **integrable** were proposed by McLachan (1995).
- Laskar and Robutel (2001) derived all orders of such integrators
- Consider the formal solution of the Hamiltonian system written in the Lie representation

$$\vec{x}(t) = \sum_{n \ge 0} \frac{t^n}{n!} L_H^n \vec{x}(0) = e^{tL_H} \vec{x}(0).$$

A symplectic integrator of order n from t to $t + \tau$ consists of approximating the Lie map $e^{\tau L_H} = e^{\tau (L_A + L_{\epsilon B})}$ by products of $e^{c_i \tau L_A}$ and $e^{d_i \tau L_{\epsilon B}}$, $i = 1, \ldots, n$ which integrate exactly A and B over the time-spans $c_i \tau$ and $d_i \tau$

lacksquare The constants c_i and d_i are chosen to reduce the error



SABA₂ integrator



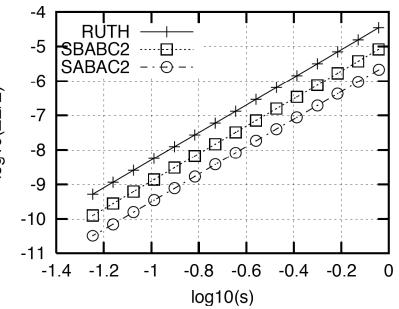
The SABA₂ integrator is written as

SABA₂ =
$$e^{c_1 \tau L_A} e^{d_1 \tau L_{\epsilon B}} e^{c_2 \tau L_A} e^{d_1 \tau L_{\epsilon B}} e^{c_1 \tau L_A}$$
, with $c_1 = \frac{1}{2} \left(1 - \frac{1}{\sqrt{3}} \right)$, $c_2 = \frac{1}{\sqrt{3}}$, $d_1 = \frac{1}{2}$.

When $\{A, B\}$, $\dot{B}\}$ is integrable, e.g. when A is quadratic in momenta and B depends only in positions, the accuracy of the integrator is improved by two small negative kicks

SABA₂C =
$$e^{-\tau^3 \epsilon^2 \frac{c}{2} L_{\{\{A,B\},B\}}}$$
 (SABA₂) $e^{-\tau^3 \epsilon^2 \frac{c}{2} L_{\{\{A,B\},B\}}}$ with $c = (2 - \sqrt{3})/24$

- The accuracy of SABA₂C is one order of magnitude higher than the Forest-Ruth 4^{th} order scheme
 - The usual "drift-kick" scheme corresponds to the $2^{\rm nd}$ order inte ${\rm SABA}_1 = e^{\frac{\tau}{2}L_A}e^{\tau L_{\epsilon B}}e^{\frac{\tau}{2}L_A}$,

