



# Electromagnetism

Christopher R Prior

Fellow and Tutor in Mathematics  
Trinity College, Oxford

ASTeC Intense Beams Group  
Rutherford Appleton Laboratory

# Contents

---

- Review of Maxwell's equations and Lorentz Force Law
- Motion of a charged particle under constant Electromagnetic fields
- Relativistic transformations of fields
- Electromagnetic waves
  - Waves in vacuo
  - Waves in conducting medium
- Waves in a uniform conducting guide
  - Simple example  $TE_{01}$  mode
  - Propagation constant, cut-off frequency
  - Group velocity, phase velocity
  - Illustrations



# Reading

---

- J.D. Jackson: *Classical Electrodynamics* (Wiley, 1998)
- H.D. Young, R.A. Freedman & L. Ford: *University Physics (with Modern Physics)* (Addison-Wesley, 2007)
- P.C. Clemmow: *Electromagnetic Theory* (CUP, 1973)
- *Feynmann Lectures on Physics* (Basic Books, 2011)
- W.K.H. Panofsky & M.N. Phillips: *Classical Electricity and Magnetism* (Addison-Wesley, 2005)
- G.L. Pollack & D.R. Stump: *Electromagnetism* (Addison-Wesley, 2001)



# Vector Calculus

For a scalar function  $\varphi(x, y, z, t)$ ,

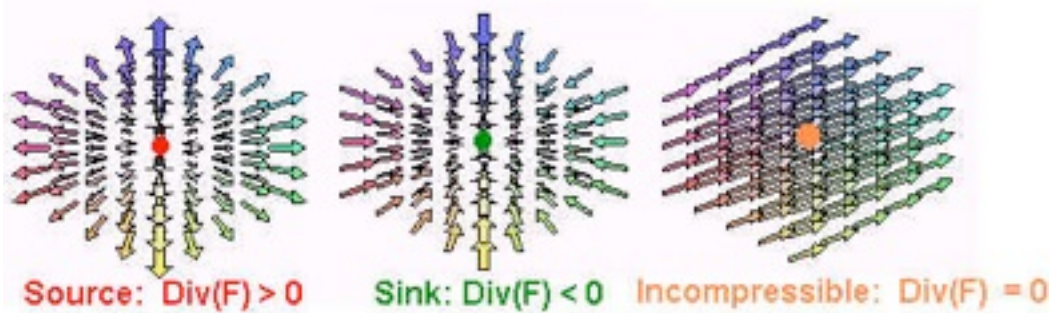
gradient: 
$$\nabla\varphi = \left( \frac{\partial\varphi}{\partial x}, \frac{\partial\varphi}{\partial y}, \frac{\partial\varphi}{\partial z} \right)$$

Gradient is normal to surface  $\varphi = \text{constant}$ .

For a vector  $\vec{F} = (F_1, F_2, F_3)$ :

divergence: 
$$\nabla \cdot \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

curl: 
$$\nabla \wedge \vec{F} = \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z}, \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x}, \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)$$



# Basic Vector Calculus

$$\nabla \cdot \vec{F} \wedge \vec{G} = \vec{G} \cdot \nabla \wedge \vec{F} - \vec{F} \cdot \nabla \wedge \vec{G}$$

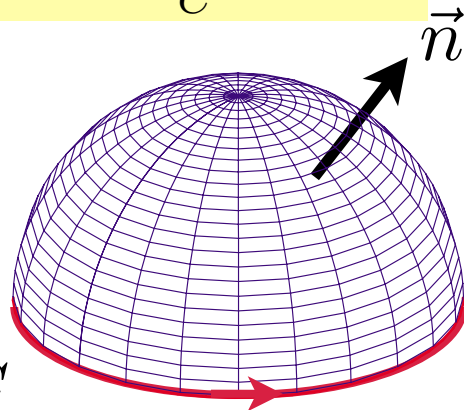
$$\nabla \wedge \nabla \phi = 0, \quad \nabla \cdot \nabla \wedge \vec{F} = 0$$

$$\nabla \wedge (\nabla \wedge \vec{F}) = \nabla(\nabla \cdot \vec{F}) - \nabla^2 \vec{F}$$

## Stokes' Theorem

$$\iint_S \nabla \wedge \vec{F} \cdot d\vec{S} = \oint_C \vec{F} \cdot d\vec{r}$$

$$d\vec{S} = \vec{n} dS$$



Oriented  
boundary  $C$

## Divergence or Gauss' Theorem

$$\iiint_V \nabla \cdot \vec{F} dV = \iint_S \vec{F} \cdot d\vec{S}$$

Closed surface  $S$ , volume  $V$ ,  
outward pointing normal

# What is Electromagnetism?

---

- The study of **Maxwell's equations**, devised in 1863 to represent the relationships between electric and magnetic fields in the presence of electric charges and currents, whether steady or rapidly fluctuating, in a vacuum or in matter.
- The equations represent one of the most elegant and concise way to describe the fundamentals of electricity and magnetism. They pull together in a consistent way earlier results known from the work of Gauss, Faraday, Ampère, Biot, Savart and others.
- Remarkably, Maxwell's equations are perfectly consistent with the transformations of special relativity.



# Maxwell's Equations



Relate Electric and Magnetic fields generated by charge and current distributions.

$\vec{E}$  = electric field

$\vec{D}$  = electric displacement

$\vec{H}$  = magnetic field

$\vec{B}$  = magnetic flux density

$\rho$  = electric charge density

$\vec{j}$  = current density

$\mu_0$  = permeability of free space,  $4\pi \cdot 10^{-7}$

$\epsilon_0$  = permittivity of free space,  $8.854 \cdot 10^{-12}$

$c$  = speed of light,  $2.99792458 \cdot 10^8$

$$\nabla \cdot \vec{D} = \rho$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \wedge \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \wedge \vec{H} = \vec{j} + \frac{\partial \vec{D}}{\partial t}$$

In vacuum:

$$\vec{D} = \epsilon_0 \vec{E}, \quad \vec{B} = \mu_0 \vec{H}, \quad \epsilon_0 \mu_0 c^2 = 1$$

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

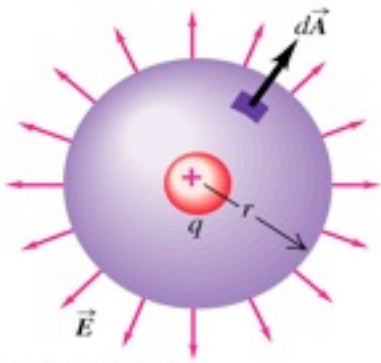
# Maxwell's 1<sup>st</sup> Equation

Equivalent to Gauss' Flux Theorem:

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} \iff \iiint_V \nabla \cdot \vec{E} \, dV = \iint_S \vec{E} \cdot d\vec{S} = \frac{1}{\epsilon_0} \iiint_V \rho \, dV = \frac{Q}{\epsilon_0}$$

The flux of electric field out of a closed region is proportional to the total electric charge  $Q$  enclosed within the surface.

