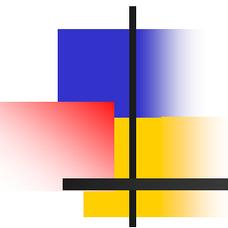


Usage of DSP and in large scale power converter installations (LHC)*

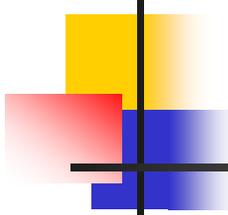


Presented by H.Schmickler

Seminar prepared for the
CAS on Digital Signal Processing

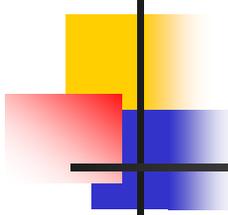
Sigtuna (Sweden), June 2007

A CERN power converter is everybody else's power supply



Contents

- The main features of the LHC
- One of the problems of the LHC:
Persistent current decays and « Snapback » of the multi-pole components of the magnetic field
- The specifications of the power converters
- The solution
 - hardware
 - software, the control algorithm



Contents

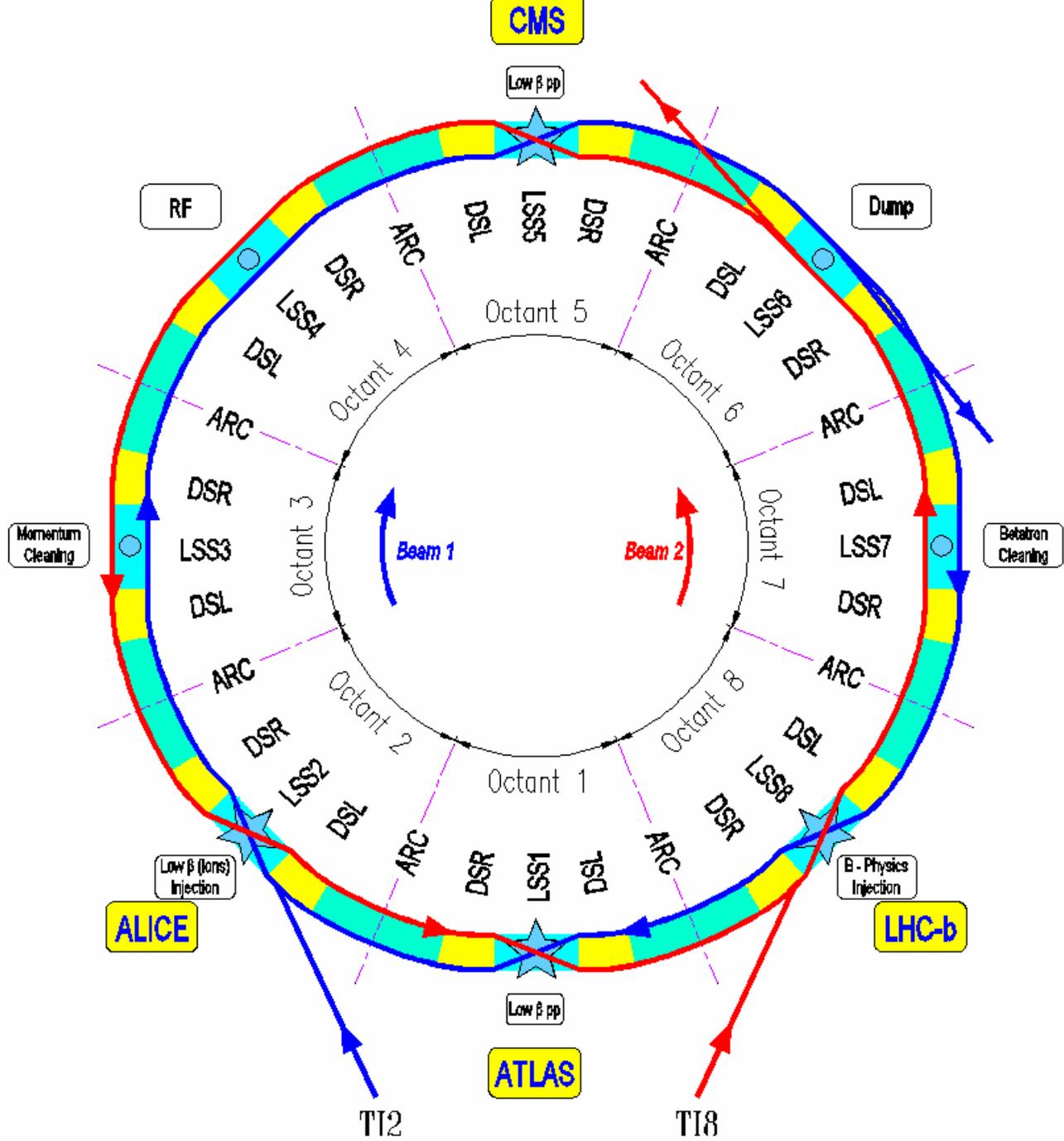
- The main features of the LHC
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Key features of the LHC

We want to produce high luminosity at high energy so we can discover the Higgs, supersymmetry and other exciting stuff.

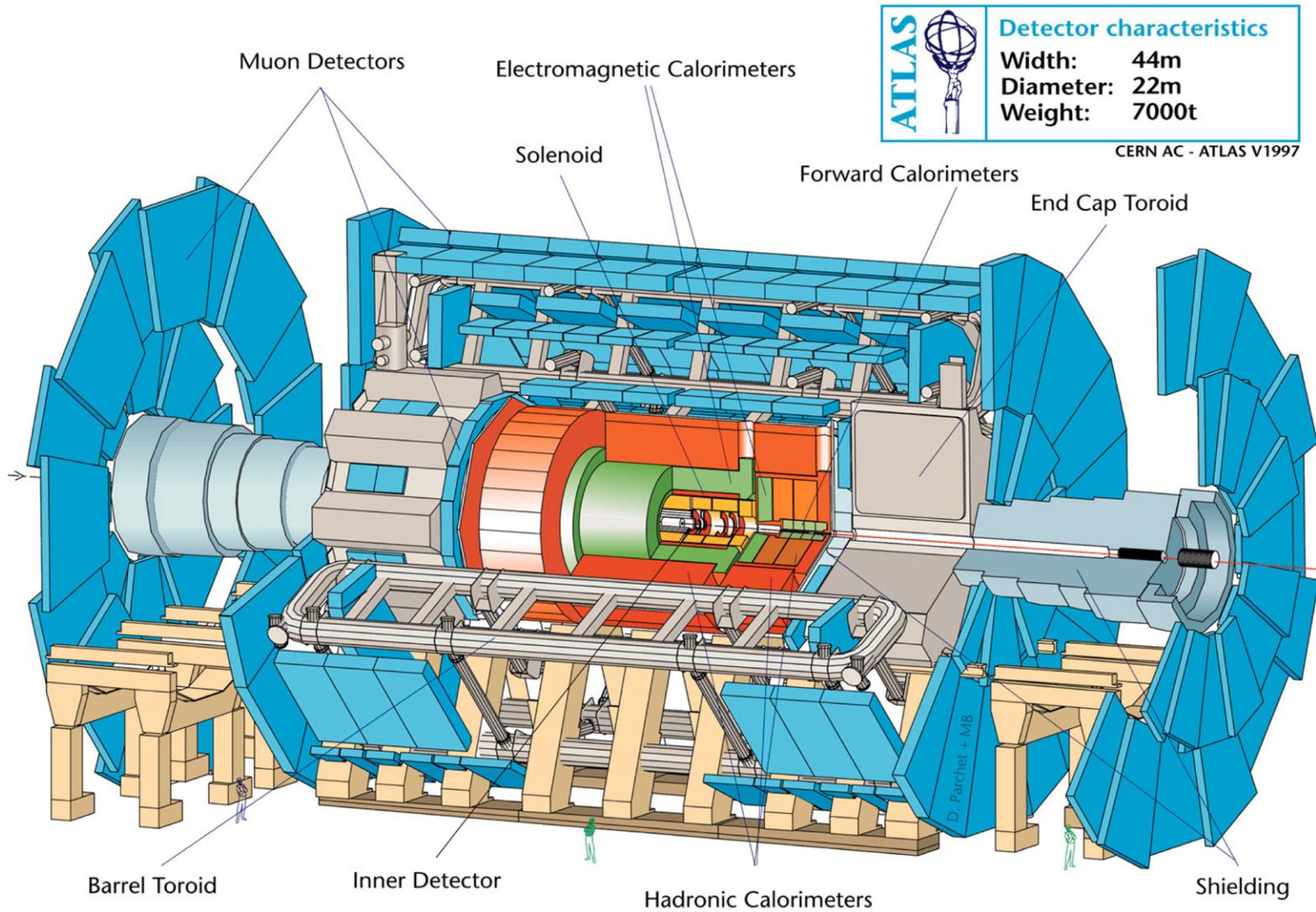
- **Protons and Ions**
- **450 GeV to 7 TeV: SPS is already there**
- **High luminosity:**
 - Many bunches: 2808 bunches per beam
 - High beam currents
 - Small beam size at the interaction points
- **Two rings:**
 - Got to keep the beam apart
 - 2 in 1 dipole design
- **LEP tunnel: might as well use that** → $B \approx 8.4 \text{ T}$
- **High field: Superconducting magnets for the most part with dipoles and lattice quadrupoles working at 1.9 K – superfluid helium (30 kTons cold mass; 90 Tons of Helium)**

- **Two high luminosity experiments**
- **Two more specialised experiments (Ions and b physics) – lower luminosity**

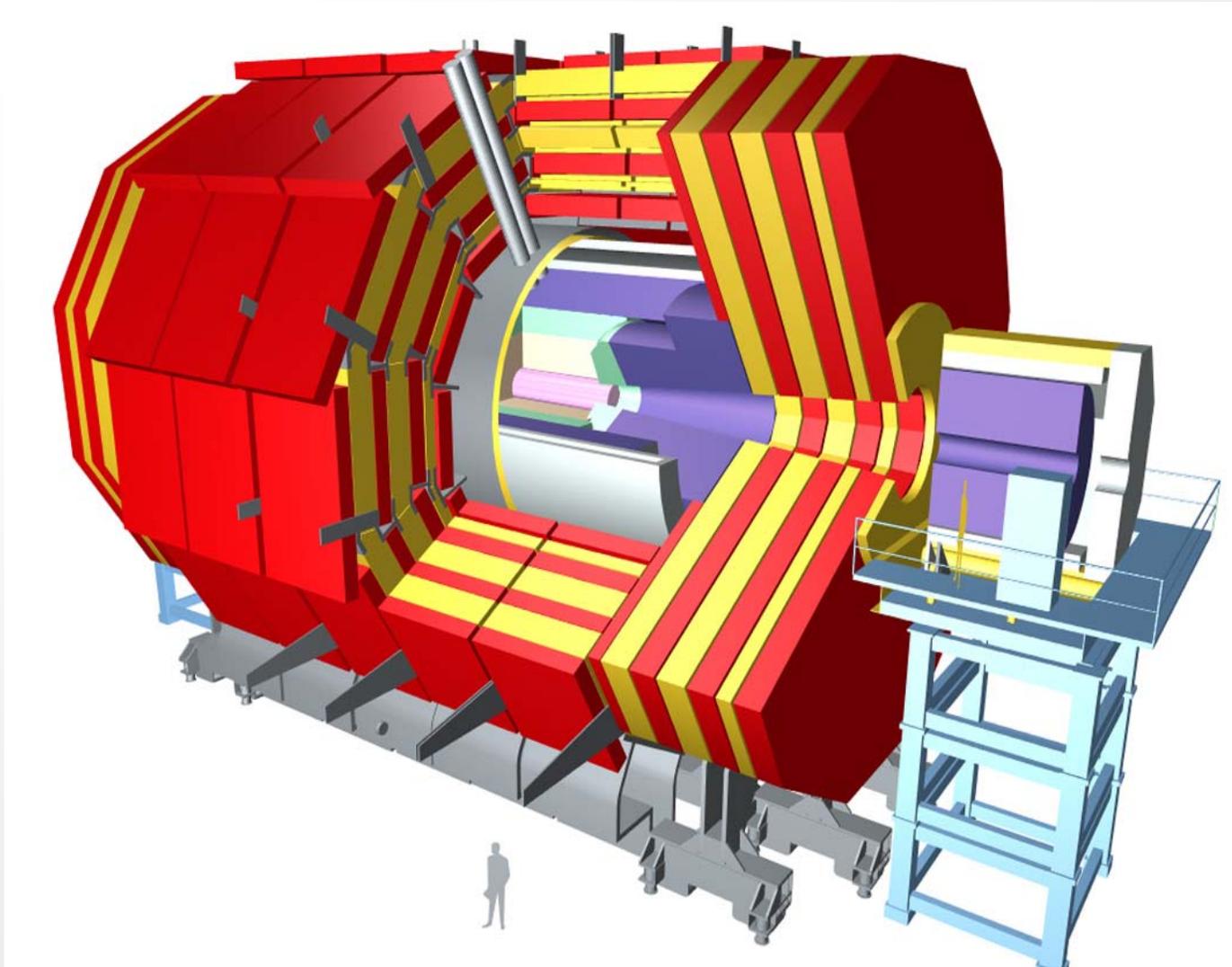


LSS1 DSR ARC DSL LSS2 DSR ARC DSL LSS3 DSR ARC DSL LSS4 DSR ARC DSL LSS5 DSR ARC DSL LSS6 DSR ARC DSL LSS7 DSR ARC DSL LSS8

