

Introduction to Transverse Beam Dynamics

Bernhard Holzer,
CERN-LHC

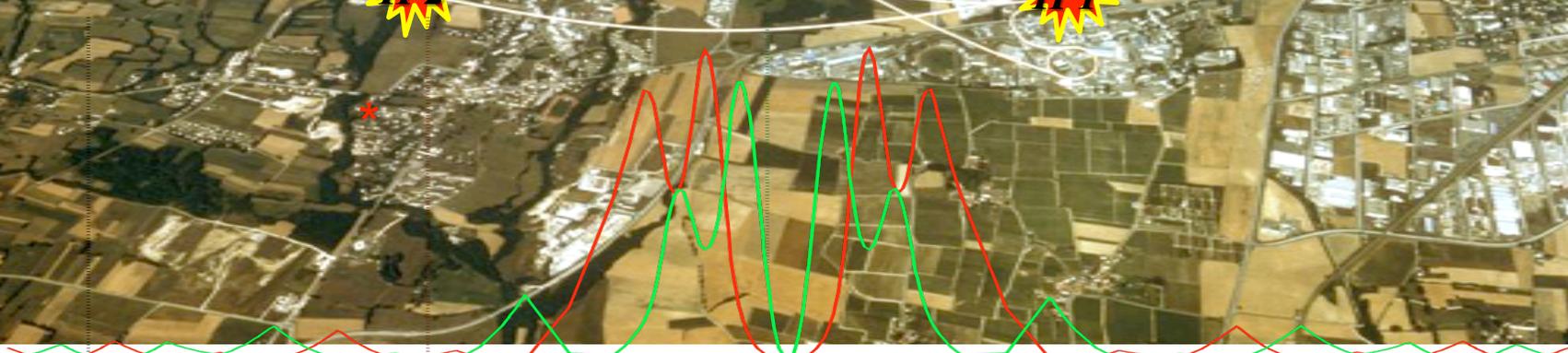
IP5 The Ideal World I.) Magnetic Fields and Particle Trajectories

IP2

IP1

IP8

*



Luminosity Run of a typical storage ring:

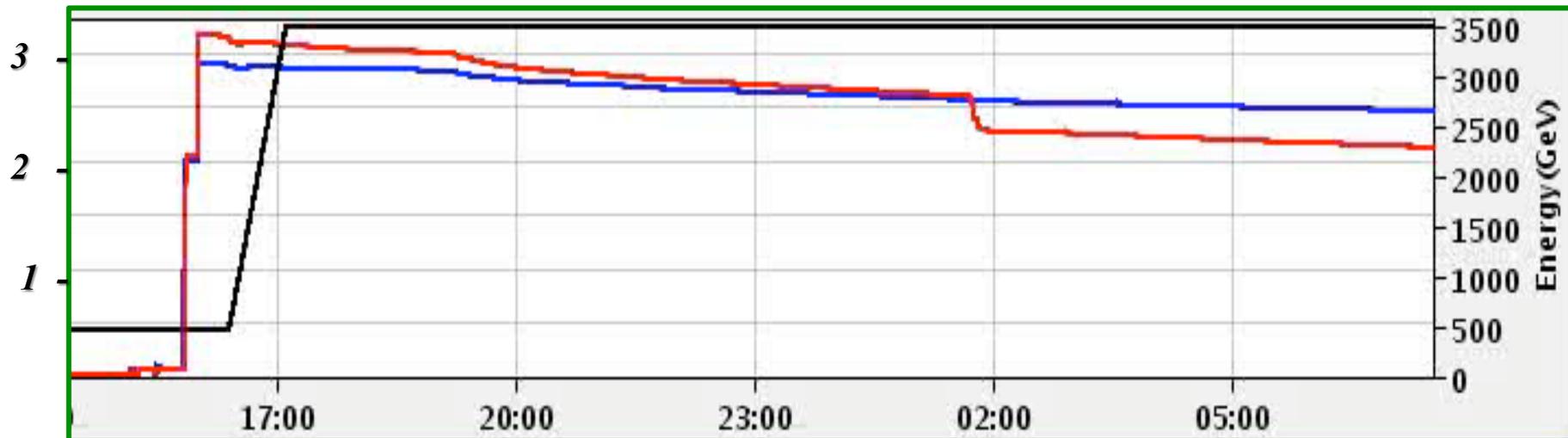
LHC Storage Ring: Protons accelerated and stored for 12 hours

distance of particles travelling at about $v \approx c$

$L = 10^{10}$ - 10^{11} km

... several times Sun - Pluto and back

intensity (10^{11})



- *guide the particles on a well defined orbit („design orbit“)*
- *focus the particles to keep each single particle trajectory within the vacuum chamber of the storage ring, i.e. close to the design orbit.*

1.) Introduction and Basic Ideas

„ ... in the end and after all it should be a kind of circular machine“
→ need transverse deflecting force

Lorentz force $\vec{F} = q * (\cancel{\vec{E}} + \vec{v} \times \vec{B})$

typical velocity in high energy machines: $v \approx c \approx 3 * 10^8 \text{ m/s}$

Example:

$$B = 1 \text{ T} \quad \rightarrow \quad F = q * 3 * 10^8 \frac{\text{m}}{\text{s}} * 1 \frac{\text{Vs}}{\text{m}^2}$$

$$F = q * 300 \frac{\text{MV}}{\text{m}}$$

equivalent el. field ... E

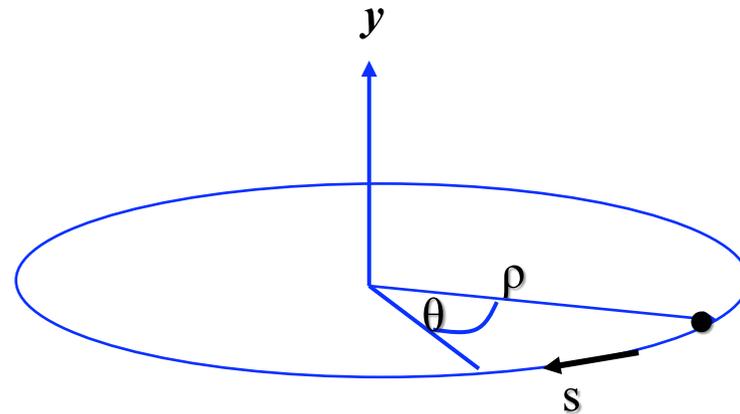
technical limit for el. field:

$$E \leq 1 \frac{\text{MV}}{\text{m}}$$

old greek dictum of wisdom:

if you are clever, you use magnetic fields in an accelerator wherever it is possible.