A point charge  $q$  generates an electric field:



$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{r^3}$$

$$\iint_{\text{sphere}} \vec{E} \cdot d\vec{S} = \frac{q}{4\pi\epsilon_0} \iint_{\text{sphere}} \frac{dS}{r^2} = \frac{q}{\epsilon_0}$$



Area integral gives a measure of the net charge enclosed; divergence of the electric field gives the density of the sources.



$$\nabla \cdot \vec{B} = 0$$

# Maxwell's 2<sup>nd</sup> Equation

Gauss' law for magnetism:

$$\nabla \cdot \vec{B} = 0 \iff \iint \vec{B} \cdot d\vec{S} = 0$$

The net magnetic flux out of any closed surface is zero. Surround a magnetic dipole with a closed surface. The magnetic flux directed inward towards the south pole will equal the flux outward from the north pole.

If there were a magnetic monopole source, this would give a non-zero integral.

Gauss' law for magnetism is then a statement that

***There are no magnetic monopoles***



Science & Technology  
Facilities Council

$$\nabla \wedge \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

# Maxwell's 3<sup>rd</sup> Equation

Equivalent to Faraday's Law of Induction:

$$\iint_S \nabla \wedge \vec{E} \cdot d\vec{S} = - \iint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S}$$
$$\iff \oint_C \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \iint_S \vec{B} \cdot d\vec{S} = -\frac{d\Phi}{dt}$$

(for a fixed circuit C)

The electromotive force round a circuit

$\varepsilon = \oint \vec{E} \cdot d\vec{l}$  is proportional to the rate of change of flux of magnetic field  $\Phi = \iint \vec{B} \cdot d\vec{S}$  through the circuit.



Michael Faraday

**Faraday's Law is the basis for electric generators. It also forms the basis for inductors and transformers.**

$$\nabla \wedge \vec{B} = \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

# Maxwell's 4<sup>th</sup> Equation

Originates from Ampère's (Circuital) Law :  $\nabla \wedge \vec{B} = \mu_0 \vec{j}$



Ampère

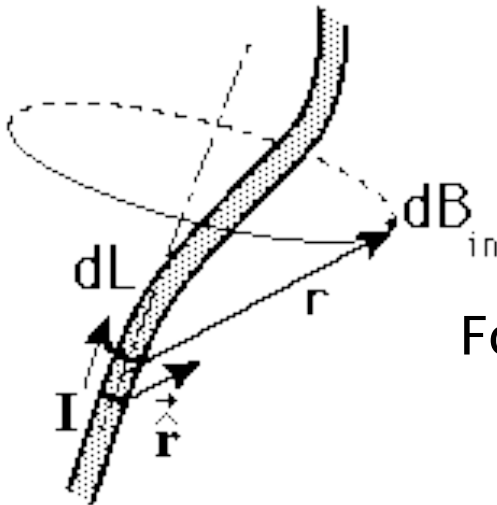
$$\oint_C \vec{B} \cdot d\vec{l} = \iint_S \nabla \wedge \vec{B} \cdot d\vec{S} = \mu_0 \iint_S \vec{j} \cdot d\vec{S} = \mu_0 I$$

Satisfied by the field for a steady line current  
(Biot-Savart Law, 1820):

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint \frac{d\vec{l} \wedge \vec{r}}{r^3}$$



Biot

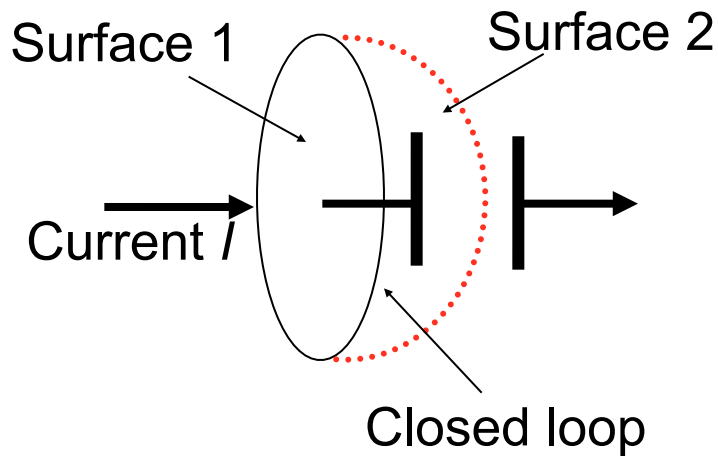


For a straight line current  $\vec{B} = \frac{\mu_0 I}{2\pi r}$



# Displacement Current

- **Faraday**: vary B-field, generate E-field
- **Maxwell**: varying E-field should then produce a B-field, but not covered by Ampère's Law.



- Apply Ampère to surface 1 (a flat disk): the line integral of  $B = \mu_0 I$ .
- Applied to surface 2, line integral is zero since no current penetrates the deformed surface.
- In a capacitor,

$$E = \frac{Q}{\epsilon_0 A} \text{ and } I = \frac{dQ}{dt} = \epsilon_0 A \frac{dE}{dt},$$

so there is a current density  $\vec{j}_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$ .

$$\nabla \wedge \vec{B} = \mu_0 (\vec{j} + \vec{j}_d) = \mu_0 \vec{j} + \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}$$

# Consistency with Charge Conservation

Charge conservation:

Total current flowing out of a region equals the rate of decrease of charge within the volume.

$$\iint \vec{j} \cdot d\vec{S} = -\frac{d}{dt} \iiint \rho dV$$

$$\iff \iiint \nabla \cdot \vec{j} dV = -\iiint \frac{\partial \rho}{\partial t} dV$$

$$\iff \nabla \cdot \vec{j} + \frac{\partial \rho}{\partial t} = 0$$

From Maxwell's equations:

Take divergence of (modified) Ampère's equation

$$\nabla \wedge \vec{B} = \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

$$\implies \nabla \cdot \nabla \wedge \vec{B} = \mu_0 \nabla \cdot \vec{j} + \frac{1}{c^2} \frac{\partial}{\partial t} (\nabla \cdot \vec{E})$$

$$\implies 0 = \nabla \cdot \vec{j} + \epsilon_0 \mu_0 \frac{\partial}{\partial t} \left( \frac{\rho}{\epsilon_0} \right)$$

$$\implies 0 = \nabla \cdot \vec{j} + \frac{\partial \rho}{\partial t}$$

*Charge conservation is implicit in Maxwell's Equations*



# Maxwell's Equations in Vacuum

In vacuum:

$$\vec{D} = \epsilon_0 \vec{E}, \quad \vec{B} = \mu_0 \vec{H}, \quad \epsilon_0 \mu_0 c^2 = 1$$

Source-free equations:

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \wedge \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

Source equations:

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \wedge \vec{B} - \frac{1}{c^2} \frac{\partial \vec{B}}{\partial t} = \mu_0 \vec{j}$$