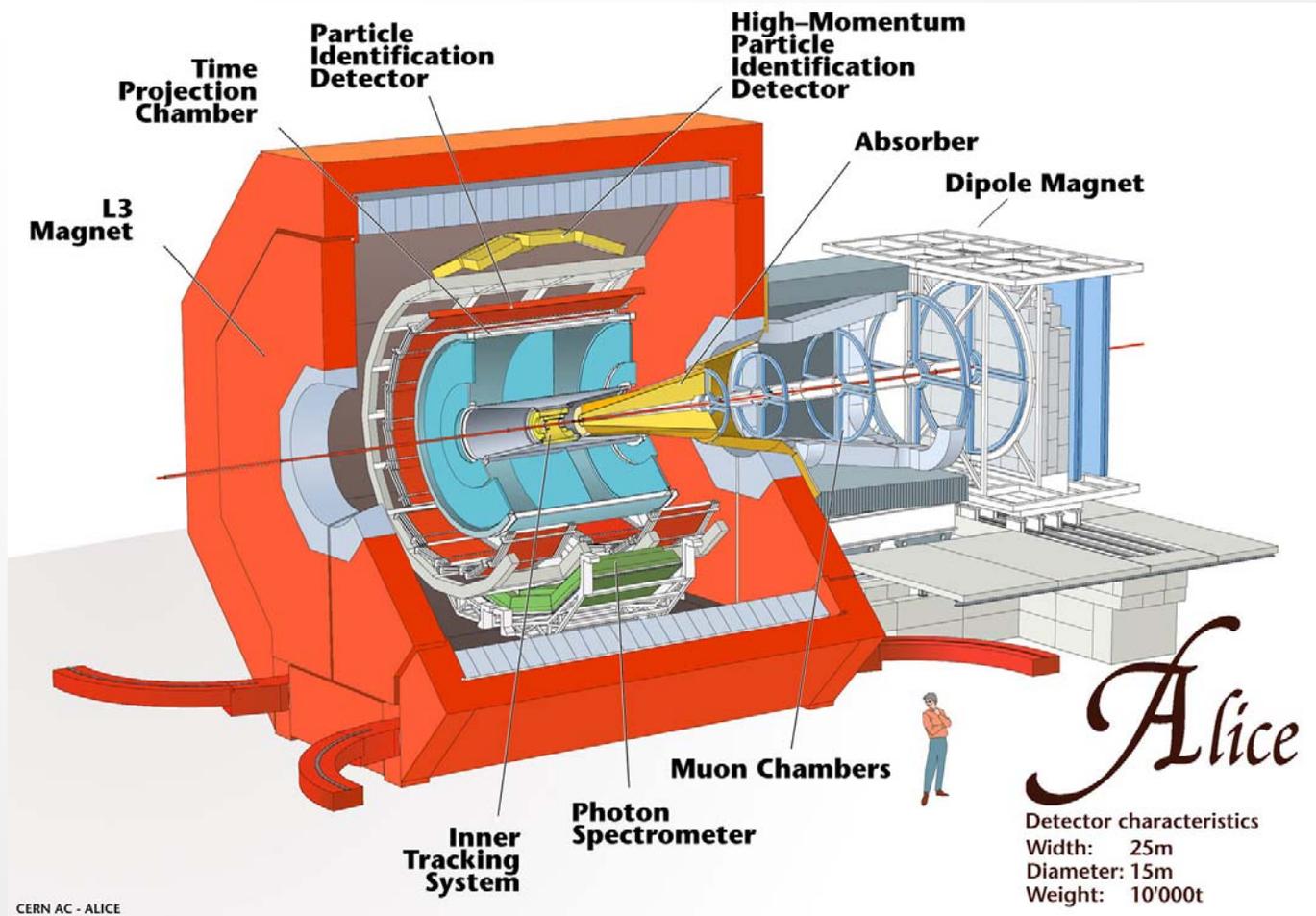
Atlas



CMS

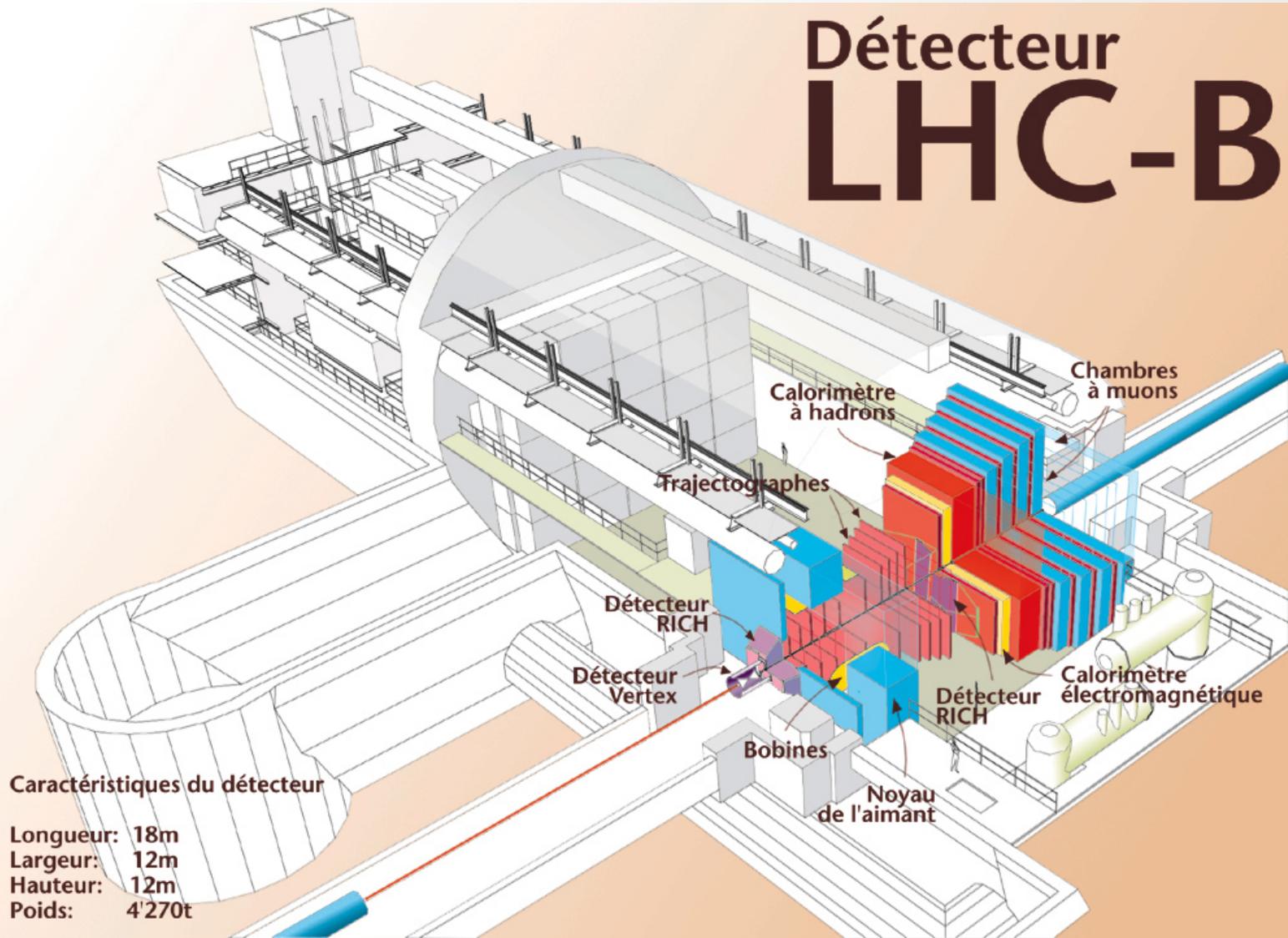


Alice



LHCb

Détecteur LHC-B



7 TeV beam in the LEP tunnel (100 GeV)

$$B\rho = \frac{mv}{e} = \frac{p}{e}$$



$$\frac{1}{\rho} = \frac{eB}{p} = \frac{0.2998 \times B[T]}{p[GeV/c]}$$

1232 magnets to get us round
in a circle

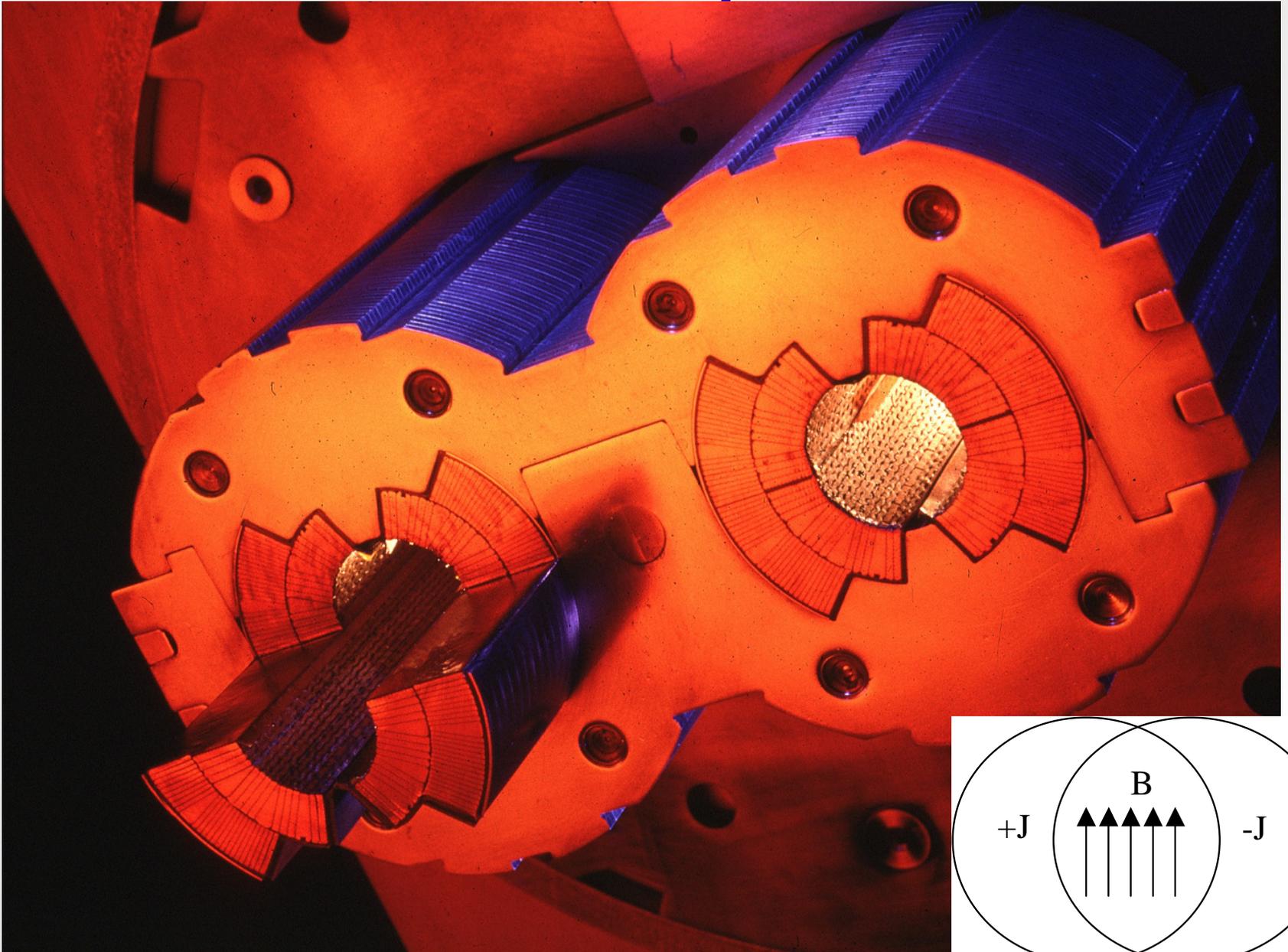


$$\theta = \frac{l}{\rho} = \frac{2\pi}{1232} = 5.1 \times 10^{-3}$$

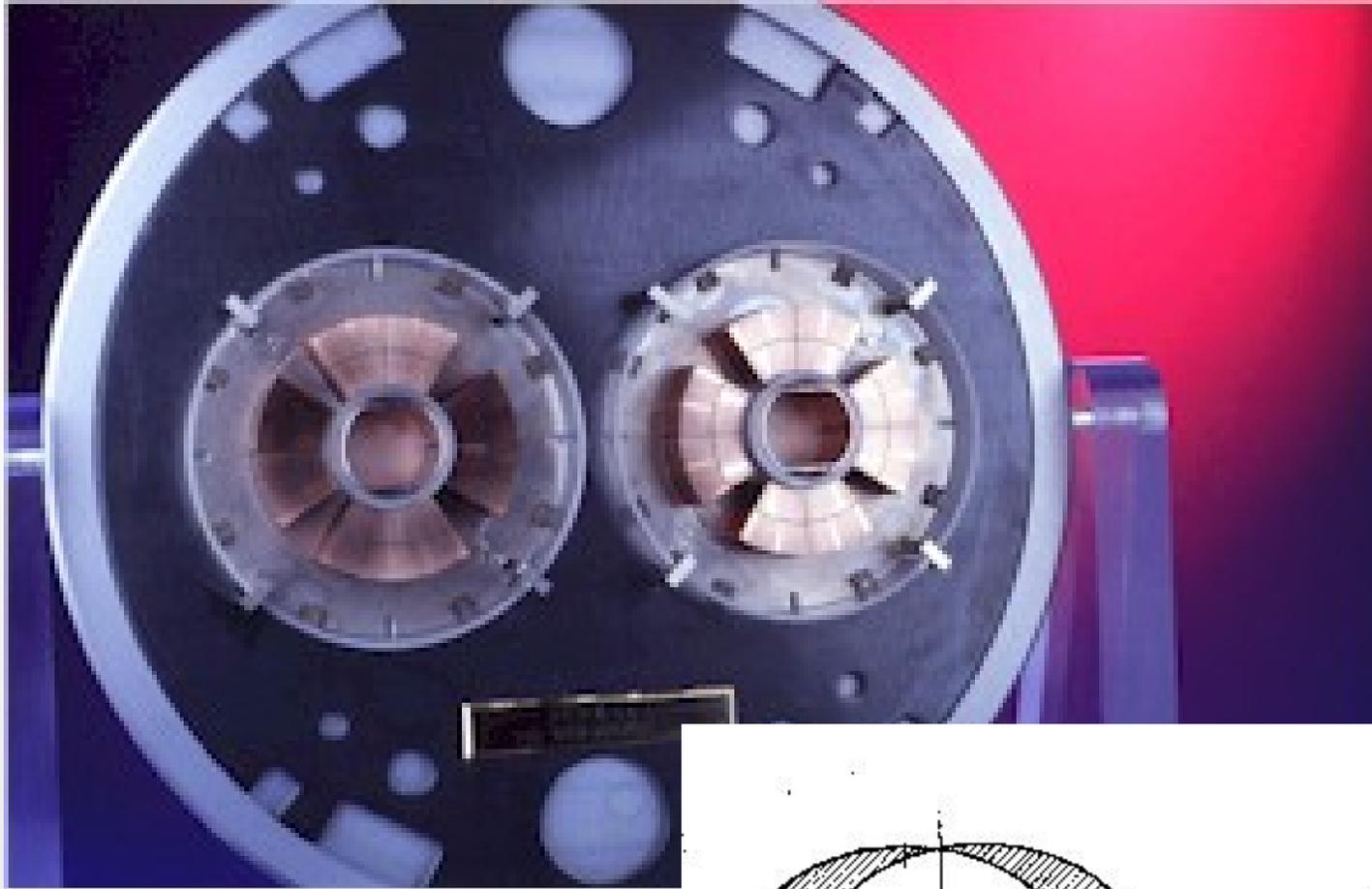
$$B[T] = \frac{\theta \times p[GeV/c]}{l \times 0.2998} = \frac{5.1 \times 10^{-3} \times 7000}{14.3 \times 0.2998} = 8.33T$$

Needs superconducting magnets

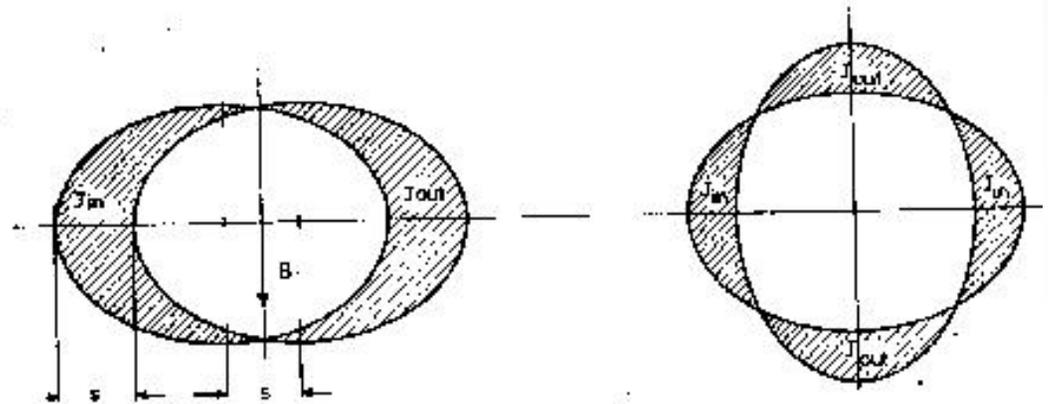
LHC - dipole



LHC - quadrupole

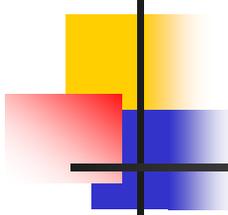


Two intersecting ellipses, rotated by 90° , generate a perfect quadrupole fields



Corrector Circuits

Name	Quantity	Purpose
MSCB	376	Combined chromaticity/ closed orbit correctors
MCS	2464	Dipole spool sextupole for persistent currents at injection
MCDO	1232	Dipole spool octupole/decapole for persistent currents
MO	336	Landau octupole for instability control
MQT	256	Trim quad for lattice correction
MCB	266	Orbit correction dipoles
MQM	100	Dispersion suppressor quadrupoles
MQY	20	Enlarged aperture quadrupoles

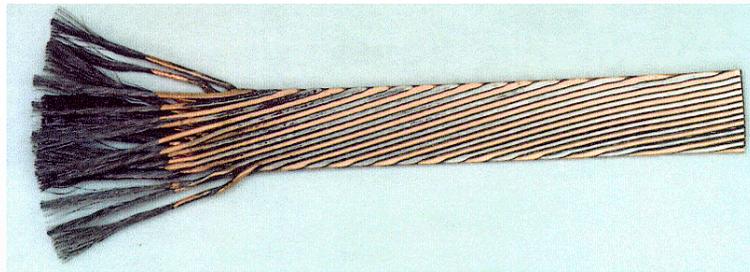


Contents

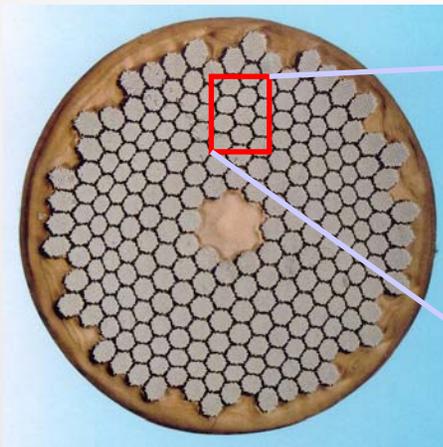
- The main features of the LHC
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In order to generate 8,33 T in the dipoles, about 11.000 Amperes have to flow in the superconducting cable

