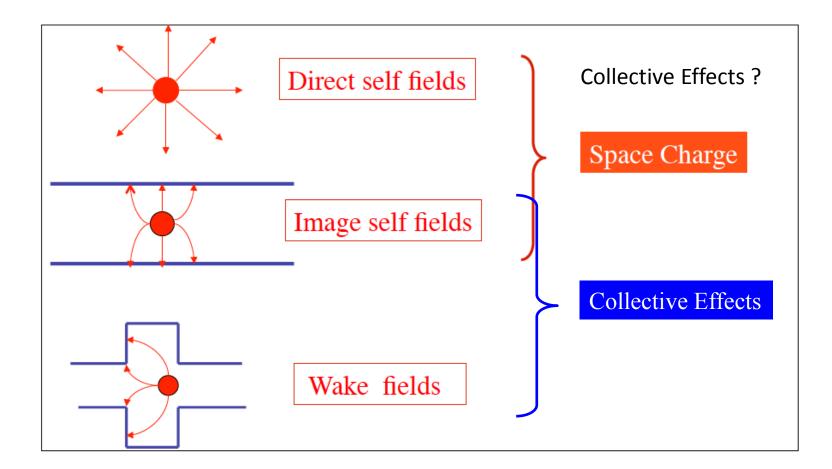
Collective Effect II

Giuliano Franchetti, GSI CERN Accelerator – School Prague

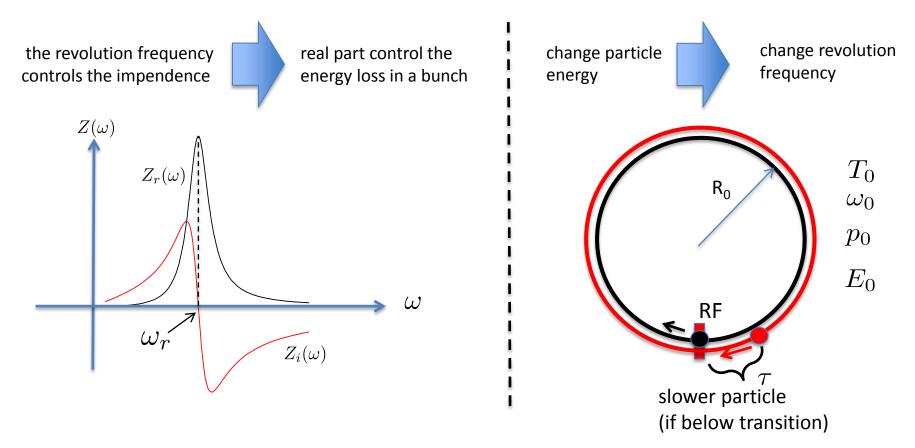
Type of fields



Robinson Instability

Robinson Instability

It is an instability arising from the coupling of the impendence and longitudinal motion