Equivalent integral form (useful for simple geometries):

$$\iint \vec{E} \cdot d\vec{S} = \frac{1}{\epsilon_0} \iiint \rho dV$$

$$\iint \vec{B} \cdot d\vec{S} = 0$$

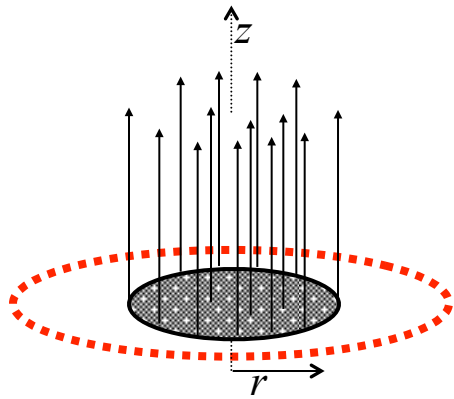
$$\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \iint \vec{B} \cdot d\vec{S} = -\frac{d\Phi}{dt}$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \iint \vec{j} \cdot d\vec{S} + \frac{1}{c^2} \frac{d}{dt} \iint \vec{E} \cdot d\vec{S}$$



# Example: Calculate E from B

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \iint \vec{B} \cdot d\vec{S}$$



$$B_z = \begin{cases} B_0 \sin \omega t & r < r_0 \\ 0 & r > r_0 \end{cases}$$

Also from  $\nabla \wedge \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

$$\nabla \wedge \vec{B} = \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

**$r < r_0$**

$$2\pi r E_\theta = -\frac{d}{dt} \pi r^2 B_0 \sin \omega t = -\pi r^2 B_0 \omega \cos \omega t$$

$$\implies E_\theta = -\frac{1}{2} B_0 \omega r \cos \omega t$$

**$r > r_0$**

$$2\pi r E_\theta = -\frac{d}{dt} \pi r_0^2 B_0 \sin \omega t = -\pi r_0^2 B_0 \omega \cos \omega t$$

$$\implies E_\theta = -\frac{\omega r_0^2 B_0}{2r} \cos \omega t$$

then gives current density necessary to sustain the fields



# The Betatron

Particles accelerated by the rotational electric field generated by a time-varying magnetic field

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \iint \vec{B} \cdot d\vec{S}$$

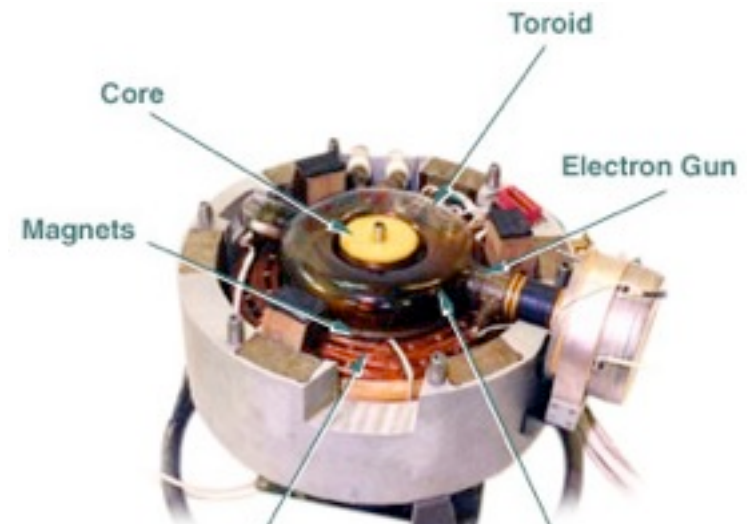
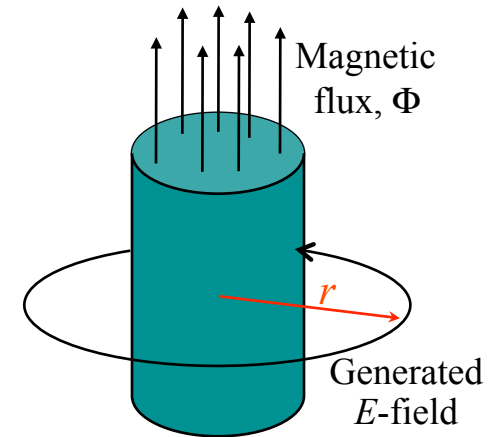
$$\implies 2\pi r E_{\theta} = -\frac{d\Phi}{dt}$$

For circular motion at a constant radius:

$$-\frac{mv^2}{r} = evB \implies B = -\frac{p}{er}$$

$$\implies \frac{\partial}{\partial t} B(r, t) = -\frac{1}{er} \frac{dp}{dt} = -\frac{E}{r} = \frac{1}{2\pi r^2} \frac{d\Phi}{dt}$$

$$\implies B(r, t) = \frac{1}{2} \frac{1}{\pi r^2} \iint B dS$$



*B*-field on orbit needs to be one half the average *B* over the circle. This imposes a limit on the energy that can be achieved. Nevertheless the constant radius principle is attractive for high energy circular accelerators.



# Lorentz Force Law

- Thought of as a supplement to Maxwell's equations but actually implicit in relativistic formulation, gives force on a charged particle moving in an electromagnetic field:

$$\vec{f} = q(\vec{E} + \vec{v} \wedge \vec{B})$$

- For continuous distributions, use force density:

$$\vec{f}_d = \rho\vec{E} + \vec{j} \wedge \vec{B}$$

- Relativistic equation of motion

- 4-vector form:  $F = \frac{dP}{d\tau} \implies \gamma \left( \frac{\vec{v} \cdot \vec{f}}{c}, \vec{f} \right) = \gamma \left( \frac{1}{c} \frac{dE}{dt}, \frac{d\vec{p}}{dt} \right)$

- 3-vector component:

Energy component:

$$\frac{d}{dt} (m_0 \gamma \vec{v}) = \vec{f} = q(\vec{E} + \vec{v} \wedge \vec{B})$$

$$\vec{v} \cdot \vec{f} = \frac{dE}{dt} = m_0 c^2 \frac{d\gamma}{dt}$$

# Motion in Constant Magnetic Fields

$$\frac{d}{dt}(m_0\gamma\vec{v}) = \vec{f} = q(\vec{E} + \vec{v} \wedge \vec{B}) = q\vec{v} \wedge \vec{B}$$

$$\frac{d}{dt}(m_0\gamma c^2) = \vec{v} \cdot \vec{f} = q\vec{v} \cdot \vec{v} \wedge \vec{B} = 0$$

- From energy equation,  $\gamma$  is constant  $\implies |\vec{v}|$  is constant

**No acceleration with a magnetic field**

- From momentum equation,

$$\vec{B} \cdot \frac{d}{dt}(\gamma\vec{v}) = 0 = \gamma \frac{d}{dt}(\vec{B} \cdot \vec{v}) \implies \vec{v}_{\parallel} \text{ is constant}$$

$|\vec{v}|$  constant and  $|\vec{v}_{\parallel}|$  constant  
 $\implies |\vec{v}_{\perp}|$  also constant