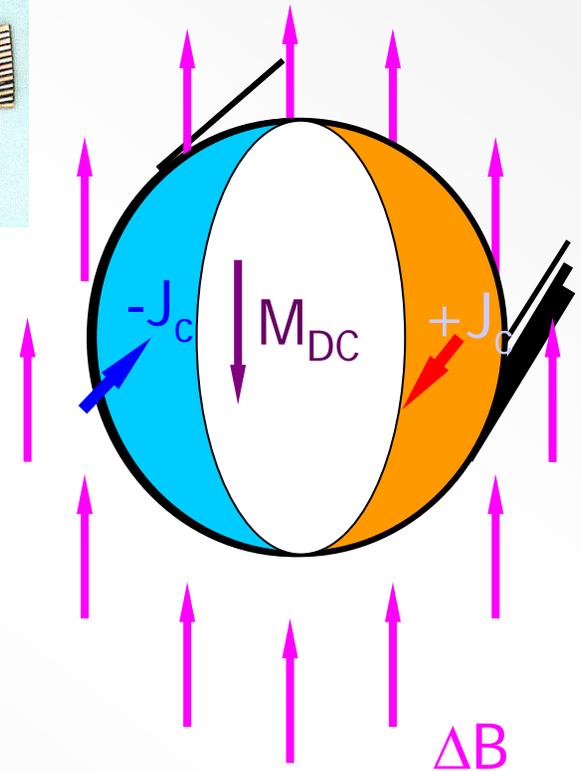
Cable



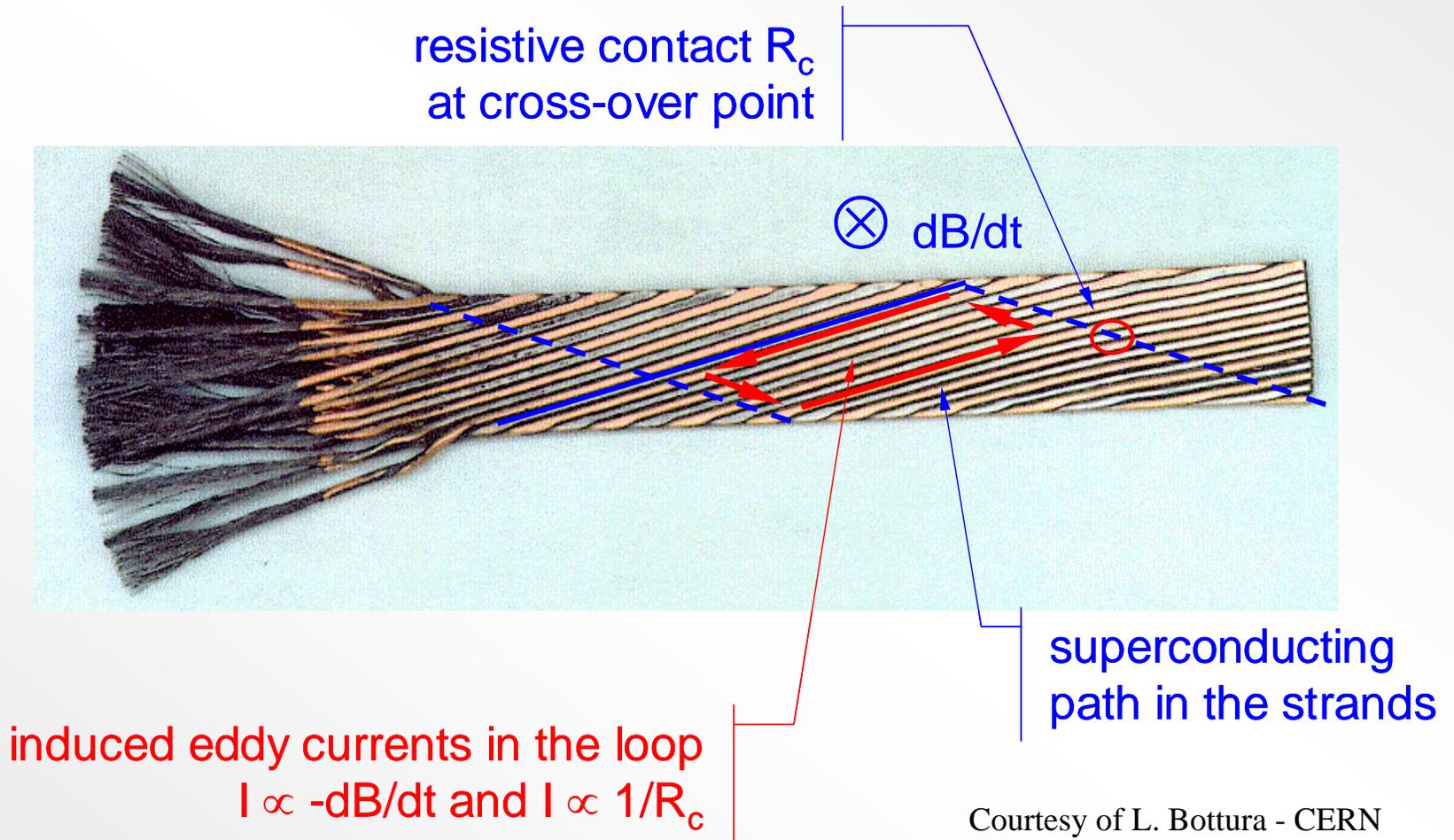
Strand



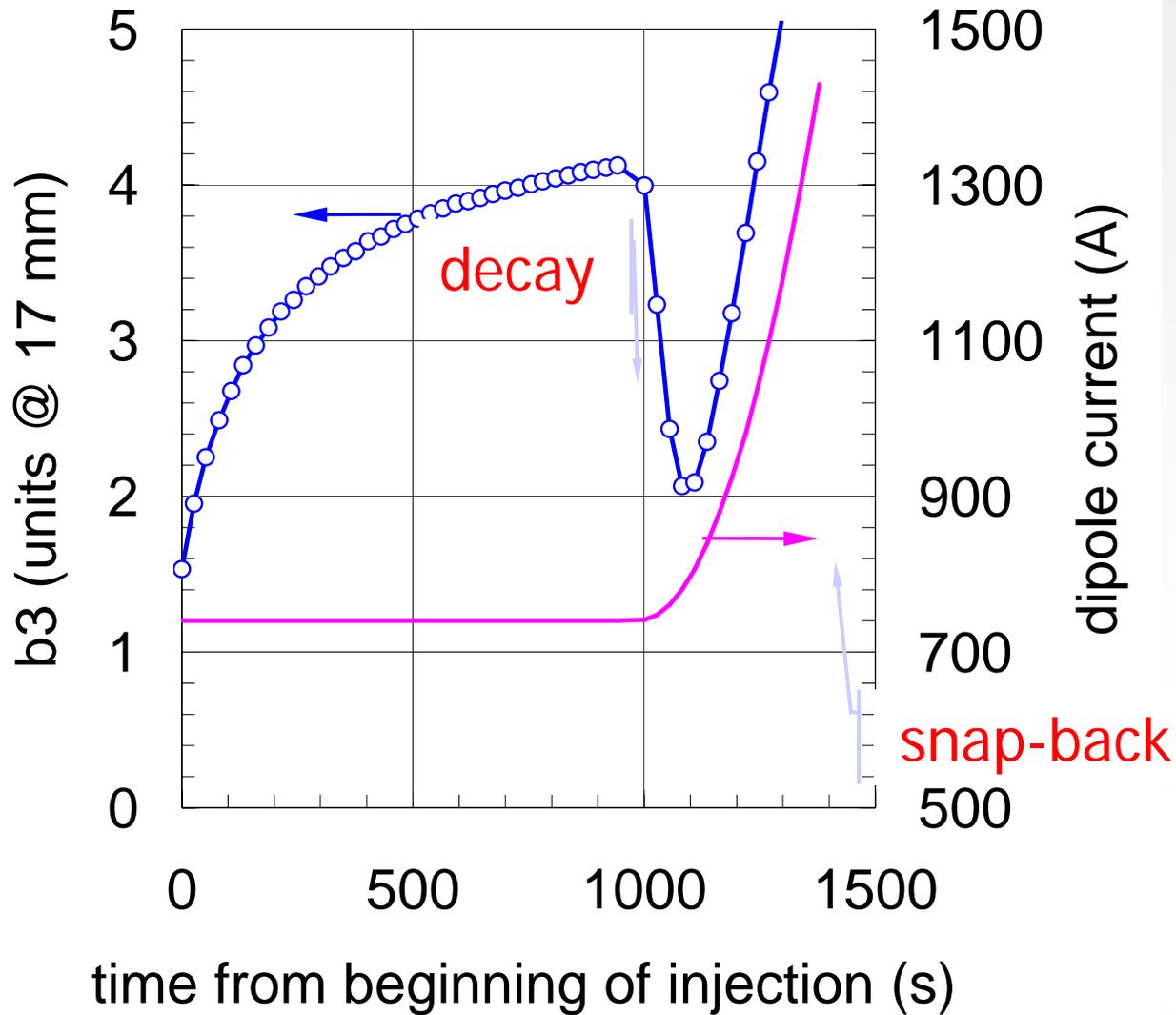
Filament

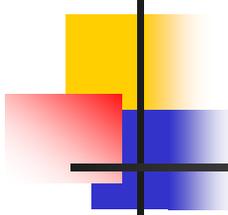


Eddy Currents



Snapback





Effect of Snap-back in LHC

- An uncorrected snap-back (of the expected magnitude) will cause in LHC:

$$\Delta b_1(\text{MB})=2.6 \rightarrow \Delta Q = 0.026 \text{ vs. } 0.003$$

$$\Delta b_2(\text{MQ})=1.7 \rightarrow \Delta Q = 5.4 \cdot 10^{-3} \Delta b_2 = 0.009 \text{ vs. } 0.003$$

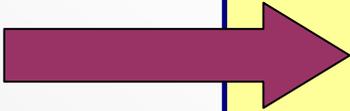
$$\Delta b_3(\text{MB})=3.3 \rightarrow \Delta \xi = 52 \Delta b_3 = 172 \text{ vs. } 1$$

Value vs. tolerance

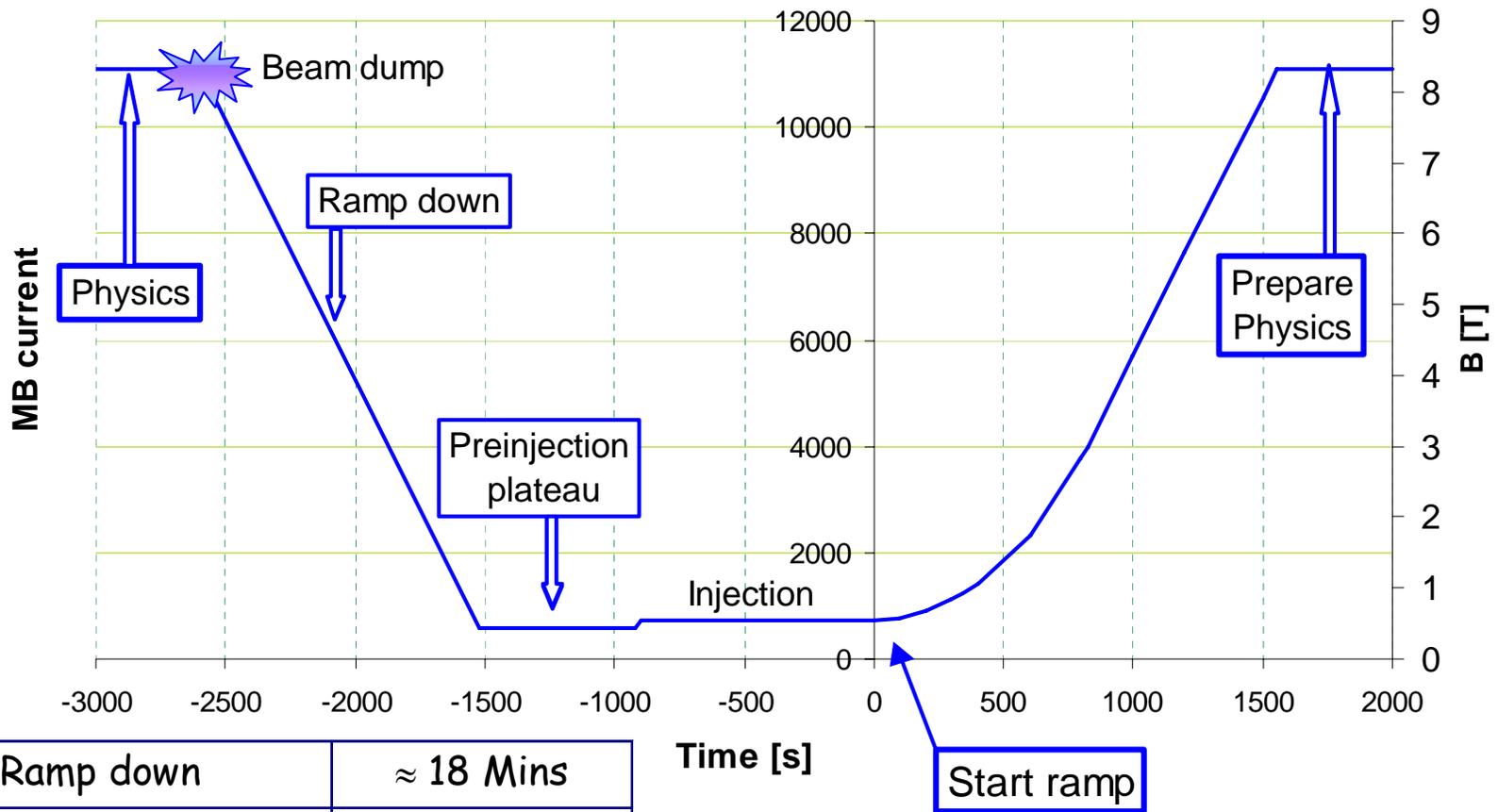
(source: O. Bruening, CERN)

Dynamic Effects problem

- **Decay of persistent currents & snap-back**
 - large variations in multipole errors
 - unacceptable effect on key beam parameters
- **Strong dependence on magnetic history**
- **Strategy:**
 - **Reproducibility**
 - well defined operational cycle
 - full recycle in case of problems
 - feed-forward of experience
 - **Multipole factory:**
 - magnetic measurements
 - models of multipole behaviour which can take into account powering history
 - on-line magnetic measurements
 - **Feedback on beam based measurements**

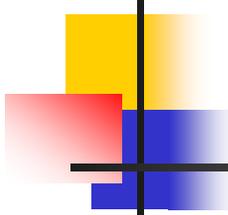


Baseline cycle



Ramp down	≈ 18 Mins
Pre-Injection Plateau	15 Mins
Injection	≈ 15 Mins
Ramp	≈ 28 Mins
Squeeze	< 5 Mins
Prepare Physics	≈ 10 Mins
Physics	10 - 20 Hrs

In the normal operations the LHC will perform a standard cycle which will be more-or-less set in stone.



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What's special about Powering Superconducting Magnets ?

Need heavy warm cabling

- Need to be near to feed point

Difficult and expensive power converter output stage

**High Current
Large Inductance
No Resistance**

Large Stored Energy, $\frac{1}{2} LI^2$

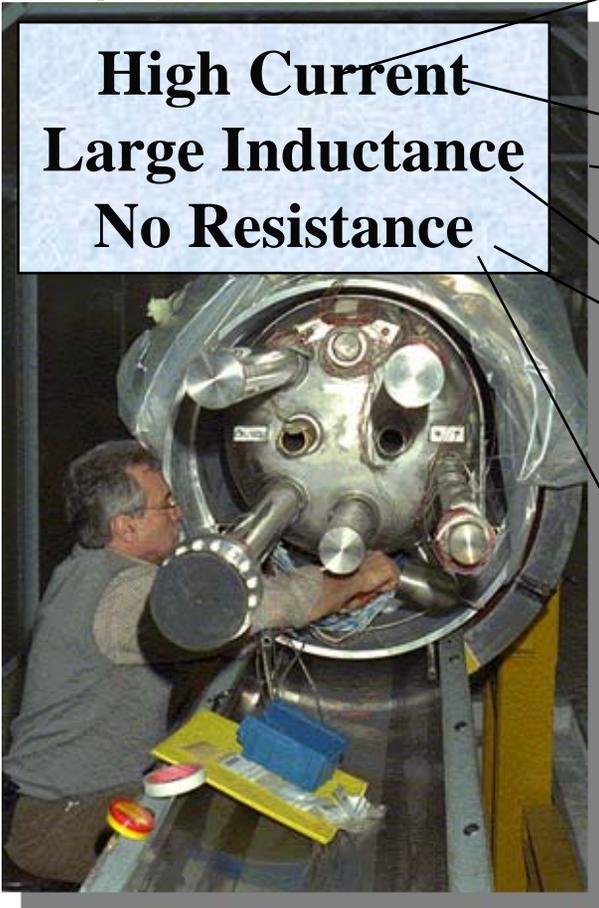
- Need to handle carefully!

Large Time Constant, L/R

- Boost voltages (high voltage only during the ramps)
- Difficult control loops

Tendency to quench

- Need to take special precautions (energy)



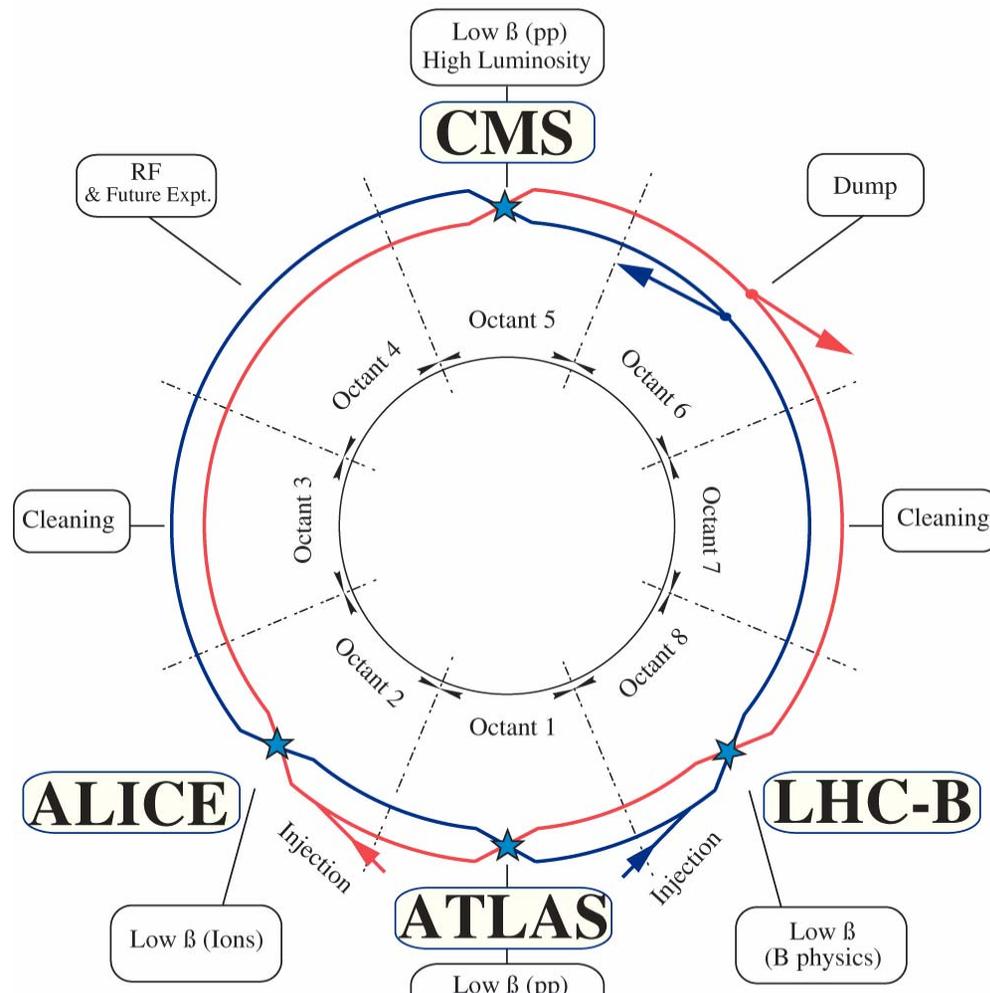
LHC : 1232 SC Main Dipole magnets

Magnet inductance :
 $L = 108 \text{ mH}$

$L_{\text{total}} = 1232 * 0.108 = 133 \text{ H}$
Ramp: $LdI/dt = 1330 \text{ V}$
Discharge (quench; 120 A/s):
 $\cong 16 \text{ kV}$

