# Physics of Landau Damping

An introduction (to a mysterious topic)

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http://cern.ch/Werner.Herr/CAS2013/lectures/Trondheim\_landau.pdf

## Landau damping - the mystery

- First publication in 1946
- Applied to longitudinal oscillations of an electron plasma
  - Was not believed for  $\approx 20$  years (but worked in simulations and experiment)
  - Still plenty of papers every year ( $\approx 6000$  in 2012) (and many attempts to teach it ...)
  - Many applications: plasma physics, accelerators
  - Physical interpretation often unclear
  - Many mathematical subtleties ...

# Landau damping - the mystery

## Chronology:

Landau	(1946)	Plasma physics
Bohm, Gross	(1949)	Plasma physics
van Kampen	(1955)	Mathematical foundation
Sessler et al.	(1959)	Accelerators
•••	•••	•••
Mouhot, Villani	(2010)	Non-linear Landau Damping
		(Very detailed maths)

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  - Landau damping damps collective oscillations
  - Leads to exponentially decaying oscillations

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  - We do not want exponentially decaying oscillations "Landau damping" is confused with <u>decoherence</u>
  - Landau damping stabilizes the beam, i.e.
    - "Landau damping" is the absence of oscillations !!!

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    - "Landau damping" is the absence of oscillations !!!

- The non-trivial part:
  - In a beam (any plasma) particles interact via Coulomb forces (binary collisions)
  - For Landau damping: particles "interact" with the beam (collective modes)
- Must distinguish:
  - Binary interactions (collisions) of particles
  - > Interactions of particles with a collective mode

- In accelerators different mechanisms have been associated with "Landau damping", most popular:
  - > "Resonance damping"
  - > "Phase mixing"
- Often confused with "decoherence"
  - Landau damping does not lead to emittance growth
  - Decoherence does!
- Different treatment (and results!) for
  - Bunch and unbunched beams
  - Transverse and longitudinal motion

#### Landau damping - the menu

- > Sketch Landau's treatment for plasmas
- Mechanisms of stabilization physical origin
- Conditions for stabilization beam transfer function and stability diagrams
- Collective motion, physics and description
- Example: how it is used, limits, problems ...
- Do not go through formal mathematics (found in many places, or discussed in the bar), rather <u>intuitive</u> approach to touch the concepts, give hints ..

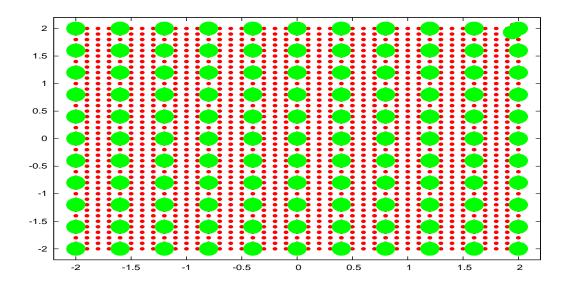
### Why an intuitive approach?

A lot of attention is often paid to interpretation of subtle (mathematical and philosophical) problems:

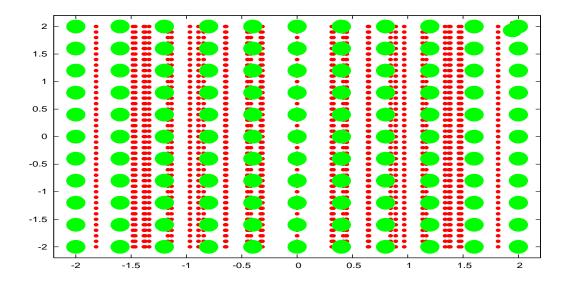
- > Singularities
- > Reversibility versus Irreversibility
- Linearity versus Non-linearity

#### The truth is:

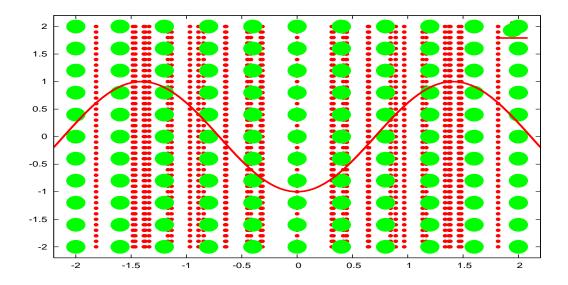
- Most "problems" are fictitious
- Not coming from the physics of the process
- Appear in specific mathematical treatment and versions of theory



Plasma without disturbance: ions (•) and electrons (•)

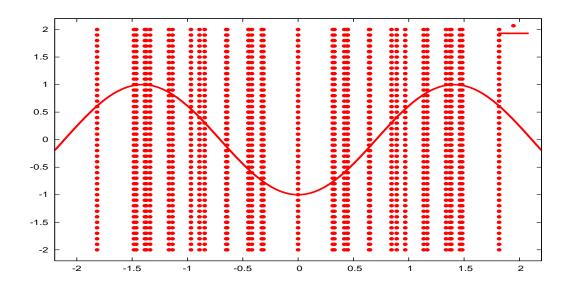


- Plasma: stationary ions (•) with displaced electrons (•)
- Restoring force: oscillate at plasma frequency  $\omega^2 = \frac{ne^2}{m\epsilon_0}$ i.e. a stationary plane wave solution (Langmuir, 1929)



- Restoring force: oscillate at plasma frequency  $\omega^2 = \frac{ne^2}{m\epsilon_0}$
- > Produces field (mode) of the form:

$$E(x,t) = E_0 \sin(kx - \omega t)$$
 (or  $E(x,t) = E_0 e^{i(kx - \omega t)}$ )



- Electrons interact with the field they produce
- Field (mode) of the form:

$$E(x,t) = E_0 \sin(kx - \omega t)$$
 (or  $E(x,t) = E_0 e^{i(kx - \omega t)}$ )

- Individual particles interact with the field produced by all particles
  - Changes behaviour of the particles
  - Can change the field producing the forces
  - → Particles may have different velocities!
- Self-consistent treatment required

If we allow  $\omega$  to be complex  $(\omega = \omega_r + i\omega_i)$ :

$$E(x,t) = E_0 e^{i(kx - \omega t)} \implies E(x,t) = E_0 e^{i(kx - \omega_r t)} \cdot e^{\omega_i t}$$

we can have a damped oscillation for  $\omega_i < 0$ 

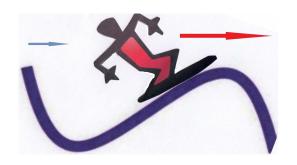
## Resonance damping

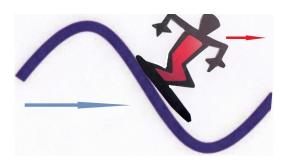
- Interaction with a "mode" -



> Surfer gains energy from the mode (wave)

## Interaction with a "mode"





- If Surfer faster than wave:

  mode gains energy from the surfer
- > If Surfer slower than wave:

  mode loses energy to the surfer
- Does that always work like that?

#### Interaction with a "mode"

- NO, consider two extreme cases:
  - > Surfer very fast: "jumps" across the wave crests, little interaction with the wave (water skiing)
  - > Surfer not moving: "oscillates" up and down with the waves
- $\longrightarrow$  Wave velocity and Surfer velocity must be similar ... !!
- Surfer is "trapped" by the wave

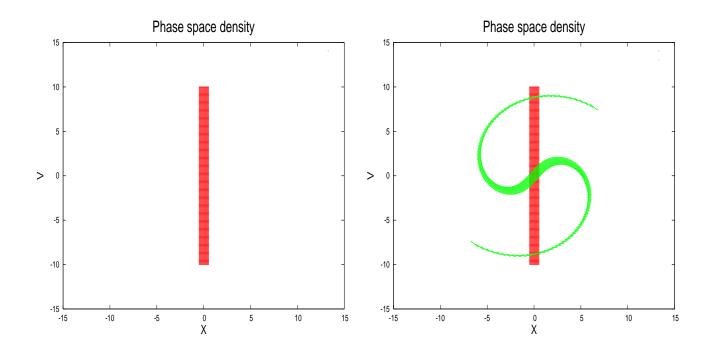
#### Interaction with a "mode"

- Remember: particles may have different velocities!
- If more particles are moving slower than the wave:
  - Net absorption of energy from the wave
  - Wave is damped!
- If more particles are moving faster than the wave:
  - Net absorption of energy by the wave
  - Wave is anti-damped!
- Always: the <u>slope</u> of the particle distribution at the wave velocity is important!
- → Have to show that now (with some theory)

