# The remote positioning of the LHC low beta triplets

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# Abstract

Because of tight alignment tolerances and severe environment (high radiation fluxes and magnetic fields), the LHC low beta quadrupoles are equipped with permanent instrumentation and are supported by motorized jacks, allowing their remote positioning thanks to the sensors' readings.

This poster describes the alignment systems, the motorized jacks as well as the first results obtained.





Alignment tolerances for the LHC low beta triplets:

- positioning of one triplet w.r.t. the other: ± 0.3 mm (3 sigma)

- stability of one quadrupole inside its triplet: a few microns

# Monitoring and Repositioning Systems

Hydrostatic Levelling System (HLS)

• based on the principle of communicating vessels

### Wire Positioning System (WPS)



• bi-axial measurement device

• horizontal plane: wire is a straight line

• vertical plane: wire follows a catenary

#### **Motorized Jacks**





- reference surface is the water network
- a sensor is fitted to each vessel
- measurement of distance to the free surface of water





resolution: 0.1 micron
range: 5 mm
repeatability: 1 micron
bandwidth: up to 10 Hz

resolution: 0.2 micron
range: 10 mm x 10 mm
repeatability: 1 micron
bandwidth: up to 10 Hz

curve



Radial Adapter Angular encoder Vertical Adapter Angular encoder Heducer Angular encoder system

- modified LHC cryo-magnets jacks, with two mechanical interfaces (traverse and vertical adaptors)
- $\bullet$  minimum effective movement 10 micron, range ± 2 mm
- motor mounting time less than 15 minutes

# Configuration



## Results



Monitoring of low beta magnets