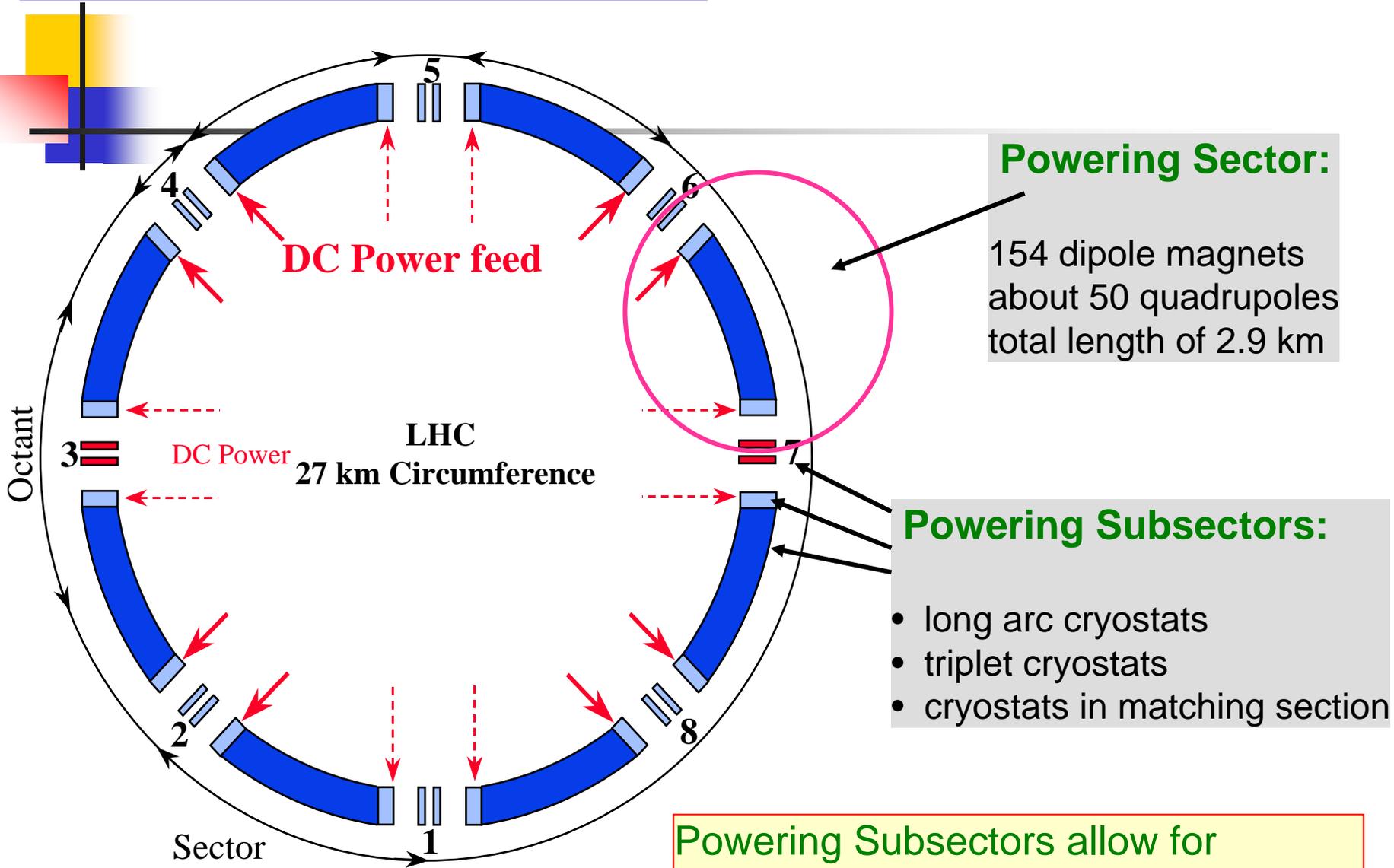
Nominal current 11.8 kA
Stored Energy = 9.3 GJ

Ultimate current = 13 kA
Stored Energy = 11.3 GJ



One circuit or several circuits ?

LHC Powering in 8 Sectors



Powering Subsectors allow for progressive Hardware Commissioning - 2 years before beam

Power Converter Tolerances for LHC

Circuit Type	Nominal Current (A)	Current Polarity	One Year Accuracy (ppm of Inominal)	One day Reproducibility (ppm of Inominal)	1/2 hour Stability (ppm of Inominal)	Resolution (ppm of Inominal)
Main Bends, Main Quads	13000	Unipolar	± 50 ± 20 with calibration	± 5	± 3	1
Inner triplet	8000/ 6000	Unipolar	± 70 ± 20 with calibration	± 10	± 5	1
Dispersion suppressor	6000	Unipolar	± 70	± 10	± 5	15
Insertion quadrupoles	6000	Unipolar	± 70	± 10	± 5	15
Separators (D1,D2,D3,D4)	6000	Unipolar	± 70	± 10	± 5	15
Trim quadrupoles	600	Bipolar	± 200	± 50	± 10	30
SSS correctors	600	Bipolar	± 200	± 50	± 10	30
Spool pieces	600	Bipolar	± 200	± 50	± 10	30
Orbit correctors	120/60	Bipolar	± 1000	± 100	± 50	30

Precision

Control

LHC Power Converters

PC-V 6-4 : General Information

Last_modif 24/3/2003

Optics version	Eq.Code	Current			Voltage		Module		Mains Input		Losses		Dimensions			Provisional Quantity	
		Type	Steady	Boost	Peak	Steady	Boost	I mod	I tot	Peak	Peak	Water	Air	Length	Depth		Height
		kA	V	V	V	V	kA	kA	kW	kVA	kW	kW	m	m	m		
6-4 01	RPTE	13.000	10	±180	190	190	16.250	16.250	2680.6	3540.0	157.9	52.6	10.8	1.8	2.0	36.00	8
6-4 02	RPHE	13.000	13	±5	18	18	16.250	16.250	264.9	288.0	27.8	3.1	4.2	0.9	2.0	7.00	16
6-4 03	RPHF	8.000	6	±2	8	8	10.000	10.000	78.2	85.0	12.8	1.4	3.0	0.9	2.0	5.00	20
6-4 04	RPHG	6.000	6	±2	8	8	10.000	10.000	58.7	63.8	9.6	1.1	2.4	0.9	2.0	4.00	132
6-4 05	RPHH	4.000	6	±2	8	8	10.000	10.000	39.1	42.5	6.4	0.7	2.4	0.9	2.0	4.00	40
6-4 10	RPMB	0.600	±8	±2	10	10	0.600	0.600	8.3	9.1	2.1	0.2	0.6	0.9	1.0	0.50	330
6-4 11	RPMC	0.600	±35	±2	10	10	0.600	0.600	8.3	9.1	2.1	0.2	0.6	0.9	1.0	0.50	24
6-4 12	RPMB	0.600	8	±2	10	10	0.600	0.600	8.3	9.1	2.1	0.2	0.6	0.9	1.0	0.50	70
6-4 13	RPMC	0.600	35	±2	10	10	0.600	0.600	8.3	9.1	2.1	0.2	0.6	0.9	1.0	0.50	2
6-4 14	RPLB	0.120	±8	±2	10	10	0.120	0.120	1.6	1.7	0.4	0.0	0.6	0.9	1.0	0.50	290
6-4 15	RPMC	0.120	±35	±2	10	10	0.120	0.120	1.6	1.7	0.4	0.0	0.6	0.9	1.0	0.50	10
6-4 16	RPLA	0.060	±2	±2	10	10	0.060	0.060	0.8	0.8	0.2	0.0	0.6	0.9	1.0	0.50	752
6-4 20	RPTL	0.650	160	±2	10	10	0.650	0.650	8.6	9.2	2.2	0.2	0.6	0.9	1.0	0.50	3
6-4 21	RPTF	0.810	450	±2	10	10	0.810	0.810	10.6	11.3	2.8	0.3	0.6	0.9	1.0	0.50	4
6-4 22	RPTG	0.810	950	±2	10	10	0.810	0.810	10.6	11.3	2.8	0.3	0.6	0.9	1.0	0.50	4
6-4 23	RPTM	1.000	600	±2	10	10	1.000	1.000	13.0	13.9	3.4	0.4	0.6	0.9	1.0	0.50	2
6-4 24	RPTI	6.500	950	±2	10	10	6.500	6.500	85.2	90.7	27.1	3.1	0.6	0.9	1.0	0.50	2
6-4 25	RPTN	1.000	±180	±2	10	10	1.000	1.000	13.0	13.9	3.4	0.4	0.6	0.9	1.0	0.50	3
6-4 30	RPTJ	20.000	±26	±2	10	10	20.000	20.000	260.0	276.0	84.0	9.8	0.6	0.9	1.0	0.50	1
6-4 31	RPHK	20.500	18	±2	10	10	20.500	20.500	266.3	282.5	85.6	10.0	0.6	0.9	1.0	0.50	1
6-4 32	RPTH	33.000	170	±2	10	10	33.000	33.000	424.1	450.9	140.1	16.6	0.6	0.9	1.0	0.50	1
6-4 40	RPTK	0.040	100000	±2	10	10	0.040	0.040	0.5	0.5	0.1	0.0	0.6	0.9	1.0	0.50	4

Number of Converters: > 1700
Total Current :1860 kA
Steady State Input : 63 MW
Peak Input : 85 MVW
Underground volume \cong 1700 m³
Surface volume \cong 300 m³

Total Current required
1861 kA

Steady State Input 63018 kW
Peak Input 85906 kW

Total Number of PCs 1719

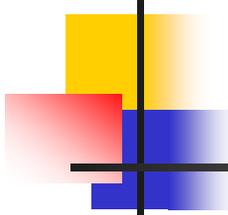
LHC Powering Challenges :

Performance :

- High current with high precision (accuracy, reproducibility, stability, resolution) and large dynamics
- current range (for 1-quadrant converter: from 1% to 100%)
- a lot of 4-quadrant converters (energy from magnets)
- tracking : ☹ Need to track from sector to sector
- voltage ripple and perturbation rejection

Installation (LEP infrastructure) and Operation:

- volume (a lot of converter shall be back-to-back)
- weight (difficult access) => modular approach
- Repairability and rapid exchange of different parts
- radiation for [$\pm 60\text{A}, \pm 8\text{V}$] converters
- losses extraction : high efficiency (>80%) , water cooling (90% of the losses)
- High reliability (MTBF > 100'000 h)
- EMC : very close to the others equipment ; system approach

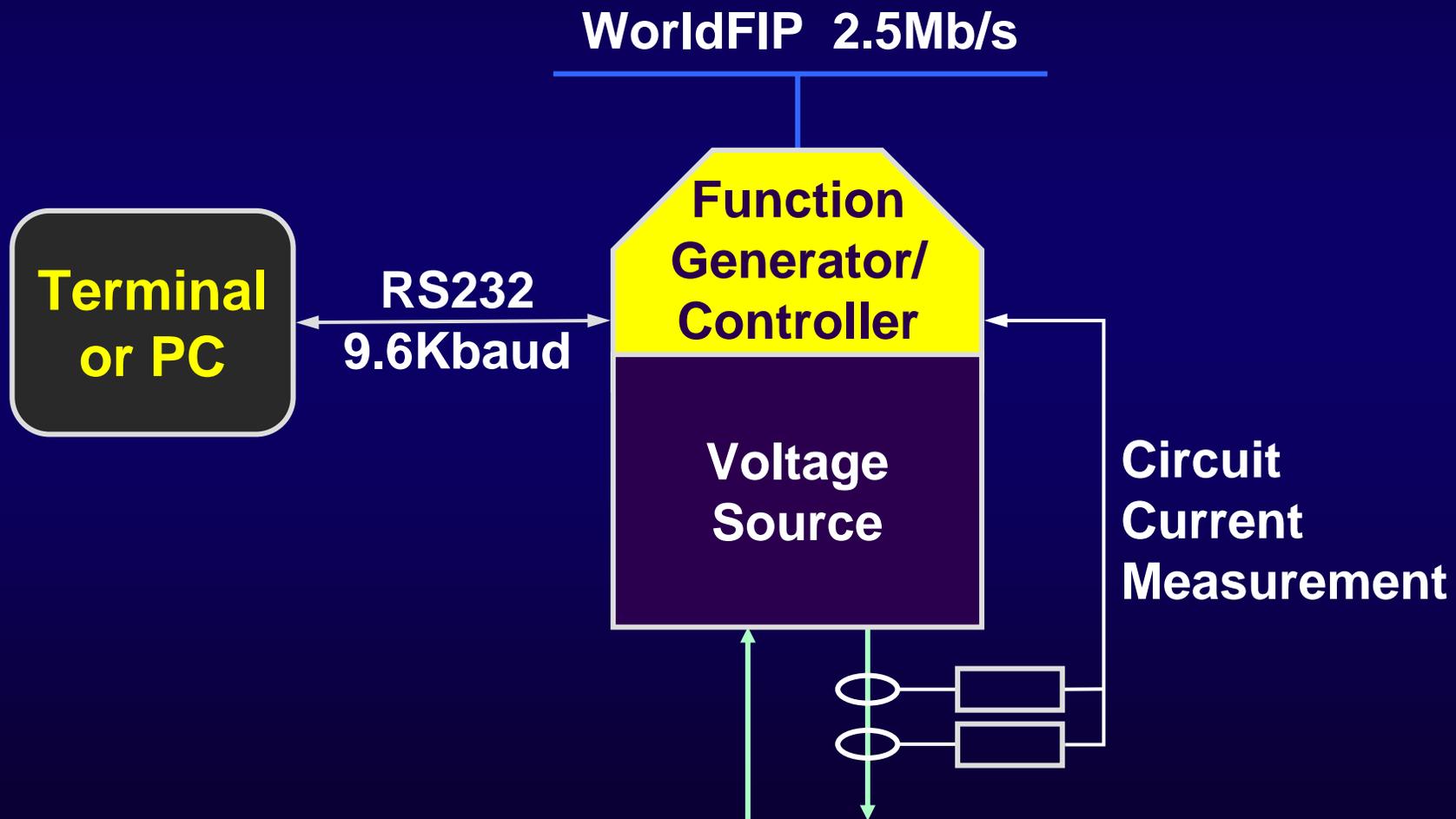


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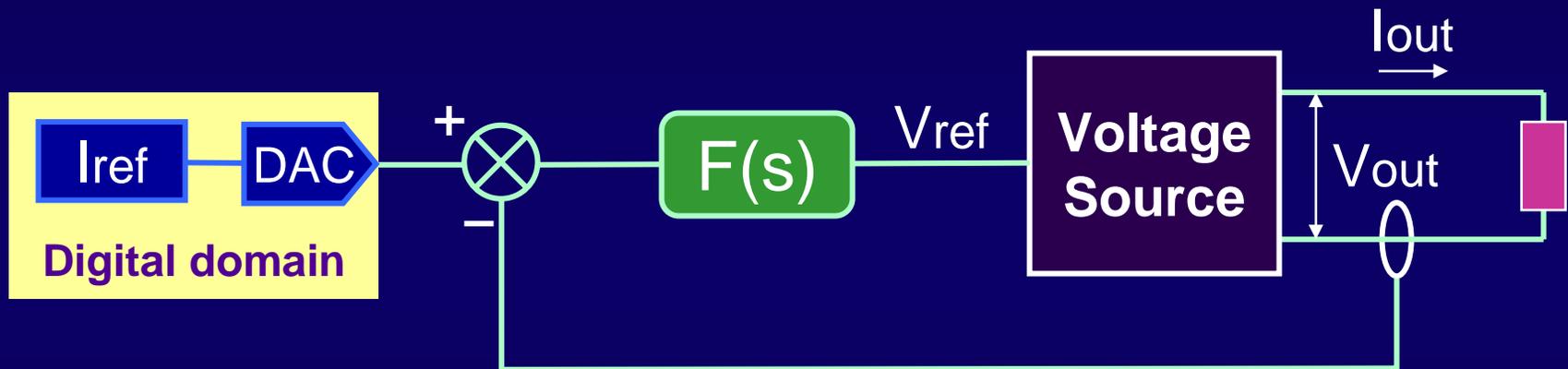
Overview – A Power Converter





Overview – Analogue Regulation

Traditional Method used for PS, SPS and LEP



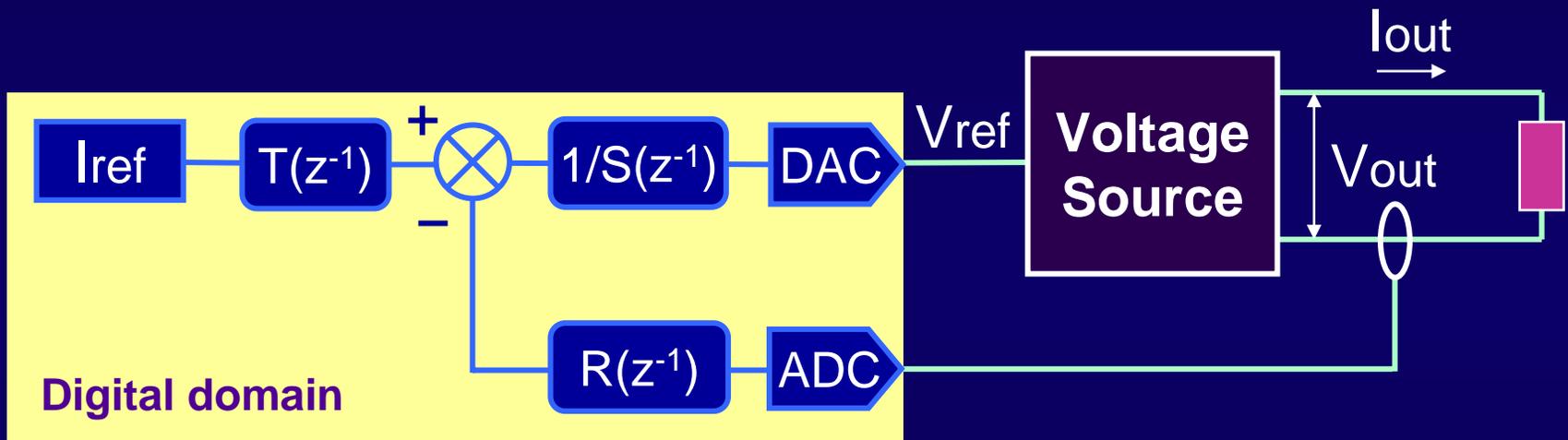
Traditional analogue regulation suffers from serious limitations:

- Inaccurate for very slow circuits (superconducting magnets)
- Simple analogue control suffers from dynamic errors
- Accuracy depends upon current transducer and DAC