#### Liouville theorem

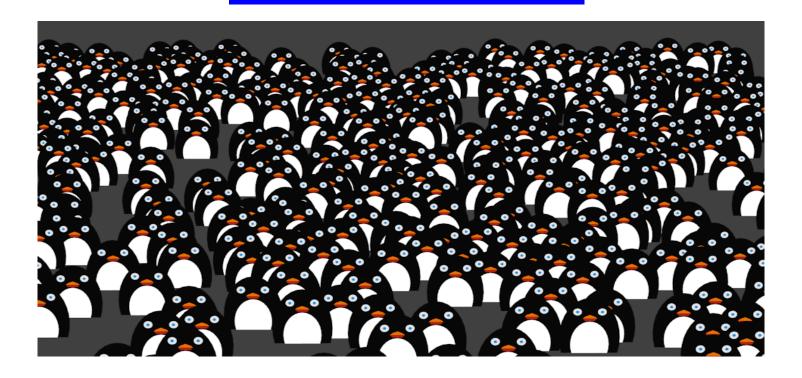
- Consider an ensemble of particles
- > Phase space moves like incompressible fluid
- Density is always conserved
- Described by a density distribution function  $\psi(\vec{x}, \vec{v}, t)$ :  $\int \psi(\vec{x}, \vec{v}, t) dx dv = N$
- If the distribution function is stationary  $\rightarrow \psi(\vec{x}, \vec{v}, t) \longrightarrow \psi(\vec{v})$

### Phase space density



- Form of phase space distorted by non-linearity
- Local phase space density is conserved
- Global density is changed (e.g. beam size)

## Phase space density



- Local phase space density is conserved (number of neighbours)
- How do we describe the evolution of the distribution?

#### Boltzmann equation

Time evolution of  $\psi(\vec{x}, \vec{v}, t)$ :

$$\frac{d\psi}{dt} = \underbrace{\frac{\partial \psi}{\partial t}}_{\text{time change}} + \underbrace{\vec{v} \cdot \frac{\partial \psi}{\partial \vec{x}}}_{\text{space change}} + \underbrace{\frac{1}{m} \vec{F}(\vec{x}, t) \cdot \frac{\partial \psi}{\partial \vec{v}}}_{\text{v change, force F}} + \underbrace{\Omega(\psi)}_{\text{collision}}$$

Without collisions and stationary, it becomes Vlasov-equation:

$$\frac{d\psi}{dt} = \frac{\partial \psi}{\partial t} + \vec{v} \cdot \frac{\partial \psi}{\partial \vec{x}} + \frac{1}{m} \vec{F}(\vec{x}, t) \cdot \frac{\partial \psi}{\partial \vec{v}} = 0$$

## Vlasov equation

In physical coordinates  $\psi(\vec{x}, \vec{v}, t)$ :

$$\frac{d\psi}{dt} = \frac{\partial\psi}{\partial t} + \vec{v} \cdot \frac{\partial\psi}{\partial\vec{x}} + \frac{1}{m}\vec{F}(\vec{x},t) \cdot \frac{\partial\psi}{\partial\vec{v}} = 0$$

 $\vec{F}(\vec{x},t)$  is force of the field (mode) on the particles No binary collisions between particles

#### INTERLUDE

Why is the Vlasov equation useful?

$$\frac{d\psi}{dt} = \frac{\partial \psi}{\partial t} + \vec{v} \cdot \frac{\partial \psi}{\partial \vec{x}} + \frac{1}{m} \vec{F}(\vec{x}, t) \cdot \frac{\partial \psi}{\partial \vec{v}} = 0$$

 $\vec{F}(\vec{x},t)$  can be forces introduced by impedances, beam-beam effects, etc. From the solution one can determine whether a disturbance is growing (instability, negative imaginary part of frequency) or decaying (stability, positive imaginary part of frequency).

#### INTERLUDE

Why is the Vlasov equation useful?

$$\frac{d\psi}{dt} = \frac{\partial \psi}{\partial t} + \vec{v} \cdot \frac{\partial \psi}{\partial \vec{x}} + \frac{1}{m} \vec{F}(\psi, \vec{x}, t) \cdot \frac{\partial \psi}{\partial \vec{v}} = 0$$

strictly speaking:  $\vec{F}(\vec{x},t)$  are given by <u>external</u> forces. When a particle interacts strongly with the <u>collective</u> forces produced by the other particles, they can be treated the same as external forces.

#### INTERLUDE

Why is the Vlasov equation useful?

$$\frac{d\psi}{dt} = \frac{\partial \psi}{\partial t} + \vec{v} \cdot \frac{\partial \psi}{\partial \vec{x}} + \frac{1}{m} \vec{F}(\vec{x}, t) \cdot \frac{\partial \psi}{\partial \vec{v}} = 0$$

- This is the basis for treatment of collective effects
- Warning, it does not apply for:

Dissipative forces (gas scattering, IBS, ...)

Random forces (e.g. radiation ..)

Would need "Fokker-Planck" equation

#### Back to Plasma Oscillations

For our problem we need:

for the force  $\vec{F}$  (depending on field  $\vec{E}$ ):

$$\vec{F} = e \cdot \vec{E}$$

for the field  $\vec{E}$  (depending on potential  $\Phi$ ):

$$\vec{E} = -\nabla\Phi$$

for the potential  $\Phi$  (depending on distribution  $\psi$ ):

$$\Delta \Phi = -\frac{\rho}{\epsilon_0} = -\frac{e}{\epsilon_0} \int \psi dv$$

Therefore:

$$\frac{d\psi}{dt} = \frac{\partial \psi}{\partial t} + \vec{v} \cdot \frac{\partial \psi}{\partial \vec{x}} + \frac{1}{m} \vec{E}(\vec{x}, t) \cdot \frac{\partial \psi}{\partial \vec{v}} = 0$$

and:

$$\Delta \Phi = \frac{e}{\epsilon_0} \int \psi dv$$

Coupled equations: perturbation produces field which acts back on perturbation.

Do we find a solution?

Assume a small <u>non-stationary</u> perturbation  $\psi_1$  on the stationary distribution  $\psi_0(\vec{v})$ :

$$\psi(\vec{x}, \vec{v}, t) = \psi_0(\vec{v}) + \psi_1(\vec{x}, \vec{v}, t)$$

Then we get:

$$\frac{d\psi}{dt} = \frac{\partial \psi_1}{\partial t} + \vec{v} \cdot \frac{\partial \psi_1}{\partial \vec{x}} + \frac{1}{m} \vec{E}(\vec{x}, t) \cdot \frac{\partial \psi_0}{\partial \vec{v}} = 0$$

and:

$$\Delta \Phi = -\frac{\rho}{\epsilon_0} = -\frac{e}{\epsilon_0} \int \psi_1 dv$$

$$\psi_1(\vec{x}, \vec{v}, t) \implies \vec{E}(\vec{x}, t) \implies \psi_1(\vec{x}, \vec{v}, t) \implies \dots$$

- > Density perturbation produces electric field
- > Electric field acts back and changes density perturbation
- Change with time ...
- How can we attack that?

#### Plasma oscillations - Vlasov's approach

#### Expand as double Fourier transform:\*)

$$\psi_1(\vec{x}, \vec{v}, t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \tilde{\psi}_1(k, \vec{v}, \omega) e^{i(kx - \omega t)} dk d\omega$$

$$\Phi(\vec{x}, \vec{v}, t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \tilde{\Phi}(k, \vec{v}, \omega) e^{i(kx - \omega t)} dk d\omega$$

#### and apply to Vlasov equation

\*) Remember: we assumed the field (mode) of the form:  $E(x,t)=E_0e^{i(kx-\omega t)}$ 

Assuming a perturbation as above, the condition for a solution is:

$$1 + \frac{e^2}{\epsilon_0 mk} \int \frac{\partial \psi_0 / \partial v}{(\omega - kv)} dv = 0$$

This is the Dispersion Relation for plasma waves i.e. relation between frequency  $(\omega)$  and wavelength (k)

#### Looking at this relation:

- $\blacktriangleright$  It depends on the (velocity) distribution  $\psi$
- $\rightarrow$  It depends on the slope of the distribution  $\partial \psi_0/\partial v$
- The effect is strongest for velocities close to the wave velocity, i.e.  $v \approx \frac{\omega}{k}$

#### Plasma oscillations

#### Looking at this relation:

- $\blacktriangleright$  It depends on the (velocity) distribution  $\psi$
- $\rightarrow$  It depends on the slope of the distribution  $\partial \psi_0/\partial v$
- The effect is strongest for velocities close to the wave velocity, i.e.  $v \approx \frac{\omega}{k}$
- There seems to be a complication (singularity) at  $v \equiv \frac{\omega}{k}$ Can we deal with this problem?