The ideal circular orbit



circular coordinate system

condition for circular orbit:

Lorentz force

$$F_L = e v B$$

centrifugal force

$$F_{centr} = \frac{\gamma m_0 v^2}{\rho}$$

$$\frac{\gamma m_0 v^2}{\rho} = e v B$$

$$\frac{p}{e} = B \rho$$

B ρ = "beam rigidity"

1.) The Magnetic Guide Field

Dipole Magnets:

define the ideal orbit
homogeneous field created
 by two flat pole shoes

$$B = \frac{\mu_0 n I}{h}$$



Normalise magnetic field to momentum:

$$\frac{p}{e} = B \rho \quad \longrightarrow \quad \frac{1}{\rho} = \frac{e B}{p}$$

convenient units:

$$B = [T] = \left[\frac{Vs}{m^2} \right] \quad p = \left[\frac{GeV}{c} \right]$$

Example LHC:

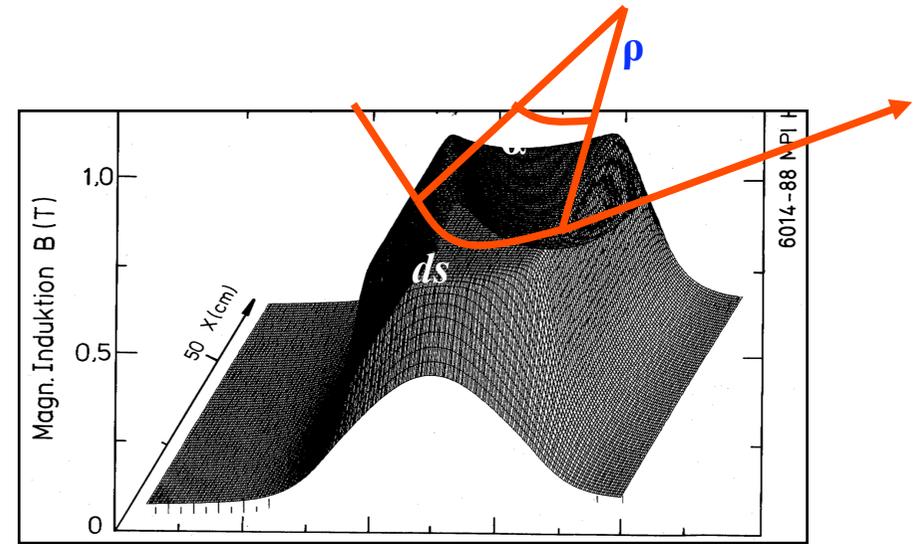
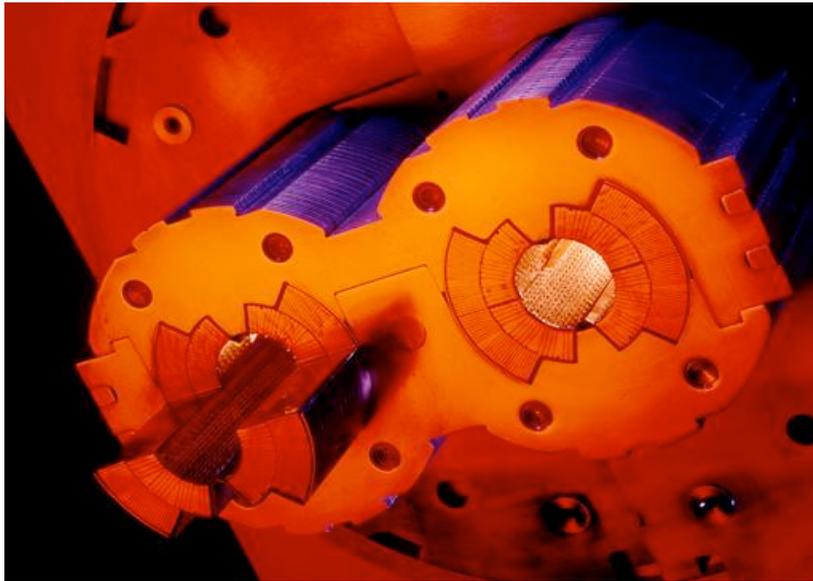
$$B = 8.3 T$$

$$p = 7000 \frac{GeV}{c}$$

$$\frac{1}{\rho} = e \frac{8.3 \frac{Vs}{m^2}}{7000 * 10^9 \frac{eV}{c}} = \frac{8.3 s 3 * 10^8 \frac{m}{s}}{7000 * 10^9 m^2}$$

$$\frac{1}{\rho} = 0.333 \frac{8.3}{7000} \frac{1}{m}$$

The Magnetic Guide Field



field map of a storage ring dipole magnet

$$\rho = 2.53 \text{ km} \quad \longrightarrow \quad 2\pi\rho = 17.6 \text{ km} \approx 66\%$$

$$B \approx 1 \dots 8 \text{ T}$$

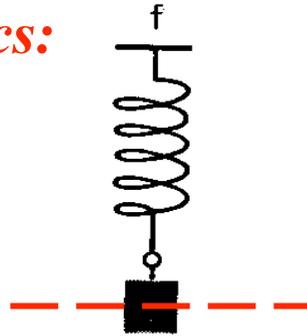
rule of thumb:

$$\frac{1}{\rho} \approx 0.3 \frac{B [T]}{p [\text{GeV}/c]}$$

„normalised bending strength“

Focusing Properties - Transverse Beam Optics

Classical Mechanics:
pendulum



there is a *restoring force*, *proportional to the elongation* x :

$$F = m * \frac{d^2 x}{dt^2} = -k * x$$

Ansatz $x(t) = A * \cos(\omega t + \varphi)$

$$\dot{x} = -A\omega * \sin(\omega t + \varphi)$$

$$\ddot{x} = -A\omega^2 * \cos(\omega t + \varphi)$$

general solution: free harmonic oscillation

Solution $\omega = \sqrt{k/m}$, $x(t) = x_0 * \cos(\sqrt{\frac{k}{m}}t + \varphi)$

Storage Ring: we need a *Lorentz force* that rises as a function of the *distance to* ?

..... *the design orbit*

$$F(x) = q * v * B(x)$$

2.) Quadrupole Magnets:

required: *focusing forces* to keep trajectories in vicinity of the ideal orbit

linear increasing Lorentz force

linear increasing magnetic field

$$B_y = g x \quad B_x = g y$$

normalised quadrupole field:

gradient of a quadrupole magnet: $g = \frac{2\mu_0 n I}{r^2}$



$$k = \frac{g}{p/e}$$

simple rule:

$$k = 0.3 \frac{g(T/m)}{p(GeV/c)}$$



LHC main quadrupole magnet

$$g \approx 25 \dots 220 \text{ T/m}$$

*what about the vertical plane:
... Maxwell*

$$\vec{\nabla} \times \vec{B} = \cancel{\vec{j}} + \frac{\partial \cancel{\vec{E}}}{\partial t} = 0 \quad \Rightarrow \quad \frac{\partial B_y}{\partial x} = \frac{\partial B_x}{\partial y}$$

3.) The equation of motion:

Linear approximation:

* *ideal particle* → *design orbit*

* *any other particle* → *coordinates x, y* **small quantities**
 $x, y \ll \rho$

→ *magnetic guide field: only linear terms in x & y of B*
have to be taken into account

Taylor Expansion of the B field:

$$B_y(x) = B_{y0} + \frac{dB_y}{dx} x + \frac{1}{2!} \frac{d^2 B_y}{dx^2} x^2 + \frac{1}{3!} \frac{eg''}{dx^3} + \dots$$