Overview – Digital Regulation

New method for LHC

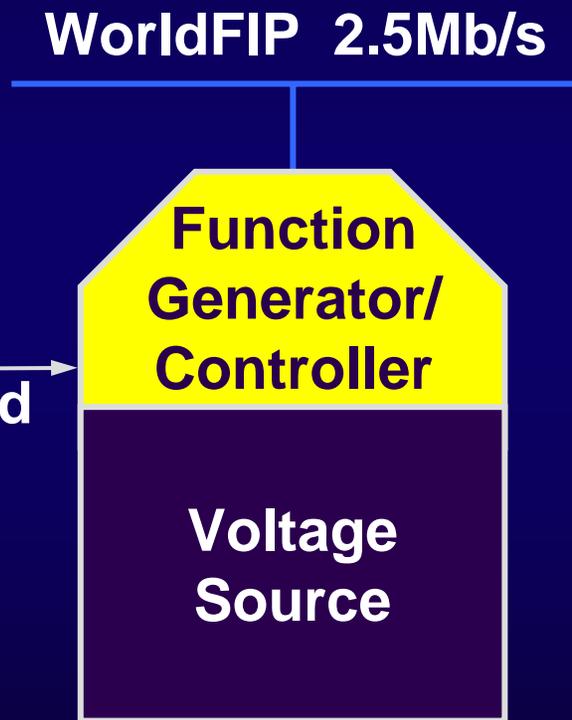


Digital regulation has been chosen for LHC because:

- It accommodates all circuit time constants (0.1 – 20000 s)
- Advanced digital control algorithm can eliminate dynamic errors
- Accuracy depends “only” upon current transducer and ADC



Controller Hardware Overview



- ◆ **Twin Processor**
 - ◆ **16 bit micro-controller (MC68HC16Z1 @ 16 MHz)**
 - ◆ **32 bit floating point DSP (TMS320C32 @ 32 MHz)**
- ◆ **Radiation tolerance**
 - ◆ **Error detection and correction on all SRAM**
 - ◆ **Multiple watchdogs including power cycling**

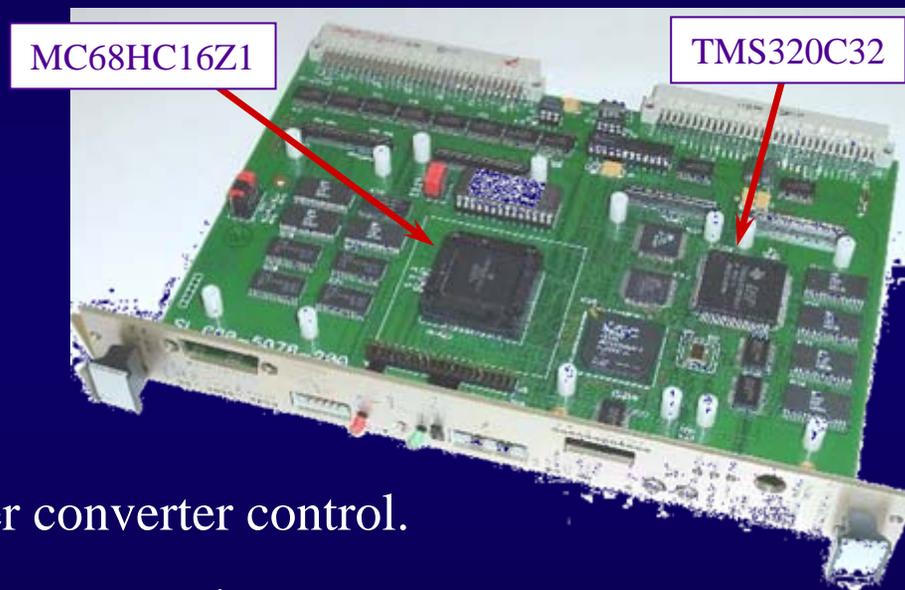


DSP Applications: LHC FGC

FGC designed and built by CERN; series production of ~2000 pieces

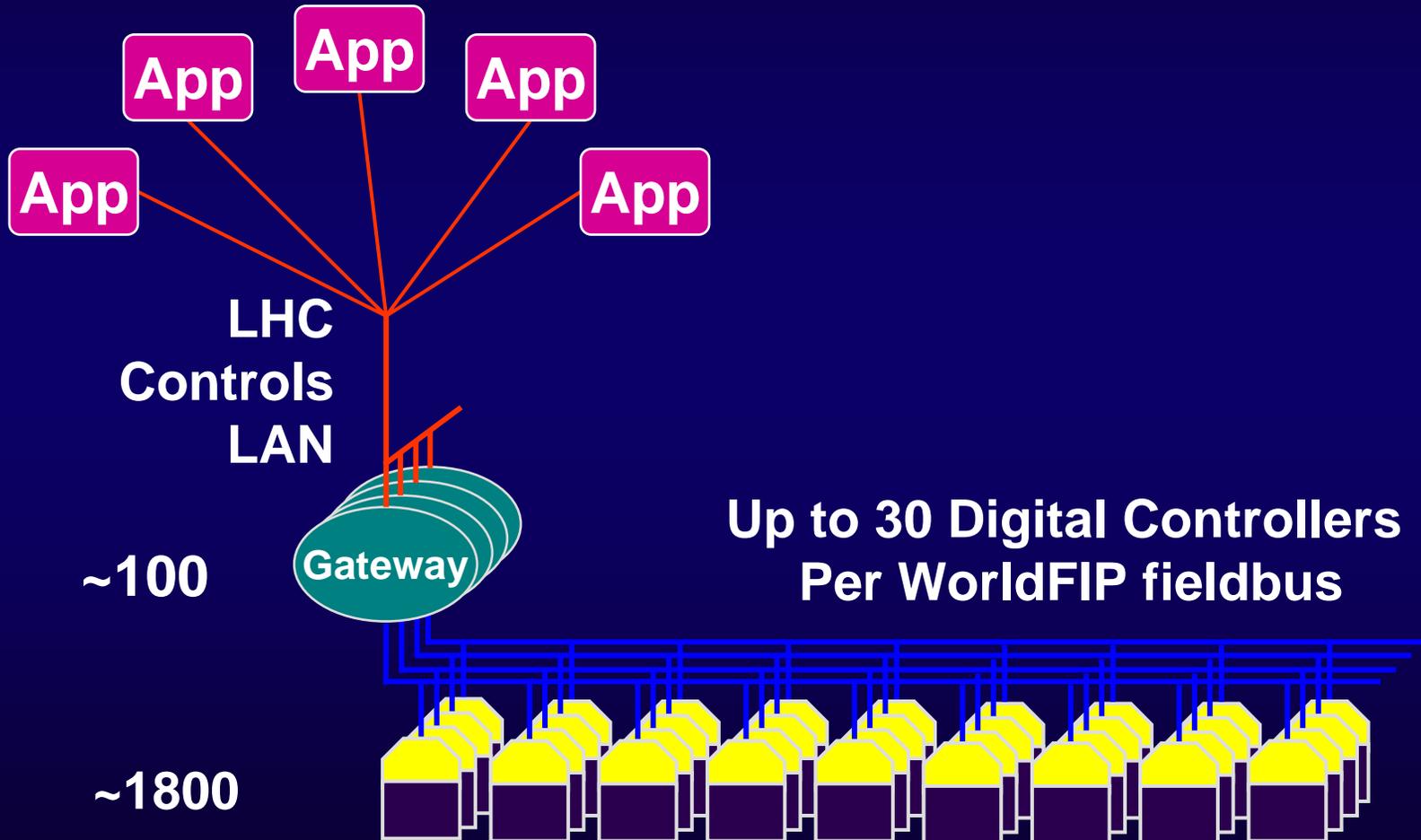
LHC Function Generator/
Controller project:

- 2000 units, mostly for power converter control.
- Motorola MC68HC16Z1 chosen a main processor.
- Significant floating point maths requirement.
- TI TMS320C32 DSP chosen as a co-processor.





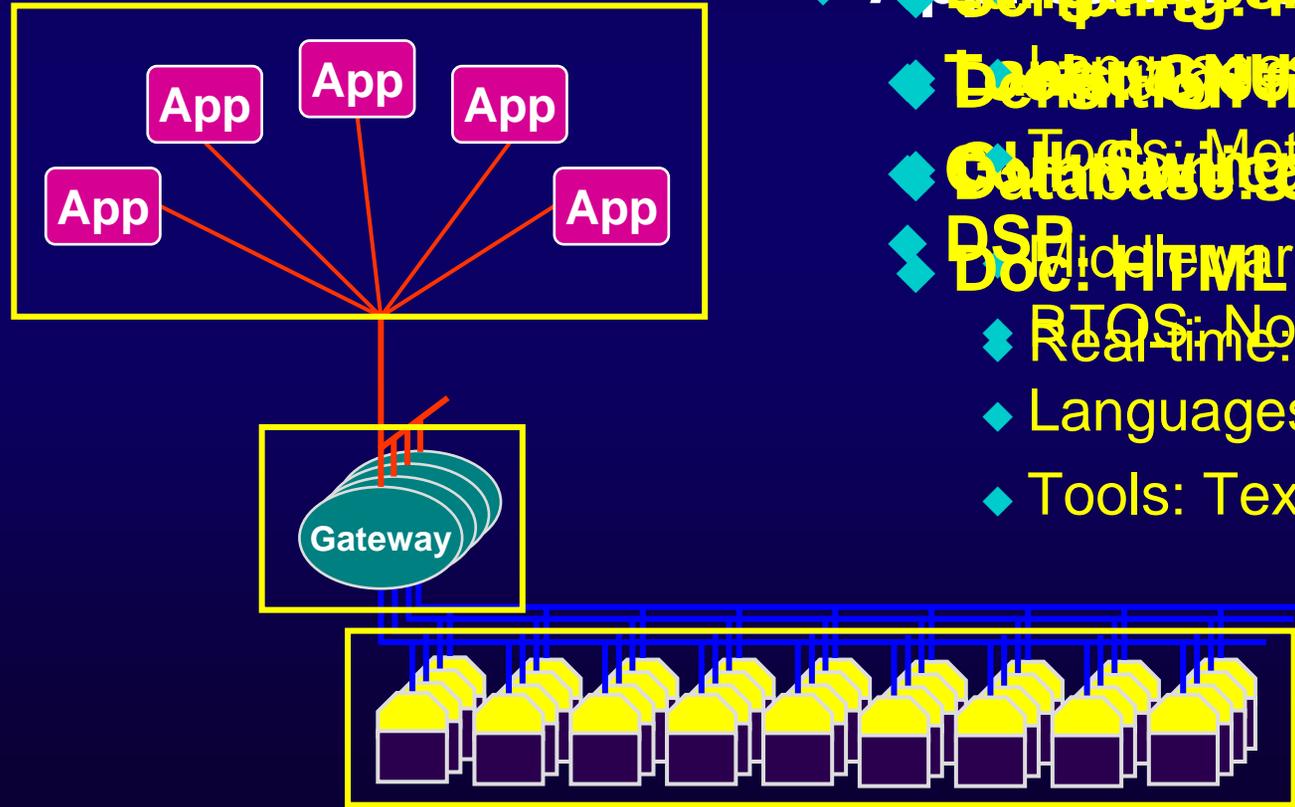
Overview – System Architecture





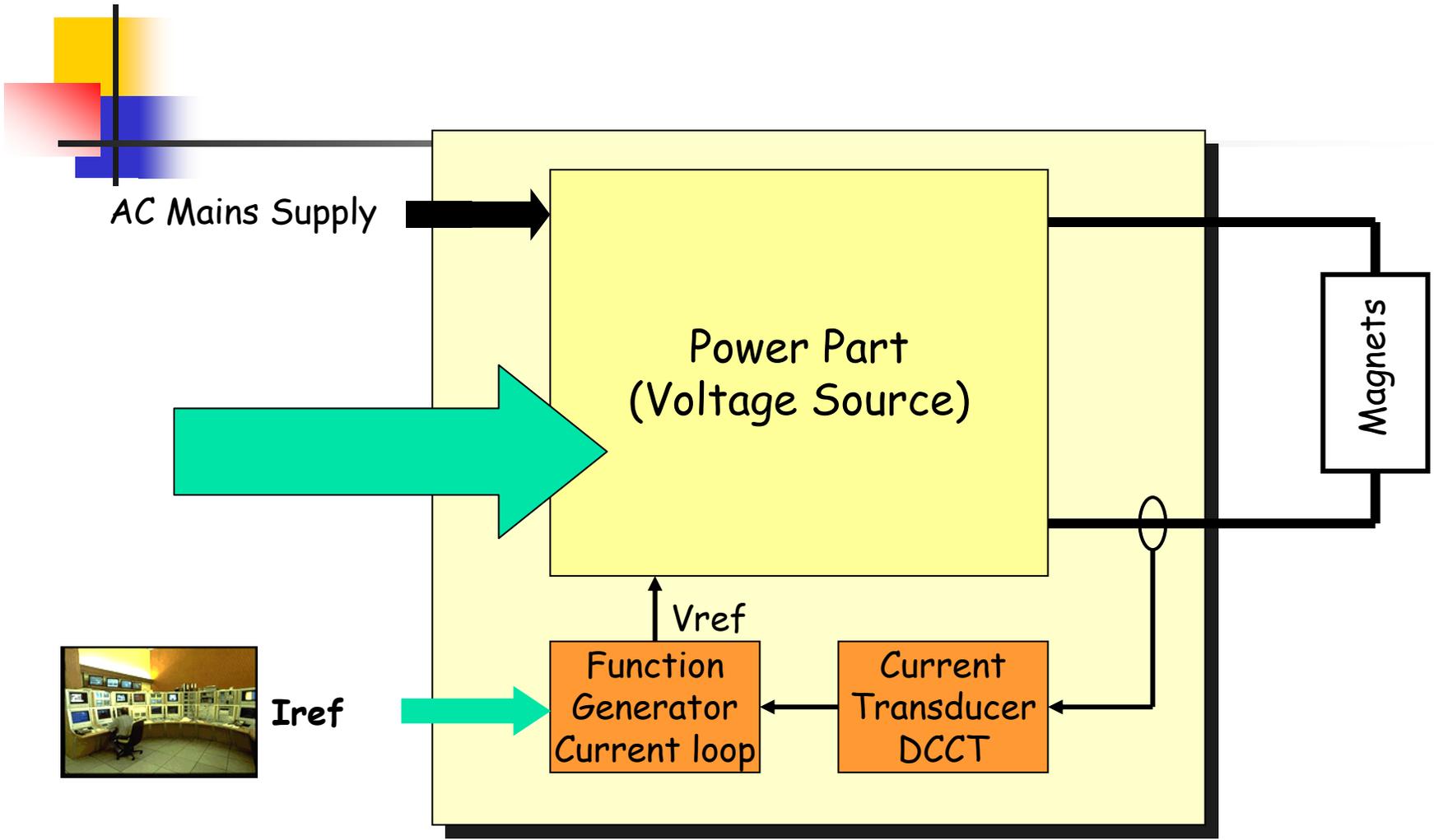
System Software Overview

- ◆ Gateway Software
- ◆ Offline Software
- ◆ Application Software
 - ◆ Scripting: PERL (4K)
 - ◆ Database: Oracle
 - ◆ Development: C, Assembler
 - ◆ Definition Files: XML
 - ◆ Tools: Metrowerks
 - ◆ Database: ORACLE
 - ◆ DSP: Hitachi
 - ◆ Doc: HTML
 - ◆ Middleware: CORBA
 - ◆ RTOS: None
 - ◆ Real-time: UDP
 - ◆ Languages: C, Assembler
 - ◆ Tools: Texas Instruments





◆ **Now a closer look**
..... **at the system components**



AC Mains Supply

Power Part
(Voltage Source)