## Dealing with the singularity

- Handwaving argument (Vlasov):
  - $\triangleright$  In practice  $\omega$  is never real (collisions !)
- Optimistic argument (Bohm et al.):
  - $\partial \psi_0/\partial v = 0$  where  $v \equiv \frac{\omega}{k}$
- Alternative approach (van Kampen):
  - > Search for stationary solutions (normal mode expansion)
  - Continous versus discrete modes (not treated here)
- Better argument (Landau):
  - Initial value problem with perturbation  $\psi_1(\vec{x}, \vec{v}, t)$  at t = 0, (time dependent solution with complex  $\omega$ )
  - Solution: in time domain use Laplace transformation in space domain use Fourier transformation

## Plasma oscillations - Landau's approach

#### Fourier transform in space domain:

$$\tilde{\psi}_1(k, \vec{v}, t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \psi_1(\vec{x}, \vec{v}, t) e^{i(kx)} dx$$

$$\tilde{E}(k,t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} E(\vec{x},t) e^{i(kx)} dx$$

#### and Laplace transform in time domain:

$$\Psi_1(k, \vec{v}, p) = \int_0^{+\infty} \tilde{\psi}_1(k, \vec{v}, t) e^{(-pt)} dt$$

$$\mathcal{E}(k,p) = \int_0^{+\infty} \tilde{E}(k,t)e^{(-pt)}dt$$

#### Plasma oscillations

In Vlasov equation and after some algebra (see books) this leads to the modified dispersion relation:

$$1 + \frac{e^2}{\epsilon_0 mk} \left[ P.V. \int \frac{\partial \psi_0 / \partial v}{(\omega - kv)} dv - \frac{i\pi}{k} \left( \frac{\partial \psi_0}{\partial v} \right)_{v = \omega/k} \right] = 0$$

P.V. refers to "Cauchy Principal Value"

Second term only in Landau's treatment 

responsible for damping

#### Plasma oscillations

#### Evaluating the term:

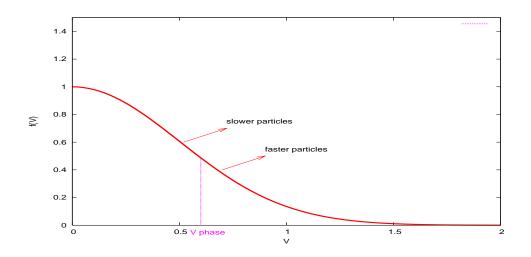
$$-\frac{i\pi}{k} \left(\frac{\partial \psi}{\partial v}\right)_{v=\omega/k}$$

 $\rightarrow \omega$  is complex and the imaginary part becomes:

$$Im(\omega) = \omega_i = \frac{\pi}{2} \frac{\omega_p e^2}{\epsilon_0 m k^2} \left(\frac{\partial \psi}{\partial v}\right)_{v = \omega/k}$$

- Example Get a damping (without collisions) if:  $\left(\frac{\partial \psi}{\partial v}\right)_{v=\omega/k} < 0$
- -> Landau Damping

# Velocity distribution



- Distribution of particle velocities (e.g. Maxwellian distribution)
- ➤ More "slower" than "faster" particles → damping
- ➤ More "faster" than "slower" particles → anti-damping

# Warning: a paradox

For a bar discussion

If this is true:

Should it not be possible to go to a Lorentz frame which is moving relative to the particles faster than the wave (phase-) velocity?

In this frame we have always anti-damping!!

Is this true???

# Now what about accelerators ???

- Landau damping in plasmas, all right
- Physical origin rather simple
- How to apply it in accelerators?
- We have:
  - No plasmas but beams
  - No distribution of velocity, but tune
  - No electrons, but ions (e.g. p)
  - > Also transverse oscillations

#### Now what about accelerators ???

- How to apply it in accelerators?
- Can be formally solved using Vlasov equation, but physical interpretation very fuzzy (and still debated ..)
- Different (more intuitive) treatment (following Chao, Hofmann, Hereward, Sagan)
- Look now at:
  - **Beam response to excitation**
  - Beam transfer function and stability diagrams
  - Phase mixing
  - Conditions and tools for stabilization, problems

How does a beam respond to an external excitation?

Consider a harmonic, linear oscillator with frequency  $\omega$  driven by an external sinusoidal force f(t) with frequency  $\Omega$ : The equation of motion is:

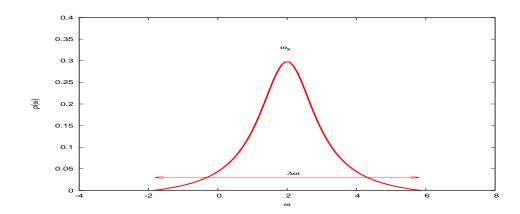
$$\ddot{x} + \omega^2 x = A \cos\Omega t = f(t)$$

for initial conditions x(0) = 0 and  $\dot{x}(0) = 0$  the solution is:

$$x(t) = -\frac{A}{(\Omega^2 - \omega^2)} (\cos \Omega t \underbrace{-\cos \omega t}_{x(0)=0, \dot{x}(0)=0})$$

The beam consists of an ensemble of oscillators with different frequencies  $\omega$  with a distribution  $\rho(\omega)$  and a spread  $\Delta\omega$ . Number of particles per frequency band:

$$\rho(\omega) = \frac{1}{N} dN/d\omega$$
 with  $\int_{-\infty}^{\infty} \rho(\omega) d\omega = 1$ 



reminder: for a transverse (betatron motion)  $\omega_x$  is the tune!

# IMPORTANT MESSAGE!

- $ho(\omega)$  is distribution of external focusing frequencies !
  - Transverse, bunched and unbunched beams: betatron tune
  - Longitudinal, bunched beams: synchrotron tune
  - Longitudinal, unbunched beams: ??? (see later!)
- $\Delta\omega$  is spread of external focusing frequencies !

The beam consists of an ensemble of oscillator with different frequencies  $\omega$  with a distribution  $\rho(\omega)$ , number of particles per frequency band:

$$\rho(\omega) = \frac{1}{N} dN/d\omega \text{ with } \int_{-\infty}^{\infty} \rho(\omega) d\omega = 1$$

The average beam response (centre of mass) is then:

$$< x(t) > = \int_{-\infty}^{\infty} x(t)\rho(\omega)d\omega =$$

$$< x(t) > = -\int_{-\infty}^{\infty} \left[ \frac{A}{(\Omega^2 - \omega^2)} (\cos \Omega t - \cos \omega t) \right] \rho(\omega) d\omega$$

We can re-write (simplify) the expression

$$< x(t) > = -\int_{-\infty}^{\infty} \left[ \frac{A}{(\Omega^2 - \omega^2)} (\cos \Omega t - \cos \omega t) \right] \rho(\omega) d\omega$$

for a narrow beam spectrum around a frequency  $\omega_x$  (tune) and the driving force near this frequency  $\Omega \approx \omega_x^{*}$ )

$$< x(t) > = -\frac{A}{2\omega_x} \int_{-\infty}^{\infty} \left[ \frac{1}{(\Omega - \omega)} (\cos \Omega t - \cos \omega t) \right] \rho(\omega) d\omega$$

For the further evaluation we transform variables from  $\omega$  to  $u = \omega - \Omega$ , and assume that  $\Omega$  is complex:  $\Omega = \Omega_r + i\Omega_i$ 

\*) justified later ... (but you may already guess!)