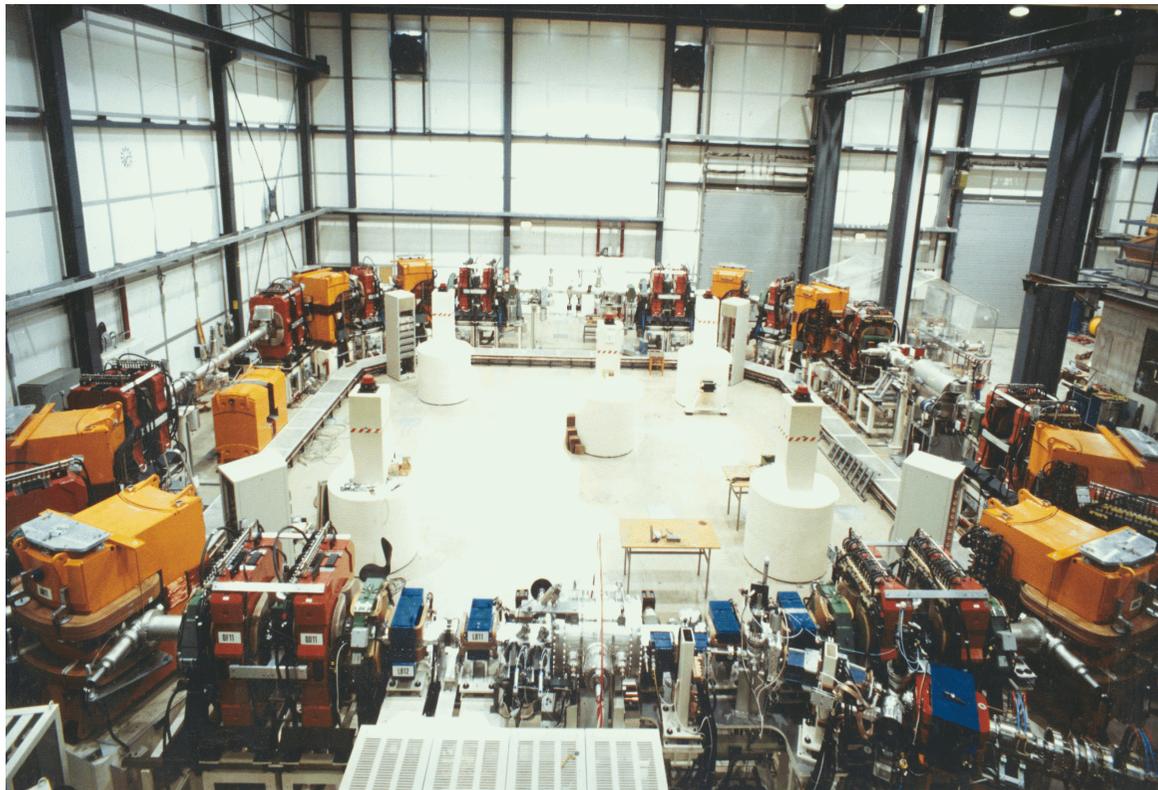
normalise to momentum
 $p/e = B\rho$

$$\frac{B(x)}{p/e} = \frac{B_0}{B_0\rho} + \frac{g^* x}{p/e} + \frac{1}{2!} \frac{eg'}{p/e} + \frac{1}{3!} \frac{eg''}{p/e} + \dots$$

The Equation of Motion:

$$\frac{B(x)}{p/e} = \frac{1}{\rho} + kx + \frac{1}{2!} \cancel{m} x^2 + \frac{1}{3!} \cancel{n} x^3 + \dots$$

only terms linear in x, y taken into account **dipole fields**
quadrupole fields



Separate Function Machines:

Split the magnets and optimise them according to their job:

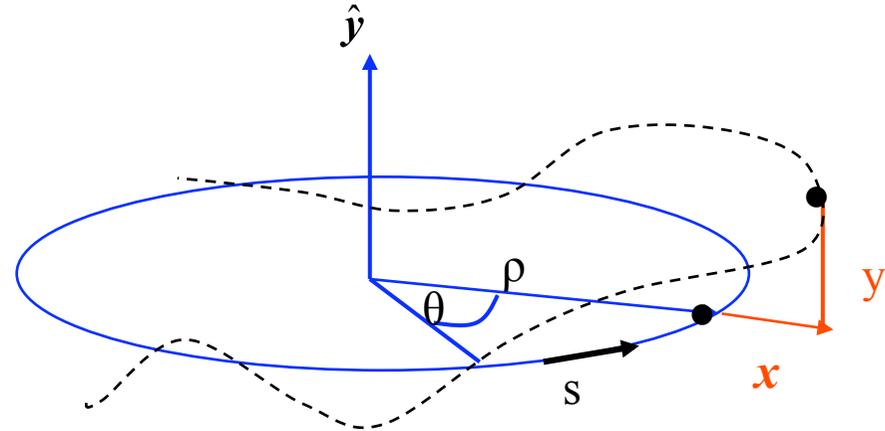
bending, focusing etc

*Example:
heavy ion storage ring TSR*

* *man sieht nur
dipole und quads → linear*

Equation of Motion:

Consider local segment of a particle trajectory
 ... and remember the old days:
 (Goldstein page 27)



radial acceleration:

$$a_r = \frac{d^2 \rho}{dt^2} - \rho \left(\frac{d\theta}{dt} \right)^2$$

general trajectory: $\rho \rightarrow \rho + x$

$$F = m \frac{d^2}{dt^2} (x + \rho) - \frac{mv^2}{x + \rho} = e B_y v$$

Ideal orbit: $\rho = \text{const}, \quad \frac{d\rho}{dt} = 0$

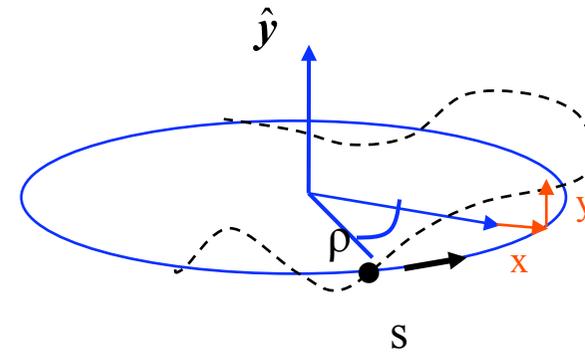
$$\text{Force: } F = m\rho \left(\frac{d\theta}{dt} \right)^2 = m\rho\omega^2$$

$$F = mv^2 / \rho$$

$$F = m \frac{d^2}{dt^2} (x + \rho) - \frac{mv^2}{x + \rho} = e B_y v$$

①

②



① $\frac{d^2}{dt^2} (x + \rho) = \frac{d^2}{dt^2} x \quad \dots \text{as } \rho = \text{const}$

② *remember: $x \approx mm$, $\rho \approx m \dots \rightarrow$ develop for small x*

$$\frac{1}{x + \rho} \approx \frac{1}{\rho} \left(1 - \frac{x}{\rho}\right)$$

Taylor Expansion

$$f(x) = f(x_0) + \frac{(x - x_0)}{1!} f'(x_0) + \frac{(x - x_0)^2}{2!} f''(x_0) + \dots$$

$$m \frac{d^2 x}{dt^2} - \frac{mv^2}{\rho} \left(1 - \frac{x}{\rho}\right) = e B_y v$$

guide field in linear approx.