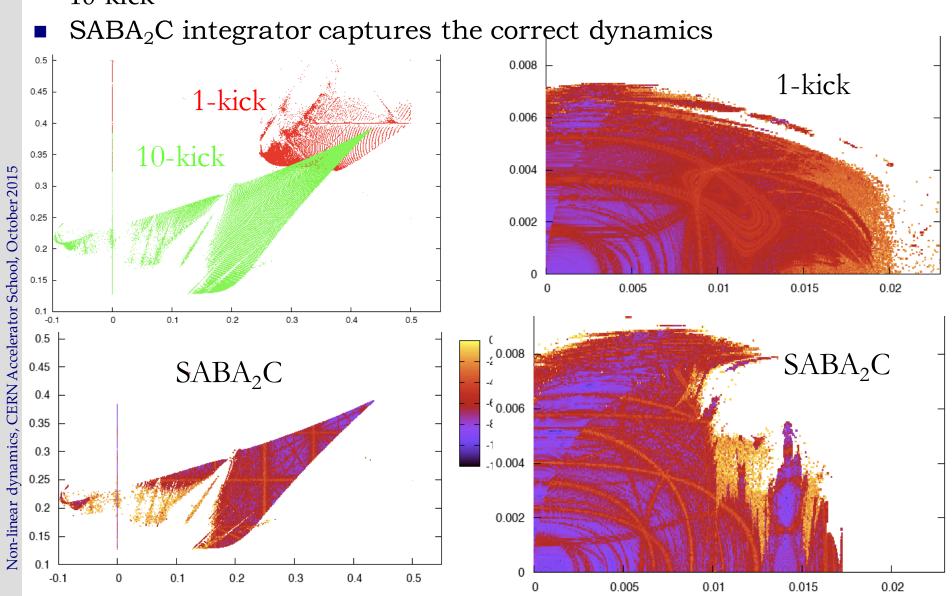




Application of the SABA₂C integrator



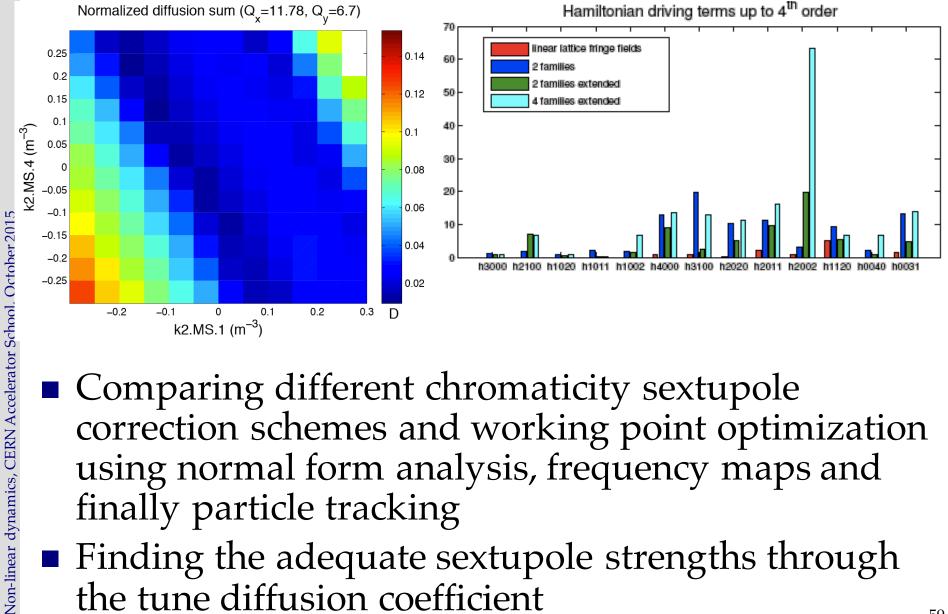
■ The one kick integrator reveals a completely different dynamics then the 10-kick





Sextupole scheme optimization





- Comparing different chromaticity sextupole correction schemes and working point optimization using normal form analysis, frequency maps and finally particle tracking
- Finding the adequate sextupole strengths through the tune diffusion coefficient



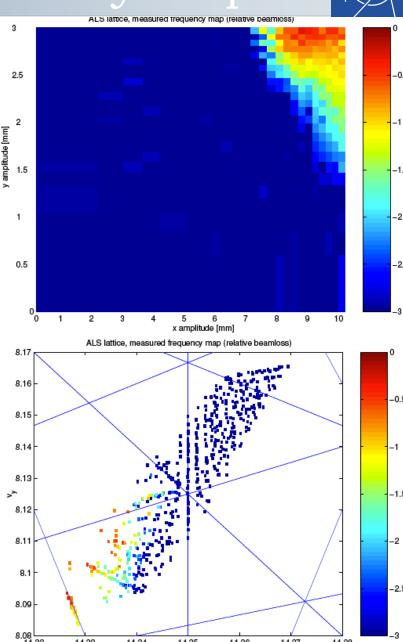


Experimental methods



Experimental frequency maps

- Frequency analysis of turnby-turn data of beam oscillations produced by a fast kicker magnet and recorded on a Beam Position Monitors
- Reproduction of the nonlinear model of the Advanced Light Source storage ring and working point optimization for increasing beam lifetime

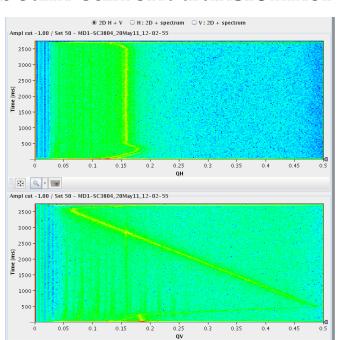


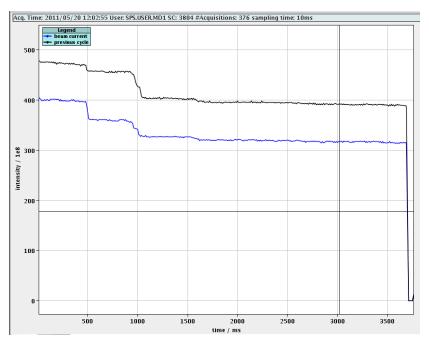


Experimental Methods – Tune scans



- Study the resonance behavior around different working points
- Strength of individual resonance lines can be identified from the beam loss rate, i.e. the derivative of the beam intensity at the moment of crossing the resonance
- □ Vertical tune is scanned from about 0.45 down to 0.05 during a period (3s) along the flat bottom
- Horizontal tune is constant during the same period
- □ Tunes are continuously monitored using tune monitor (tune postprocessed with NAFF) and the beam intensity is recorded with a beam current transformer