Magnets

V_{ref}

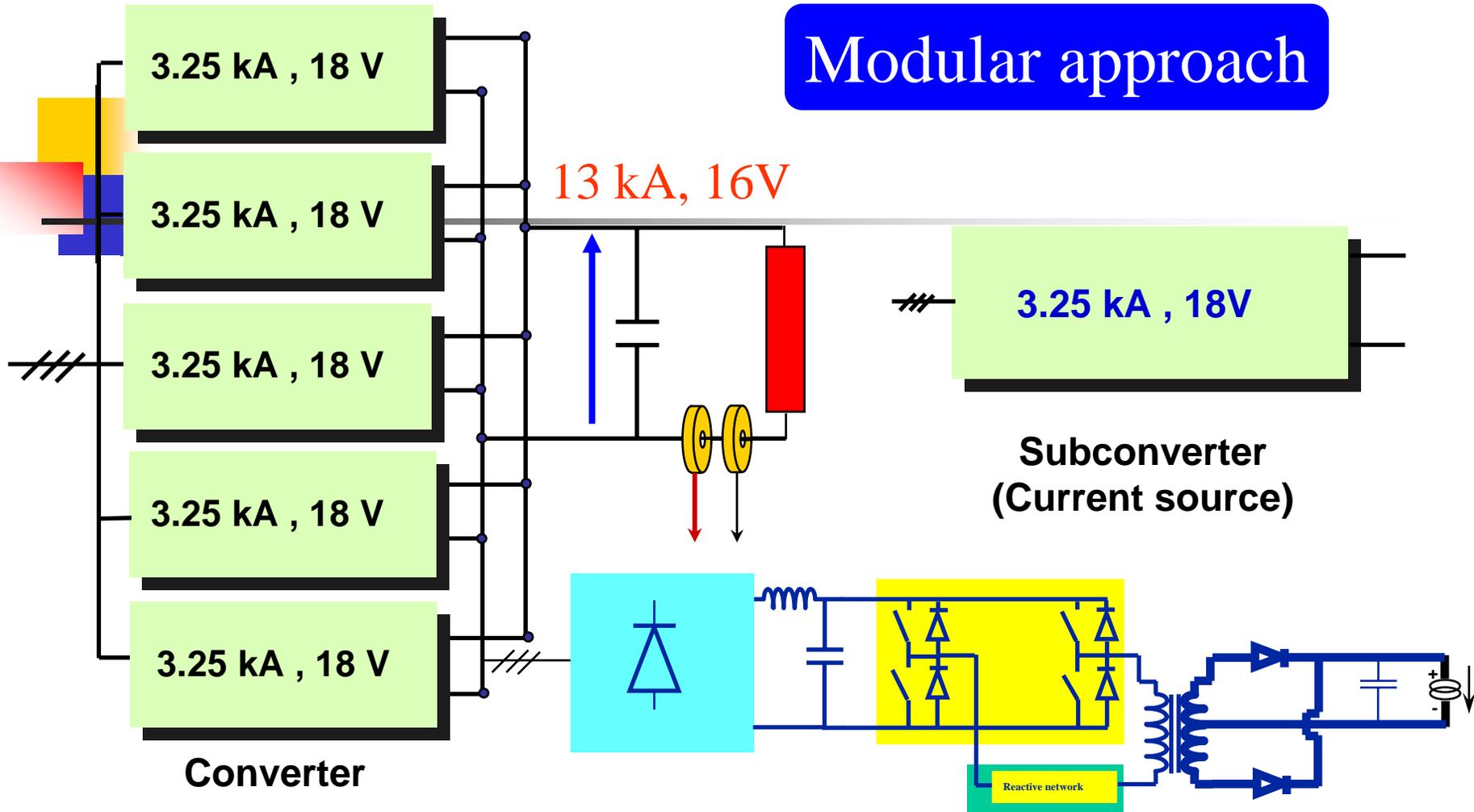
Function
Generator
Current loop

Current
Transducer
DCCT

I_{ref}



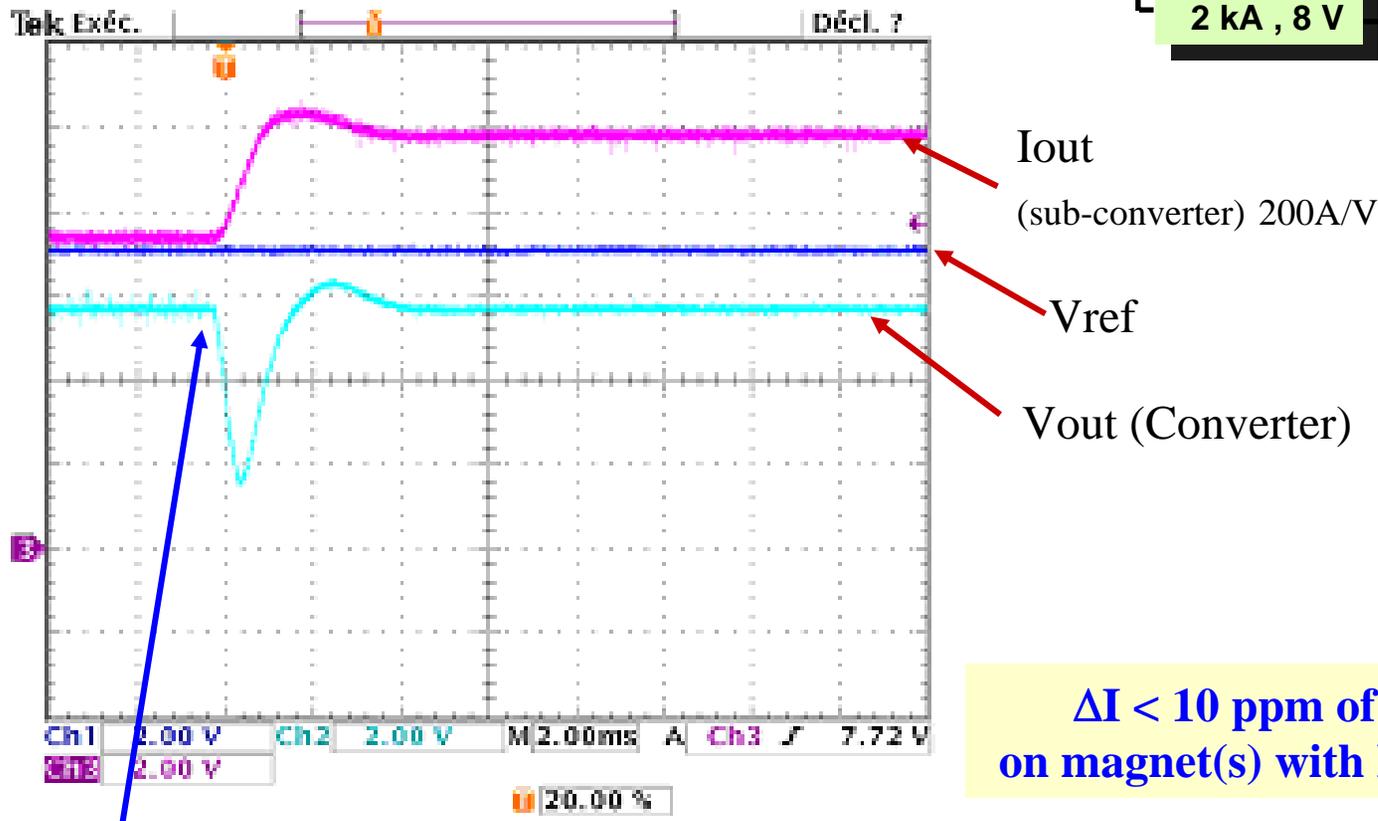
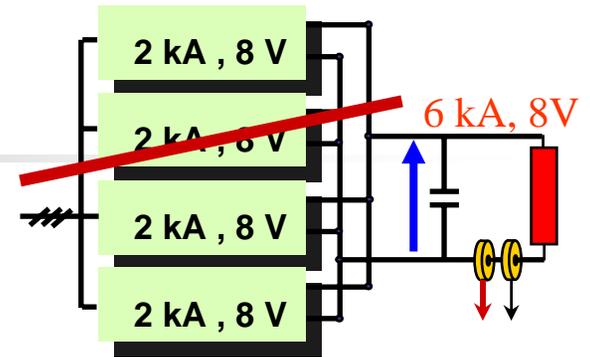
Modular approach



- $n + 1$ subconverters : redundancy, reliability
- repairability
- ease of handling underground
- versatility (6.5kA, 9.75kA, 13kA, 21 kA)

Converter Operation during a subconverter failure

Example: [6kA,8V] converter :
(3+1) x [2kA,8V] subconverters



$\Delta I < 10$ ppm of I_{max}
on magnet(s) with $L > 0.1$ H

One subconverter failure

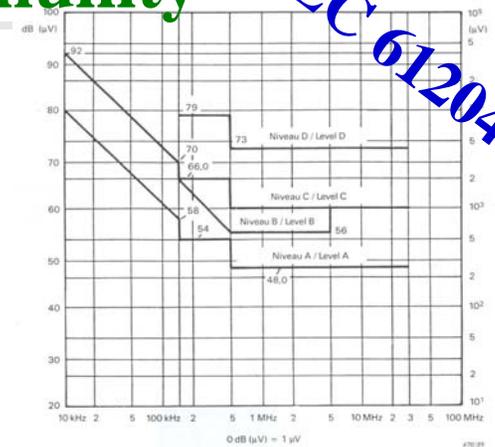
EMC : ELECTROMAGNETIC COMPATIBILITY

COMPATIBILITY : Emission - Immunity

Norms for the power converters :

Emission :

IEC 61204-3 (replaced IEC-60478-3)
(CISPR 11 ; EN 55011)



IEC 61204-3

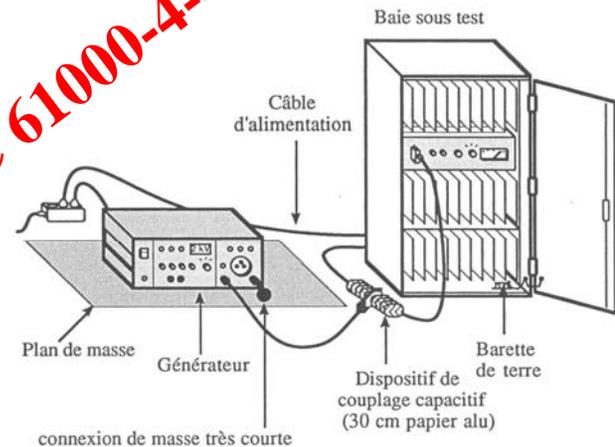
Immunity :

IEC 61000 - 4 :

Burst 61000 - 4 - 4

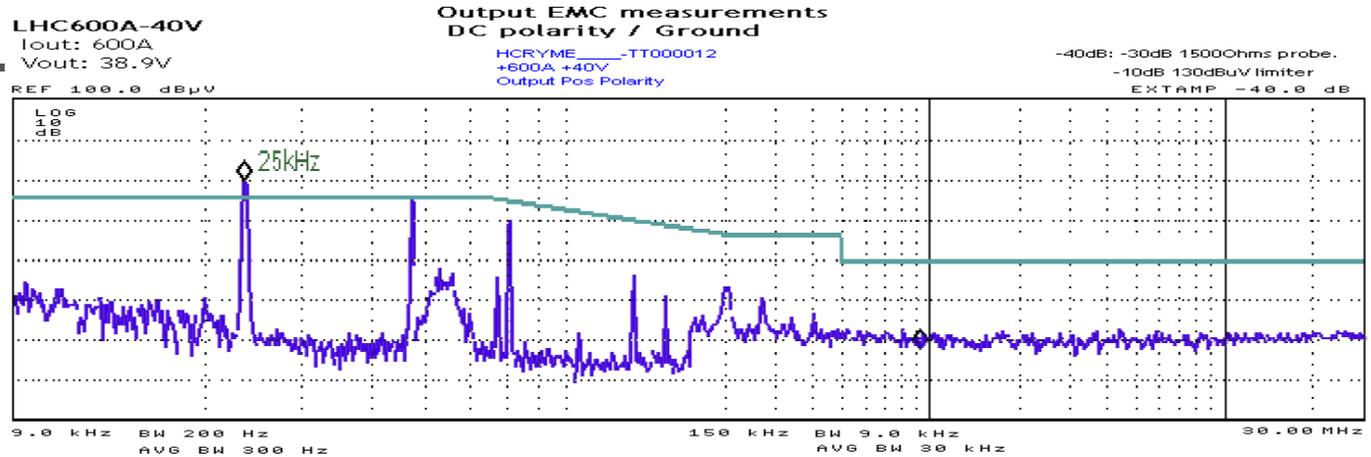
Surge 61000- 4 - 5

IEC 61000-4-4

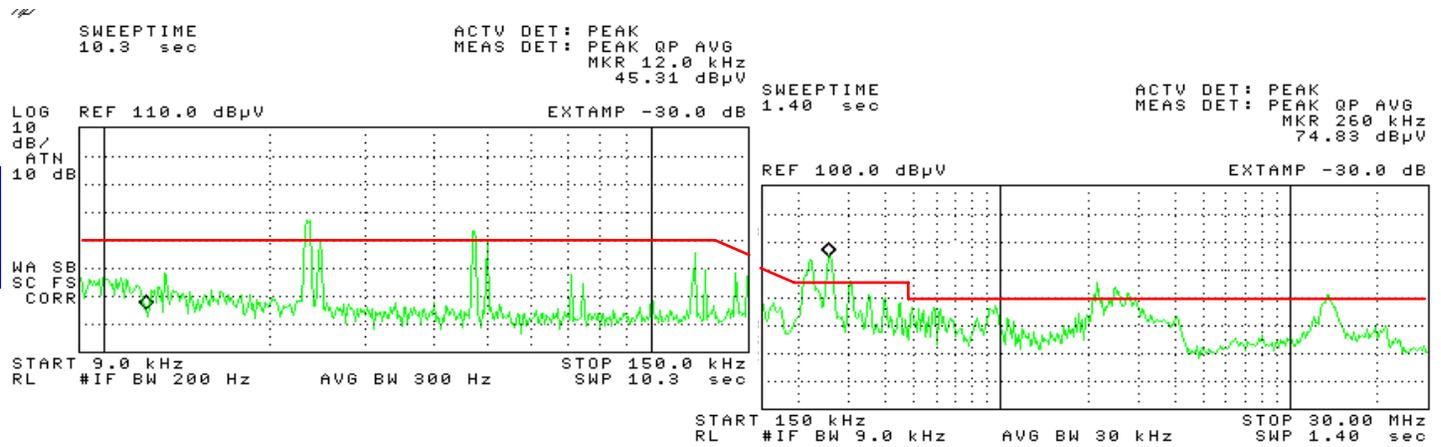


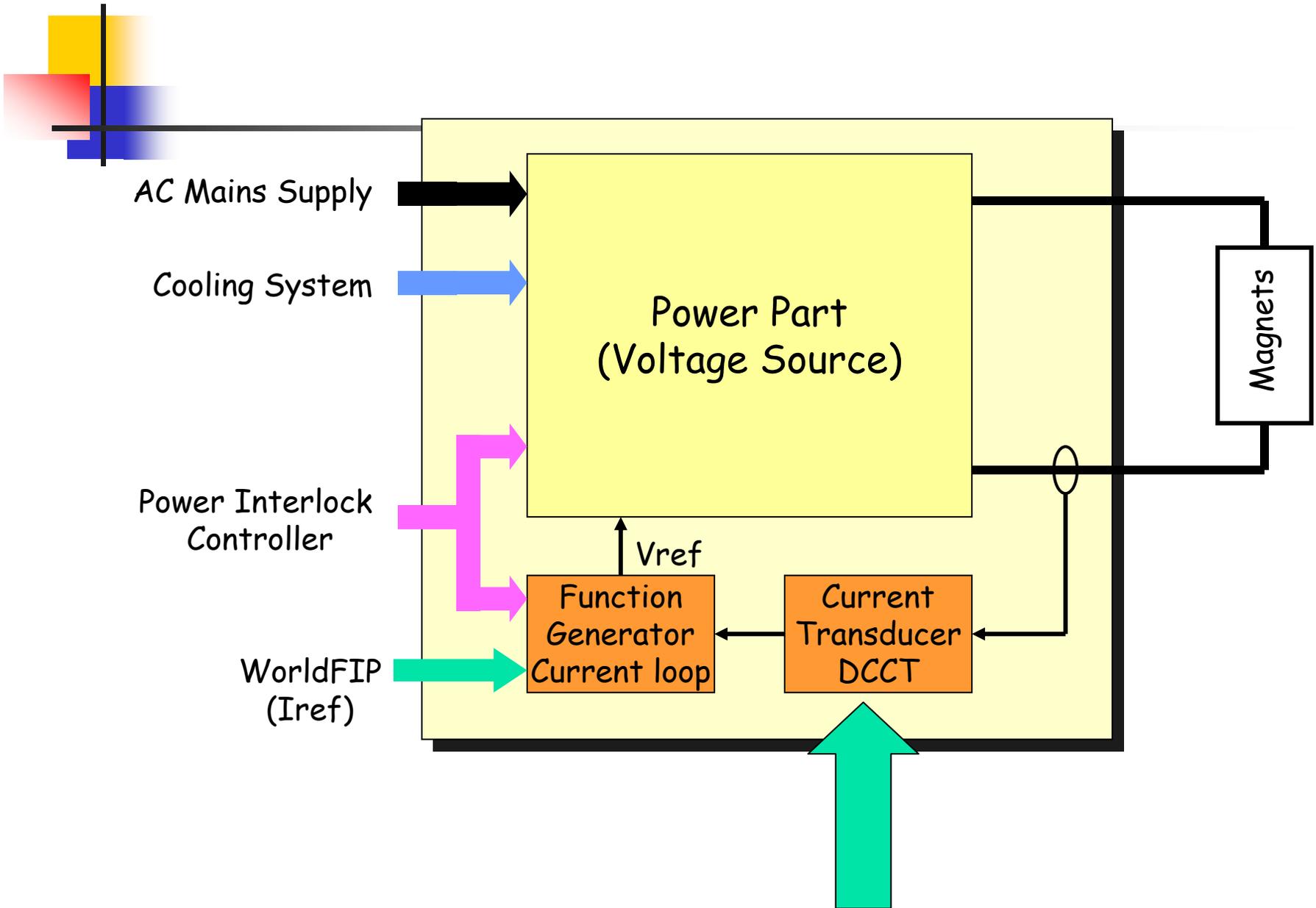
EMC conducted noise: Common Mode Emissions (9 kHz - 30 MHz) DC- Side

**[±600A, ±40V]
at 600A, 39V**



**[6kA, 8V]
at 6kA, 8V**





DCCTs (13kA)

- Highest performance - state of the art
- Separate Head and electronics chassis 19" rack mounting.
- Fitted with Calibration Windings
- Temperature-controlled environment in the Accelerator.
- Full testing and calibration at CERN on a 20kA Test Bed.