We get now two contributions to the integral:

$$\langle x(t) \rangle = -\frac{A}{2\omega_x} cos(\Omega t) \int_{-\infty}^{\infty} du \ \rho(u + \Omega) \frac{1 - cos(ut)}{u} + \frac{A}{2\omega_x} sin(\Omega t) \int_{-\infty}^{\infty} du \ \rho(u + \Omega) \frac{sin(ut)}{u}$$

This avoids singularities for u = 0

We are interested in long term behaviour,

i.e.  $t \to \infty$ , so we use:

$$\lim_{t \to \infty} \frac{\sin(ut)}{u} = \pi \delta(u)$$

$$\lim_{t \to \infty} \frac{1 - \cos(ut)}{u} = P.V. \left(\frac{1}{u}\right)$$

and obtain for the asymptotic behaviour (back to  $\omega, \Omega$ )\*):

$$< x(t) > = \frac{A}{2\omega_x} \left[ \pi \rho(\Omega) sin(\Omega t) + cos(\Omega t) P.V. \int_{-\infty}^{\infty} d\omega \frac{\rho(\omega)}{(\omega - \Omega)} \right]$$

The response or Beam Transfer Function has a:

- Resistive part: absorbs energy from oscillation damping (would not be there without the term  $-\cos \omega t$ )
- Reactive part: "capacitive" or "inductive", depending on sign of term relative to driving force

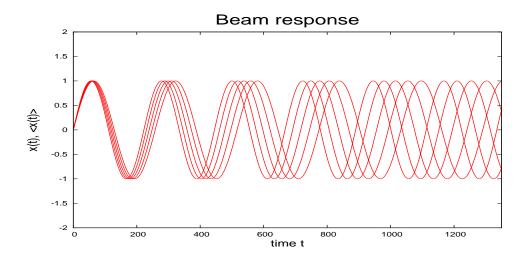
<sup>\*)</sup> Assuming  $\Omega$  is complex, we integrate around the pole and obtain a 'principal value P.V.' and a 'residuum' (Sokhotski-Plemelj formula)

#### What do we see:

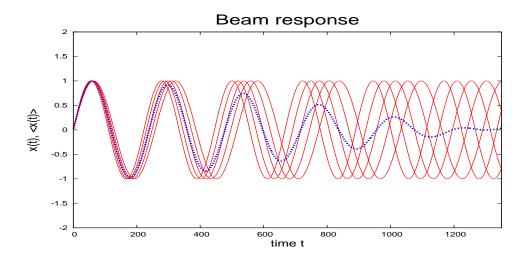
- The "damping" part only appeared because of the initial conditions !!!
- With other initial conditions, we get additional terms in the beam response
- $\blacktriangleright$  I.e. for  $x(0) \neq 0$  and  $\dot{x}(0) \neq 0$  we may add:

$$x(0) \int d\omega \rho(\omega) cos(\omega t) + \dot{x}(0) \int d\omega \rho(\omega) \frac{sin(\omega t)}{\omega}$$

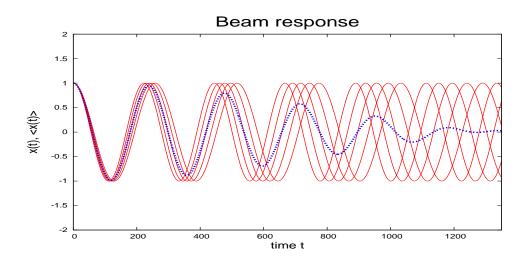
> Do not participate in the dynamics, what do they do?



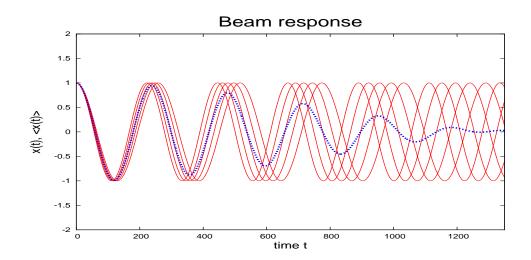
- Oscillation of particles with different tunes
- $\rightarrow$  Initial conditions: x(0) = 0 and  $\dot{x}(0) \neq 0$



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- Average over particles, centre of mass motion



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This is NOT Landau Damping!!

# Physics of Landau Damping

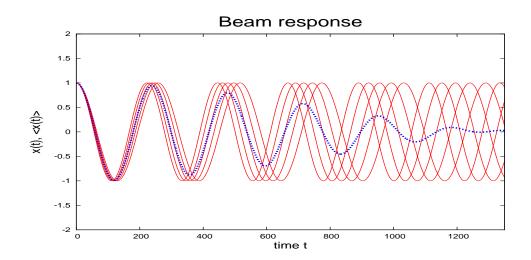
Part 2

Werner Herr CERN

http://cern.ch/Werner.Herr/CAS2013/lectures/Trondheim\_landau.pdf

# Interpretation of Landau Damping

- Initial conditions: x(0) = 0 and  $\dot{x}(0) = 0$ , beam is quiet
- Spread of frequencies  $\rho(\omega)$
- When an excitation is applied:
  - Particles cannot organize into collective response (phase mixing)
  - > Average response is zero
  - The beam is kept stable, i.e. stabilized



- > Oscillation of particles with different tunes
- $\rightarrow$  Initial conditions:  $x(0) \neq 0$  and  $\dot{x}(0) = 0$
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# Interpretation of Landau Damping

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- Spread of frequencies  $\rho(\omega)$
- When an excitation is applied:
  - Particles cannot organize into collective response (phase mixing)
  - > Average response is zero
  - The beam is kept stable, i.e. stabilized
- → Next : quantitative analysis

For this, we re-write (simplify) the response in complex notation:

$$< x(t) > = \frac{A}{2\omega_x} \left[ \pi \rho(\Omega) sin(\Omega t) + cos(\Omega t) P.V. \int_{-\infty}^{\infty} d\omega \frac{\rho(\omega)}{(\omega - \Omega)} \right]$$

becomes:

$$< x(t) > = \frac{A}{2\omega_x} e^{-i\Omega t} \left[ P.V. \int d\omega \frac{\rho(\omega)}{(\omega - \Omega)} + i\pi \rho(\Omega) \right]$$

First part describes oscillation with complex frequency  $\Omega$ 

Reminds us a few things ....

Since we know the collective motion is described as  $e^{(-i\Omega t)}$ For an oscillating solution  $\Omega$  must fulfill the relation

$$1 + \frac{1}{2\omega_x} \left[ P.V. \int d\omega \frac{\rho(\omega)}{(\omega - \Omega)} + i\pi \rho(\Omega) \right] = 0$$

This is again a dispersion relation, i.e. condition for oscillating solution.

What do we do with that ??

Well, look where  $\Omega_i < 0$  provides damping !!

Note: no contribution to damping when  $\Omega$  outside spectrum !!

Simplify by moving to normalized parametrization. Following Chao's proposal, in the expression:

$$< x(t) > = \frac{A}{2\omega_x} e^{-i\Omega t} \left[ P.V. \int d\omega \frac{\rho(\omega)}{(\omega - \Omega)} + i\pi \rho(\Omega) \right]$$

we use again u, but normalized to frequency spread  $\Delta\omega$ :

with 
$$u = (\omega_x - \Omega)$$
  $\longrightarrow$   $u = \frac{(\omega_x - \Omega)}{\Delta\omega}$ 

and introduce two functions f(u) and g(u):

$$f(u) = \Delta \omega P.V. \int d\omega \frac{\rho(\omega)}{\omega - \Omega}$$

$$g(u) = \pi \Delta \omega \rho(\omega_x - u \Delta \omega) = \pi \Delta \omega \rho(\Omega)$$

The response with the driving force discussed above:

$$\langle x(t) \rangle = \frac{A}{2\omega_x \Delta\omega} e^{-i\Omega t} [f(u) + i \cdot g(u)]$$

where  $\Delta\omega$  is the frequency spread of the distribution. The expression  $f(u) + i \cdot g(u)$  is the Beam Transfer Function Easier with this to evaluate the different cases and

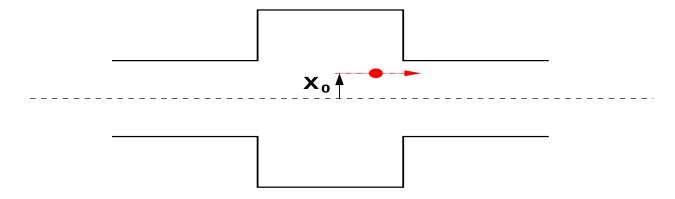
examples ....

For important distributions  $\rho(\omega)$  analytical functions f(u) and g(u) exist (see e.g. Chao, Tigner, "Handbook ..")

Will lead us to stability diagrams.

# Response of a beam in presence of wake fields

Example: the driving force comes from the displacement of the beam as a whole, i.e.  $\langle x \rangle = X_0$ ! For example driven by a wakefield or impedance.