The coupling of two effects

via the longitudinal dynamics

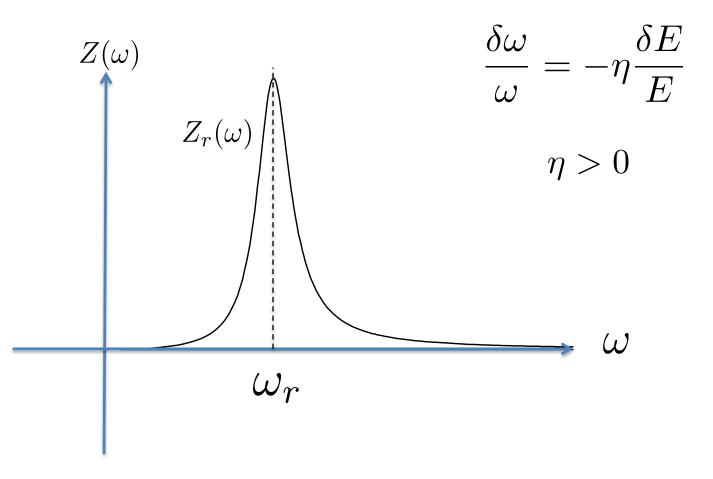


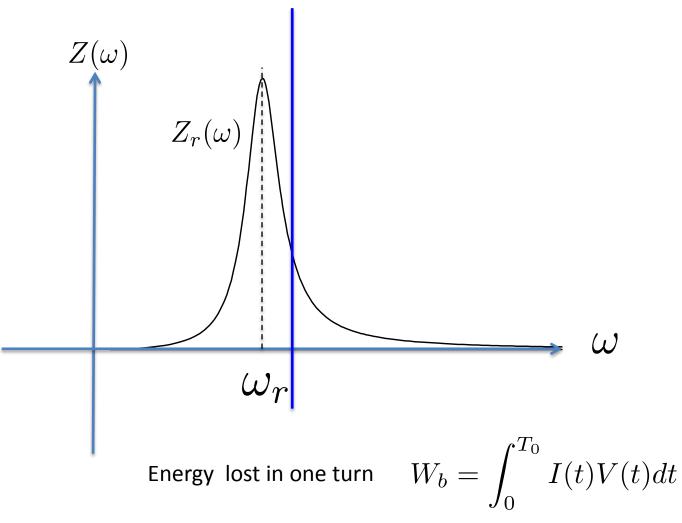
Energy loss due to impedance

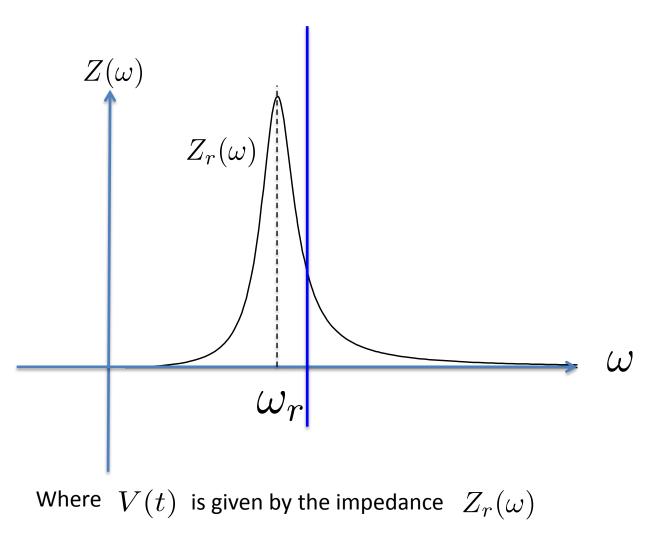
Change of revolution frequency



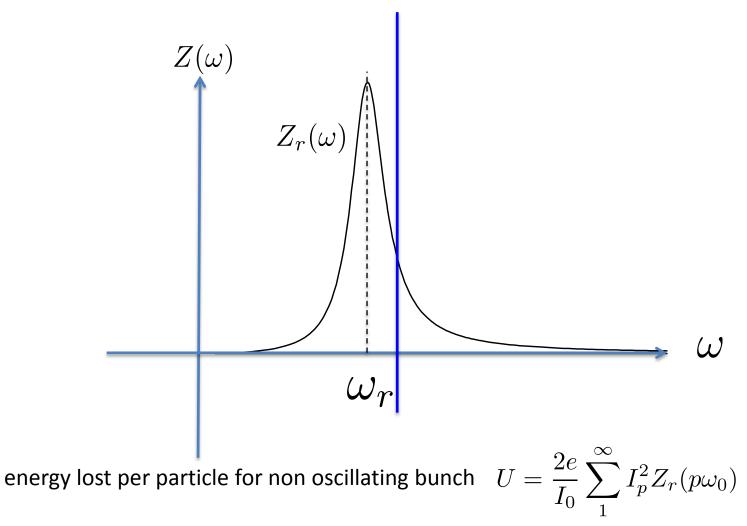
because of the impedance $Z(\omega)$

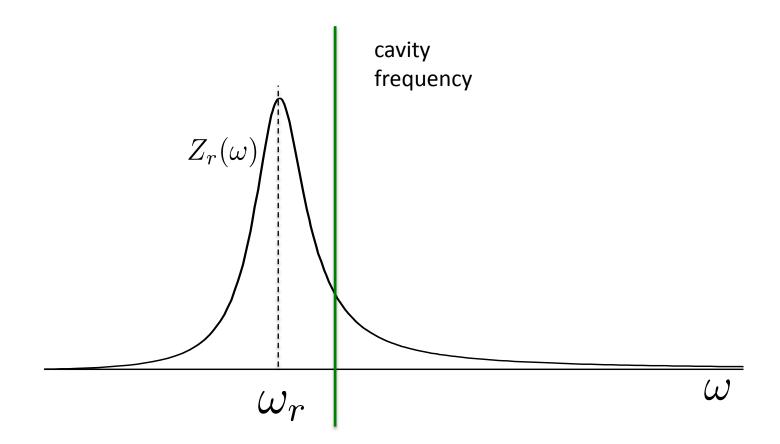




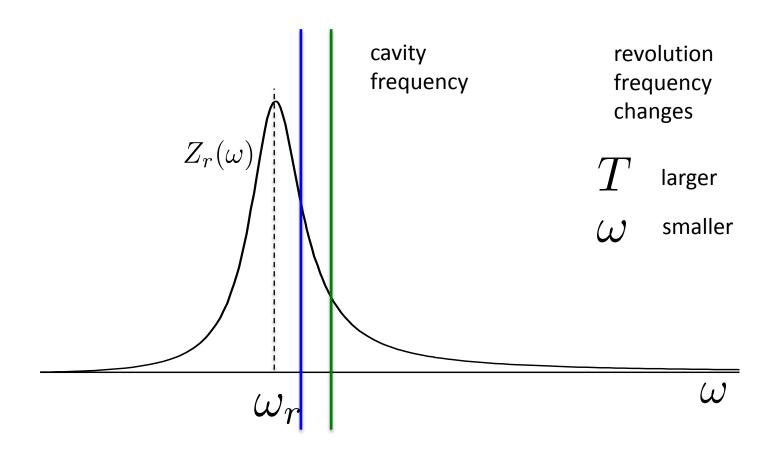


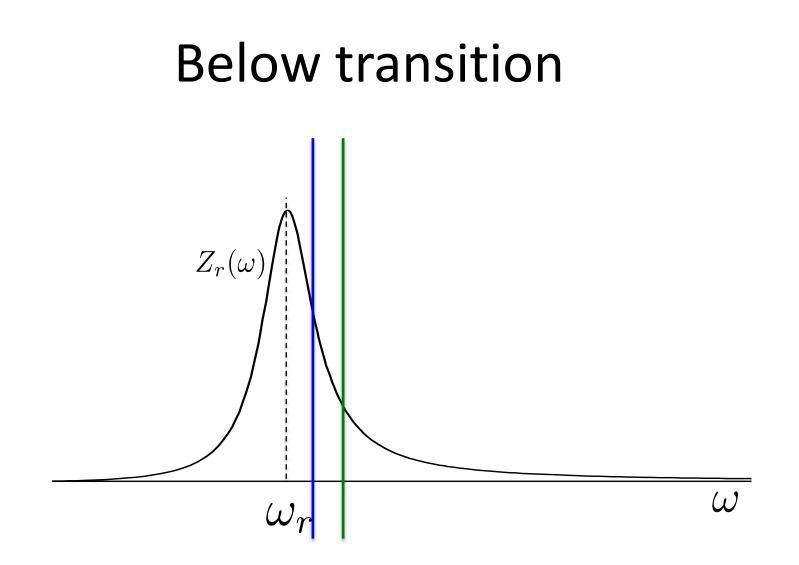
G. Franchetti



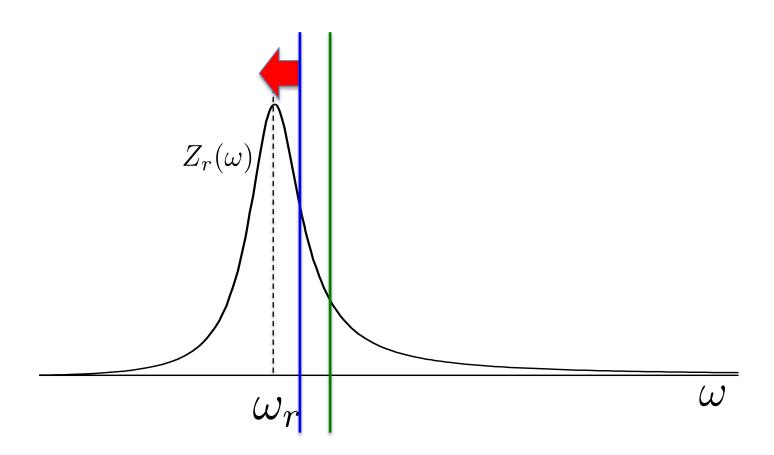


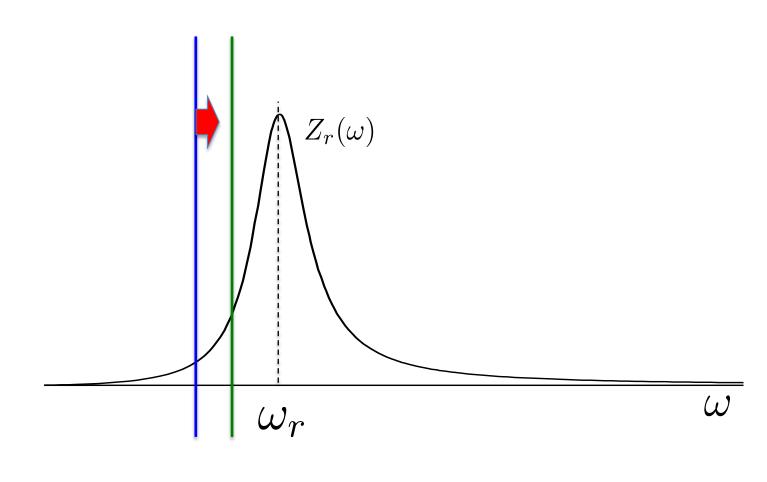
In one turn energy is lost but compensated by the RF



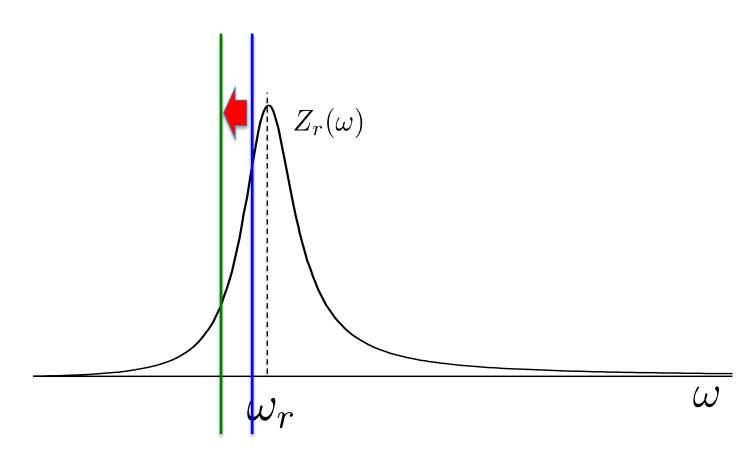


Energy lost \rightarrow increase $\omega \rightarrow$ increase $Z_r \rightarrow$ increase energy loss !!!