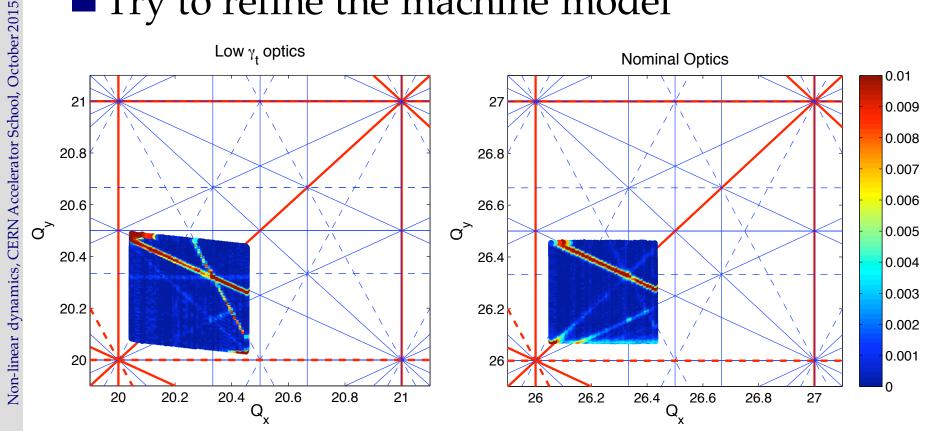




Tune Scans from the SPS



- Plot the tunes color-coded with the amount of loss
- Identify the dangerous resonances
- Compare between two different optics
- Try to refine the machine model





Summary



- Resonances (stable and unstable fixed points) are responsible for the onset of chaos
- **Dynamic aperture** by brute force tracking (with symplectic numerical integrators) is the usual quality criterion for evaluating non-linear dynamics performance of a machine
- Frequency Map Analysis is a numerical tool that enables to study in a global way the dynamics, by identifying the excited resonances and the extent of chaotic regions
- It can be directly applied to tracking but also experimental data
- A combination of these modern methods enable a thorough analysis of non-linear dynamics and lead to a robust design



Acknowledgments



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Appendix



The pendulum



An important non-linear equation which can be integrated is the one of the pendulum, for a string of length L and gravitational constant g

$$\frac{d^2\phi}{dt^2} + \frac{g}{L}\sin\phi = 0$$

- $\frac{d^2\phi}{dt^2} + \frac{g}{L}\sin\phi = 0$ For small displacements it reduces to an harmonic oscillator with frequency $\omega_0 = \sqrt{\frac{g}{L}}$
- The integral of motion (scaled energy) is

$$\frac{1}{2} \left(\frac{d\phi}{dt} \right)^2 - \frac{g}{L} \cos \phi = I_1 = E'$$

and the quadrature is written as $t=\int \frac{d\phi}{\sqrt{2(I_1+\frac{g}{L}\cos\phi)}}$ assuming that for t=0 , $\phi=0$



Solution for the pendulum



Using the substitutions $\cos \phi = 1 - 2k^2 \sin^2 \theta$ with $k = \sqrt{1/2(1 + I_1 L/g)}$, the integral is

$$t = \sqrt{\frac{L}{g}} \int_0^{\theta} \frac{d\theta}{\sqrt{1 - k^2 \sin^2 \theta}}$$
 and can be solved using

Jacobi elliptic functions: $\phi(t) = 2\arcsin\left|k\sin\left(t\sqrt{\frac{g}{L}},k\right)\right|$

For recovering the period, the integration is performed between the two extrema, i.e. $\phi = 0$ and $\phi = \arccos(-I_1L/g)$, corresponding to $\theta = 0$ and $\theta = \pi/2$, for which

$$T = 4\sqrt{\frac{L}{g}} \int_0^{\pi/2} \frac{d\theta}{\sqrt{1 - k^2 \sin^2 \theta}} = 4\sqrt{\frac{L}{g}} \mathcal{F}(\pi/2, k)$$

i.e. the complete elliptic integral multiplied by four times the period of the harmonic oscillator