The equation of motion for a particle is then something like:

$$\ddot{x} + \omega^2 x = f(t) = K \cdot \langle x \rangle$$

where K is a "coupling coefficient"

Coupling coefficient K depends on nature of wake field:

- Purely real:
  - Force in phase with the displacement
  - e.g. image space charge in perfect conductor
- > Purely imaginary:
  - Force in phase with the velocity
- In practice, have both and we can write:

$$K = 2\omega_x(U - iV)$$

## Response of a beam in presence of wake fields

#### Interpretation:

- A beam travelling off centre through an impedance induces transverse fields
- Transverse fields kick back on all particles in the beam, via:

$$\ddot{x} + \omega^2 x = f(t) = K \cdot \langle x \rangle$$

- If beam moves as a whole (in phase, collectively !) this can grow for V > 0
- The coherent frequency  $\Omega$  becomes complex and shifted by  $(\Omega \omega_x)^{*}$

 $<sup>^{*)}</sup>$  without impedance:  $\Omega=\omega_x$  (betatron frequency, i.e.tune)

For a beam without frequency spread  $(\rho(\omega) = \delta(\omega - \omega_x))$  we can easily sum over all particles and for the centre of mass motion < x > we get:

$$<\ddot{x}> + \Omega^2 < x> = f(t) = -2\omega_x(U - iV) < x>$$

- For the original coherent motion with frequency  $\Omega$  this means
  - In-phase component U changes the frequency
  - Out-of-phase component V creates growth (V > 0) or damping (V < 0)

For any V > 0 the beam is unstable (even if very small) !!

# Response of a beam in presence of wake fields

What happens for a beam with an frequency spread?

The response (and therefore the driving force) was:

$$\langle x(t) \rangle = \frac{A}{2\omega_x \Delta\omega} e^{-i\Omega t} [f(u) + i \cdot g(u)]$$

# Response of a beam in presence of wake fields

The (complex) frequency  $\Omega$  is now determined by the condition:

$$-\frac{(\Omega - \omega_x)}{\Delta \omega} = \frac{1}{(f(u) + ig(u))}$$

All information about stability contained in this relation!

- The (complex) frequency difference  $(\Omega \omega_x)$  contains impedance, intensity,  $\gamma$ , ... (see lecture by G. Rumolo).
- The right hand side contains information about the frequency spectrum (see definitions for f(u) and g(u)).

Without Landau damping (no frequency spread):

- If  $\Im(\Omega \omega_x) < 0$  beam is stable
- If  $\Im(\Omega \omega_x) > 0$  beam is unstable (growth rate  $\tau^{-1}$ !)

With Landau damping we have a condition for stability:

$$-\frac{(\Omega - \omega_x)}{\Delta \omega} = \frac{1}{(f(u) + ig(u))}$$

How to proceed to find limits?

Could find the complex  $\Omega$  at edge of stability ( $\tau^{-1} = 0$ !)

→ Can do a bit more ...

Look at the right hand side first.

Take the (real) parameter u in

$$D_1 = \frac{1}{(f(u) + ig(u))}$$

- 1 Scan u from  $-\infty$  to  $+\infty$
- 2 Plot the real and imaginary part of  $D_1$  in complex plane

Why is this formulation interesting ??? The expression:

$$(f(u) + ig(u))$$

is actually the Beam Transfer Function, i.e. it can be measured!!

- With its knowledge (more precise: its inverse) we have conditions on  $(\Omega \omega_x)$  for stability
- > Intensities, impedances, ...

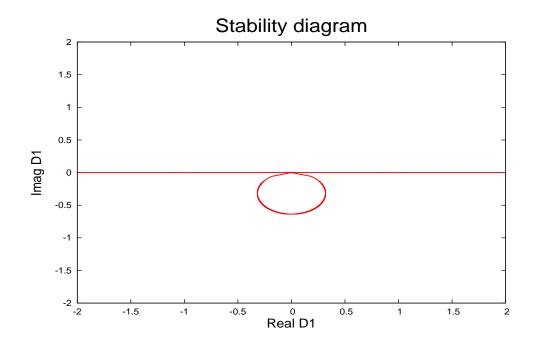
Example: rectangular distribution:

$$\rho(\omega) = \begin{cases} \frac{1}{2\Delta\omega} & \text{for} |\omega - \omega_x| \le \Delta\omega \\ 0 & \text{otherwise} \end{cases}$$

Step 1: Compute f(u) and g(u) (or look it up, e.g. Chao, Tigner, "Handbook of ...")

$$f(u) = \frac{1}{2} \ln \left| \frac{u+1}{u-1} \right|$$
  $g(u) = \frac{\pi}{2} \cdot H(1-|u|)$ 

Step 2: Plot the real and imaginary part of  $D_1$ 

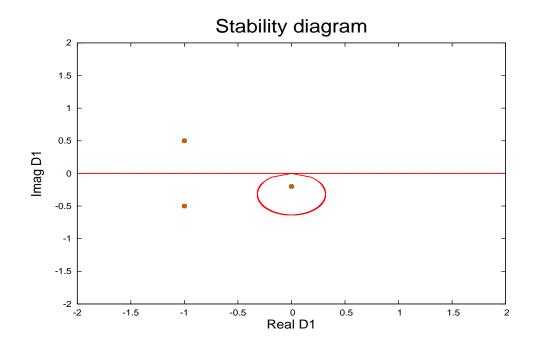


- $\triangleright$  Real $(D_1)$  versus Imag $(D_1)$  for rectangular  $\rho(\omega)$
- This is a Stability Boundary Diagram
- > Separates stable from unstable regions (stability limit)

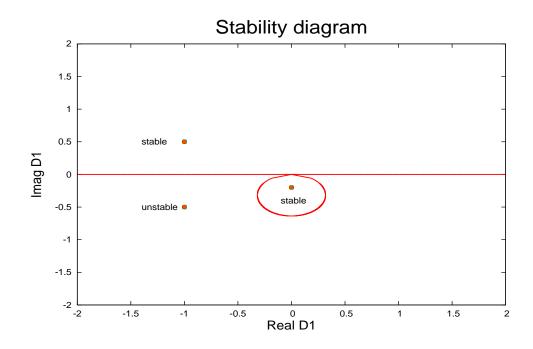
Take the (real) parameter u in

$$D_1 = \frac{1}{(f(u) + ig(u))}$$

- 1 Scan u from  $-\infty$  to  $+\infty$
- 2 Plot the real and imaginary part of  $D_1$  in complex plane
- Plot the complex expression of  $-\frac{(\Omega \omega_x)}{\Delta \omega}$  in the same plane as a point (this point depends on impedances, intensities ..)

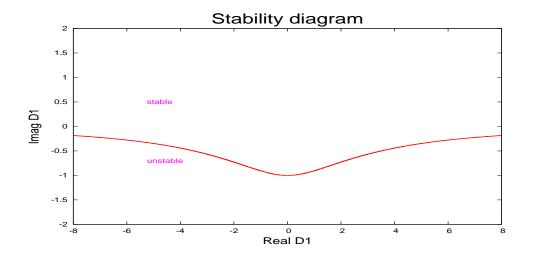


- This is a Stability Boundary Diagram
- > Separates stable from unstable regions



- This is a Stability Boundary Diagram
- > Separates stable from unstable regions

For other types of frequency distributions, example:



Real $(D_1)$  versus Imag $(D_1)$  for bi-Lorentz distribution  $\rho(\omega)$  In all cases: half of the complex plane is stable without Landau Damping

#### Now: transverse instability of unbunched beams

The technique applies directly. Frequency (tune) spread from:

- Change of revolution frequency with energy spread (momentum compaction)
- Change of betatron frequency with energy spread (chromaticity)

but oscillation depends on mode number n (number of oscillations around the circumference C):

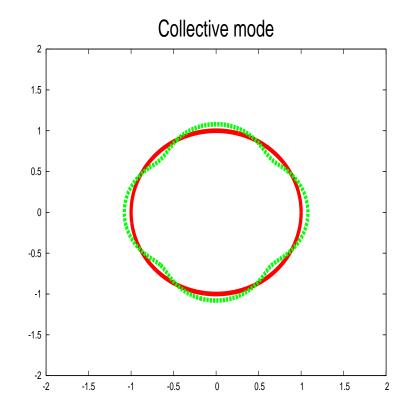
$$\propto exp(-i\Omega t + in(s/C))$$

and the variable u should be written:

$$u = (\omega_x + n \cdot \omega_0 - \Omega)/\Delta\omega$$

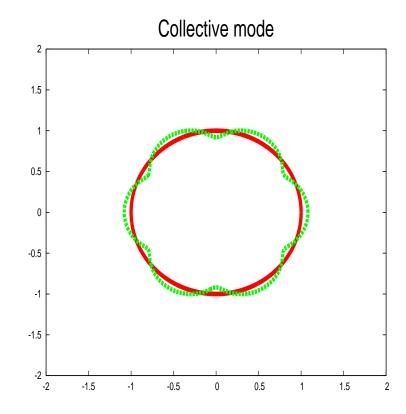
the rest is the same treatment.