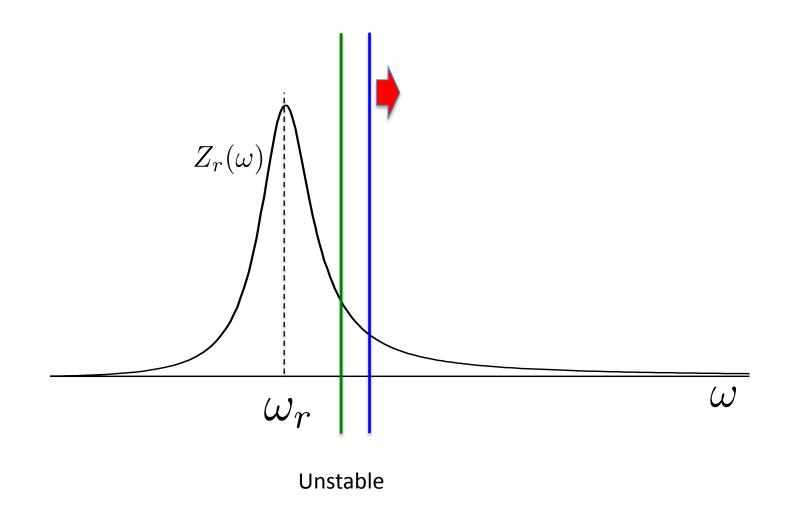


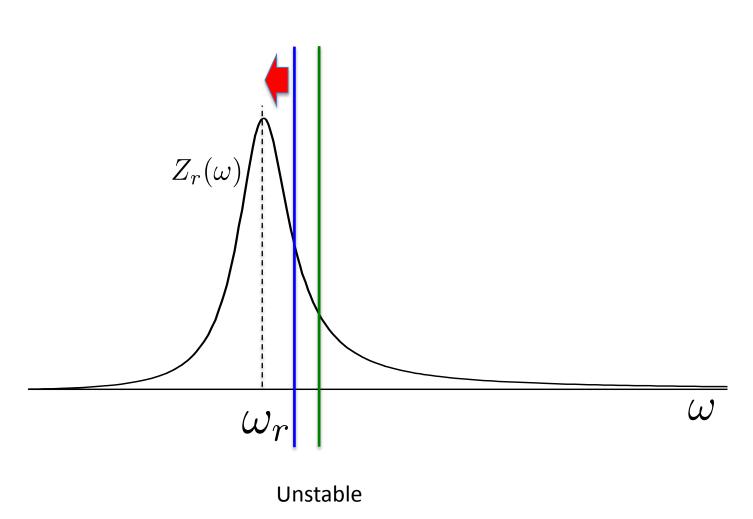




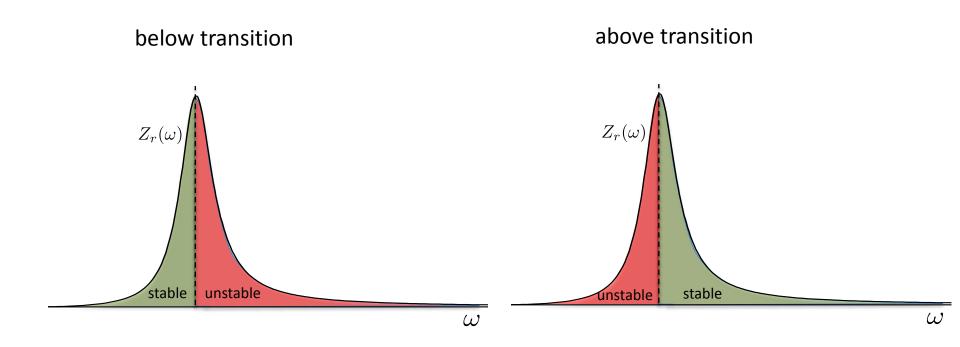


Stable

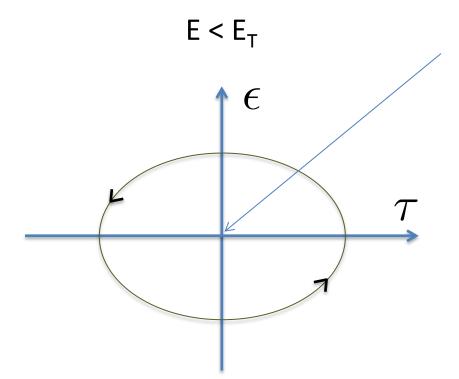




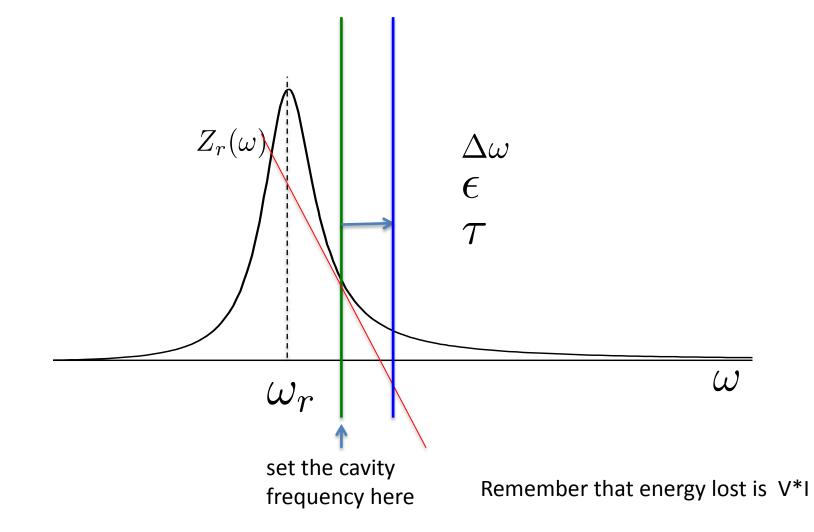
Summary of the reasoning

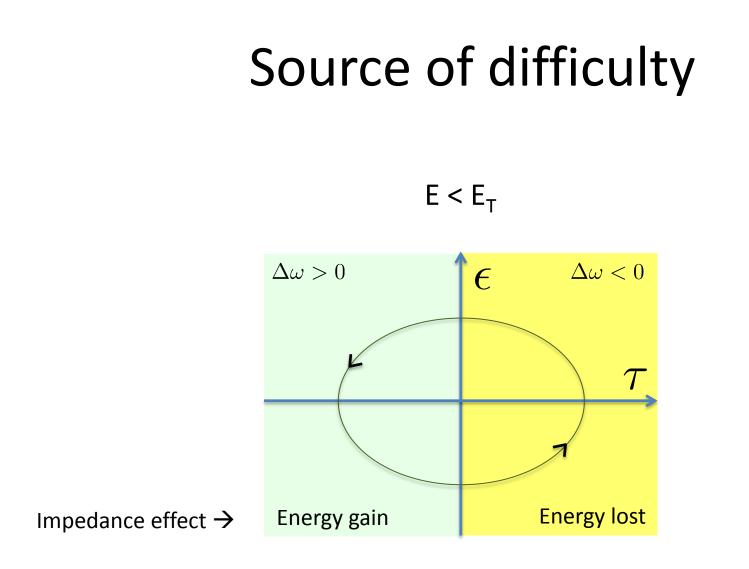


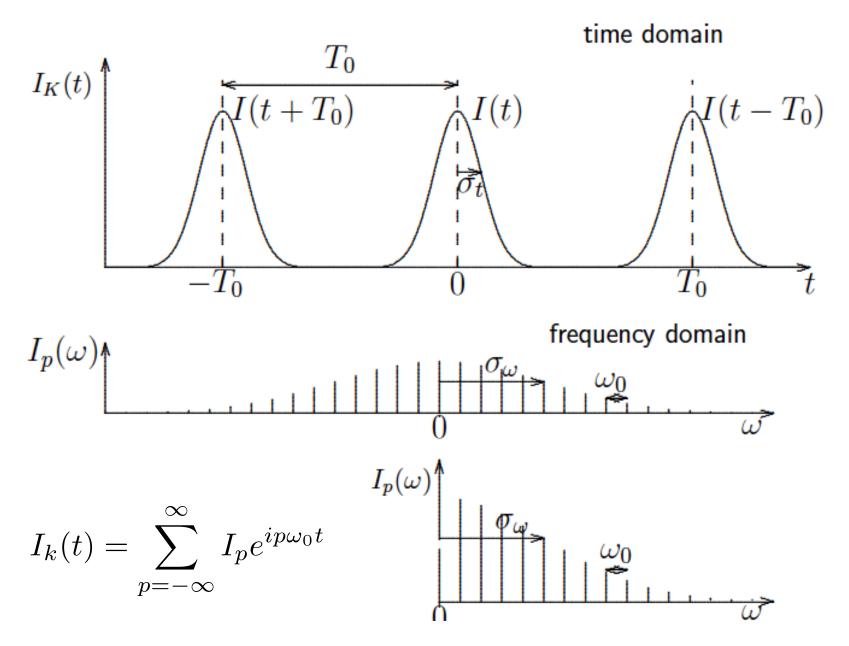
More complicated



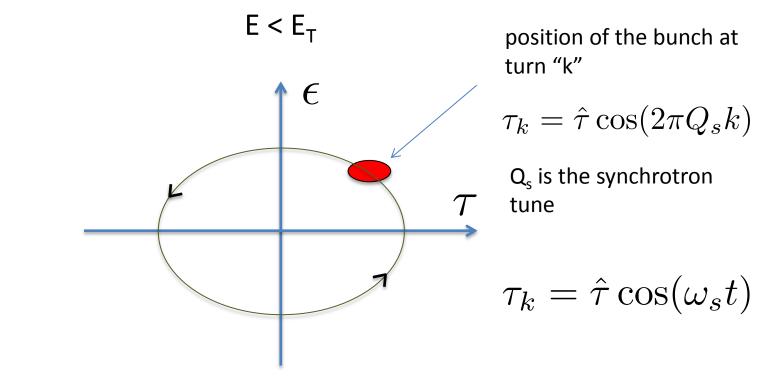
No Energy Loss: RF give the same energy lost by the impedance



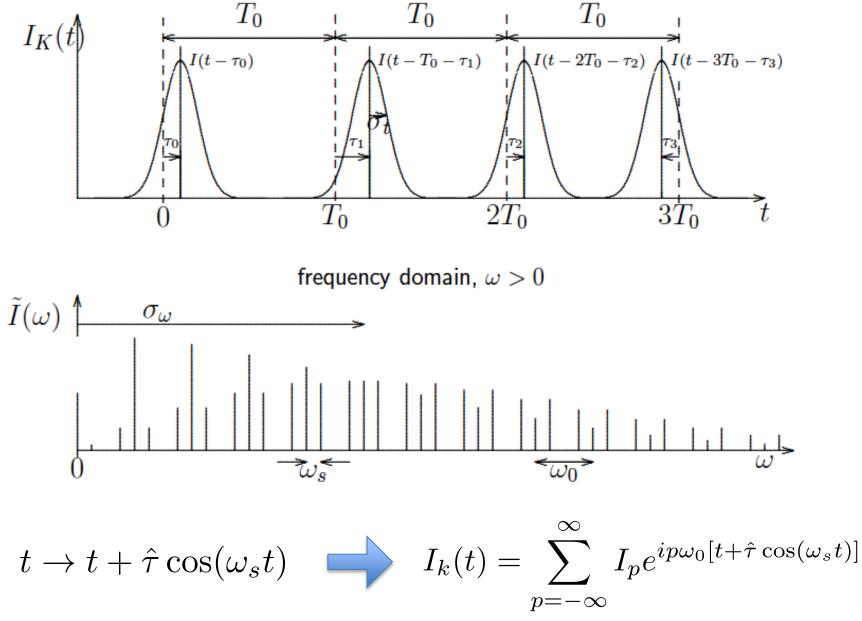




Still we neglect something



time domain

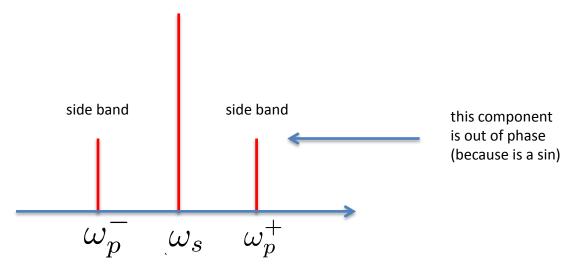


G. Franchetti

Current

$$I_k(t) \simeq \sum_{\omega > 0} I_p \left[\cos(p\omega_0 t) + \frac{p\omega_0 \tau}{2} \sin((p + Q_s)\omega_0 t) + \frac{p\omega_0 \tau}{2} \sin((p - Q_s)\omega_0 t) \right]$$
$$\underbrace{\omega_p^+}{\omega_p^+}$$

The bunch current can be described by 3 components with frequency very close



That means that the energy loss due to the impedance has to be computed on the 3 currents...

Voltage created by the resistive impedance

$$\begin{split} \text{Main component} & V = 2\sum_{\omega>0}^{\infty} I_p Z_r(p\omega_0) \cos(p\omega_0 t) \\ \\ \text{1}^{\text{st}} \text{ sideband} & V = \sum_{\omega>0}^{\infty} I_p p\omega_0 \hat{\tau} Z_r(\omega_p^+) \sin(\omega_p^+ t) \\ \\ \text{2}^{\text{nd}} \text{ sideband} & V = \sum_{\omega>0}^{\infty} I_p p\omega_0 \hat{\tau} Z_r(\omega_p^-) \sin(\omega_p^- t) \end{split}$$

$$\sin(\omega_p^- t) = \sin(p\omega_0 t)\cos(\omega_s t) - \cos(p\omega_0 t)\sin(\omega_s t)$$
$$\sin(\omega_p^+ t) = \sin(p\omega_0 t)\cos(\omega_s t) + \cos(p\omega_0 t)\sin(\omega_s t)$$

But
$$\tau = \hat{\tau} \cos(\omega_s t)$$
 \Rightarrow
$$\begin{cases} \cos(\omega_s t) = \frac{\tau}{\hat{\tau}} \\ \sin(\omega_s t) = -\frac{\dot{\tau}}{\hat{\tau}\omega_s} \end{cases}$$

(

$$\sin(\omega_p^+ t) = \sin(p\omega_0 t)\frac{\tau}{\hat{\tau}} - \cos(p\omega_0 t)\frac{\dot{\tau}}{\hat{\tau}\omega_s}$$
$$\sin(\omega_p^- t) = \sin(p\omega_0 t)\frac{\tau}{\hat{\tau}} + \cos(p\omega_0 t)\frac{\dot{\tau}}{\hat{\tau}\omega_s}$$

Voltage created by the resistive impedance

Main component

$$V = 2\sum_{\omega>0}^{\infty} I_p Z_r(p\omega_0) \cos(p\omega_0 t)$$

1st sideband
$$V = \sum_{\omega>0} I_p p \omega_0 Z_r(\omega_p^+) [\sin(p\omega_0 t)\tau - \cos(p\omega_0 t)\frac{\tau}{\omega_s}]$$

2nd sideband
$$V = \sum_{\omega>0}^{\infty} I_p p \omega_0 Z_r(\omega_p^-) [\sin(p\omega_0 t)\tau + \cos(p\omega_0 t)\frac{\dot{\tau}}{\omega_s}]$$

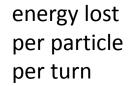
Therefore the induced Voltage depends on $~~ au, \dot{ au}$

 ∞

Energy lost in one turn

$$E_l = \int_0^{T_0} V(t)I(t)dt$$

 $U = \frac{2e}{I_0} \left[I_p^2 Z_r(p\omega_0) - \frac{I_p^2 p\omega_0}{2} (Z_r(\omega_p^+) - Z_r(\omega_p^-)) \frac{\dot{\tau}}{\omega_s} \right]$



this term can give rise to a constant loss, or a constant gain of energy

In terms of the energy of a particle

$$U = \frac{2e}{I_0} \left[I_p^2 Z_r(p\omega_0) - \frac{I_p^2 p\omega_0}{2} (Z_r(\omega_p^+) - Z_r(\omega_p^-)) \frac{\eta \epsilon}{\omega_s} \right]$$

$$\frac{\partial U}{\partial \epsilon} = -\frac{e}{I_0} \sum_{\omega > 0} \frac{I_p^2 p \omega_0}{2} (Z_r(\omega_p^+) - Z_r(\omega_p^-)) \frac{\eta}{\omega_s}$$

This is a slope in the energy, and the sign of the slope depends on

$$Z_r(\omega_p^+)-Z_r(\omega_p^-)$$
 and η

G. Franchetti

The longitudinal motion now!

$$\ddot{\tau} + 2\alpha_s \dot{\tau} + \omega_{s0}^2 \tau = 0$$

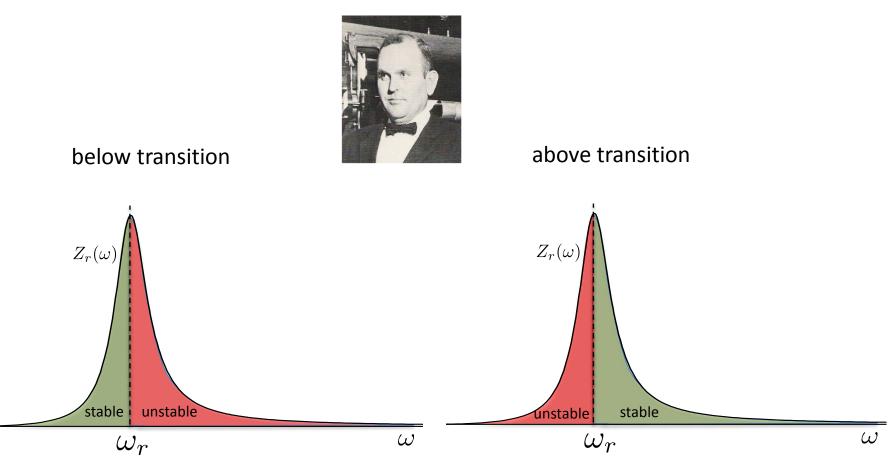
$$\alpha_S = \frac{1}{2} \frac{\omega_0}{2\pi} \frac{\partial U}{\partial E} = \frac{\omega_0}{4\pi E} \frac{\partial U}{\partial \epsilon} = \frac{\omega_s \sum p I_p^2 (Z_r(\omega_p^+) - Z_r(\omega_p^-))}{2I_0 h \hat{V} \cos \phi_s}$$