$$B_y = B_0 + x \frac{\partial B_y}{\partial x} \qquad m \frac{d^2 x}{dt^2} - \frac{mv^2}{\rho} \left(1 - \frac{x}{\rho}\right) = ev \left\{ B_0 + x \frac{\partial B_y}{\partial x} \right\} \quad : m$$

$$\frac{d^2 x}{dt^2} - \frac{v^2}{\rho} \left(1 - \frac{x}{\rho}\right) = \frac{ev B_0}{m} + \frac{ev x g}{m}$$

independent variable: $t \rightarrow s$

$$\frac{dx}{dt} = \frac{dx}{ds} \frac{ds}{dt}$$

$$\frac{d^2 x}{dt^2} = \frac{d}{dt} \left(\frac{dx}{ds} \frac{ds}{dt} \right) = \frac{d}{ds} \left(\underbrace{\frac{dx}{ds}}_{x'} \underbrace{\frac{ds}{dt}}_v \right) \frac{ds}{dt}$$

$$\frac{d^2 x}{dt^2} = x'' v^2 + \cancel{\frac{dx}{ds} \frac{dv}{ds} v}$$

$$x'' v^2 - \frac{v^2}{\rho} \left(1 - \frac{x}{\rho}\right) = \frac{ev B_0}{m} + \frac{ev x g}{m} \quad : v^2$$

$$x'' - \frac{1}{\rho} \left(1 - \frac{x}{\rho}\right) = \frac{e B_0}{mv} + \frac{e x g}{mv}$$

$$x'' - \frac{1}{\rho} + \frac{x}{\rho^2} = \frac{B_0}{p/e} + \frac{x g}{p/e}$$

$$x'' - \cancel{\frac{1}{\rho}} + \frac{x}{\rho^2} = -\cancel{\frac{1}{\rho}} + k x$$

$$x'' + x \left(\frac{1}{\rho^2} - k \right) = 0$$

$$m v = p$$

normalize to momentum of particle

$$\frac{B_0}{p/e} = -\frac{1}{\rho}$$

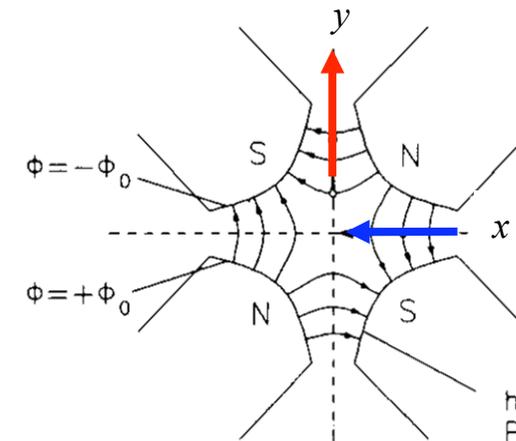
$$\frac{g}{p/e} = k$$

* *Equation for the vertical motion:*

$$\frac{1}{\rho^2} = 0 \quad \text{no dipoles ... in general ...}$$

$$k \Leftrightarrow -k \quad \text{quadrupole field changes sign}$$

$$y'' + k y = 0$$



Remarks:

$$* \quad x'' + \left(\frac{1}{\rho^2} - k\right) \cdot x = 0$$

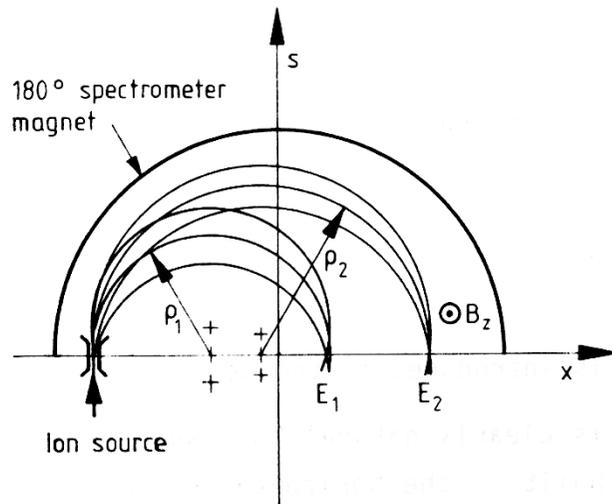
... there seems to be a focusing even without a quadrupole gradient

„weak focusing of dipole magnets“

$$k = 0 \quad \Rightarrow \quad x'' = -\frac{1}{\rho^2} x$$

even without quadrupoles there is a retraining force (i.e. focusing) in the bending plane of the dipole magnets

... in large machines it is weak. (!)



Mass spectrometer: particles are separated according to their energy and focused due to the $1/\rho$ effect of the dipole

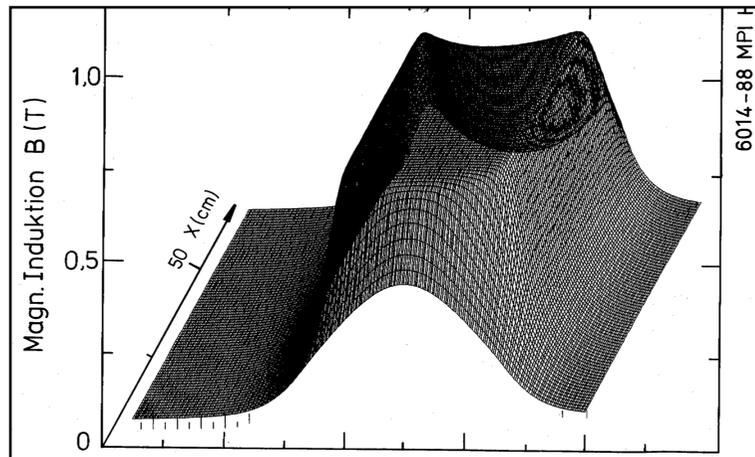
* **Hard Edge Model:**

$$x'' + \left\{ \frac{1}{\rho^2} - k \right\} x = 0$$

$$x''(s) + \left\{ \frac{1}{\rho^2(s)} - k(s) \right\} x(s) = 0$$

... this equation is not correct !!!

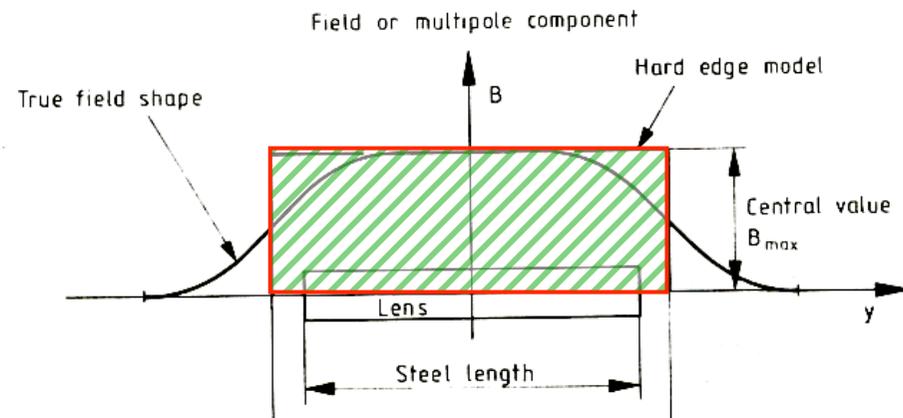
bending and focusing fields ... are functions of the independent variable „s“



Inside a magnet we assume constant focusing properties !

$$\frac{1}{\rho} = const \quad k = const$$

$$B l_{eff} = \int_0^{l_{mag}} B ds$$



4.) Solution of Trajectory Equations

$$\left. \begin{array}{l} \text{Define ... hor. plane: } K = 1/\rho^2 - k \\ \text{... vert. Plane: } K = k \end{array} \right\} \quad x'' + K x = 0$$