# Motion in Constant Magnetic Field

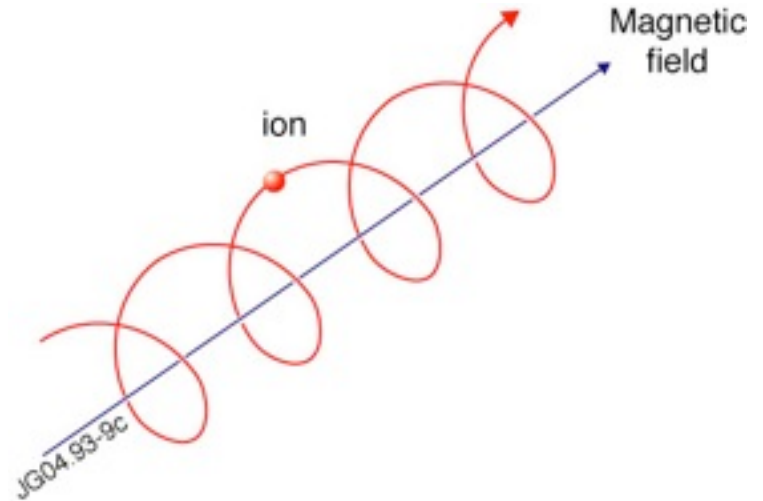
$$\frac{d}{dt}(m_0\gamma\vec{v}) = q\vec{v} \wedge \vec{B}$$

$$\implies \frac{d\vec{v}}{dt} = \frac{q}{m_0\gamma} \vec{v} \wedge \vec{B}$$

$$\implies \frac{v_{\perp}^2}{\rho} = \frac{q}{m_0\gamma} v_{\perp} B$$

$\implies$  circular motion with radius

at an angular frequency



$$\rho = \frac{m_0\gamma v_{\perp}}{qB}$$

$$\omega = \frac{v_{\perp}}{\rho} = \frac{qB}{m_0\gamma} = \frac{qB}{m}$$

Constant magnetic field gives uniform spiral about B with constant energy.

$$B\rho = \frac{m_0\gamma v}{q} = \frac{p}{q}$$

Magnetic Rigidity

# Motion in Constant Electric Field

$$\frac{d}{dt}(m_0\gamma\vec{v}) = \vec{f} = q(\vec{E} + \vec{v} \wedge \vec{B}) \implies \boxed{\frac{d}{dt}(m_0\gamma\vec{v}) = q\vec{E}}$$

Solution is  $\gamma\vec{v} = \frac{q\vec{E}}{m_0}t$

Then  $\gamma^2 = 1 + \left(\frac{\gamma\vec{v}}{c}\right)^2 \implies \gamma = \sqrt{1 + \left(\frac{q\vec{E}t}{m_0c}\right)^2}$

If  $\vec{E} = (E, 0, 0)$ ,  $\frac{dx}{dt} = \frac{(\gamma v)}{\gamma} \implies x = x_0 + \frac{m_0c^2}{qE} \left[ \sqrt{1 + \left(\frac{qEt}{m_0c}\right)^2} - 1 \right]$   
 $\approx x_0 + \frac{1}{2} \left(\frac{qE}{m_0}\right) t^2$  for  $qE \ll m_0c$

Energy gain is

$$\boxed{m_0c^2(\gamma - 1) = qE(x - x_0)}$$

**Constant E-field gives uniform acceleration in straight line**

# Relativistic Transformations of E and B

- According to observer O in frame F, particle has velocity  $\vec{v}$ , fields are  $\vec{E}$  and  $\vec{B}$  and Lorentz force is  $\vec{f} = q(\vec{E} + \vec{v} \wedge \vec{B})$

- In Frame F', particle is at rest and force is  $\vec{f}' = q' \vec{E}'$

- Assume measurements give same charge and force, so

$$q' = q \quad \text{and} \quad \vec{E}' = \vec{E} + \vec{v} \times \vec{B}$$

- Point charge  $q$  at rest in F:  $\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{r^3}, \quad \vec{B} = 0$

- See a current in F' giving a field  $\vec{B}' = -\frac{\mu_0 q}{4\pi} \frac{\vec{v} \times \vec{r}}{r^3} = -\frac{1}{c^2} \vec{v} \times \vec{E}$

- Suggests  $\vec{B}' = \vec{B} - \frac{1}{c^2} \vec{v} \times \vec{E}$



# Review of Waves

- 1D wave equation is  $\frac{\partial^2 u}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 u}{\partial t^2}$  with general solution

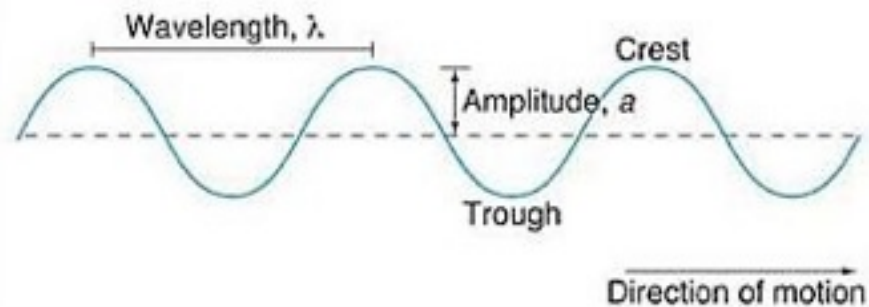
$$u(x, t) = f(vt - x) + g(vt + x)$$

- Simple plane wave:  $\longrightarrow$   $\longleftarrow$

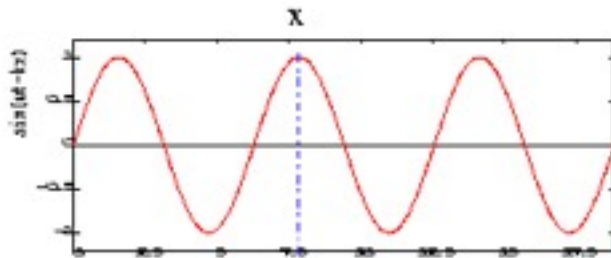
$$1\text{D: } \sin(\omega t - kx) \quad 3\text{D: } \sin(\omega t - \vec{k} \cdot \vec{x})$$

Wavelength is  $\lambda = \frac{2\pi}{|\vec{k}|}$

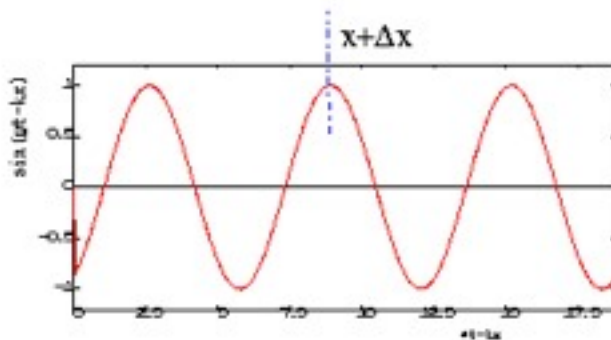
Frequency is  $\nu = \frac{\omega}{2\pi}$