Robinson Instability

If $\alpha_S > 0$ there is a damping If $\alpha_s < 0$ there is an instability

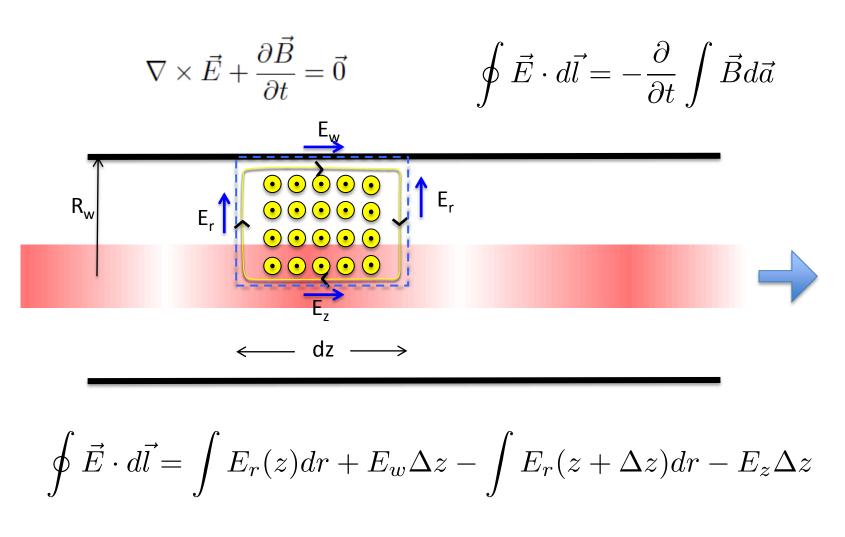


Robinson Instability



Longitudinal space charge and resistive wall impedance

Space charge longitudinal field



For a KV beam Electric Field $E_r = \begin{cases} \frac{\lambda(z)}{2\epsilon_0}r & \text{if } r < r_0\\ \frac{\lambda(z)r_0^2}{2\epsilon_0}\frac{1}{r} & \text{if } r > r_0 \end{cases}$

$$\int_0^{r_w} E_r(z)dr = \int_0^{r_0} \frac{\lambda(z)}{2\epsilon_0} r dr + \int_{r_0}^{r_w} \frac{\lambda(z)r_0^2}{2\epsilon_0} \frac{1}{r} dr$$
$$\int_0^{r_w} E_r(z)dr = \frac{\lambda(z)r_0^2}{4\epsilon_0} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right)\right]$$

Therefore

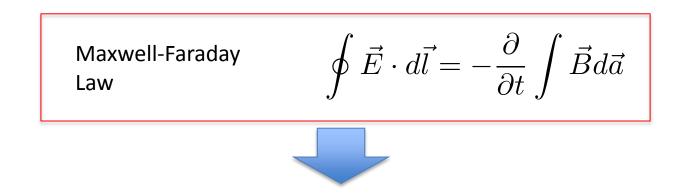
$$\int E_r(z)dr - \int E_r(z + \Delta z)dr = -\frac{r_0^2}{4\epsilon_0} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda(z)}{\partial z} \Delta z$$

$$\oint \vec{E} \cdot d\vec{l} = (E_w - E_z)\Delta z - \frac{r_0^2}{4\epsilon_0} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda(z)}{\partial z} \Delta z$$

Magnetic Field
$$B_{\perp} = \begin{cases} \frac{\mu_0 v_z \lambda(z)}{2} r & \text{if } r < r_0 \\ \frac{\mu_0 v_z \lambda(z) r_0^2}{2} \frac{1}{r} & \text{if } r > r_0 \end{cases}$$

$$\int B_{\perp} da = \int_0^{r_0} dr \int_z^{z+\Delta z} \frac{\mu_0 v_z \lambda(z)}{2} r + \int_{r_0}^{r_w} dr \int_z^{z+\Delta z} \frac{\mu_0 v_z \lambda(z) r_0^2}{2} \frac{1}{r}$$

$$\int B_{\perp} da = \frac{\mu_0 v_z r_0^2 \lambda \Delta z}{4} \left[1 + 2 \ln \left(\frac{r_w}{r_0} \right) \right]$$



$$(E_w - E_z)\Delta z - \frac{r_0^2}{4\epsilon_0} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda(z)}{\partial z} \Delta z = +\frac{\mu_0 v_z r_0^2 \Delta z}{4} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda}{\partial t} \frac{\partial\lambda(z)}{\partial t} \Delta z = +\frac{\mu_0 v_z r_0^2 \Delta z}{4} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda}{\partial t} \frac{\partial\lambda(z)}{\partial t} \Delta z = +\frac{\mu_0 v_z r_0^2 \Delta z}{4} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda}{\partial t} \frac{\partial\lambda(z)}{\partial t} \Delta z = +\frac{\mu_0 v_z r_0^2 \Delta z}{4} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda}{\partial t} \frac{\partial\lambda(z)}{\partial t} \Delta z = +\frac{\mu_0 v_z r_0^2 \Delta z}{4} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda}{\partial t} \frac{\partial\lambda(z)}{\partial t} \Delta z = +\frac{\mu_0 v_z r_0^2 \Delta z}{4} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] \frac{\partial\lambda}{\partial t} \frac{\partial\lambda}{$$

from the equation of continuity

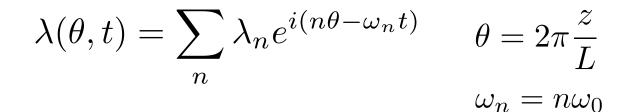
 $\frac{\partial \lambda}{\partial t} + v_z \frac{\partial \lambda}{\partial z} = 0$

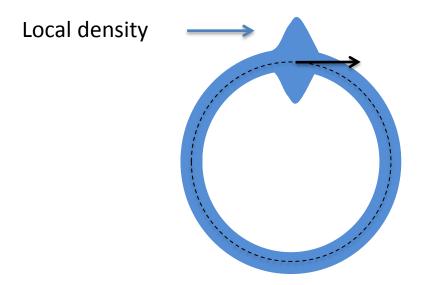
$$E_{z} = E_{w} - \frac{r_{0}^{2}}{4\epsilon_{0}} \left[1 + 2\ln\left(\frac{r_{w}}{r_{0}}\right) \right] \frac{1}{\gamma^{2}} \frac{\partial\lambda}{\partial z}$$

$$\uparrow$$
again we find the factor $1/\gamma^{2}$

ļ

Space charge impedance





$$V_{z0} = 2\pi R E_{zw} - i \sum_{n} \frac{I_n}{4\pi\epsilon_0} \frac{2\pi n}{\beta c \gamma^2} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] e^{i(n\theta - \omega_n t)}$$

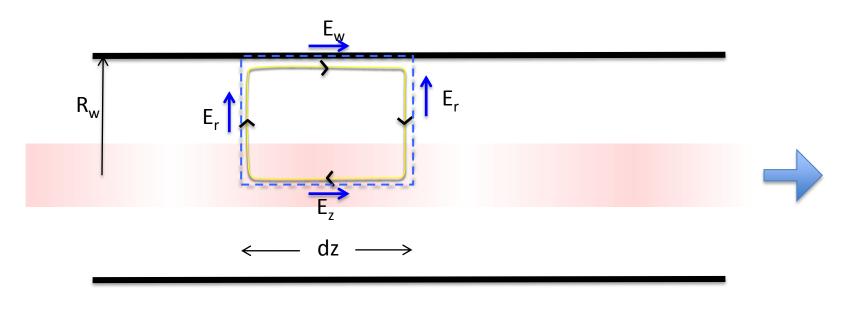
Perfect vacuum chamber $E_{zw} = 0$

Г

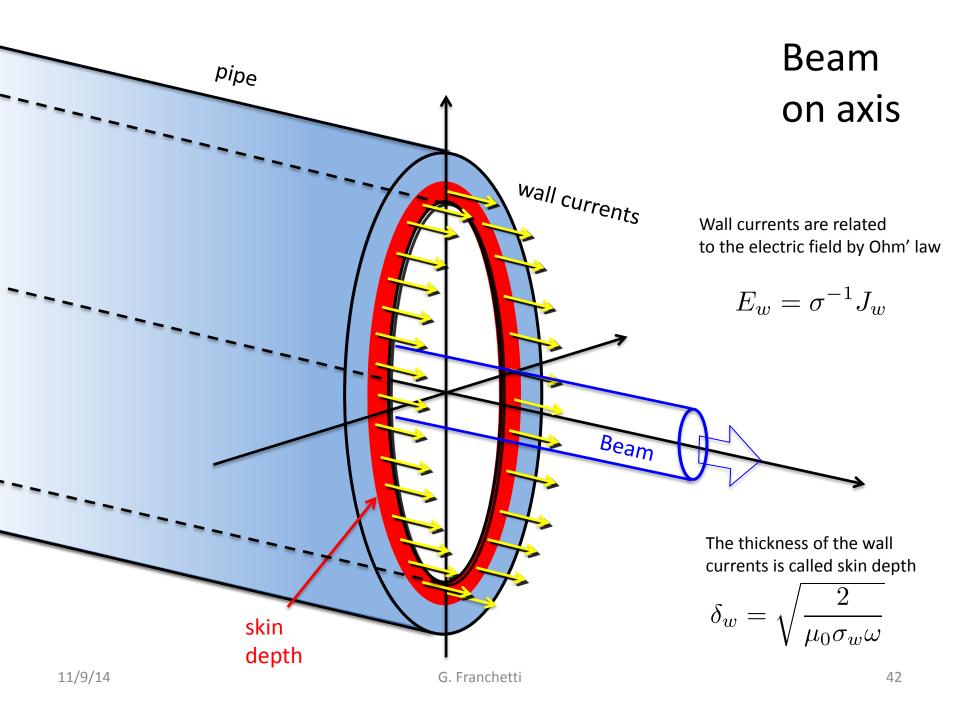
$$I = I_n e^{i(n\theta - \omega_n t)} \qquad \checkmark \qquad V = -i \frac{I_n}{4\pi\epsilon_0} \frac{2\pi n}{\beta c \gamma^2} \left[1 + 2\ln\left(\frac{r_w}{r_0}\right) \right] e^{i(n\theta - \omega_n t)}$$

Resistive Wall impedance

Do not take into account B



 $E_w = E_z$



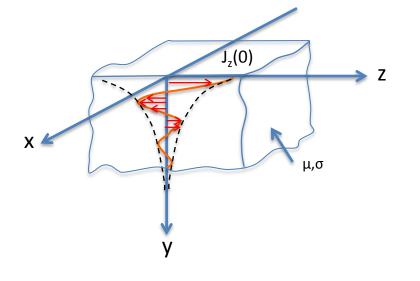
Impedance of the surface (pipe)

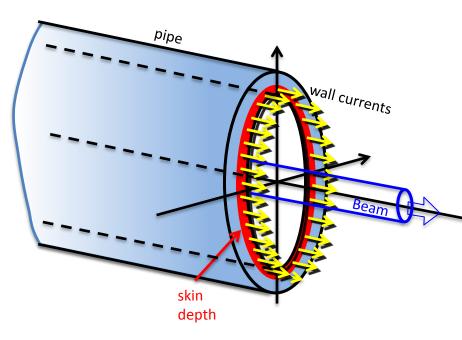
$$Z_{surf} = \frac{1+i}{\sigma\delta_w}$$



Longitudinal impedance (beam)