Differential Equation of harmonic oscillator ... with spring constant K

Ansatz: $x(s) = a_1 \cdot \cos(\omega s) + a_2 \cdot \sin(\omega s)$

general solution: linear combination of two independent solutions

$$x'(s) = -a_1 \omega \sin(\omega s) + a_2 \omega \cos(\omega s)$$

$$x''(s) = -a_1 \omega^2 \cos(\omega s) - a_2 \omega^2 \sin(\omega s) = -\omega^2 x(s) \quad \longrightarrow \quad \omega = \sqrt{K}$$

general solution:

$$x(s) = a_1 \cos(\sqrt{K} s) + a_2 \sin(\sqrt{K} s)$$

determine a_1, a_2 by boundary conditions:

$$s = 0 \quad \longrightarrow \quad \left\{ \begin{array}{l} x(0) = x_0 \quad , \quad a_1 = x_0 \\ x'(0) = x'_0 \quad , \quad a_2 = \frac{x'_0}{\sqrt{K}} \end{array} \right.$$

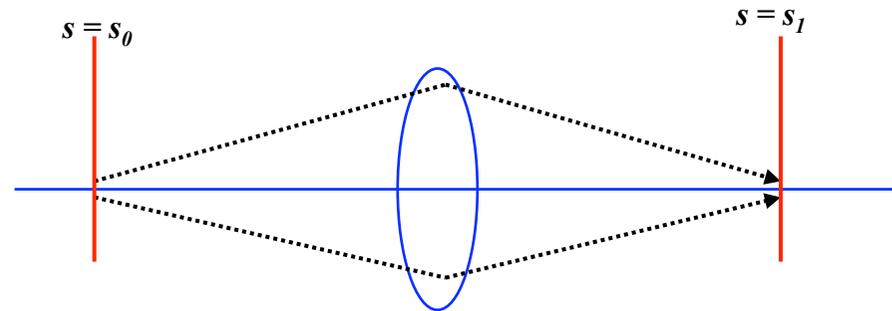
Hor. Focusing Quadrupole $K > 0$:

$$x(s) = x_0 \cdot \cos(\sqrt{|K|}s) + x'_0 \cdot \frac{1}{\sqrt{|K|}} \sin(\sqrt{|K|}s)$$

$$x'(s) = -x_0 \cdot \sqrt{|K|} \cdot \sin(\sqrt{|K|}s) + x'_0 \cdot \cos(\sqrt{|K|}s)$$

For convenience expressed in matrix formalism:

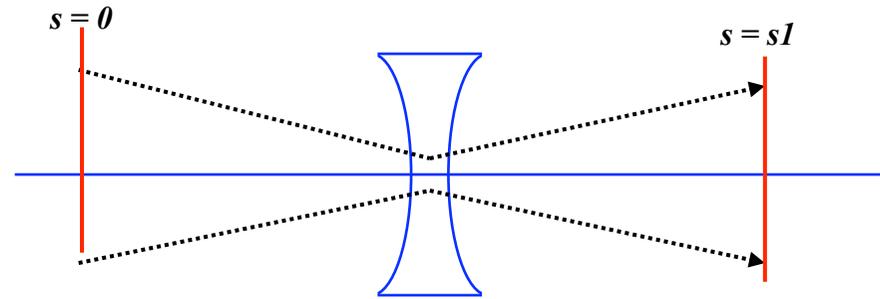
$$\begin{pmatrix} x \\ x' \end{pmatrix}_{s_1} = M_{foc} * \begin{pmatrix} x \\ x' \end{pmatrix}_{s_0}$$



$$M_{foc} = \begin{pmatrix} \cos(\sqrt{|K|}s) & \frac{1}{\sqrt{|K|}} \sin(\sqrt{|K|}s) \\ -\sqrt{|K|} \sin(\sqrt{|K|}s) & \cos(\sqrt{|K|}s) \end{pmatrix}_0$$

hor. defocusing quadrupole:

$$x'' - K x = 0$$



Remember from school:

$$f(s) = \cosh(s) \quad , \quad f'(s) = \sinh(s)$$

Ansatz: $x(s) = a_1 \cdot \cosh(\omega s) + a_2 \cdot \sinh(\omega s)$

$$M_{defoc} = \begin{pmatrix} \cosh \sqrt{|K|}l & \frac{1}{\sqrt{|K|}} \sinh \sqrt{|K|}l \\ \sqrt{|K|} \sinh \sqrt{|K|}l & \cosh \sqrt{|K|}l \end{pmatrix}$$

drift space:

$$K = 0$$

$$M_{drift} = \begin{pmatrix} 1 & l \\ 0 & 1 \end{pmatrix}$$

! with the assumptions made, the motion in the horizontal and vertical planes are independent „ ... the particle motion in x & y is uncoupled“

Thin Lens Approximation:

matrix of a quadrupole lens

$$M = \begin{pmatrix} \cos \sqrt{|k|}l & \frac{1}{\sqrt{|k|}} \sin \sqrt{|k|}l \\ -\sqrt{|k|} \sin \sqrt{|k|}l & \cos \sqrt{|k|}l \end{pmatrix}$$

in many practical cases we have the situation:

$$f = \frac{1}{kl_q} \gg l_q \quad \dots \text{focal length of the lens is much bigger than the length of the magnet}$$

limes: $l_q \rightarrow 0$ while keeping $kl_q = \text{const}$

$$M_x = \begin{pmatrix} 1 & 0 \\ \frac{1}{f} & 1 \end{pmatrix}$$

$$M_z = \begin{pmatrix} 1 & 0 \\ -\frac{1}{f} & 1 \end{pmatrix}$$

... useful for fast (and in large machines still quite accurate) „back on the envelope calculations“ ... and for the guided studies !

Combining the two planes:

Clear enough (hopefully ... ?) : a quadrupole magnet that is focussing o-in one plane acts as defocusing lens in the other plane ... et vice versa.

hor foc. quadrupole lens

$$M_{foc} = \begin{pmatrix} \cos(\sqrt{|K|}s) & \frac{1}{\sqrt{|K|}} \sin(\sqrt{|K|}s) \\ -\sqrt{|K|} \sin(\sqrt{|K|}s) & \cos(\sqrt{|K|}s) \end{pmatrix}$$

matrix of the same magnet in the vert. plane:

$$M_{defoc} = \begin{pmatrix} \cosh \sqrt{|K|}l & \frac{1}{\sqrt{|K|}} \sinh \sqrt{|K|}l \\ \sqrt{|K|} \sinh \sqrt{|K|}l & \cosh \sqrt{|K|}l \end{pmatrix}$$

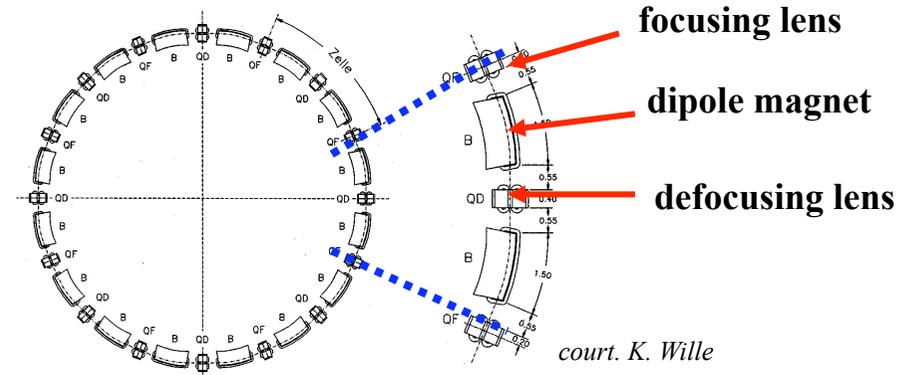
$$\begin{pmatrix} x \\ x' \\ y \\ y' \end{pmatrix}_f = \begin{pmatrix} \cos(\sqrt{|k|}s) & \frac{1}{\sqrt{|k|}} \sin(\sqrt{|k|}s) & 0 & 0 \\ -\sqrt{|k|} \sin(\sqrt{|k|}s) & \cos(\sqrt{|k|}s) & 0 & 0 \\ 0 & 0 & \cosh(\sqrt{|k|}s) & \frac{1}{\sqrt{|k|}} \sinh(\sqrt{|k|}s) \\ 0 & 0 & \sqrt{|k|} \sinh(\sqrt{|k|}s) & \cosh(\sqrt{|k|}s) \end{pmatrix} * \begin{pmatrix} x \\ x' \\ y \\ y' \end{pmatrix}_i$$