# Examples: transverse instability of unbunched beams



Transverse collective mode with mode index n = 4

# Examples: transverse instability of unbunched beams



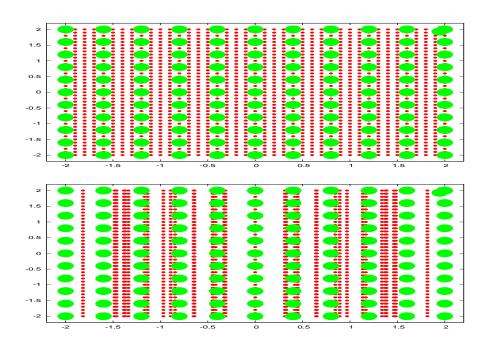
Transverse collective mode with mode index n = 6

- No external focusing !
- $lue{}$  No spread  $\Delta\omega$  of focusing frequencies !
  - > Spread in revolution frequency: related to energy
  - Energy excitations directly affect frequency spread

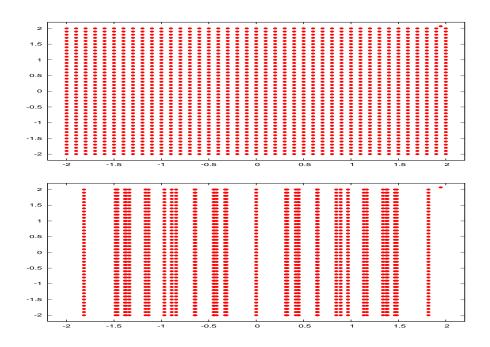
$$\frac{\Delta\omega_{rev}}{\omega_0} = -\frac{\eta}{\beta^2} \frac{\Delta E}{E_0}$$

Frequency distribution by:

$$\rho(\omega_{rev}) \quad \text{and} \quad \Delta\omega_{rev}$$



With and without perturbation in a plasma



> With and without longitudinal modulation in a beam

No external focusing  $(\omega_x = 0)$ :

$$u = \frac{(\omega_x + n \cdot \omega_0 - \Omega)}{\Delta \omega} \qquad \longrightarrow \qquad u = \frac{(n \cdot \omega_0 - \Omega)}{n \cdot \Delta \omega}$$

$$-\frac{(\Omega - n \cdot \omega_0)^2}{n^2 \Delta \omega^2} = \frac{1}{(F(u) + iG(u))} = D_1$$

and introduce two new functions F(u) and G(u):

$$F(u) = n \cdot \Delta \omega^2 P.V. \int d\omega_0 \frac{\rho'(\omega_0)}{n \cdot \omega_0 - \Omega}$$

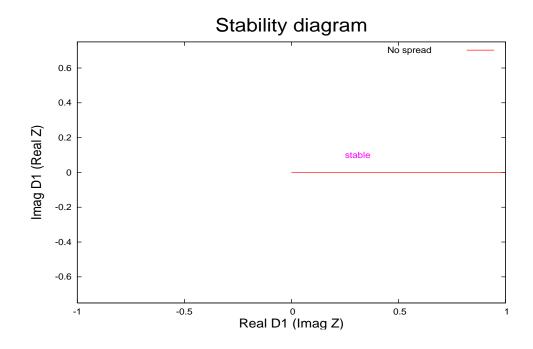
$$G(u) = \pi \Delta \omega^2 \rho'(\Omega/n)$$

# IMPORTANT MESSAGE!

$$-\frac{(\Omega - n \cdot \omega_0)^2}{n^2 \Delta \omega^2} = \frac{1}{(F(u) + iG(u))} = D_1$$

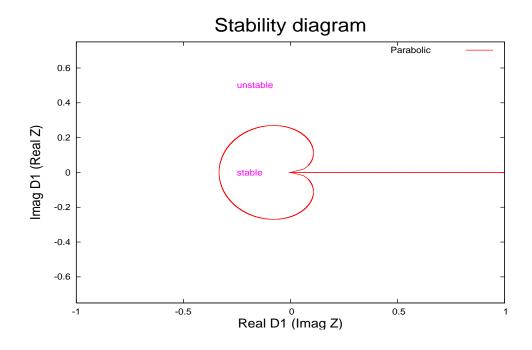
- The impedance now related to the square of the complex frequency shift  $(\Omega n \cdot \omega_0)^2$
- Consequence: no more stable in one half of the plane!
- Landau damping always required

Stability diagram for unbunched beams, longitudinal, no spread:



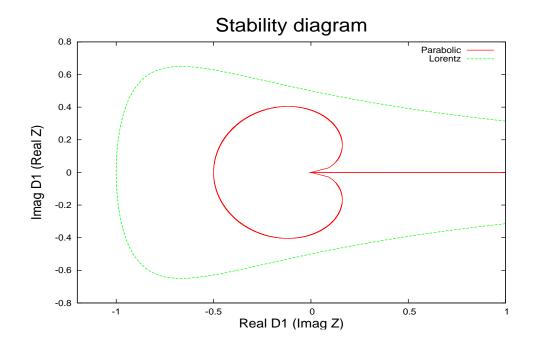
 $Real(D_1)$  versus  $Imag(D_1)$  unbunched beam without spread

Stability diagram for unbunched beams, longitudinal:



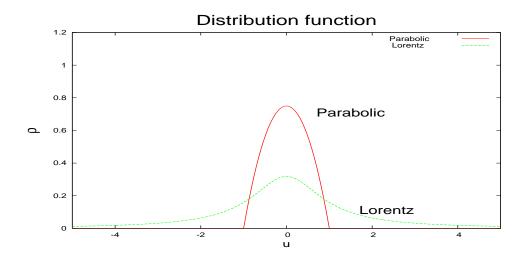
 $\mathbf{Real}(D_1)$  versus  $\mathbf{Imag}(D_1)$  for parabolic  $\rho(\omega)$  and unbunched beam

Stability diagram for unbunched beams, longitudinal:

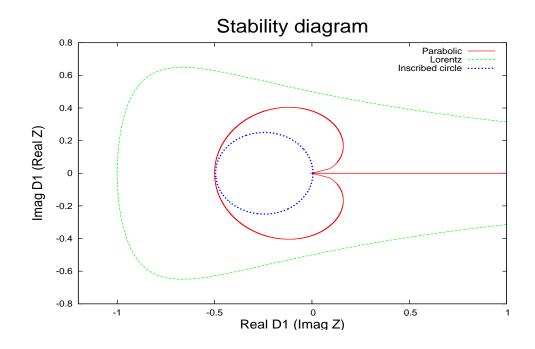


Real $(D_1)$  versus Imag $(D_1)$  for parabolic and Lorentz distribution  $\rho(\omega)$  and unbunched beam

Why so different stability region:



- Larger stability provided by tail of frequency distribution ....
- What if we do not know exactly the distribution function?



- $\blacksquare$  Stability boundary relates Z, I, etc. with frequency spread
- Can derive criteria for stable or unstable beams
- $lue{f B}$  Simplified criterion: inscribe pprox circle as estimate

For longitudinal stability/instability:

$$\frac{|Z_{\parallel}|}{n} \leq F \frac{\beta^2 E_0 |\eta_c|}{qI} \left(\frac{\Delta p}{p}\right)^2$$

- In Items In
- For given beam parameters define maximum impedance  $\frac{|Z_{\parallel}|}{n}$
- Can derive similar criteria for other instabilities (see lecture by G. Rumolo)

### Effect of the simplifications

- We have used a few simplifications in the derivation:
  - > Oscillators are linear
  - Movement of the beam is rigid (i.e. beam shape and size does not change)
- What if we consider the "real" cases?
  - i.e. non-linear oscillators

### The case of non-linear oscillators

Consider now a bunched beam, because of the synchrotron oscillation: revolution frequency and betatron spread (from chromaticity) average out!

- > Source of frequency spread: non-linear force
  - Longitudinal: sinusoidal RF wave
  - Transverse: octupolar or high multipolar field components

Can we use the same considerations as for an ensemble of linear oscillators?