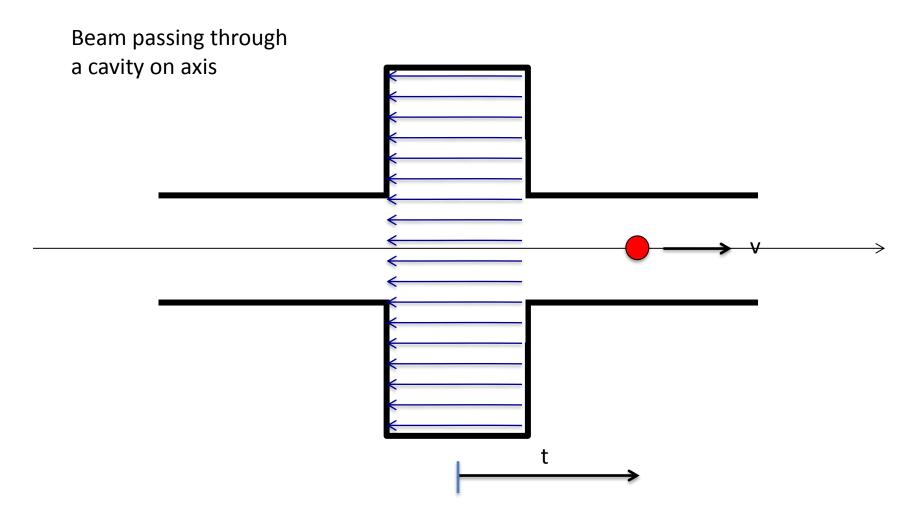
$$Z_{||} = \frac{2\pi R}{2\pi r_p} \frac{1+i}{\sigma \delta_w}$$



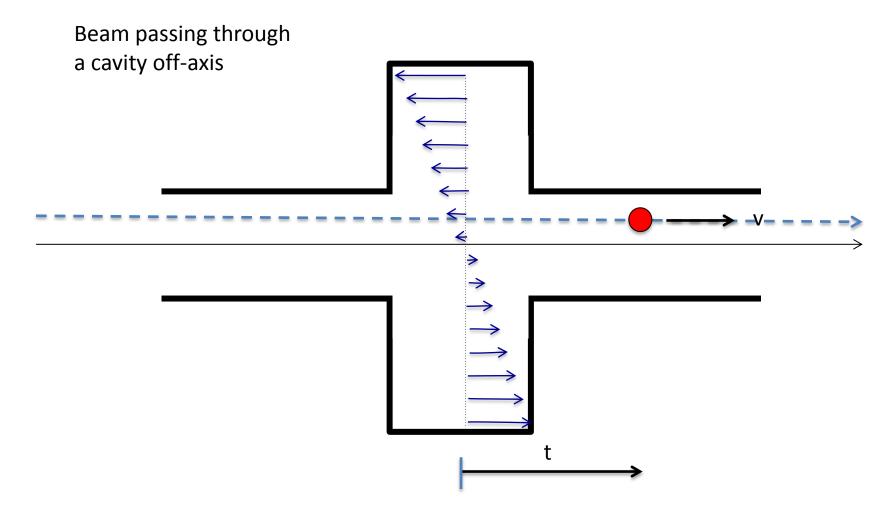


Transverse impedance

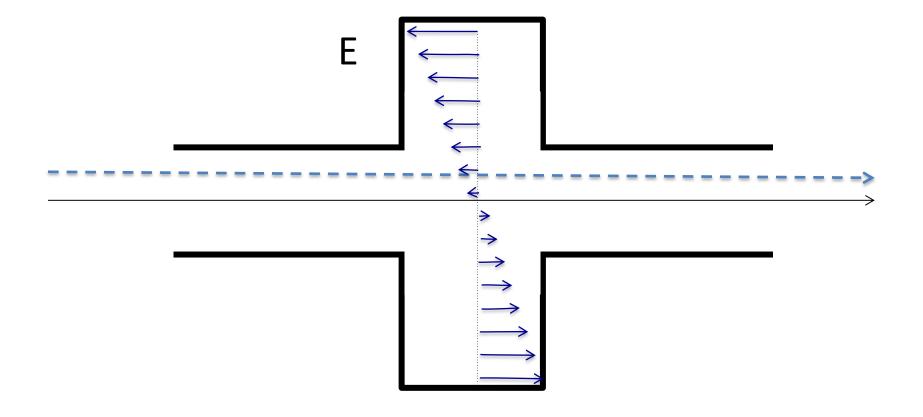
Origin

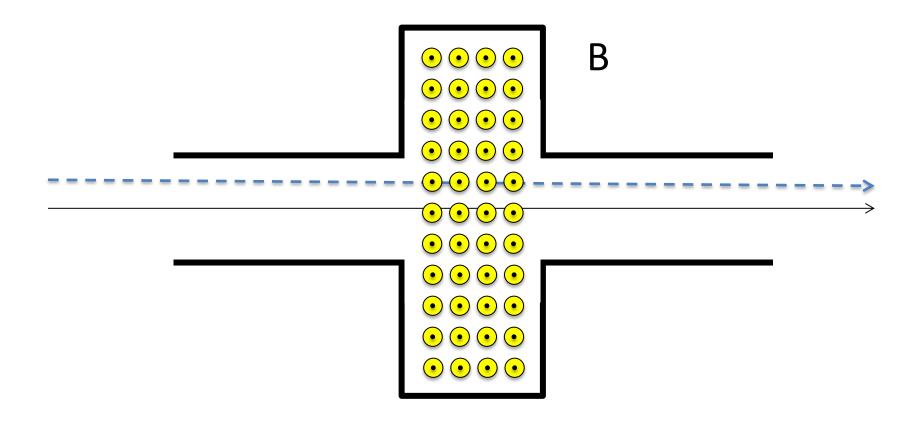


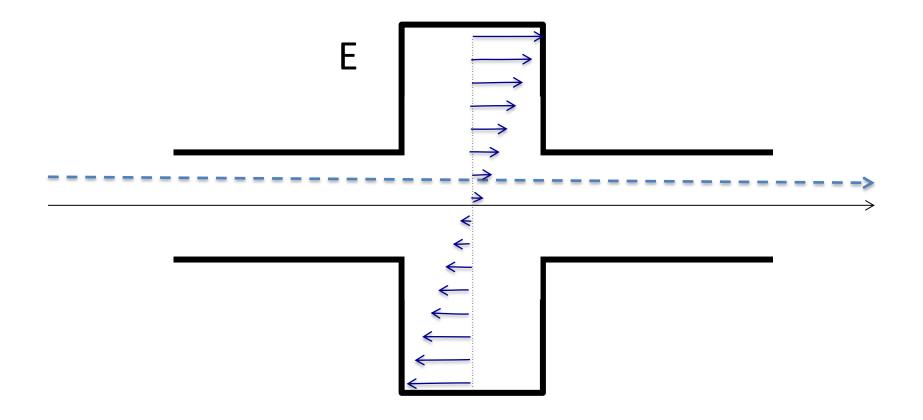
Origin

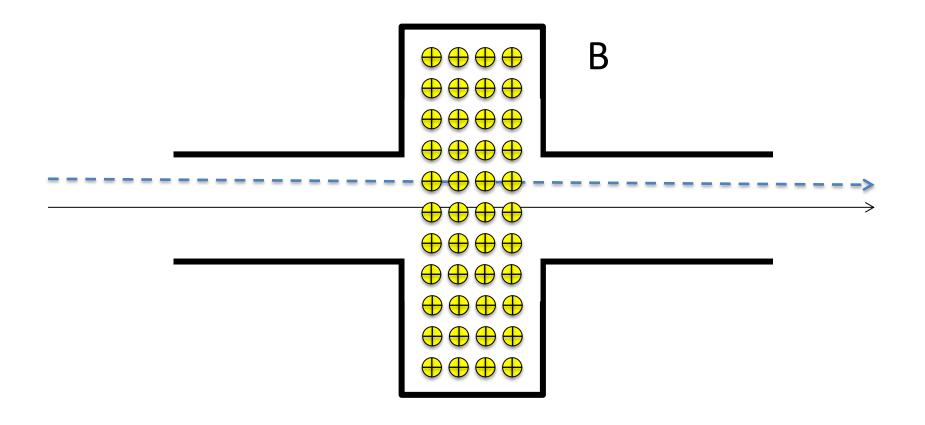


But the field transform it-self !









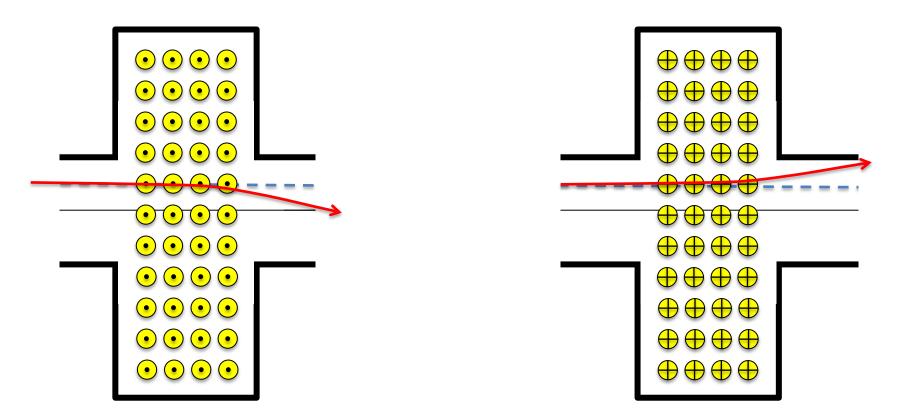
Effect on the dynamics

The dynamics is much more affected by B, than E because

$$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$$

this speed is high

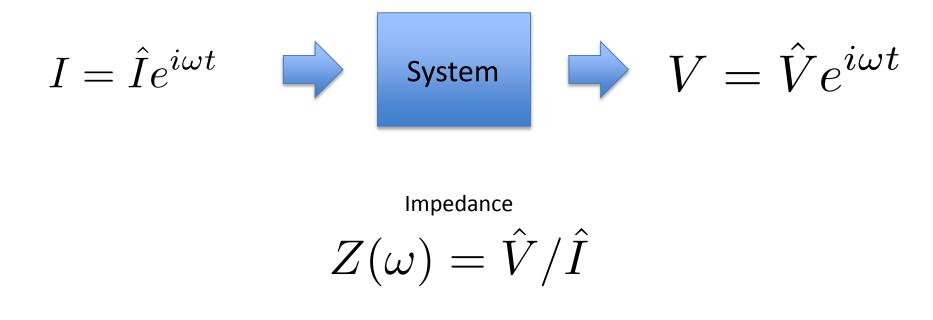
The beam creates its own dipolar magnetic field !



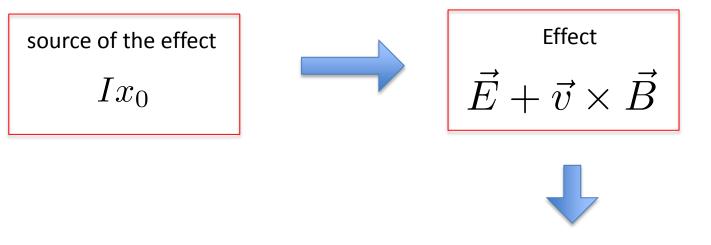
(dipolar errors create integer resonances.... we expect the same...)