Secular perturbation theory



Consider a general two degrees of freedom Hamiltonian:

$$H(\mathbf{J}, \boldsymbol{\varphi}) = H_0(\mathbf{J}) + \varepsilon H_1(\mathbf{J}, \boldsymbol{\varphi})$$
 with the perturbed part periodic in angles:

$$H_1(\mathbf{J}, \boldsymbol{\varphi}) = \sum_{k_1, k_1} H_{k_1, k_2}(J_1, J_2) \exp[i(k_1 \varphi_1 + k_2 \varphi_2)]$$

- The resonance $n_1\omega_1 + n_2\omega_2 = 0$ prevents the convergence of the series
- A canonical transformation can be applied for eliminating one action: $(\mathbf{J}, \boldsymbol{\varphi}) \longmapsto (\hat{\mathbf{J}}, \hat{\boldsymbol{\varphi}})$ using the generating function $F_r(\hat{\mathbf{J}}, \boldsymbol{\varphi}) = (n_1 \varphi_1 - n_2 \varphi_2) \hat{J}_1 + \varphi_2 \hat{J}_2$
- The relationships between new and old variables are

$$J_1 = n_1 \hat{J}_1$$
 , $J_2 = \hat{J}_2 - n_2 \hat{J}_1$
 $\hat{\varphi}_1 = n_1 \varphi_1 - n_2 \varphi_2$, $\hat{\varphi}_2 = \varphi_2$

■ This transformation put us in a rotating frame where the rate of change $\dot{\hat{\varphi_1}} = n_1 \dot{\varphi_1} - n_2 \dot{\varphi_2}$ measures the deviation from resonance



Secular perturbation theory



The transformed Hamiltonian is $\hat{H}(\hat{\mathbf{J}}, \hat{\boldsymbol{\varphi}}) = \hat{H}_0(\hat{\mathbf{J}}) + \varepsilon \hat{H}_1(\hat{\mathbf{J}}, \hat{\boldsymbol{\varphi}})$ with the perturbation written as a Fourier series

$$\hat{H}_1(\hat{\mathbf{J}}, \hat{\boldsymbol{\varphi}}) = \sum_{k_1, k_2} H_{k_1, k_2}(\hat{\mathbf{J}}) \exp\left\{ \frac{i}{n_1} \left[k_1 \hat{\varphi}_1 + (k_1 n_2 + k_2 n_1) \hat{\varphi}_1 \right] \right\}$$

■ This transformation assumes that $\dot{\varphi}_2$ is the slow frequency and we can average the Hamiltonian over the corresponding angle to obtain

$$\bar{H}(\hat{\mathbf{J}}, \hat{\boldsymbol{\varphi}}) = \bar{H}_0(\hat{\mathbf{J}}) + \varepsilon \bar{H}_1(\hat{\mathbf{J}}, \hat{\varphi}_1) \quad \text{with } \bar{H}_0(\hat{\mathbf{J}}) = \hat{H}_0(\hat{\mathbf{J}}) \text{ and}
\bar{H}_1(\hat{\mathbf{J}}, \hat{\varphi}_1) = \langle \hat{H}_1(\hat{\mathbf{J}}, \hat{\varphi}_1) \rangle_{\hat{\varphi}_2} = \sum_{\boldsymbol{H}_{-pn_1, pn_2}} H_{-pn_1, pn_2}(\hat{\mathbf{J}}) \exp(-ip\hat{\varphi}_1)$$

- The averaging eliminated one angle and thus $\hat{J}_2 = J_2 + J_1 \frac{n_2}{n_1}$ is an invariant of motion
- This means that the Hamiltonian has effectively only one degree of freedom and it is integrable



Secular perturbation theory



Assuming that the dominant Fourier harmonics for $p = 0, \pm 1$ the Hamiltonian is written as

$$\bar{H}(\hat{\mathbf{J}}, \hat{\boldsymbol{\phi}}_1) = \bar{H}_0(\hat{\mathbf{J}}) + \varepsilon \bar{H}_{0,0}(\hat{\mathbf{J}}) + 2\varepsilon \bar{H}_{n_1,-n_2}(\hat{\mathbf{J}}) \cos \hat{\varphi}_1$$