# Phase and Group Velocities



Time  $t$

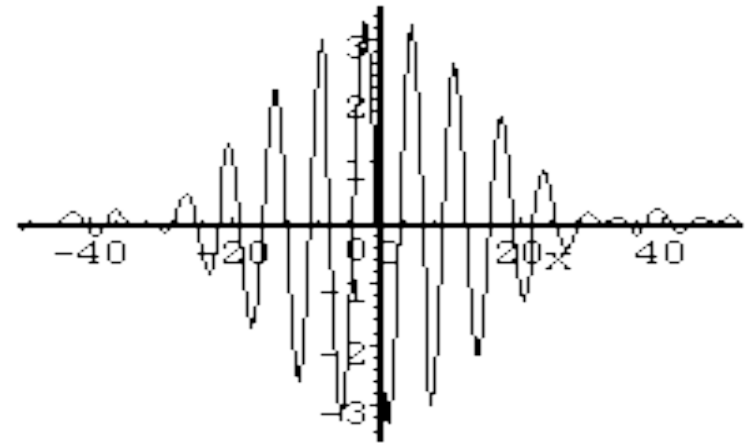


Time  $t + \Delta t$

Plane wave  $\sin(\omega t - kx)$  has constant phase  $\omega t - kx = \frac{1}{2}\pi$  at peaks

$$\omega \Delta t - k \Delta x = 0$$

$$\iff v_p = \frac{\Delta x}{\Delta t} = \frac{\omega}{k}$$

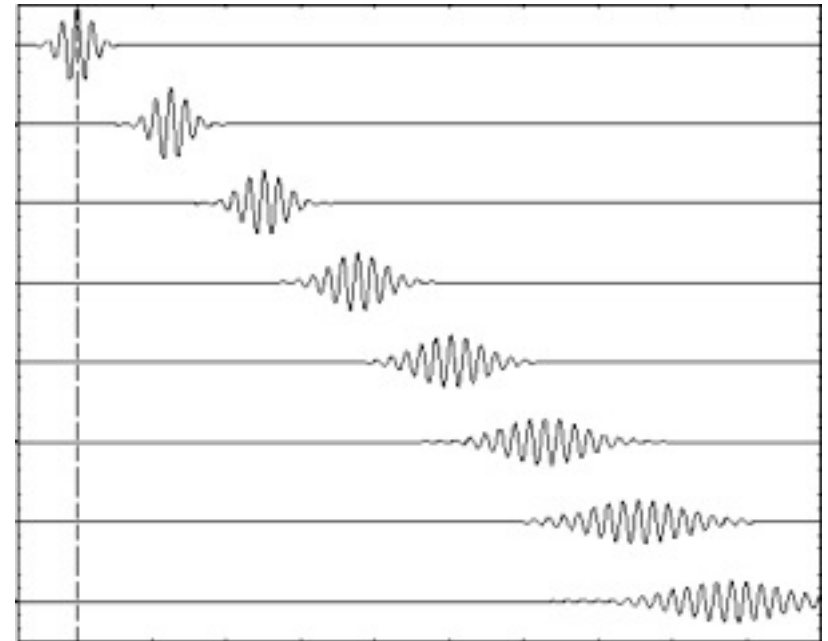
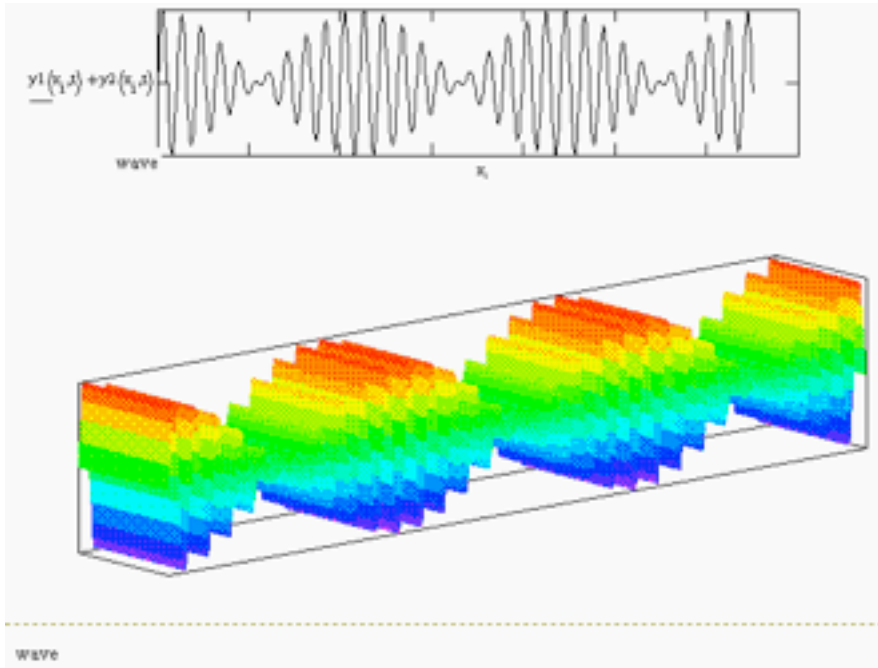


$$\int_{-\infty}^{\infty} A(k) e^{i[\omega(k)t - kx]} dk$$

Superposition of plane waves. While shape is relatively undistorted, pulse travels with the **Group Velocity**

$$v_g = \frac{d\omega}{dk}$$

# Wave Packet Structure



- Phase velocities of individual plane waves making up the wave packet are different,
- The wave packet will then disperse with time





# Electromagnetic waves

- Maxwell's equations predict the existence of electromagnetic waves, later discovered by Hertz.
- No charges, no currents:

$$\begin{aligned}\nabla \wedge (\nabla \wedge \vec{E}) &= -\nabla \wedge \frac{\partial \vec{B}}{\partial t} \\ &= -\frac{\partial}{\partial t} (\nabla \wedge \vec{B}) \\ &= -\mu \frac{\partial^2 \vec{D}}{\partial t^2} = -\mu\epsilon \frac{\partial^2 \vec{E}}{\partial t^2}\end{aligned}$$

$$\begin{aligned}\nabla \wedge \vec{H} &= \frac{\partial \vec{D}}{\partial t}, & \nabla \wedge \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\ \nabla \cdot \vec{D} &= 0, & \nabla \cdot \vec{B} &= 0\end{aligned}$$

3D wave equation:

$$\nabla^2 \vec{E} = \frac{\partial^2 \vec{E}}{\partial x^2} + \frac{\partial^2 \vec{E}}{\partial y^2} + \frac{\partial^2 \vec{E}}{\partial z^2} = \mu\epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\begin{aligned}\nabla \wedge (\nabla \wedge \vec{E}) &= \nabla(\nabla \cdot \vec{E}) - \nabla^2 \vec{E} \\ &= -\nabla^2 \vec{E}\end{aligned}$$

Similarly for  $\vec{H}$ .