Transformation through a system of lattice elements

combine the single element solutions by multiplication of the matrices

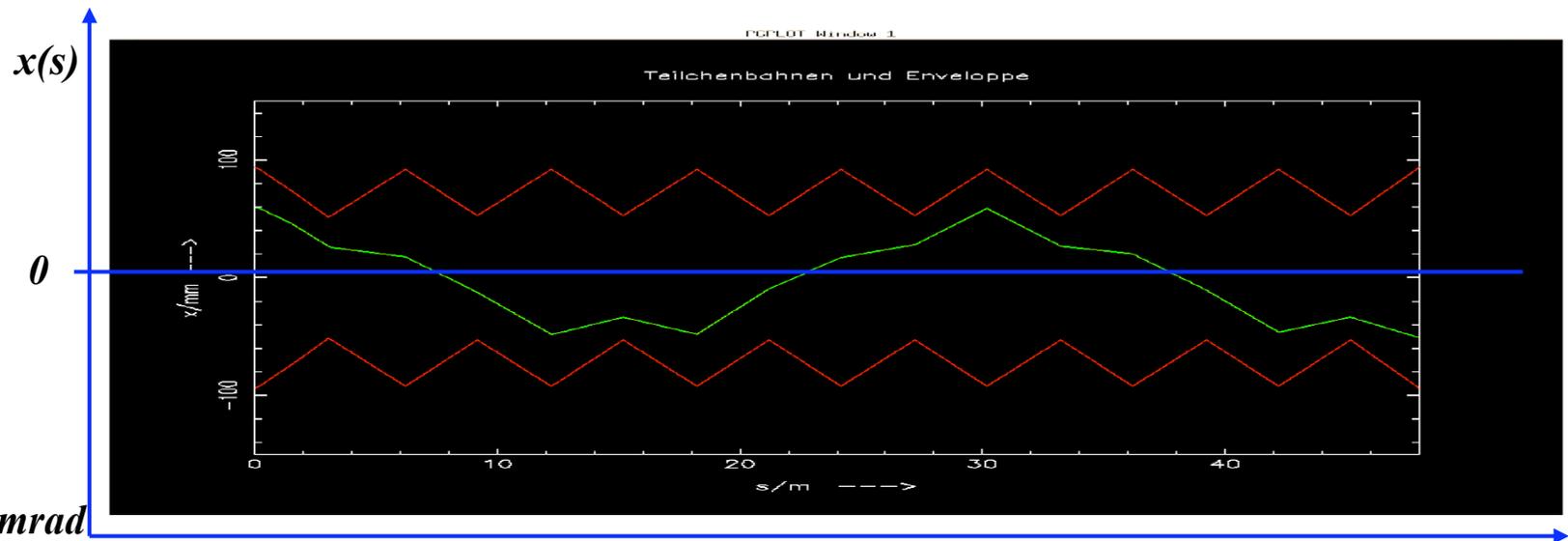
$$M_{total} = M_{QF} * M_D * M_{QD} * M_{Bend} * M_D * \dots$$

$$\begin{pmatrix} x \\ x' \end{pmatrix}_{s_2} = M(s_2, s_1) * \begin{pmatrix} x \\ x' \end{pmatrix}_{s_1}$$



in each accelerator element the particle trajectory corresponds to the movement of a harmonic oscillator ,,

typical values
in a strong
foc. machine:
 $x \approx \text{mm}$, $x' \leq \text{mrad}$



5.) Orbit & Tune:

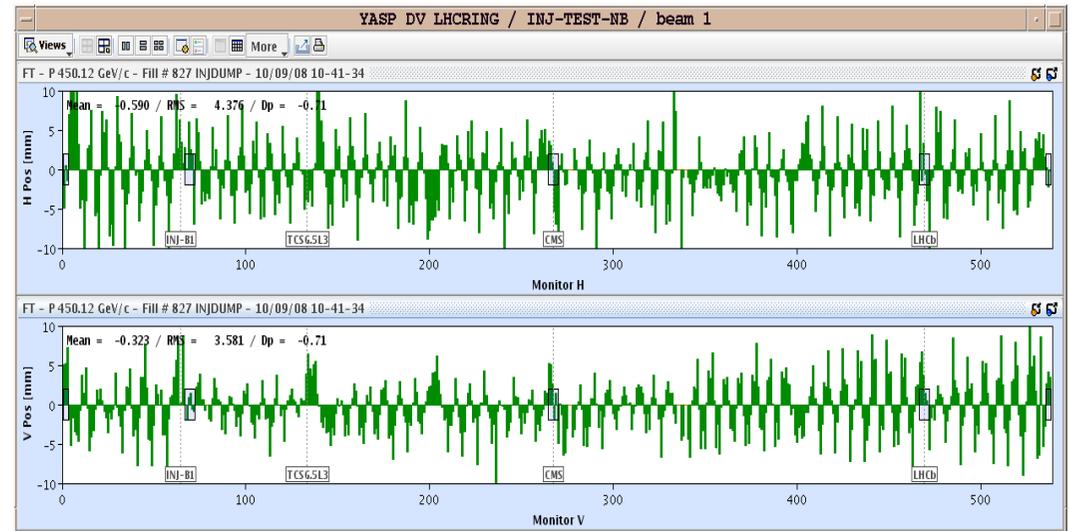
Tune: number of oscillations per turn

64.31

59.32

Relevant for beam stability:

non integer part



LHC revolution frequency: 11.3 kHz

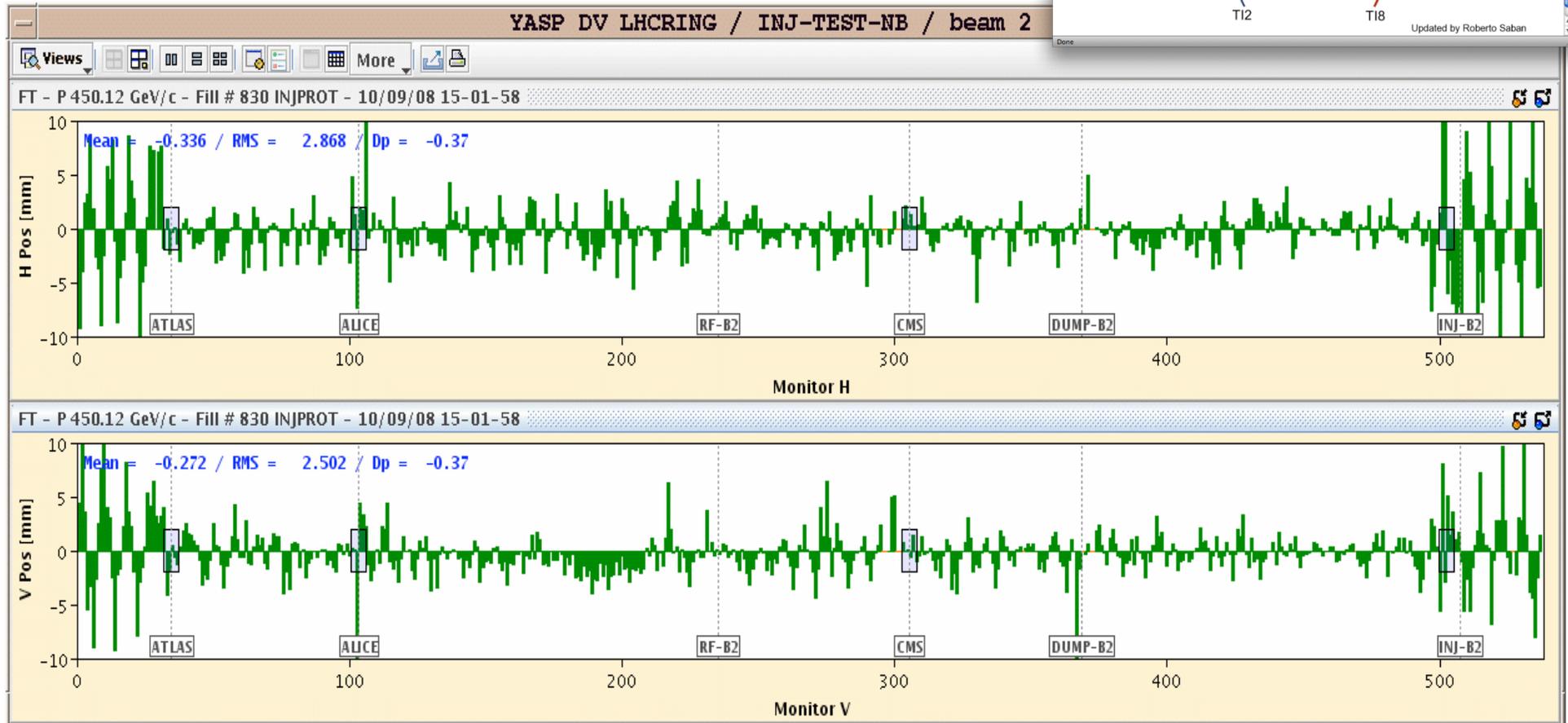
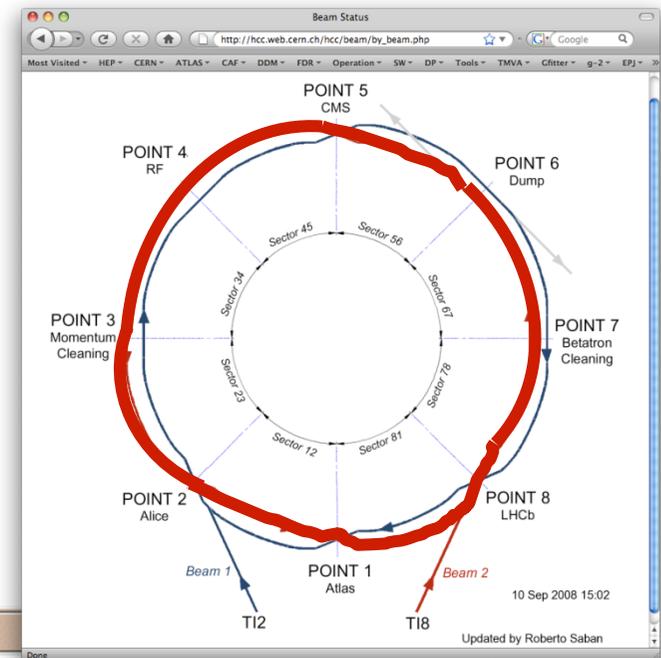
$$0.31 * 11.3 = 3.5 \text{ kHz}$$



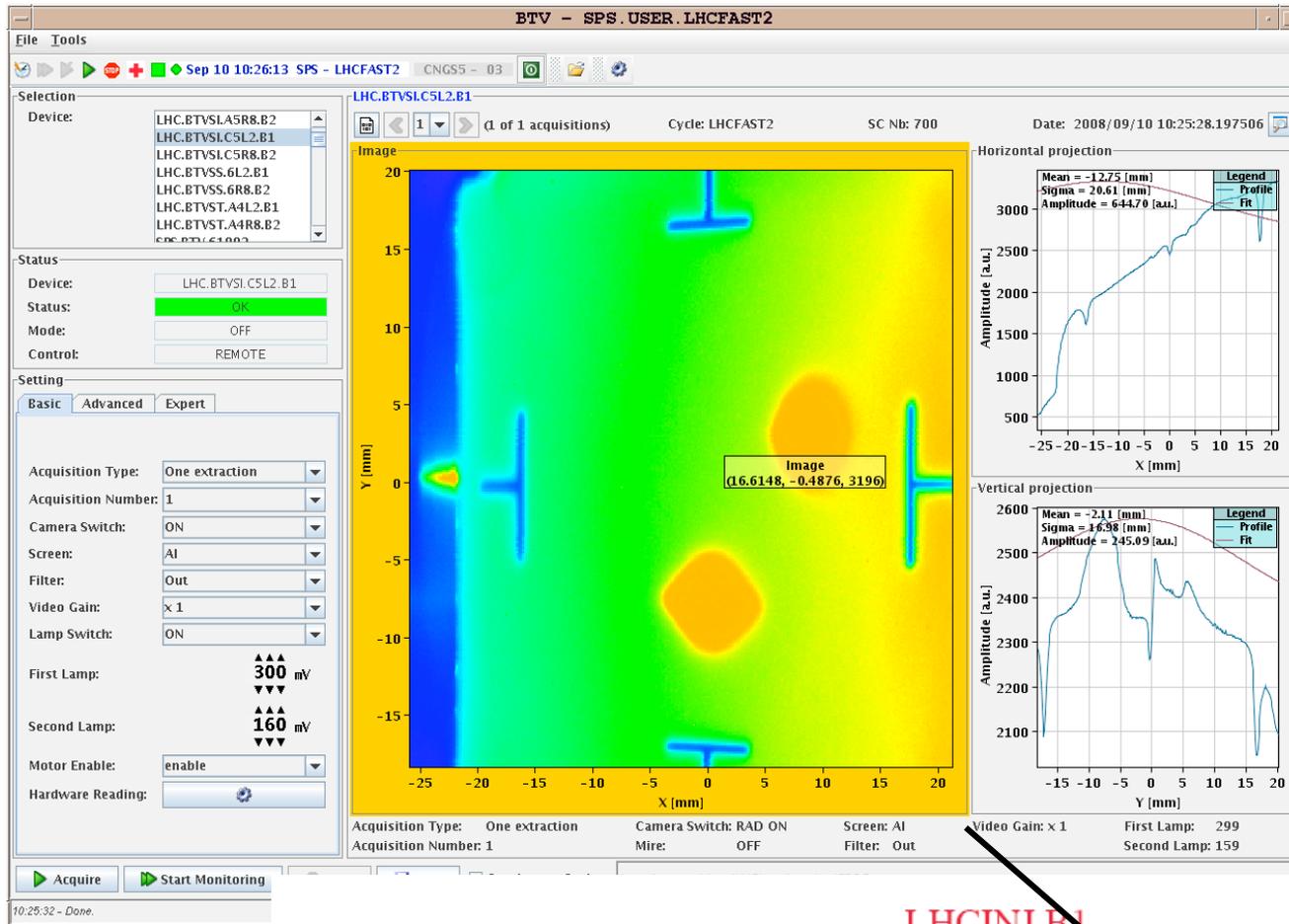
LHC Operation: Beam Commissioning

First turn steering "by sector:"