Transverse impedance

Definition of longitudinal impedance (classical)



For a displaced beam



this field acts on a single particle

It means that in the equation of motion we have to add this effect

$$\frac{d^2x}{ds^2} + k_x x = \frac{q}{m\gamma v_0^2} [E_x + (\vec{v} \times \vec{E})_x]$$

therefore for a weak effect or distributed we find

$$\frac{d^2x}{ds^2} + \left(\frac{Q_x}{R}\right)^2 x = \frac{q}{m\gamma v_0^2} \frac{1}{2\pi R} \int_0^{2\pi R} [E_x + (\vec{v} \times \vec{E})_x] ds$$

In the time domain

$$\frac{d^2x}{dt^2} + (Q_x\omega_0)^2 x = \frac{q}{m\gamma} \frac{1}{2\pi R} \int_0^{2\pi R} [E_x + (\vec{v} \times \vec{E})_x] ds$$

But
$$\int_{0}^{2\pi R} [E_x + (\vec{v} \times \vec{E})_x] ds$$
 is like a "strange" voltage

$$V = -\int_0^{2\pi R} [\vec{E} + \vec{v} \times \vec{B}]_\perp ds$$

Now the situation is the following:

$$Ix_0$$

 System $V = -\int_0^{2\pi R} [\vec{E} + \vec{v} \times \vec{B}]_{\perp} ds$

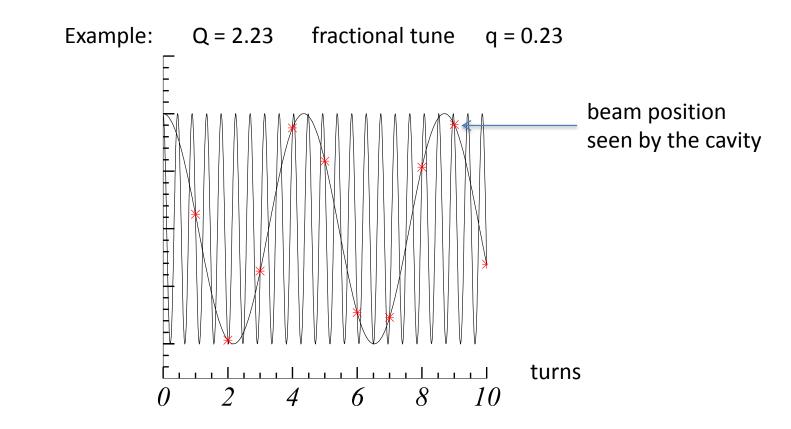
Transverse beam coupling impedance

$$Z_{\perp}(\omega) = i \frac{\int_{0}^{2\pi R} [\vec{E} + \vec{v} \times \vec{B}]_{\perp} ds}{\beta I x_{0}}$$

now the question is what is ω ?

What is it ω ?

It is given by the fractional tune, as this is the frequency seen in a cavity



B-field induced by beam displacement

From
$$\frac{\partial E_z}{\partial x} = kIx_0$$
 $E_z = kIx_0x$

electric field at the position of beam x_0 is

$$E_z(x_0) = kIx_0^2$$

Longitudinal impedance

$$Z_{||} = -\frac{E_z(x_0)l}{I} = -kx_0^2l$$

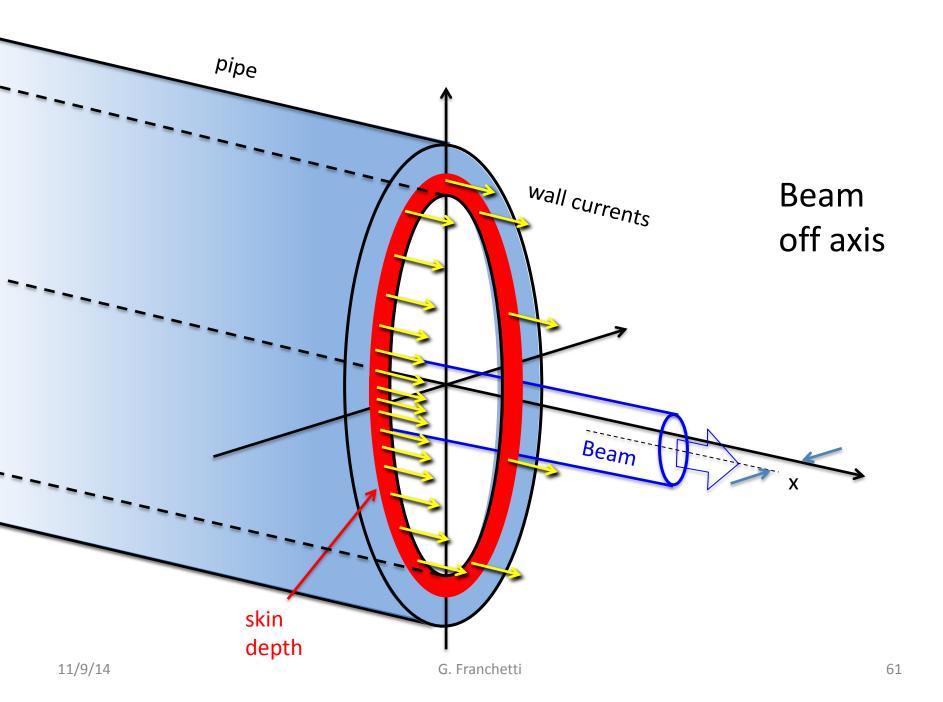
The magnetic field comes from Maxwell

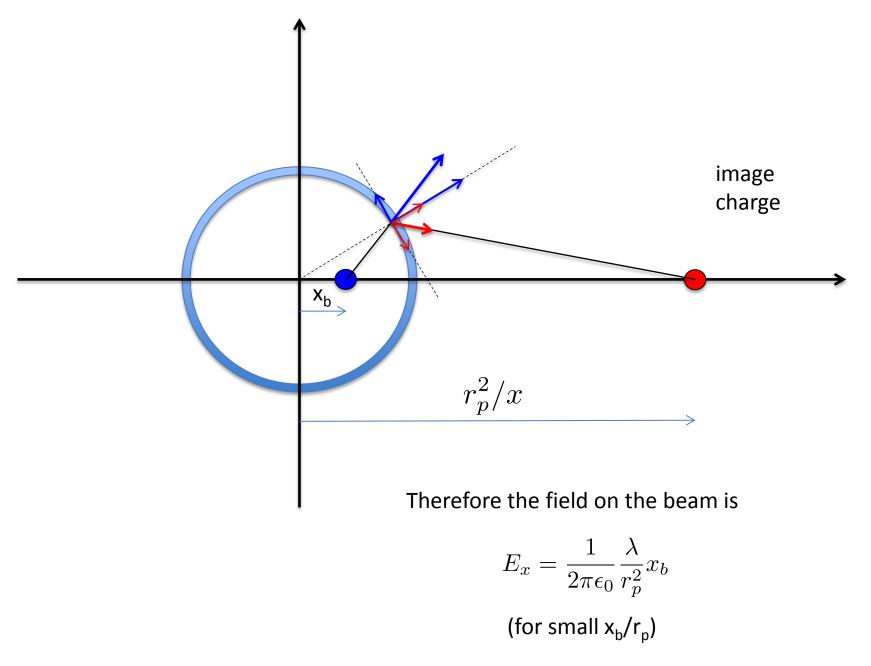
$$\nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = \vec{0}$$

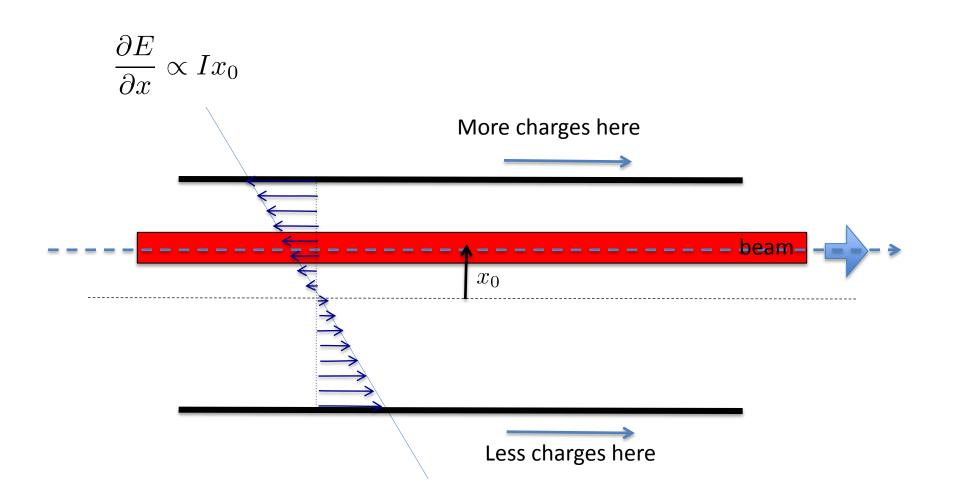
 $\frac{\partial B_y}{\partial t}|_{x_0} = kIx_0 \qquad \qquad \text{taking} \qquad Ix_0 = I\hat{x}e^{i\omega t}$

$$B_y = \frac{kI\hat{x}}{i\omega}e^{i\omega t} = \frac{kIx_0}{i\omega}$$

Transverse impedance







Transverse resistive Wall impedance

$$Z(\omega_n)_{\perp} = \frac{2R}{r_p^2} \frac{Z_{||}(\omega_n)}{n}|_{res}$$

Transverse instability

Coasting beam instability

Force due to the impedance (in the complex notation)

 $F_{\perp} = i \frac{q Z_{\perp} I_0}{2\pi R} x_b$



Equation of motion of one particle for a beam on axis

 $\ddot{x} + Q^2 \omega_0^2 x = 0$

Equation of motion of a beam particle when the beam is off-axis

$$\ddot{x} + Q^2 \omega_0^2 x = -i \frac{q Z_\perp I_0}{2\pi R m \gamma} x_b$$

Collective motion

On the other hand the beam center is

$$x_b = \int x n(x, y, s) dx dy$$
$$\int \tilde{n} dV = 1$$

therefore

$$\int \ddot{x}\tilde{n}dV + \int Q^2\omega_0^2x\tilde{n}dV = -i\frac{qZ_\perp I_0}{2\pi Rm\gamma}x_b$$

If all particles have the same frequency, i.e. each particle experience a force

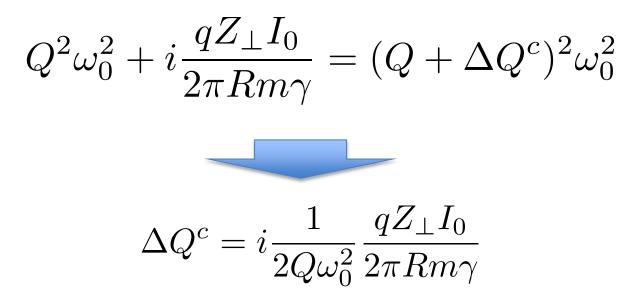
with

 $Q^2 \omega^2 x$

then
$$\ddot{x}_b + Q^2 \omega_0^2 x_b = -i \frac{q Z_\perp I_0}{2\pi R m \gamma} x_b$$

$$\ddot{x}_b + Q^2 \omega_0^2 x_b = -i \frac{q Z_\perp I_0}{2\pi R m \gamma} x_b$$

We can define a coherent "detuning" because this is a linear equation



$$\ddot{x}_b + Q^2 \omega_0^2 x_b = -2Q\omega^2 \Delta Q^c x_b$$

that is

$$\ddot{x}_b + (Q^2\omega_0^2 + 2Q\omega_0^2\Delta Q^c)x_b = 0$$

But now ΔQ^c is a complex number !!