Electromagnetic waves travelling with

speed  $\boxed{\frac{1}{\sqrt{\epsilon\mu}}}$

# Nature of Electromagnetic Waves

- A general plane wave with angular frequency  $\omega$  travelling in the direction of the wave vector  $\vec{k}$  has the form

$$\vec{E} = \vec{E}_0 e^{i(\omega t - \vec{k} \cdot \vec{x})}, \quad \vec{B} = \vec{B}_0 e^{i(\omega t - \vec{k} \cdot \vec{x})}$$

- Phase  $\omega t - \vec{k} \cdot \vec{x} = 2\pi \times$  number of waves and so is a Lorentz invariant.
- Apply Maxwell's equations:

$$\begin{aligned} \nabla &\leftrightarrow -i\vec{k} \\ \frac{\partial}{\partial t} &\leftrightarrow i\omega \end{aligned}$$

$$\begin{aligned} \nabla \cdot \vec{E} = 0 &= \nabla \cdot \vec{B} &\leftrightarrow & \vec{k} \cdot \vec{E} = 0 = \vec{k} \cdot \vec{B} \\ \nabla \wedge \vec{E} &= -\frac{\partial \vec{B}}{\partial t} &\leftrightarrow & \vec{k} \wedge \vec{E} = \omega \vec{B} \end{aligned}$$

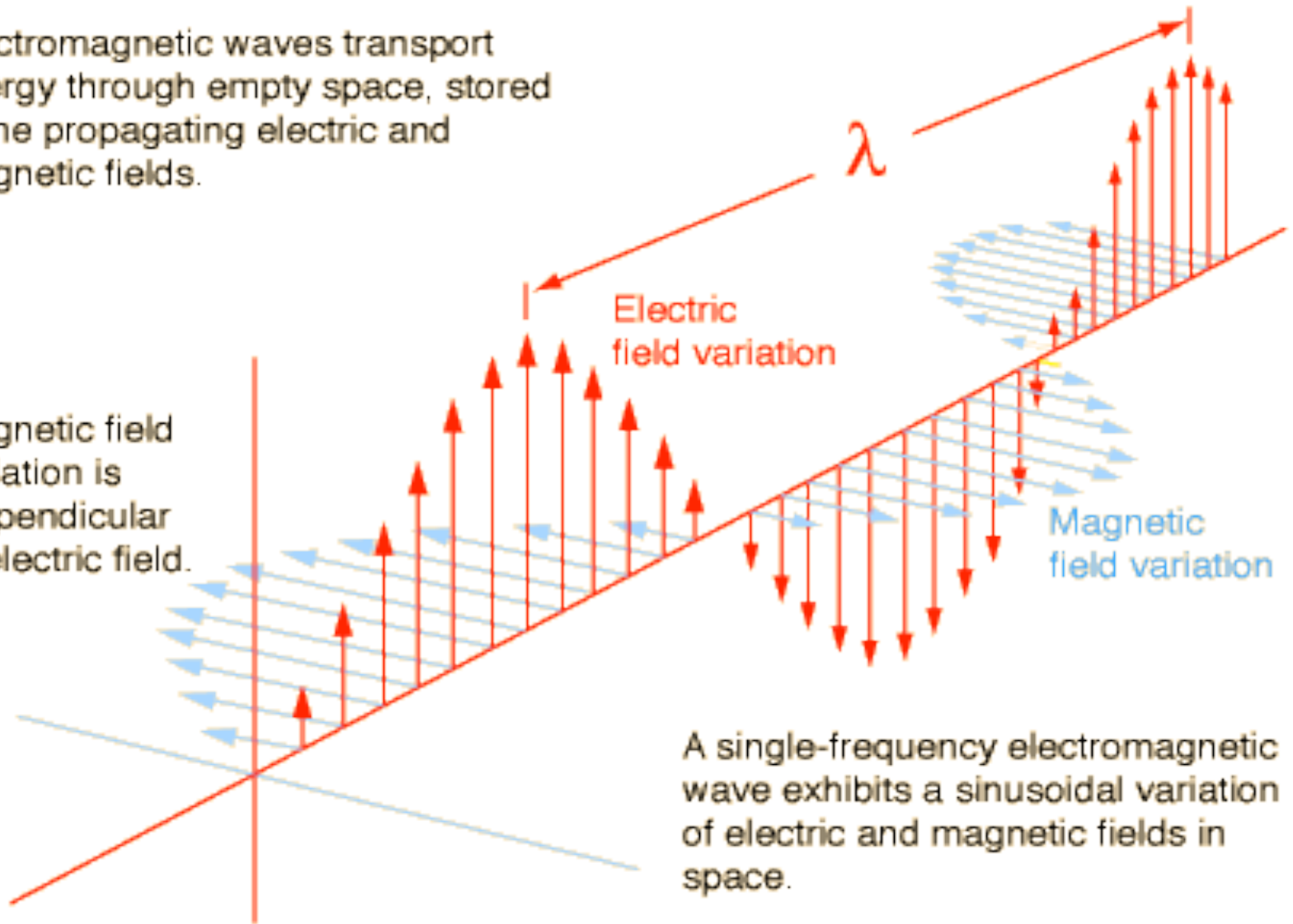
- Waves are transverse to the direction of propagation;  $\vec{E}$ ,  $\vec{B}$  and  $\vec{k}$  are mutually perpendicular



# Plane Electromagnetic Wave

Electromagnetic waves transport energy through empty space, stored in the propagating electric and magnetic fields.

Magnetic field variation is perpendicular to electric field.

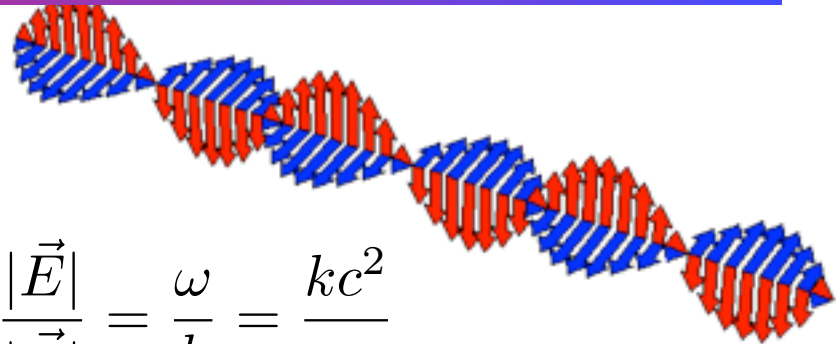


A single-frequency electromagnetic wave exhibits a sinusoidal variation of electric and magnetic fields in space.

# Plane Electromagnetic Waves

$$\nabla \wedge \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} \iff \vec{k} \wedge \vec{B} = -\frac{\omega}{c^2} \vec{E}$$

Combined with  $\vec{k} \wedge \vec{E} = \omega \vec{B} \implies \frac{|\vec{E}|}{|\vec{B}|} = \frac{\omega}{k} = \frac{kc^2}{\omega}$



$\implies$  speed of electromagnetic waves in vacuum is  $\frac{\omega}{k} = c$

Wavelength  $\lambda = \frac{2\pi}{|\vec{k}|}$

Frequency  $\nu = \frac{\omega}{2\pi}$

Reminder: The fact that  $\omega t - \vec{k} \cdot \vec{x}$  is an invariant tells us that

$$\Lambda = \left( \frac{\omega}{c}, \vec{k} \right)$$

is a Lorentz 4-vector, the 4-Frequency vector. Deduce frequency transforms as

$$\omega' = \gamma(\omega - \vec{v} \cdot \vec{k}) = \omega \sqrt{\frac{c-v}{c+v}}$$

# Waves in a Conducting Medium

$$\vec{E} = \vec{E}_0 e^{i(\omega t - \vec{k} \cdot \vec{x})}, \quad \vec{B} = \vec{B}_0 e^{i(\omega t - \vec{k} \cdot \vec{x})}$$

- (Ohm's Law) For a medium of conductivity  $\sigma$ ,  $\vec{j} = \sigma \vec{E}$