- Fixed points $(\hat{J}_{10}, \hat{\phi}_{10})$ (i.e. periodic orbits) in phase space $(\hat{J}_1, \hat{\phi}_1)$ are defined by $\frac{\partial \bar{H}}{\partial \hat{J}_1} = 0$, $\frac{\partial \bar{H}}{\partial \hat{\phi}_1} = 0$
- Move the reference on fixed point and expand $\bar{H}(\mathbf{\hat{J}})$ around $\Delta \hat{J}_1 = \hat{J}_1 \hat{J}_{10}$
- Hamiltonian describing motion near a resonance:

$$\bar{H}_r(\Delta \hat{J}_1, \hat{\phi}_1) = \frac{\partial^2 \bar{H}_0(\hat{\mathbf{J}})}{\partial \hat{J}_1^2} \bigg|_{\hat{I}_t = \hat{I}_{t,s}} \frac{(\Delta \hat{J}_1)^2}{2} + 2\varepsilon \bar{H}_{n_1, -n_2}(\hat{\mathbf{J}}) \cos \hat{\varphi}_1$$

■ Motion near a typical resonance is like the one of the pendulum!!! The frequency and the resonance half width are

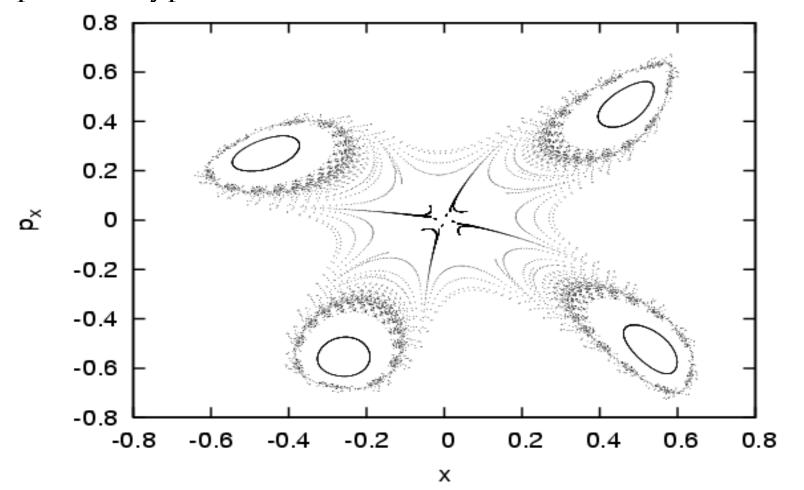
$$\hat{\omega}_{1} = \left(2\varepsilon \bar{H}_{n_{1},-n_{2}}(\mathbf{\hat{J}})\frac{\partial^{2}\bar{H}_{0}(\mathbf{\hat{J}})}{\partial\hat{J}_{1}^{2}}\Big|_{\hat{J}_{1}=\hat{J}_{10}}\right)^{1/2} \Delta \hat{J}_{1\;max} = 2\left(\frac{2\varepsilon \bar{H}_{n_{1},-n_{2}}(\mathbf{\hat{J}})}{\frac{\partial^{2}\bar{H}_{0}(\mathbf{\hat{J}})}{\partial\hat{J}_{1}^{2}}\Big|_{\hat{J}_{1}=\hat{J}_{10}}}\right)^{1/2}$$



Octupole with hyperbolic central fixed point



- lacksquare Now, if c=0 the solution for the action is $J_{20}=0$
- So there is no minima in the potential, i.e. the central fixed point is hyperbolic

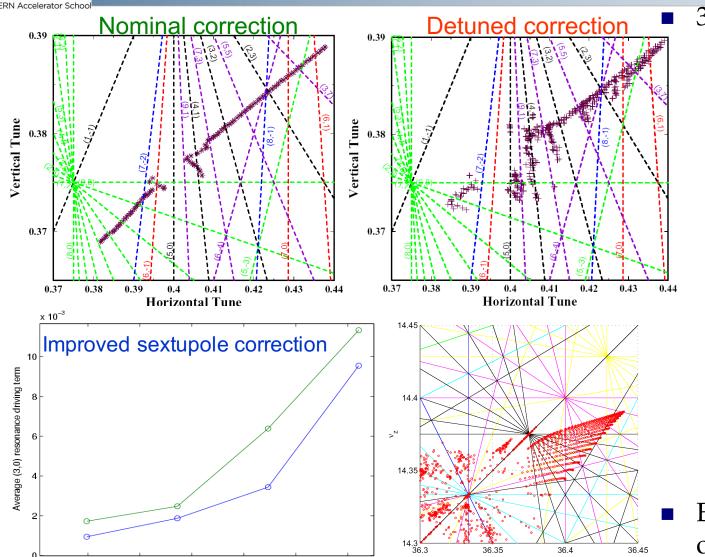




Non-linear dynamics, CERN Accelerator School, October 2019

Experimental non-linear dynamics at ESR





2.4

Initial horizontal position [m]