#### The case of non-linear oscillators

#### NO!

The excited betatron oscillation will change the frequency distribution  $\rho(\omega)$  (frequency depends on amplitude) !! Complete derivation through Vlasov equation. The equation:

$$\langle x(t) \rangle = \frac{A}{2\omega_x} e^{-i\Omega t} \left[ P.V. \int d\omega \frac{\rho(\omega)}{(\omega - \Omega)} + i\pi \rho(\Omega) \right]$$

becomes:

$$< x(t) > = \frac{A}{2\omega_x} e^{-i\Omega t} \left[ P.V. \int d\omega \frac{\partial \rho(\omega)/\partial \omega}{(\omega - \Omega)} + i\pi \partial \rho(\Omega)/\partial \Omega \right]$$

#### Response in the presence of non-linear fields

Study this configuration for instabilities in the transverse plane

Since the frequency  $\omega$  depends now on the particles amplitudes  $J_x$  and  $J_y^{*}$ :

$$\omega_x(J_x, J_y) = \frac{\partial H}{\partial J_x}$$

is the amplitude dependent betatron tune (similar for  $\omega_y$ ). We then have to write:

$$\rho(\omega) \longrightarrow \rho(J_x, J_y)$$

\*) see e.g. "Tools for Non-Linear Dynamics" (W.Herr, this school)

#### Response in the presence of non-linear fields

Assuming a periodic force in the horizontal (x) plane and using now the tune (normalized frequency)  $Q = \frac{\omega}{\omega_0}$ :

$$F_x = A \cdot exp(-i\omega_0 Qt)$$

the dispersion integral can be written as:

$$1 = -\Delta Q_{coh} \int_0^\infty dJ_x \int_0^\infty dJ_y \frac{J_x \frac{\partial \rho(J_x, J_y)}{\partial J_x}}{Q - Q_x(J_x, J_y)}$$

Then proceed as before to get stability diagram ...

### What happens when bunches are not rigid?

If particle distribution changes (often as a function of time), obviously the frequency distribution  $\rho(\omega)$  changes as well. :

- **Examples:** 
  - Higher order modes
  - Coherent beam-beam modes
- Treatment requires solving the Vlasov equation (perturbation theory or numerical integration)
- Pragmatic approach (20-20 hindsight): use unperturbed stability region and perturbed complex tune shift ...

#### Landau damping as a cure

If the boundary of

$$D_1 = \frac{1}{(f(u) + ig(u))}$$

determines the stability, can we:

- Increase the stable region by:
  - Modifying the frequency distribution  $\rho(\omega)$ , i.e.  $\rho(J_x, J_y)$
  - Introducing tune spread artificially (octupoles, other high order fields)

The tune dependence of an octupole  $(k_3)$  can be written as<sup>\*)</sup>:

$$Q_x(J_x, J_y) = Q_0 + a \cdot \mathbf{k_3} \cdot J_x + b \cdot \mathbf{k_3} \cdot J_y$$

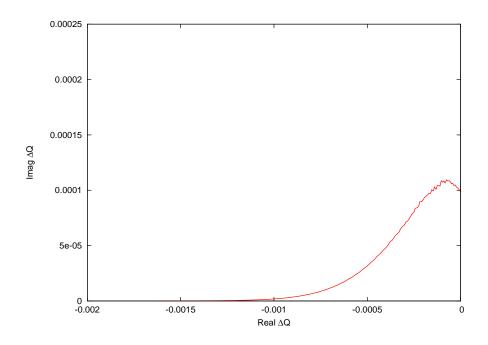
<sup>\*)</sup> see e.g. "Tools for Non-Linear Dynamics" (W.Herr, this school)

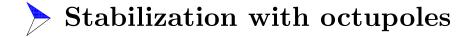
## Landau damping as a cure

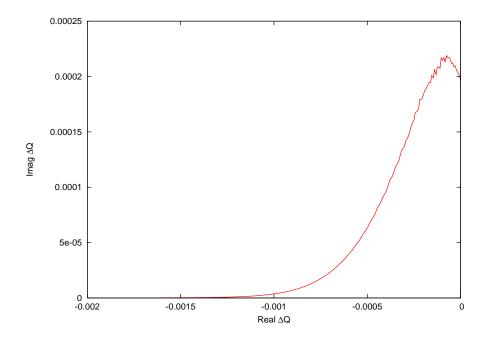
- Other sources to introduce tune spread:
  - > Space charge
  - > Chromaticity
  - High order multipole fields
  - Beam-beam effects (colliders only)

## Landau damping as a cure

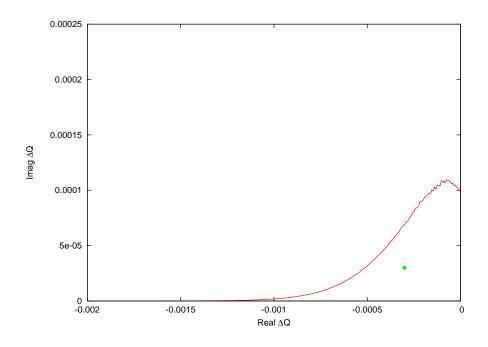
- Recipe for "generating" Landau damping:
  - For a multipole field, compute detuning  $Q(J_x, J_y)$
  - Given the distribution  $\rho(J_x, J_y)$
  - Compute the stability diagram by scanning frequency



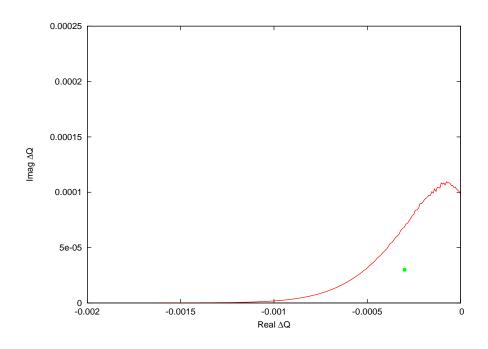




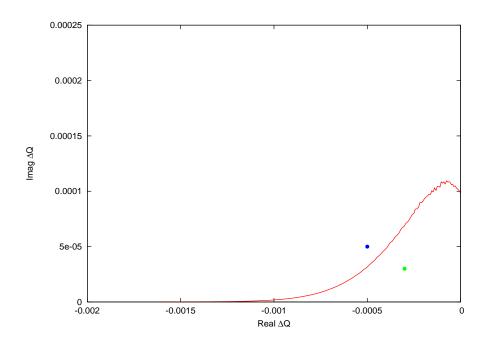
> Stabilization with octupoles, increased strengths



- Complex coherent tune of an unstable mode
- Now in the stable region

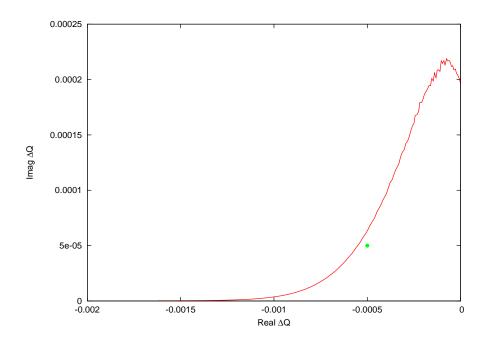


- Complex coherent tune of an unstable mode
- > What if we increase the impedance (or intensity)?



- > Complex coherent tune of an unstable mode
- Now in the unstable region

## Stability diagram with octupoles



- > Complex coherent tune of an unstable mode
- Increased octupole strength makes it stable again

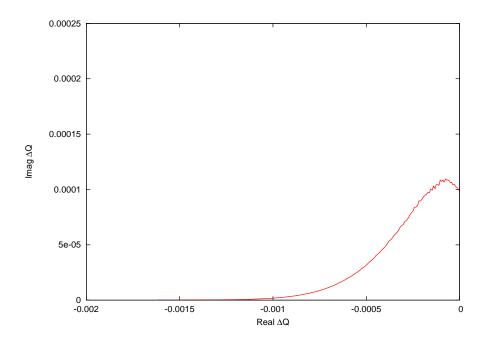
### Stability diagram with octupoles

- Can we increase the octupole strength as we like ??
- The downside:
  - Ctupoles introduce strong non-linearities at large amplitudes
  - Not many particles at large amplitudes: requires large strengths
  - Can cause reduction of dynamic aperture and life time
  - They can change the chromaticity!
- The lesson: use them if you have no choice ....