Solution $x_b = A \exp[-\omega_0 I_m(\Delta Q^c)t + i\omega_0 [Q + Re(\Delta Q^c)]t]$

$$\tau_I^{-1} = \omega_0 Im(\Delta Q^c)$$

Is the growth rate of the transverse resistive wall instability

$$\frac{1}{\tau} = \frac{qRe\{Z_{\perp}\}I_0}{4\pi Rm\gamma Q\omega_0}$$

This instability always take place

Instability suppression
 → Landau damping

An important assumption

We assumed that all particles have the same frequency so that

$$\int Q^2 \omega_0^2 x \tilde{n} dV = Q^2 \omega_0^2 \int x \tilde{n} dV = Q^2 \omega_0^2 x_b$$

This assumption means that each particle of the beam respond in the same way to a change of particle amplitude

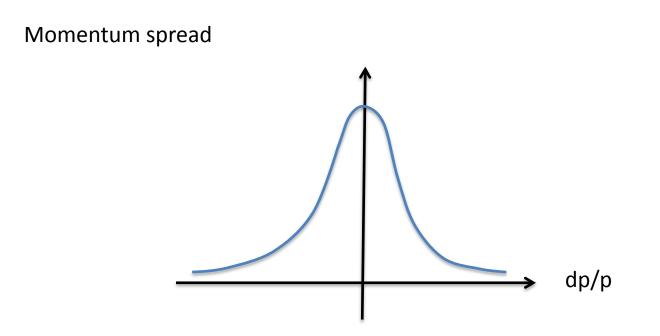
Coherent motion



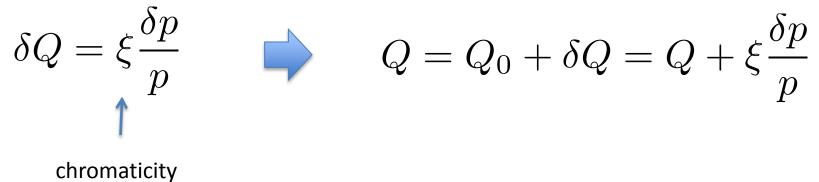
drive particle motion, which is again coherent

Chromaticity ?

What happened if the incoherent force created by the accelerator do not allow a coherent build up



one particle with off-momentum dp/p has tune



If each particle of the beam has different dp/p then the force that the lattice exert on a particle depends on the particle !

$$F_x = \left(Q_0 + \xi \frac{\delta p}{p}\right)^2 \omega^2 x$$

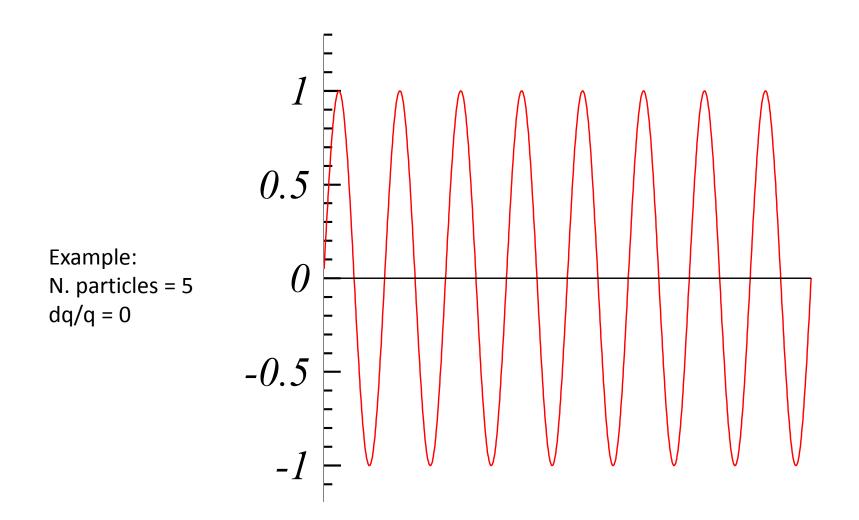
Incoherent motion damps x_b

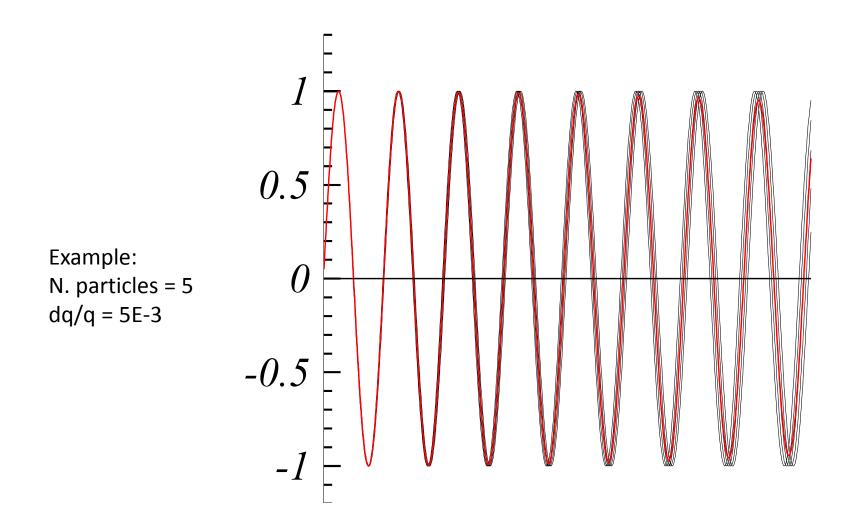
Equation of motion without impedances

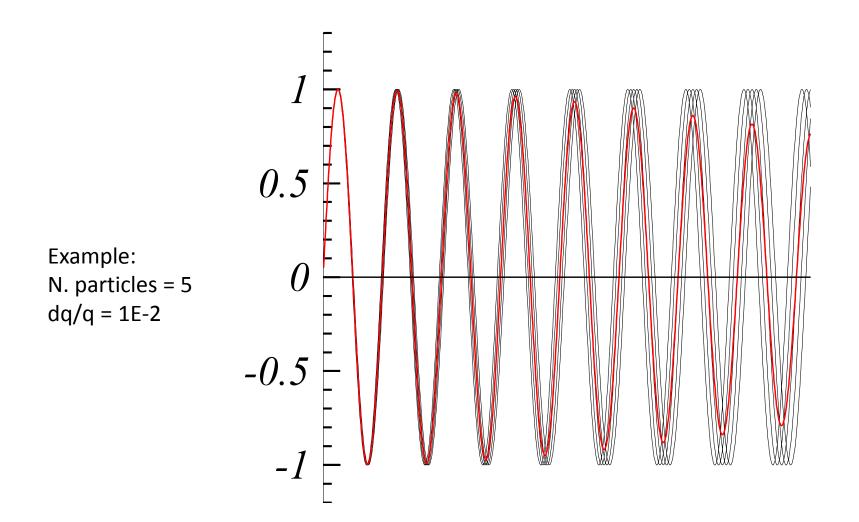
$$\ddot{x} + \left(Q_0 + \xi \frac{\delta p}{p}\right)^2 \omega^2 x = 0$$

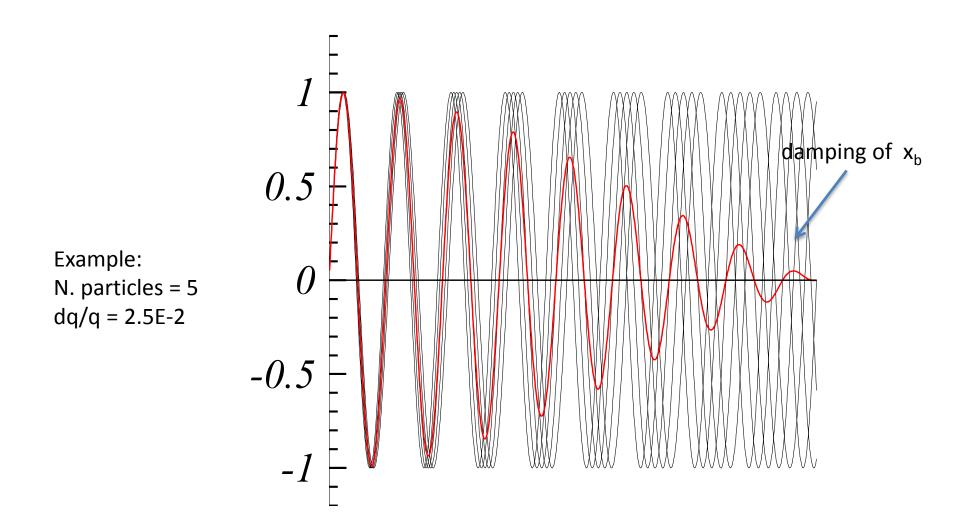
Motion of center of mass as an effect of the spread of the frequencies of oscillation