- Modified Maxwell:  $\nabla \wedge \vec{H} = \vec{j} + \epsilon \frac{\partial \vec{E}}{\partial t} = \sigma \vec{E} + \epsilon \frac{\partial \vec{E}}{\partial t}$

$$-i\vec{k} \wedge \vec{H} = \sigma \vec{E} + i\omega\epsilon \vec{E}$$

- Put  $D = \frac{\sigma}{\omega\epsilon}$

Dissipation  
factor

conduction  
current

displacement  
current

$$\text{Copper: } \sigma = 5.8 \times 10^7, \epsilon = \epsilon_0 \Rightarrow D = 10^{12}$$

$$\text{Teflon: } \sigma = 3 \times 10^{-8}, \epsilon = 2.1\epsilon_0 \Rightarrow D = 2.57 \times 10^{-4}$$

# Attenuation in a Good Conductor

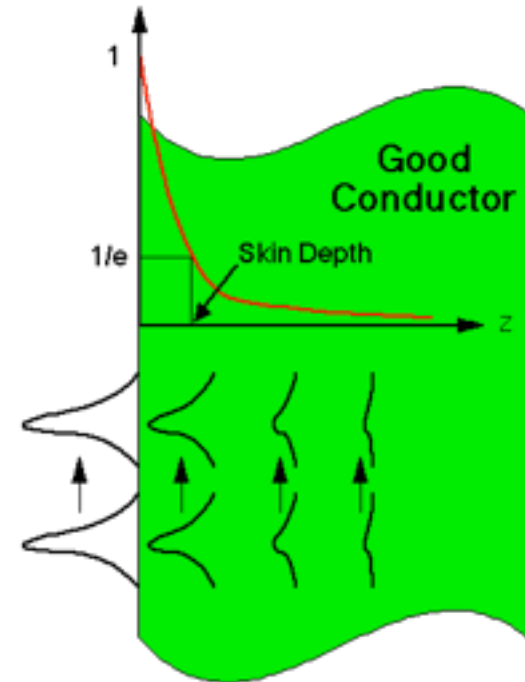
$$-i\vec{k} \wedge \vec{H} = \sigma \vec{E} + i\omega\epsilon \vec{E} \iff \vec{k} \wedge \vec{H} = i\sigma \vec{E} - \omega\epsilon \vec{E} = (i\sigma - \omega\epsilon) \vec{E}$$

Combine with  $\nabla \wedge \vec{E} = -\frac{\partial \vec{B}}{\partial t} \implies \vec{k} \wedge \vec{E} = \omega\mu \vec{H}$

$$\implies \vec{k} \wedge (\vec{k} \wedge \vec{E}) = \omega\mu \vec{k} \wedge \vec{H} = \omega\mu (i\sigma - \omega\epsilon) \vec{E}$$

$$\implies (\vec{k} \cdot \vec{E}) \vec{k} - k^2 \vec{E} = \omega\mu (i\sigma - \omega\epsilon) \vec{E}$$

$$\implies k^2 = \omega\mu(-i\sigma + \omega\epsilon) \text{ since } \vec{k} \cdot \vec{E} = 0$$



For a good conductor,  $D \gg 1$ ,  $\sigma \gg \omega\epsilon$ ,  $k^2 \approx -i\omega\mu\sigma$

$$\implies k \approx \sqrt{\frac{\omega\mu\sigma}{2}} (1 - i) = \frac{1}{\delta} (1 - i) \text{ where } \delta = \sqrt{\frac{2}{\omega\mu\sigma}} \text{ is the skin-depth}$$

Wave-form is:  $e^{i(\omega t - kx)} = e^{i(\omega t - (1-i)x/\delta)} = e^{-x/\delta} e^{i(\omega t - x/\delta)}$

# Charge Density in a Conducting Material

- Inside a conductor (Ohm's law)  $\vec{j} = \sigma \vec{E}$
- Continuity equation is

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{j} = 0 \quad \Longleftrightarrow \quad \frac{\partial \rho}{\partial t} + \sigma \nabla \cdot \vec{E} = 0$$

$$\Longleftrightarrow \quad \frac{\partial \rho}{\partial t} + \frac{\sigma}{\epsilon} \rho = 0.$$

- Solution is

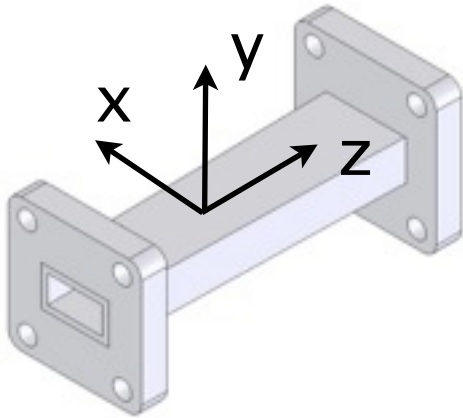
$$\rho = \rho_0 e^{-\sigma t / \epsilon}$$

- Charge density decays exponentially with time. For a very good conductor, charge flows instantly to the surface to form a surface current density and (for time varying fields) a surface current. Inside a perfect conductor:

$$(\sigma \rightarrow \infty) \quad \vec{E} = \vec{H} = 0$$



# A Uniform Perfectly Conducting Guide



Hollow metallic cylinder with perfectly conducting boundary surfaces

Maxwell's equations with time dependence  $e^{i\omega t}$  are:

$$\left. \begin{aligned} \nabla \wedge \vec{E} &= -\frac{\partial \vec{B}}{\partial t} = -i\omega\mu\vec{H} \\ \nabla \wedge \vec{H} &= \frac{\partial \vec{D}}{\partial t} = i\omega\epsilon\vec{E} \end{aligned} \right\} \Rightarrow \begin{aligned} \nabla^2 \vec{E} &= \nabla(\nabla \cdot \vec{E}) - \nabla \wedge \nabla \wedge \vec{E} \\ &= i\omega\mu\nabla \wedge \vec{H} \\ &= -\omega^2\epsilon\mu\vec{E} \end{aligned}$$

$$(\nabla^2 + \omega^2\epsilon\mu) \begin{Bmatrix} \vec{E} \\ \vec{H} \end{Bmatrix} = 0 \quad \text{Helmholtz Equation}$$

Assume  $\vec{E}(x, y, z, t) = \vec{E}(x, y)e^{(i\omega t - \gamma z)}$

$\vec{H}(x, y, z, t) = \vec{H}(x, y)e^{(i\omega t - \gamma z)}$

$\gamma$  is the propagation constant

Can solve for the fields completely in terms of  $E_z$  and  $H_z$

$$\text{Then } [\nabla_t^2 + (\omega^2\epsilon\mu + \gamma^2)] \begin{Bmatrix} \vec{E} \\ \vec{H} \end{Bmatrix} = 0$$





# A simple model: “Parallel Plate Waveguide”

Transport between two infinite conducting plates (TE<sub>01</sub> mode):

$$\vec{E} = (0, 1, 0)E(x)e^{i\omega t - \gamma z} \quad \text{where } E \text{ satisfies}$$

$$\nabla_t^2 E = \frac{d^2 E}{dx^2} = -K^2 E, \quad K^2 = \omega^2 \epsilon \mu + \gamma^2.$$