3 regions:

- Small amplitudes: regular motion
- Medium amplitudes: 5th order resonance crossing
- □ Large
 amplitudes:
 losses due to
 3rd order
 resonance
 crossing

Excitation of 3rd order resonance and correction with sextupole correctors

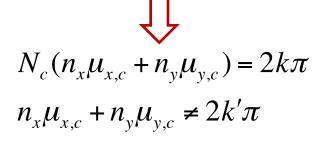


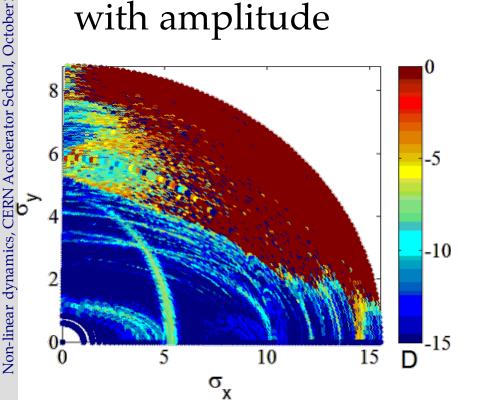
Resonance free lattice for CLIC PDR

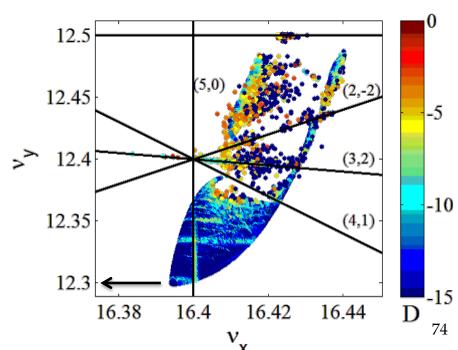


Non linear
 optimization based
 on phase advance
 scan for minimization
 of resonance driving
 terms and tune-shift

$$\left| \sum_{p=0}^{N_c - 1} e^{ip(n_x \mu_{x,c} + n_y \mu_{y,c})} \right| = \sqrt{\frac{1 - \cos\left[N_c(n_x \mu_{x,c} + n_y \mu_{y,c})\right]}{1 - \cos(n_x \mu_{x,c} + n_y \mu_{y,c})}} = 0$$







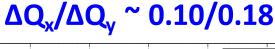


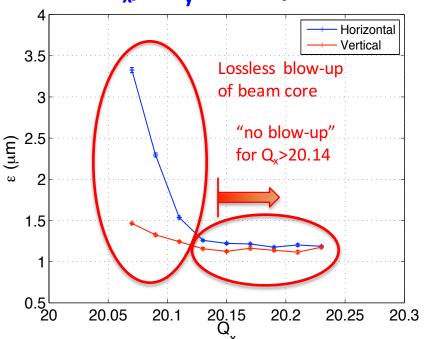
Non-linear dynamics, CERN Accelerator School,

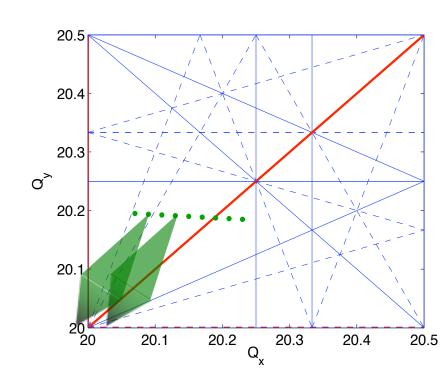
Space charge frequency scan



- Injecting high bunch density beam into the SPS
- Space charge effect quite strong with (linear) tune-shifts of
- Changing horizontal/vertical frequency and measuring emittance (action) blow-up











Space charge frequency scan



- Injecting high bunch density beam into the SPS
- Space charge effect quite strong with (linear) tuneshifts of
- Changing horizontal/vertical frequency and measuring emittance (action) blow-up

$\Delta Q_x/\Delta Q_v \sim 0.10/0.18$