The momentum compaction also provides a spread of the betatron oscillations



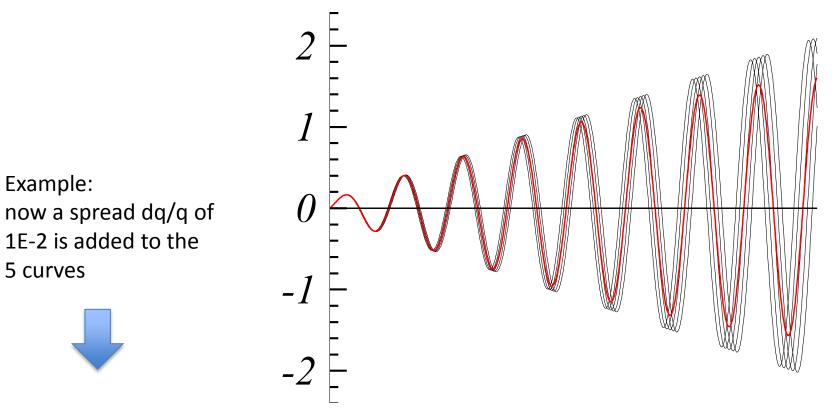




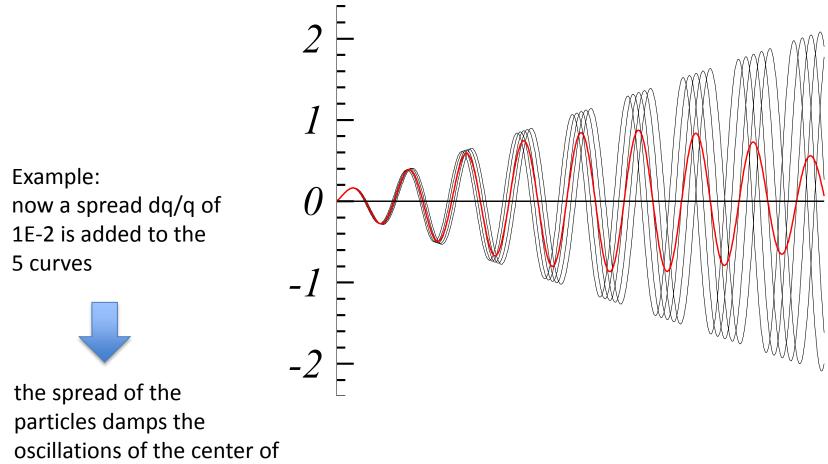


But incoherent motion reduces x_b

Example: these are 5 sinusoid with amplitude linearly growth -1 -2

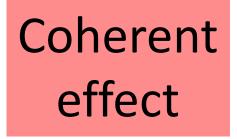


The center of mass growth slower



mass \rightarrow the instability cannot develop

Situation



Growth rate



Incoherent effect

Damping rate

 au_I

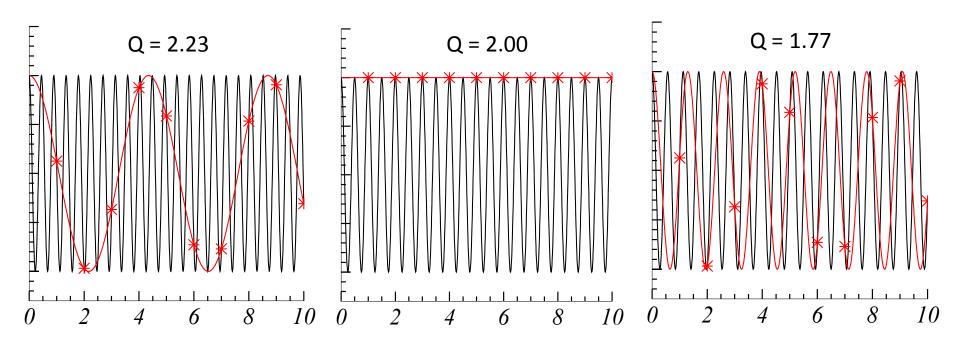
The faster wins

 au_D

instability of a single bunch

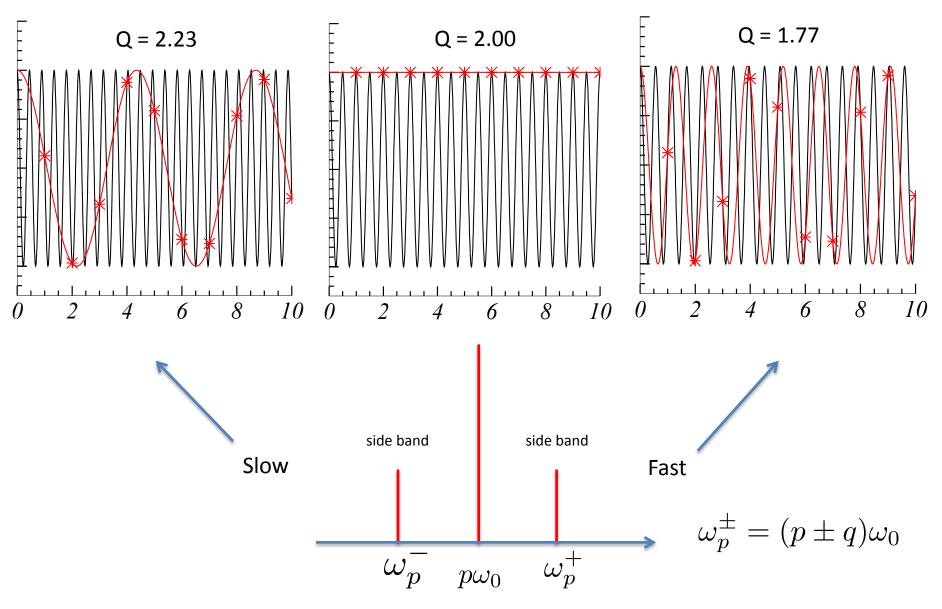
Example

beam position at the cavity



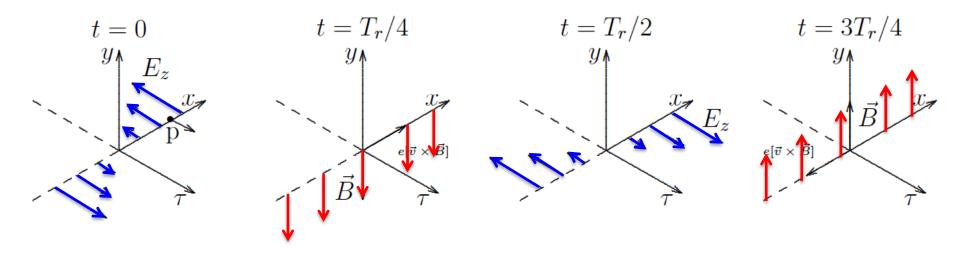
No oscillations \rightarrow

 $\omega = 0$

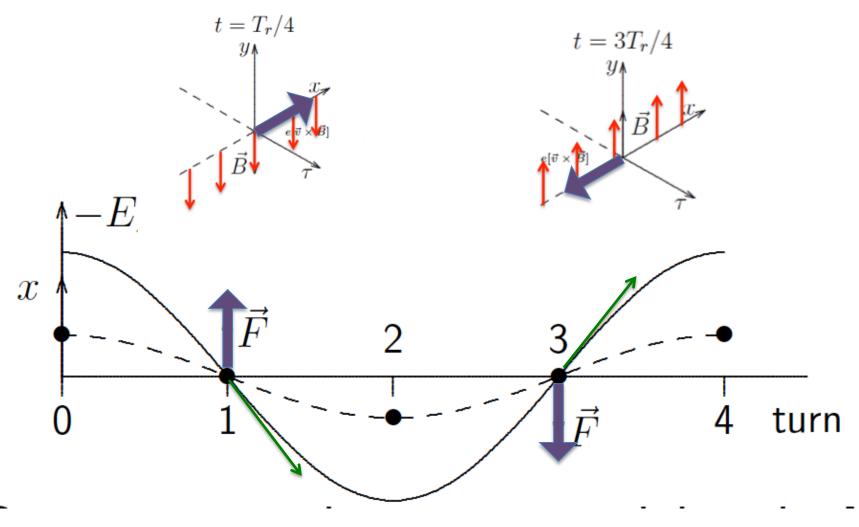


behavior of the field in the cavity

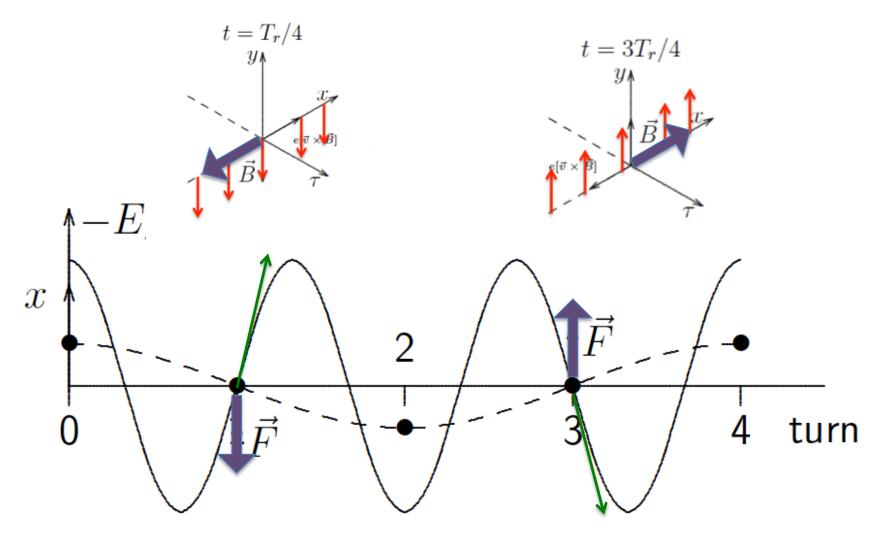
 T_r = time of oscillation of the field in the cavity



Cavity tuned upper sideband

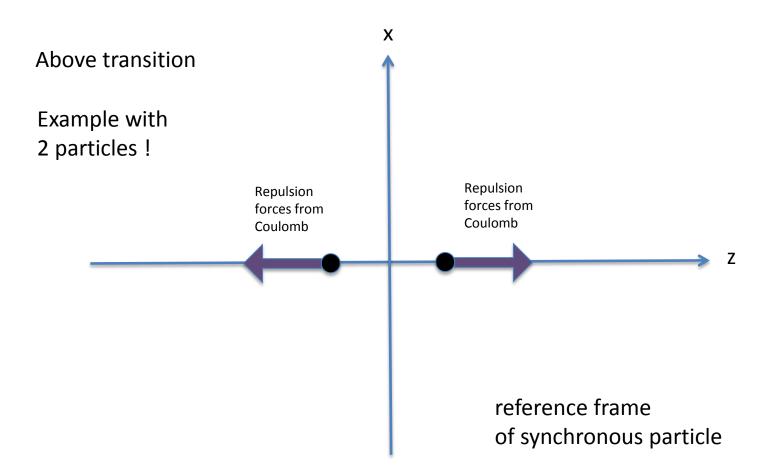


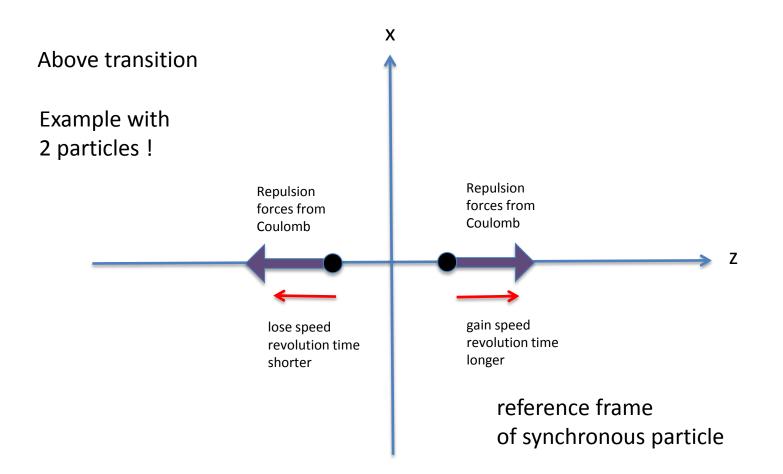
Cavity tuned upper sideband

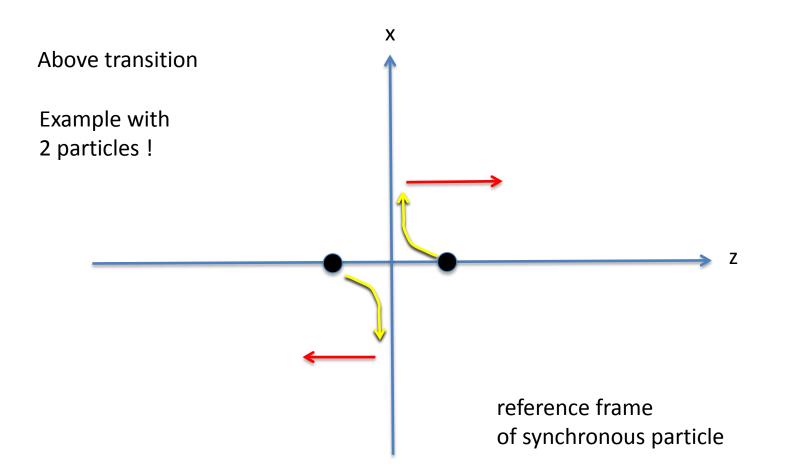


As for the Robinson Instability

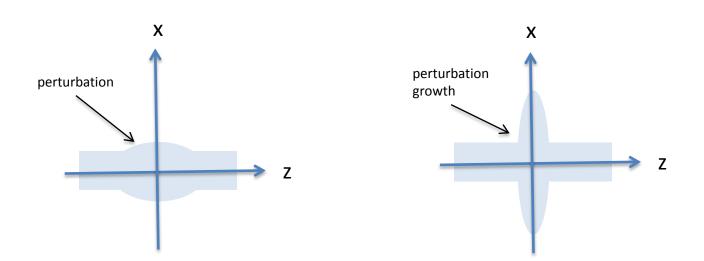
 $\alpha_s = \frac{1}{\tau} \propto \sum_p I_p^2 [Z_\perp(\omega_p^+) - Z_\perp(\omega_p^-)]$ \mathcal{D}







Above transition



repulsive forces attract particles as if their mass were negative

Summary

Robinson instability Longitudinal space charge and resistive wall impedance Transverse impedance Transverse instability Landau damping Single bunch instability Negative mass instability