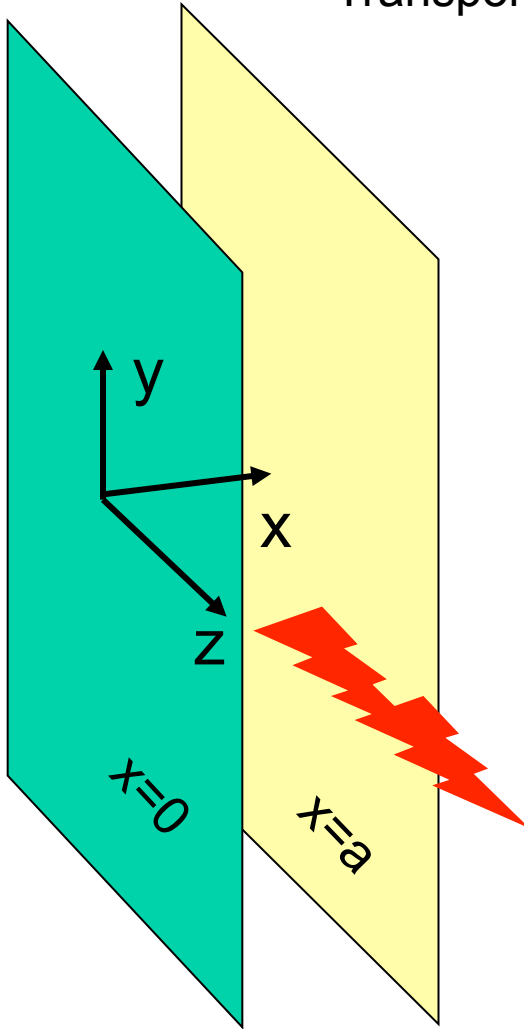
with solution  $E = A \cos Kx$  or  $A \sin Kx$

To satisfy boundary conditions:  $E = 0$  on  $x = 0$  and  $x = a$ .

$$\Rightarrow E = A \sin Kx, \quad \text{with } K = K_n \equiv \frac{n\pi}{a}, \quad n \text{ integer}$$

Propagation constant is

$$\gamma = \sqrt{K_n^2 - \omega^2 \epsilon \mu} = \frac{n\pi}{a} \sqrt{1 - \left(\frac{\omega}{\omega_c}\right)^2}, \quad \omega_c = \frac{K_n}{\sqrt{\epsilon \mu}}$$



# Cut-off Frequency, $\omega_c$

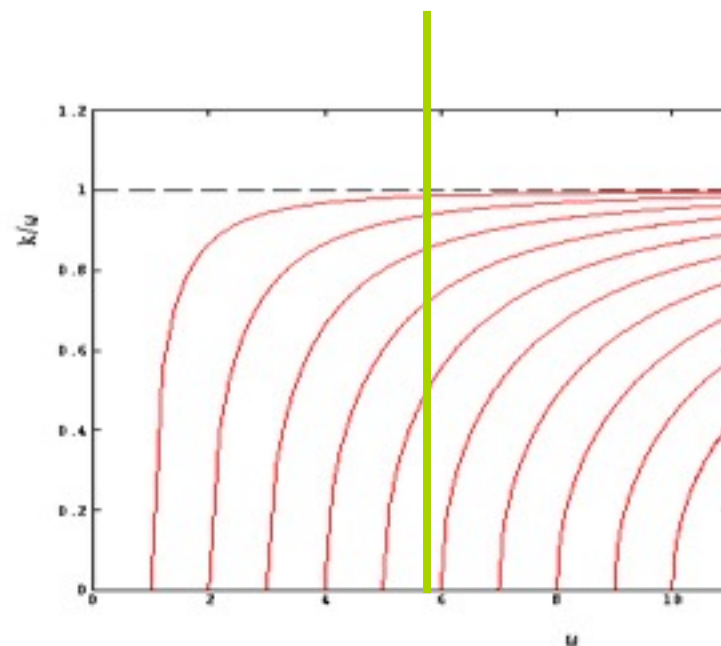
$$\gamma = \frac{n\pi}{a} \sqrt{1 - \left(\frac{\omega}{\omega_c}\right)^2}, \quad E = \sin \frac{n\pi x}{a} e^{i\omega t - \gamma z}, \quad \omega_c = \frac{n\pi}{a\sqrt{\epsilon\mu}}$$

- $\omega < \omega_c$  gives real solution for  $\gamma$ , so attenuation only. No wave propagates: cut-off modes.
- $\omega > \omega_c$  gives purely imaginary solution for  $\gamma$ , and a wave propagates without attenuation.

$$\gamma = ik, \quad k = \sqrt{\epsilon\mu}(\omega^2 - \omega_c^2)^{\frac{1}{2}} = \omega\sqrt{\epsilon\mu} \left(1 - \frac{\omega_c^2}{\omega^2}\right)^{\frac{1}{2}}$$

- For a given frequency  $\omega$  only a finite number of modes can propagate.

$$\omega > \omega_c = \frac{n\pi}{a\sqrt{\epsilon\mu}} \implies n < \frac{a\omega}{\pi} \sqrt{\epsilon\mu}$$



For given frequency, convenient to choose  $a$  s.t. only  $n=1$  mode occurs.



# Phase and Group Velocities

- Wave number  $k = \sqrt{\epsilon\mu}(\omega^2 - \omega_c^2)^{\frac{1}{2}} < \omega\sqrt{\epsilon\mu}$
- Wavelength  $\lambda = \frac{2\pi}{k} > \frac{2\pi}{\omega\sqrt{\epsilon\mu}}$ , ▶ free-space wavelength
- Phase velocity  $v_p = \frac{\omega}{k} > \frac{1}{\sqrt{\epsilon\mu}}$  ▶ larger than free-space velocity
- Group velocity  $k^2 = \epsilon\mu(\omega^2 - \omega_c^2) \implies v_g = \frac{d\omega}{dk} = \frac{k}{\omega\epsilon\mu} < \frac{1}{\sqrt{\epsilon\mu}}$  ▶ smaller than free-space velocity



# Calculation of Wave Properties

- If  $a = 3$  cm, cut-off frequency of lowest order mode is

$$f_c = \frac{\omega_c}{2\pi} = \frac{1}{2a\sqrt{\epsilon\mu}} \approx \frac{3 \times 10^8}{2 \times 0.03} \approx 5 \text{ GHz} \quad \left( \omega_c = \frac{n\pi}{a\sqrt{\epsilon\mu}} \right)$$

- At 7 GHz, only the  $n=1$  mode propagates and

$$k = \sqrt{\epsilon\mu}(\omega^2 - \omega_c^2)^{\frac{1}{2}} \approx 2\pi(7^2 - 5^2)^{\frac{1}{2}} \times 10^9 / 3 \times 10^8 = 103 \text{ m}^{-1}$$

$$\lambda = \frac{2\pi}{k} \approx 6 \text{ cm}$$

$$v_p = \frac{\omega}{k} = 4.3 \times 10^8 \text{ ms}^{-1} > c$$

$$v_g = \frac{k}{\omega\epsilon\mu} = 2.1 \times 10^8 \text{ ms}^{-1} < c$$