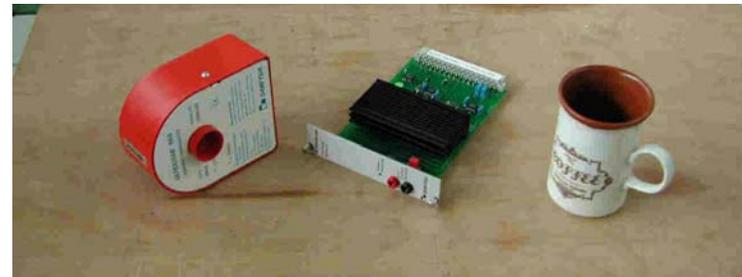


DCCTs

4kA to 8kA

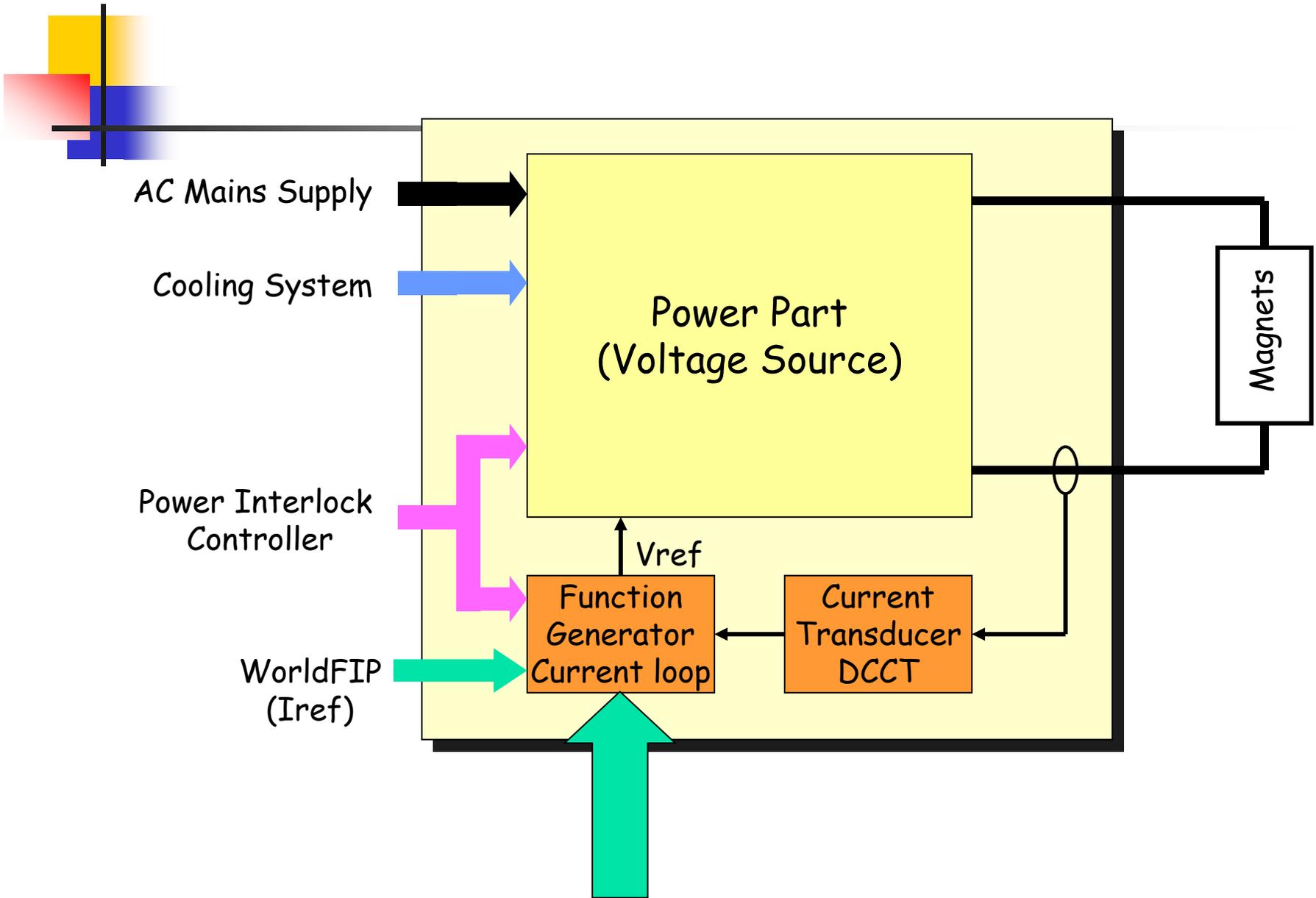


600A



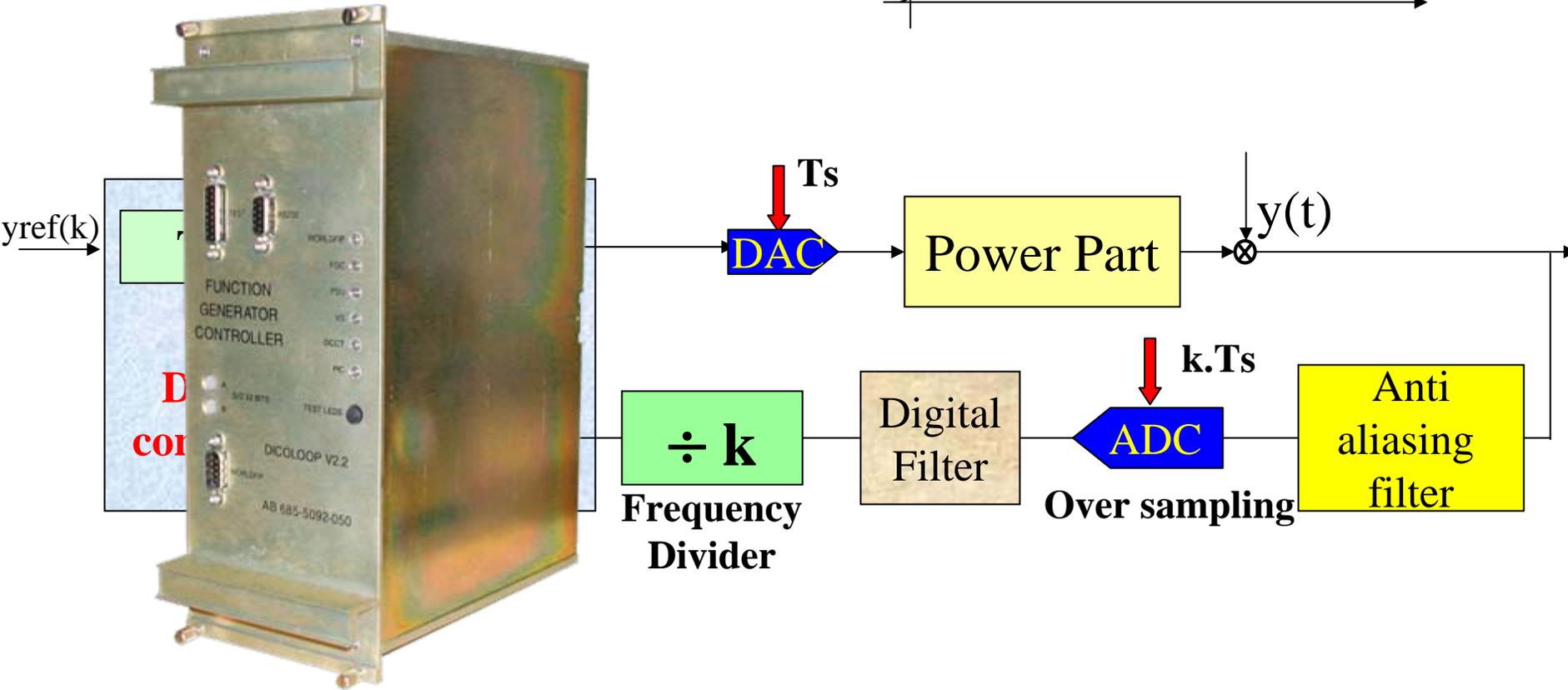
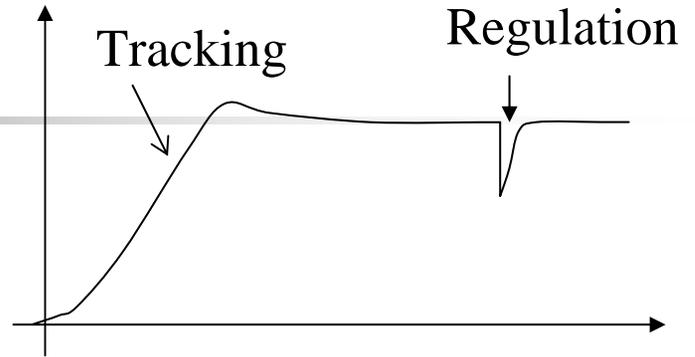
120A





Digital current loop : RST algorithm

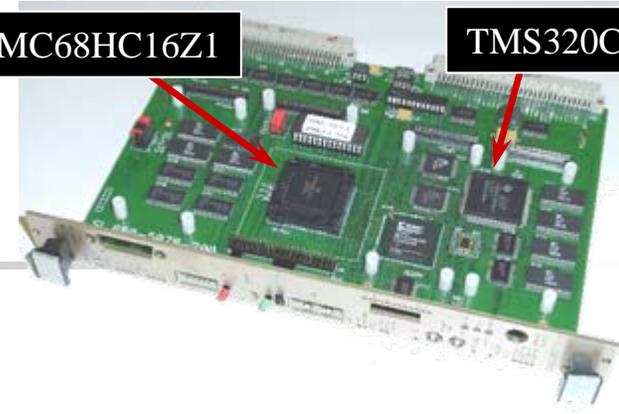
Tracking and Regulation with independent objectives



RST CONTROLLER DESIGN

MC68HC16Z1

TMS320C32



Tracking:

To get a good tracking of the reference (no lagging error, no overshoot), the transfer function that the controller must achieve between the reference i_{ref}^* and the output i_m^* is:

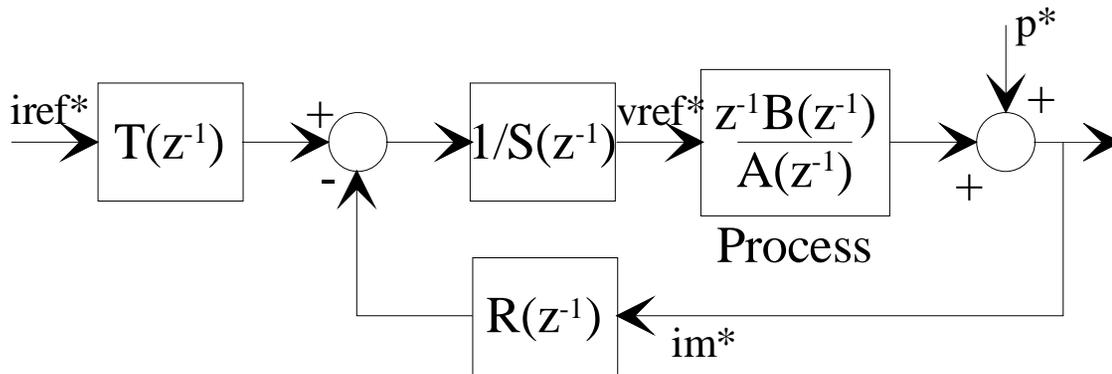
$$\frac{i_m^*}{i_{ref}^*} = z^{-1}$$

Regulation:

According to the LHC cycle, the bandwidth for the closed-loop system is chosen $f_B^{CL} \in [0.1\text{Hz}, 1\text{Hz}]$. The regulation is defined by the pole placement with a natural frequency $\omega_{cl} \in [0.628\text{rad/s}, 6.28\text{rad/s}]$ and with a damping factor greater than 1. To ensure a zero steady-state error when the reference is constant, the transfer function $1/S(z^{-1})$ must contain two integrators .

$$\left(1 - z^{-1}\right)^2$$

R.S.T



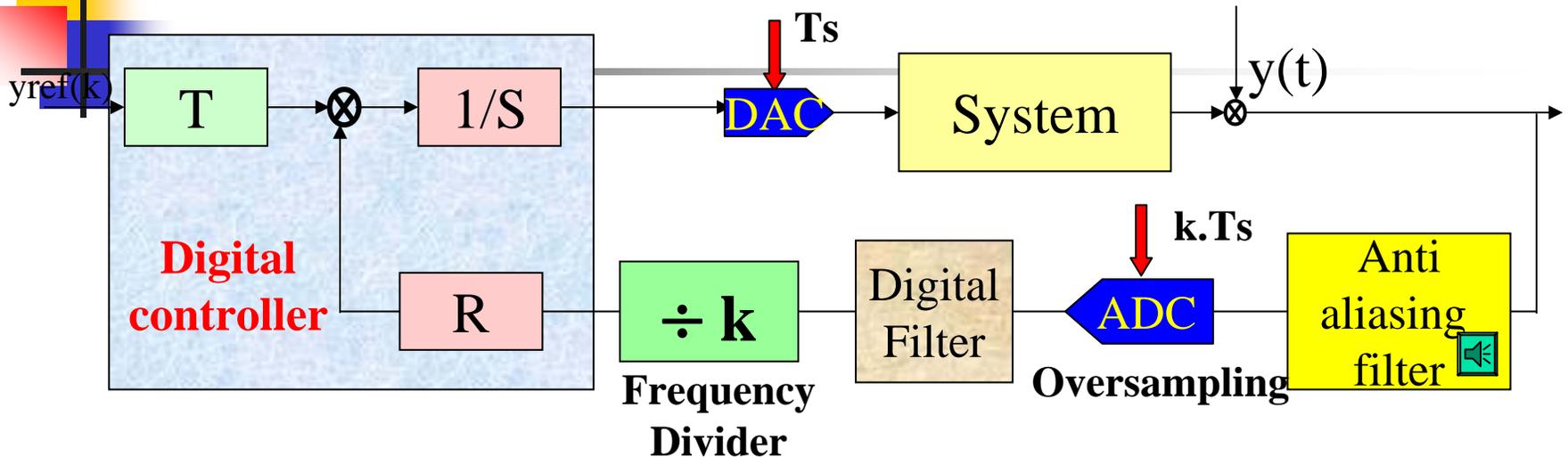
Tracking:

$$\frac{i_m^*}{i_{ref}^*} = \frac{z^{-1}BT}{A.S + R.B.z^{-1}}$$

Regulation:

$$\frac{i_m^*}{p^*} = \frac{A.S}{A.S + R.B.z^{-1}}$$

Summary



Based on f_B^{OL} and power of the actuator : choice of the closed-loop performance [$f_B^{CL}(t_r)$ and $Q(M)$]

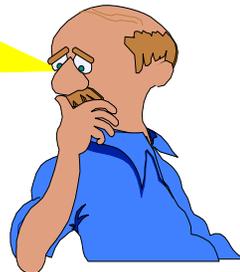
Robustness ; f_B^{CL} / f_B^{OL} (Internal saturation : controlability)

f_s (sampling frequency) : choice based on the f_B^{CL}

$$f_s = 1/Ts = (6 \text{ to } 25) * f_B^{CL}$$

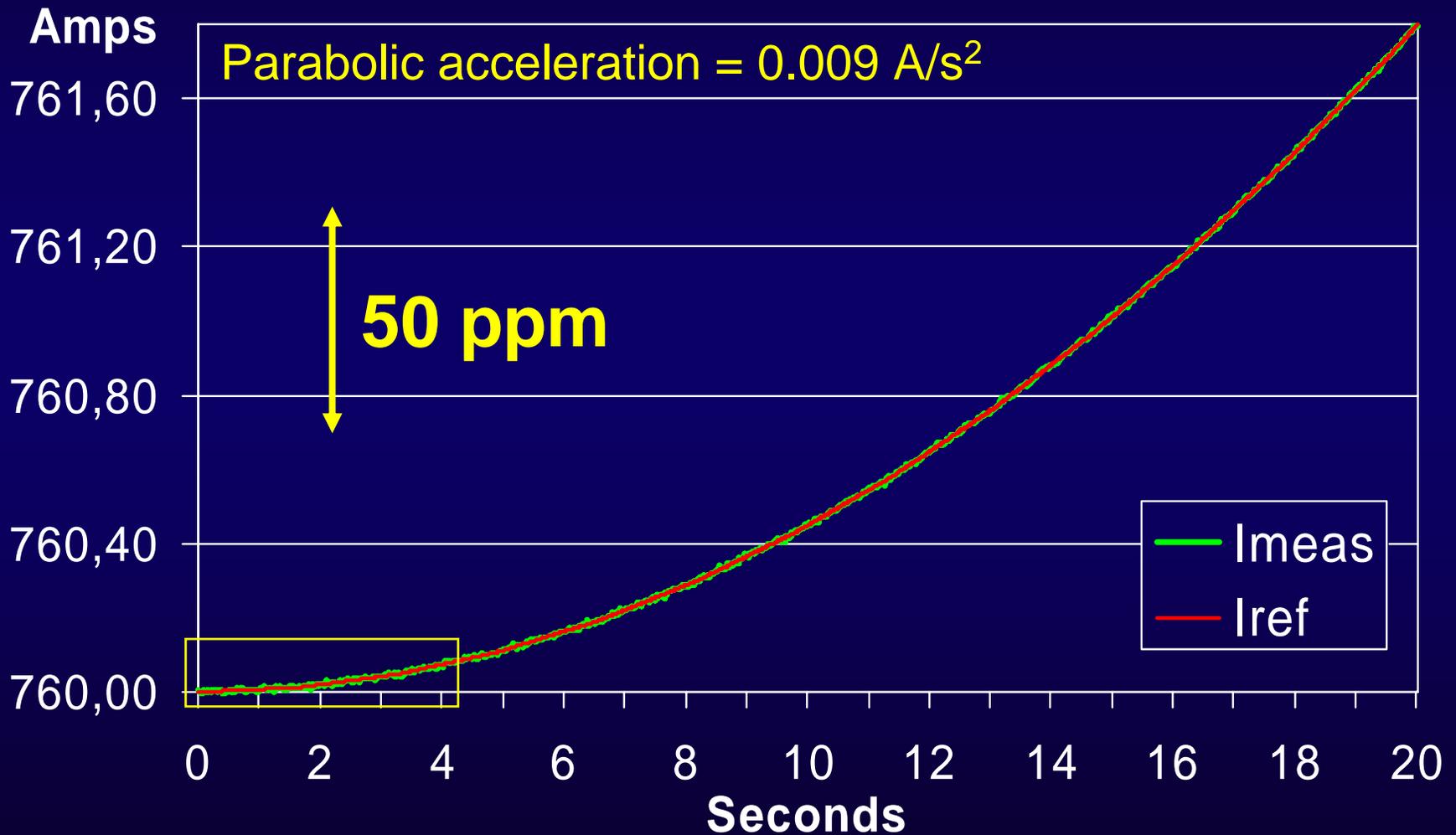
Discrete model $H(z^{-1})$ at Ts

System model ?
 $f_B^{CL}(t_r)$, $Q(M)$?
 Ts ?