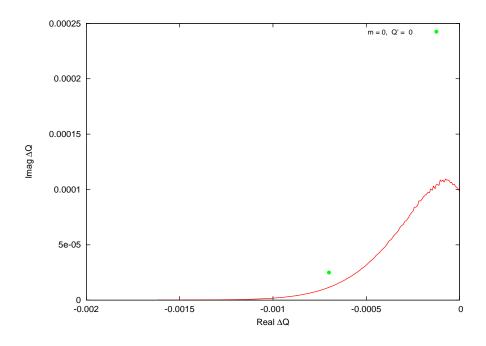
### Another example: Head-Tail modes

(see e.g. Lecture G. Rumolo)

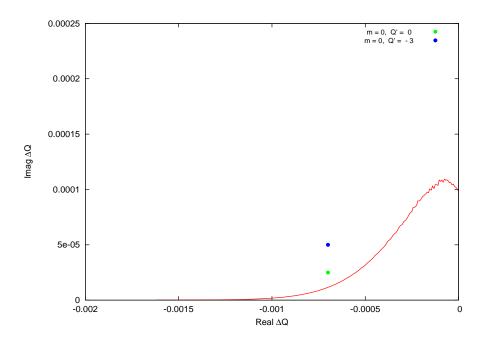
- For short range wake fields
- > Broad band impedance
- > Growth and damping controlled with chromaticity Q'
  - Some modes need positive Q'
  - Some modes need negative Q'
  - Some modes can be damped by feedback (m = 0)
- In the control room: juggle with octupoles and Q' ....



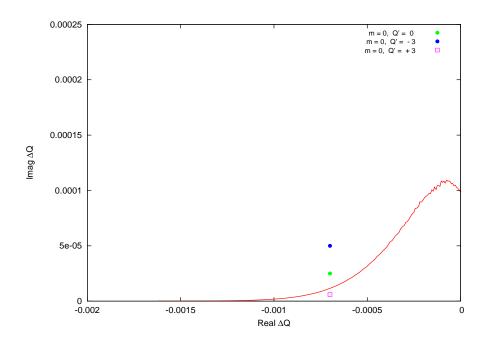
- > Stability region and head-tail modes for different chromaticity
- > Stabilization with octupoles



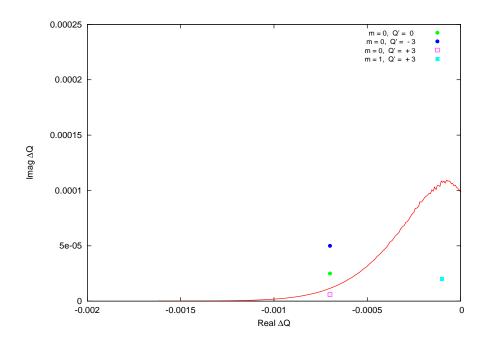
- > Stability region and head-tail modes for different chromaticity
- > Stabilization with octupoles



- > Stability region and head-tail modes for different chromaticity
- > Stabilization with octupoles



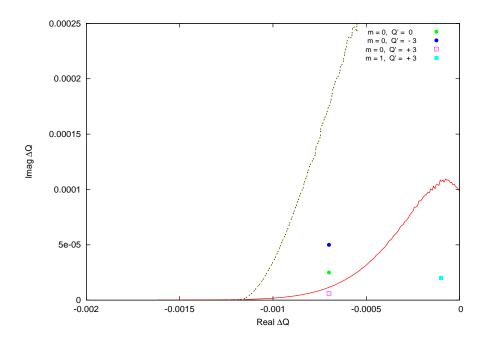
- Head-tail mode m = 0 stabilized with positive chromaticity, (what about higher orders?)
- > Stabilization with octupoles



- Head-tail mode m = 0 stabilized with positive chromaticity, (what about higher orders?)
- > Stabilization with octupoles

### Stability diagram with octupoles

- Would need very large octupole strength for stabilization
- The known problems:
  - Can cause reduction of dynamic aperture and life time
  - > Life time important when beam stays in the machine for a long time
  - Colliders: life time more than 10 20 hours needed ...
- Is there another option?



- > Stability region and head-tail modes for different chromaticity
- > Stabilization with octupoles or colliding beams

#### What makes the difference ...?

The tune dependence of an octupole can be written as:

$$Q_x(J_x, J_y) = Q_0 + aJ_x + bJ_y$$

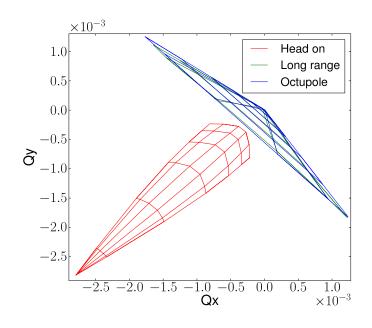
linear in the action (for coefficients, see Appendix).

The tune dependence of a head-on beam-beam collision can be written as\*):

with 
$$\alpha = \frac{x}{\sigma^*}$$
 we get  $\Delta Q/\xi = \frac{4}{\alpha^2} \left[ 1 - I_0(\frac{\alpha^2}{4}) \cdot e^{\frac{-\alpha^2}{4}} \right]$ 

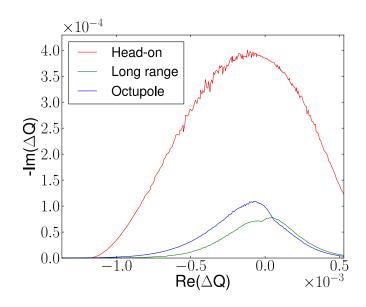
<sup>\*)</sup> see e.g. "Beam-Beam effects" (Tatiana Pieloni, this school)

### Response in the presence of non-linear fields



- Tune footprints for beam-beam and octupoles
- Overall tune spread always the same!
- But: for beam-beam largest effect for small amplitudes

### Response in the presence of non-linear fields



- > Stability diagrams for beam-beam and octupoles
- > Stability region very different!

#### The Good, the Bad, and the Weird ...

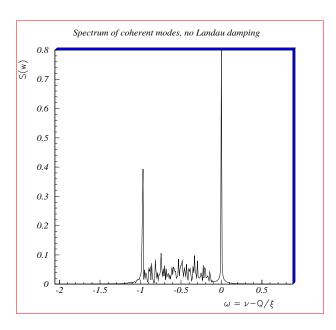
Landau Damping with non-linear fields: Are there any side effects?

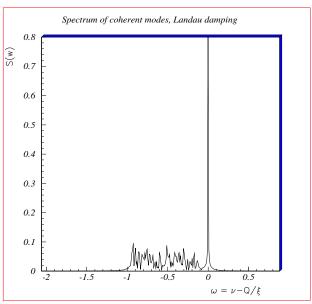
- Good:
  - > Stability region increased
- Bad:
  - Non-linear fields introduced (resonances!)
  - Changes optical properties, e.g. chromaticity ... (feed-down!)
- Weird:
  - Non-linear effects for large amplitudes (octupoles)
  - Much better: head-on beam-beam (but only in colliders ...)

# Conditions for Landau "damping"

- > Presence of incoherent frequency (tune) spread
- Coherent mode must be inside this spread remember the convolution integral of the surfer ...

## Beams with and without damping





- Coherent mode inside or outside the incoherent spectrum
- > Landau damping restored

## Conditions for Landau "damping"

- > Presence of incoherent frequency (tune) spread
- Coherent mode must be inside this spread remember the convolution integral of the surfer ...
- The same particles must be involved!

### Summary

- Long history
- Different approaches to the mathematical treatment, (needed for rigorous treatment of different configurations)
- Many applications (plasmas, accelerators, wind waves, bio-physics, ...)
- Very important for hadron accelerators, but should be used with care ...
- It works! It is not a mystery!

## **APPENDIX:**

#### Tune shift of an octupole:

The tune dependence of an octupole can be written as:

$$Q_x(J_x, J_y) = Q_0 + aJ_x + bJ_y$$

for the coefficients:

$$\Delta Q_x = \left[ \frac{3}{8\pi} \int \beta_x^2 \frac{K_3}{B\rho} ds \right] J_x - \left[ \frac{3}{8\pi} \int 2\beta_x \beta_y \frac{K_3}{B\rho} ds \right] J_y$$

$$\Delta Q_y = \left[ \frac{3}{8\pi} \int \beta_y^2 \frac{K_3}{B\rho} ds \right] J_y - \left[ \frac{3}{8\pi} \int 2\beta_x \beta_y \frac{K_3}{B\rho} ds \right] J_x$$