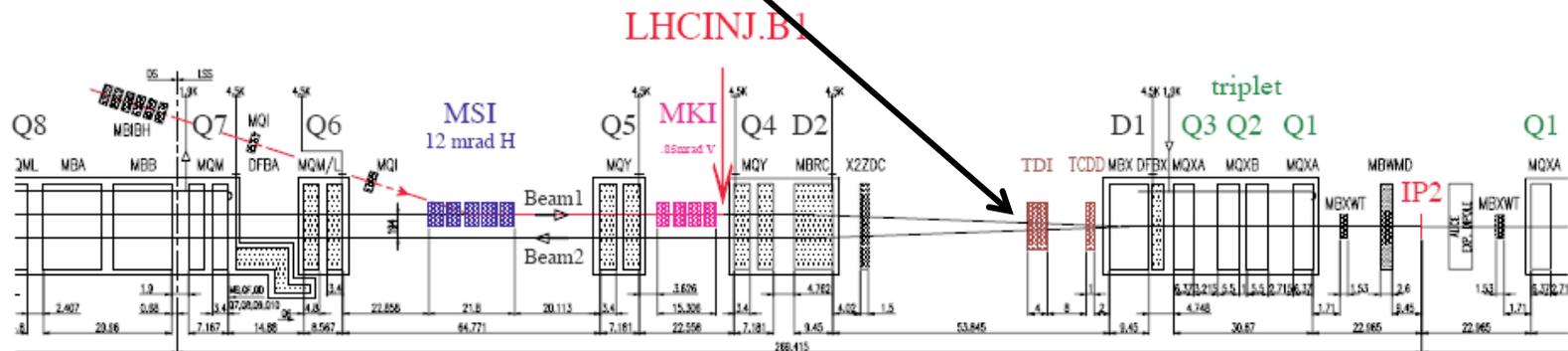
- One beam at the time
- Beam through 1 sector (1/8 ring), correct trajectory, open collimator and move on.



LHC Operation: the First Beam

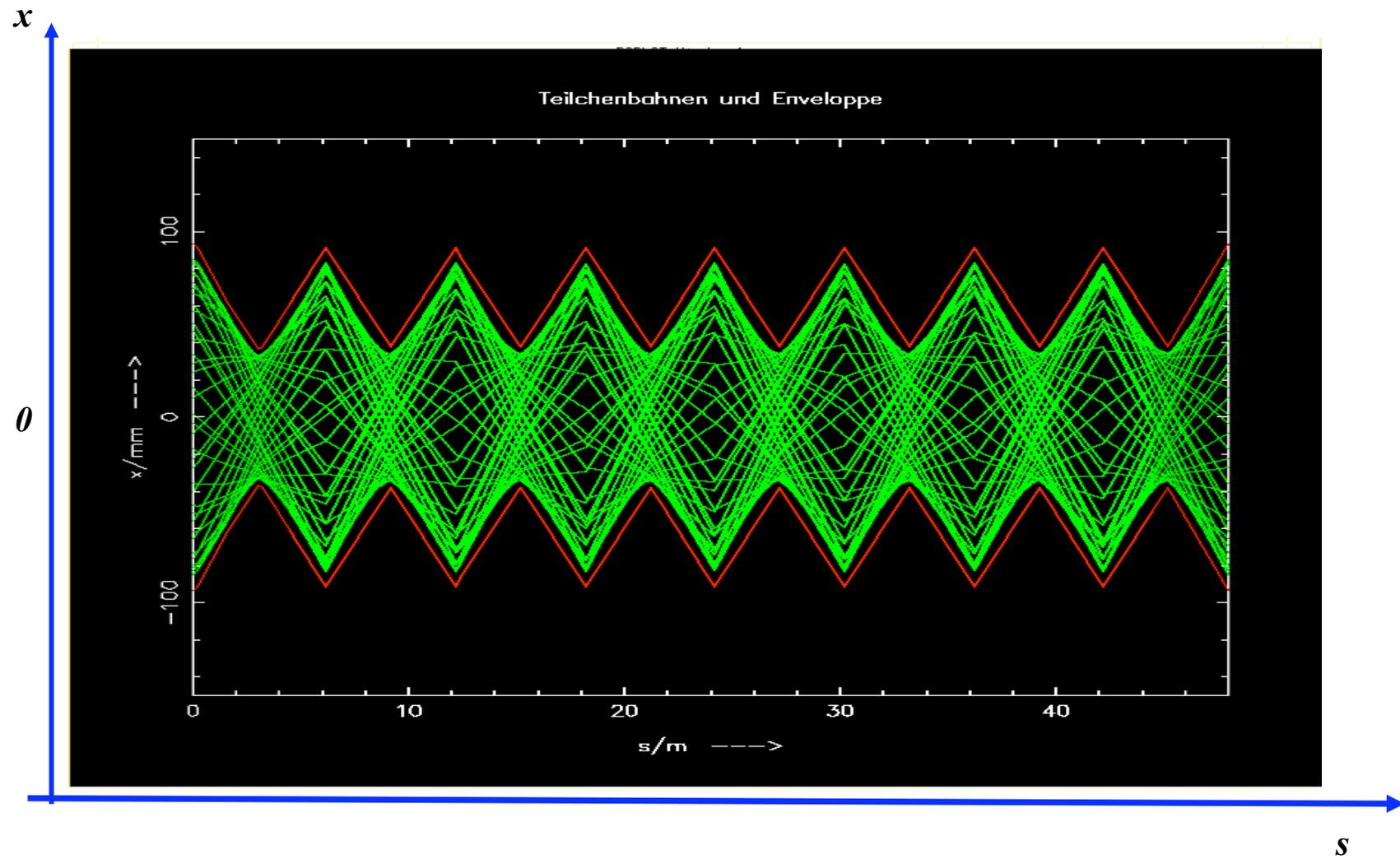


*Beam 1 on OTR screen
1st and 2nd turn*



Question: what will happen, if the particle performs a second turn ?

... or a third one or ... 10^{10} turns



Résumé:

beam rigidity:

$$B \cdot \rho = \frac{p}{q}$$

bending strength of a dipole:

$$\frac{1}{\rho} [m^{-1}] = \frac{0.2998 \cdot B_0(T)}{p(\text{GeV}/c)}$$

focusing strength of a quadrupole:

$$k [m^{-2}] = \frac{0.2998 \cdot g}{p(\text{GeV}/c)}$$

focal length of a quadrupole:

$$f = \frac{1}{k \cdot l_q}$$

equation of motion:

$$x'' + Kx = \frac{1}{\rho} \frac{\Delta p}{p}$$

matrix of a foc. quadrupole:

$$x_{s2} = M \cdot x_{s1}$$

$$M = \begin{pmatrix} \cos \sqrt{|K|}l & \frac{1}{\sqrt{|K|}} \sin \sqrt{|K|}l \\ -\sqrt{|K|} \sin \sqrt{|K|}l & \cos \sqrt{|K|}l \end{pmatrix}, \quad M = \begin{pmatrix} 1 & 0 \\ \frac{1}{f} & 1 \end{pmatrix}$$

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