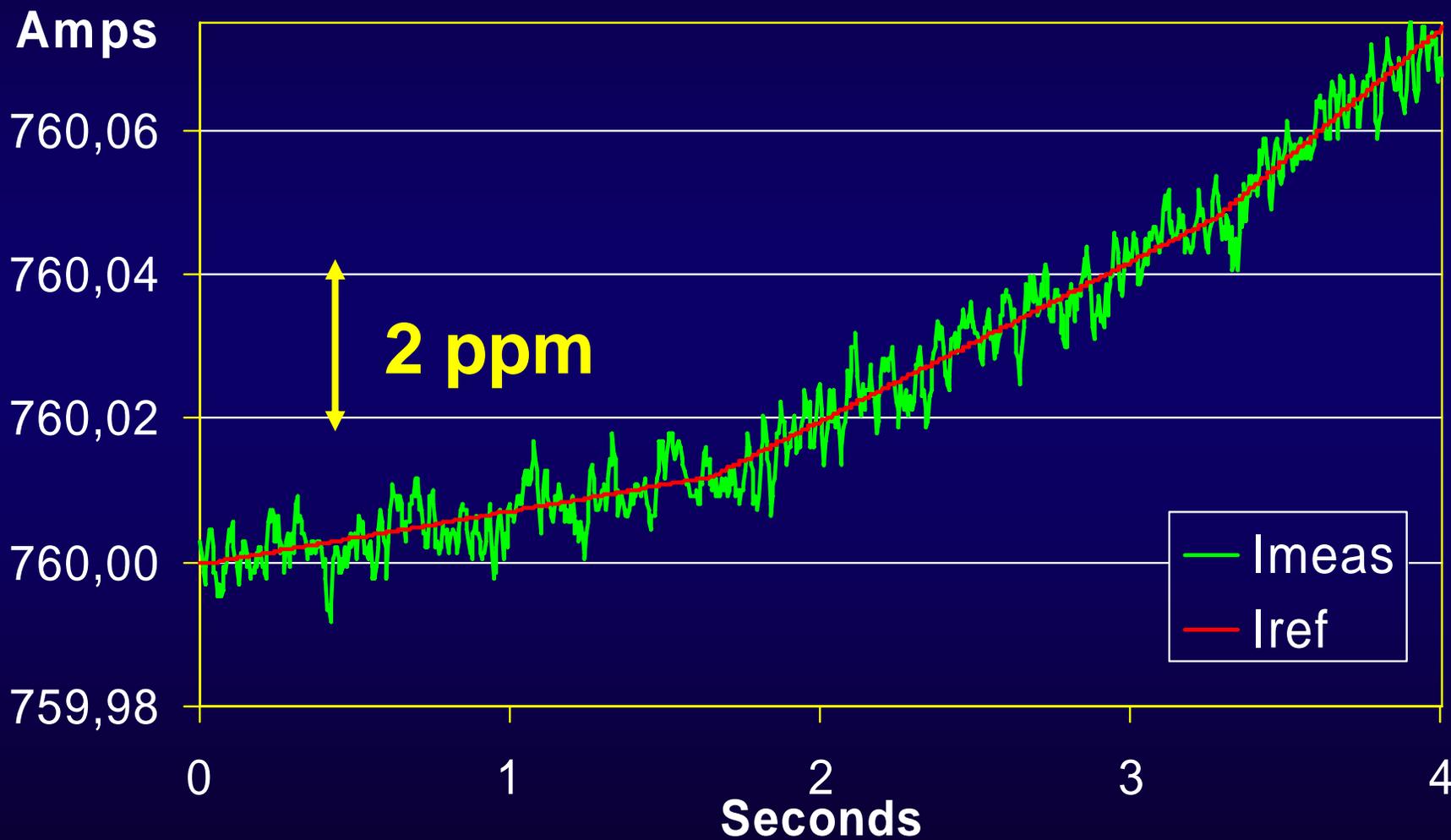


LHC dipole circuit ramp (0-20s)



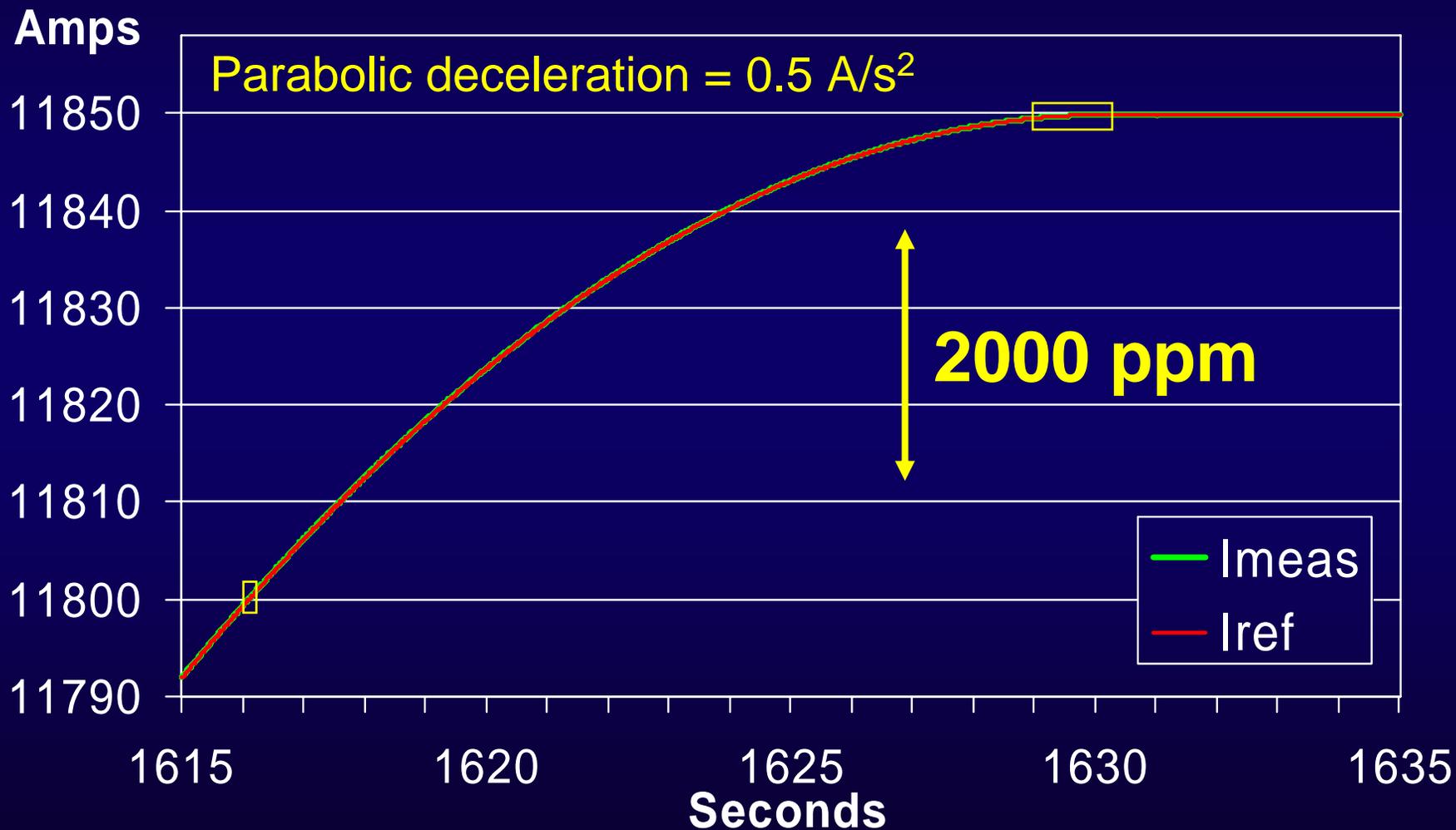


LHC dipole circuit ramp (0-4s)



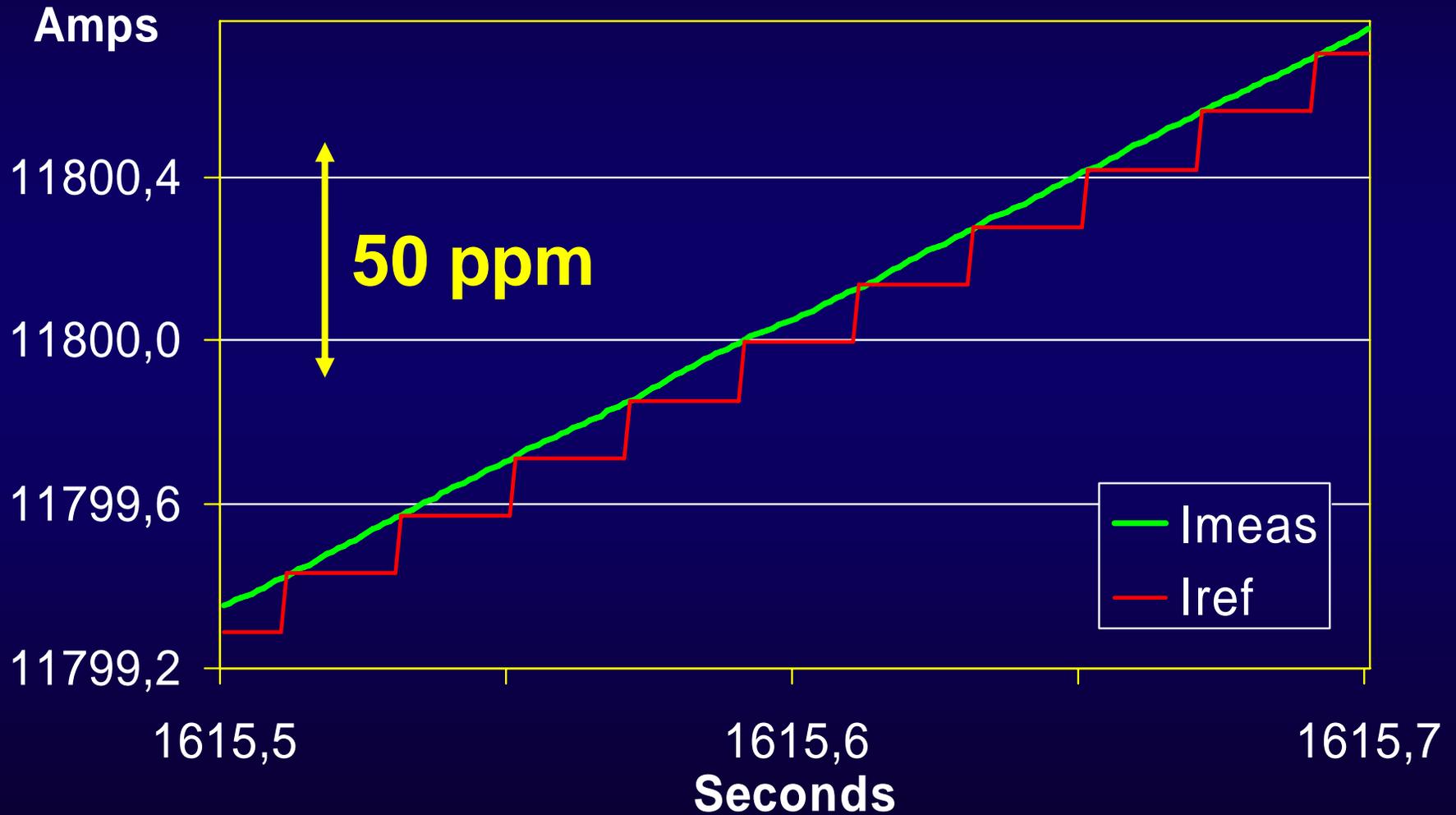


LHC dipole circuit ramp (last 15s)



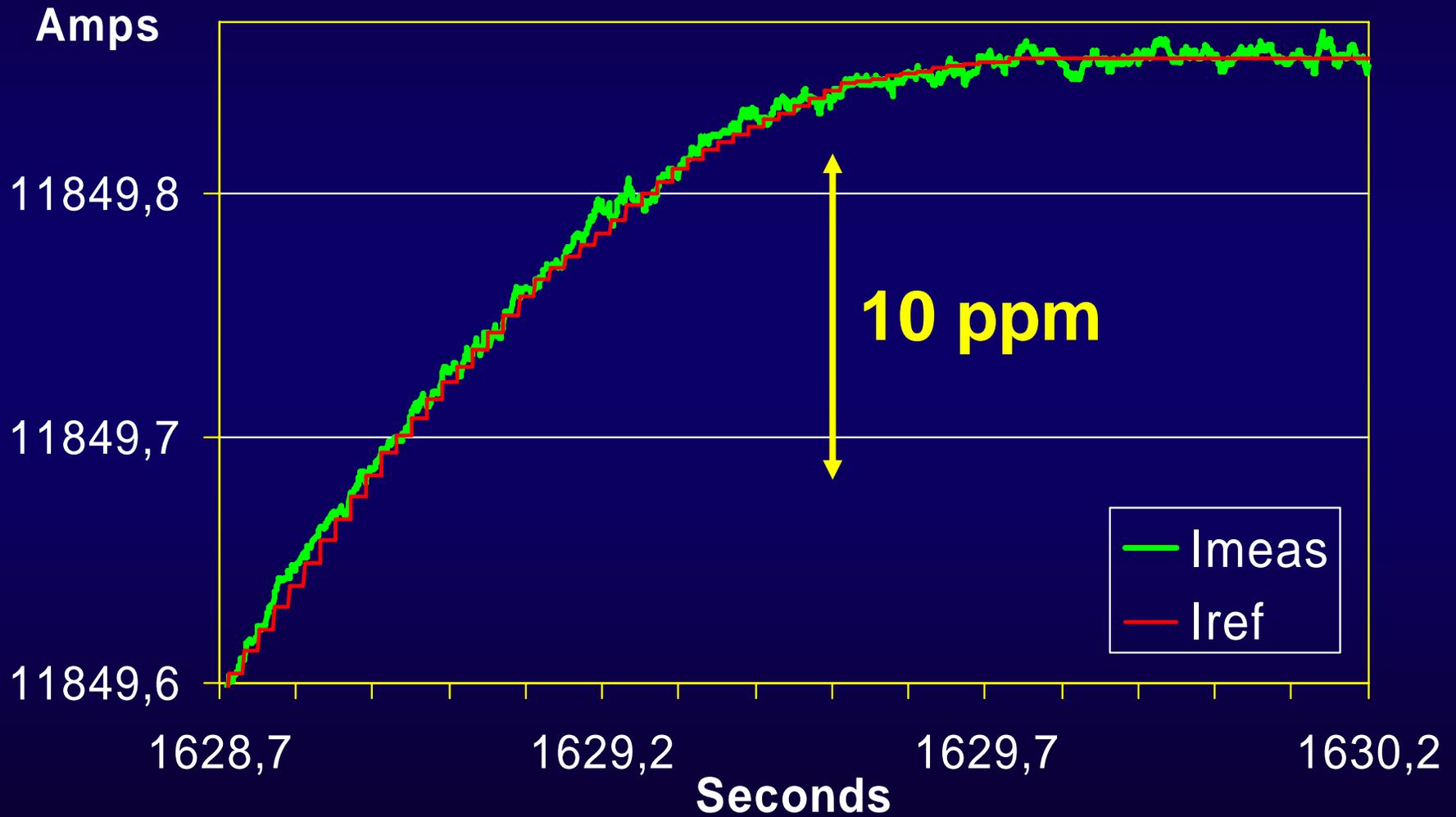


LHC dipole circuit ramp (200ms)



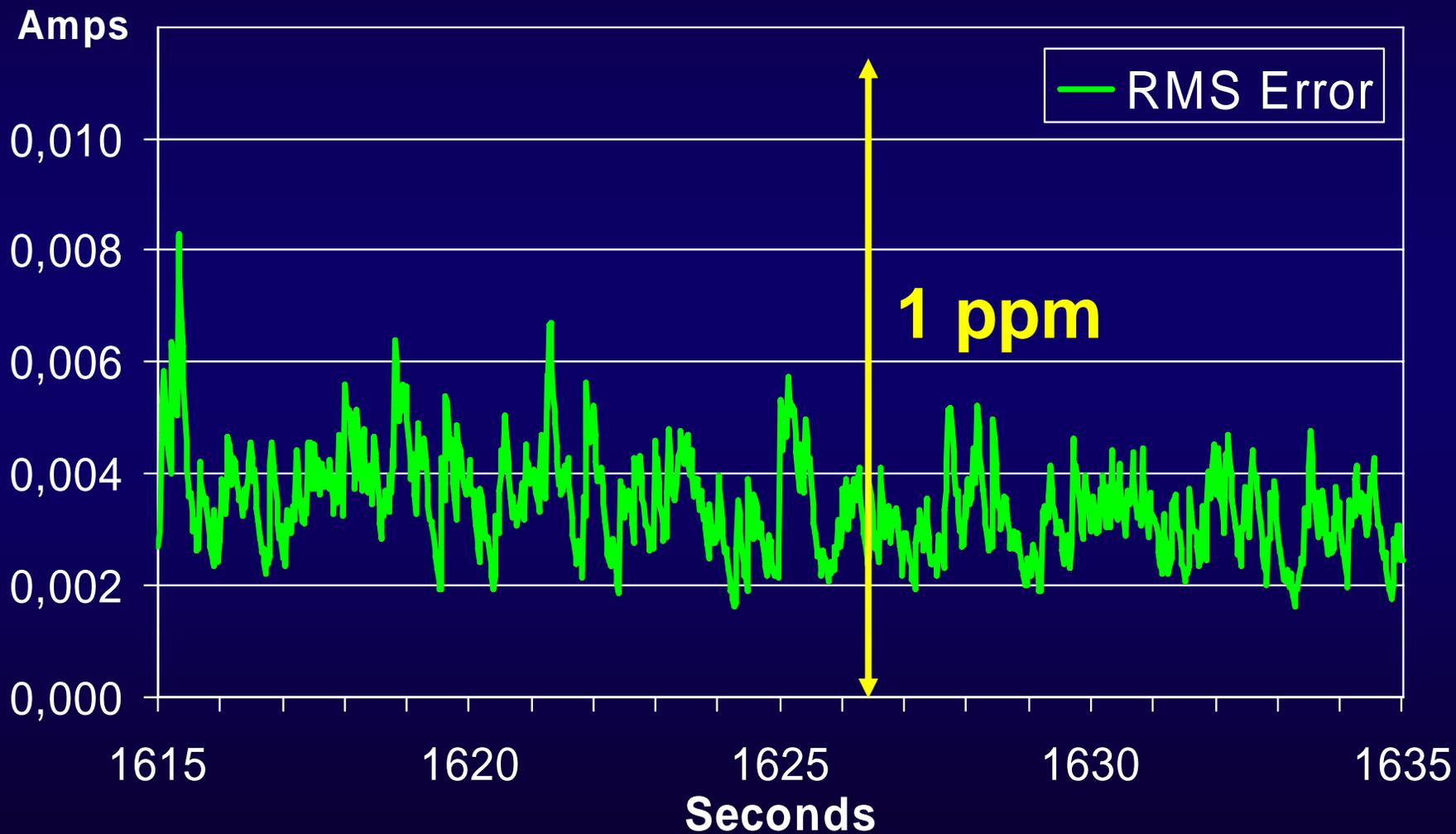


LHC dipole circuit ramp (last 1 s)





Control Algorithm RMS Error



Quick Summary:

- The LHC represents many technological challenges
 - One challenge is cost effective time synchronous control of 1700 power converters with very high precision... plus radiation resistance
 - The challenge is met with a CERN built system based on floating point DSPs
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Thanks to:

- Freddy Bordry, Quentin King; Luca Bottura and Mike Lamont for their slides

 - To you for listening!
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