

CERN Accelerator School

Beam Dynamics and Technologies for Future Colliders

Zürich, Switzerland, 21. Feb. – 6. Mar. 2018

Normal-conducting & Permanent Magnets

Thomas Zickler

CERN



Scope of this lecture



The **main goal** is to provide an overview on 'room temperature' magnets (i.e. normal-conducting, iron-dominated electro-magnets and permanent magnets), to introduce recent innovative concepts and encourage you to take on the challenge developing new ideas for future colliders

Outline

Magnet basics:

- Producing magnetic fields
- Magnet technologies
- Describing magnetic fields
- Magnet types in accelerators

Magnets for future colliders:

- Limitations in conventional magnet designs
- Why RT magnets in future colliders?
- New concepts for future colliders taking the example of FCC-ee & CLIC





Acknowledgements

Many thanks ...

... to all my colleagues who contributed to this lecture, in particular:

A.Milanese, M.Bohdanowicz (CERN)
for the slides on [FCC-ee Dipole and Quadrupole Magnets](#)

A.Aloev, A.Bartalesi, R.Leuxe, C.Lopez, E.Solodko, M.Struik, P.Thonet, A.Vorozhtsov (CERN)
for the slides on [CLIC Main Beam and Final Focusing Magnets](#)

A.Bainbridge, B.Shepherd, N.Collomb, J.Clark (STFC Daresbury Laboratory, UK)
for the slides on [Tuneable Permanent Dipole and Quadrupole Magnets](#)



Magnetic units



IEEE defines the following units:

- **Magnetic field:**

- H (vector) [A/m]
- the magnetizing force produced by electric currents

- **Electromotive force:**

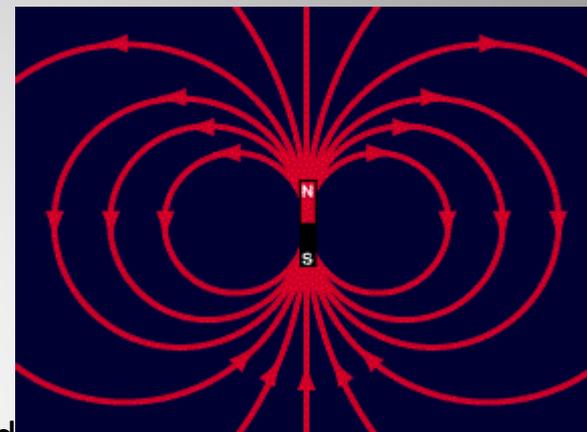
- e.m.f. or U [V or $(\text{kg m}^2)/(\text{A s}^3)$]
- here: voltage generated by a time varying magnetic field

- **Magnetic flux density or magnetic induction:**

- B (vector) [T or $\text{kg}/(\text{A s}^2)$]
- the density of magnetic flux driven through a medium by the magnetic field
- Note: induction is frequently referred to as "Magnetic Field"
- H , B and μ relates by: $B = \mu H$

- **Permeability:**

- $\mu = \mu_0 \mu_r$
- permeability of free space $\mu_0 = 4 \pi 10^{-7}$ [V s/A m]
- relative permeability μ_r (dimensionless): $\mu_{\text{air}} = 1$; $\mu_{\text{iron}} > 1000$ (not saturated)

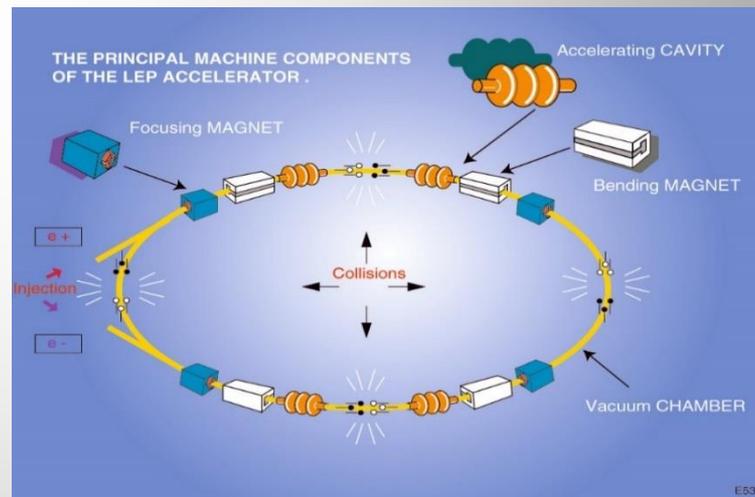
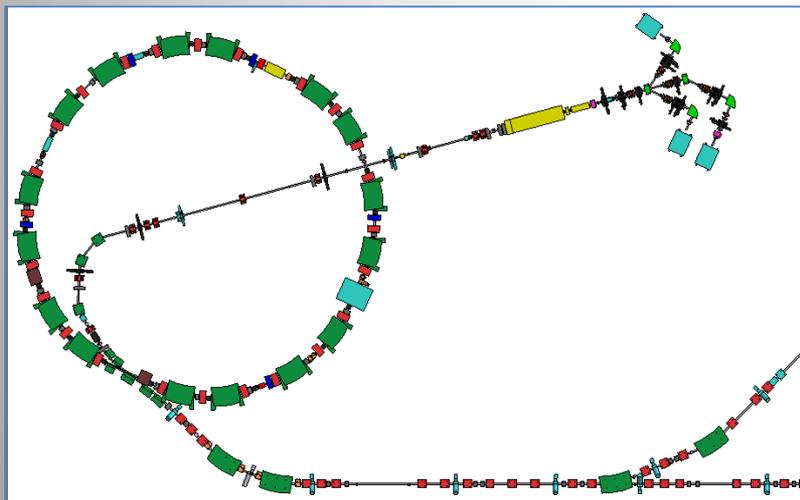




Why do we need magnets?



- Interaction with the beam
 - guide the beam to keep it on the orbit
 - focus and shape the beam
- Lorentz's force: $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$
 - for relativistic particles this effect is equivalent if $\vec{E} = c\vec{B}$
 - if $B = 1 \text{ T}$ then $E = 3 \cdot 10^8 \text{ V/m(!)}$



- Permanent magnets provide only constant magnetic fields
- Electro-magnets can provide adjustable magnetic fields



Maxwell's equations



In 1873, **Maxwell** published "Treatise on Electricity and Magnetism" in which he summarized the discoveries of Coulomb, Oersted, Ampere, Faraday, et. al. in four mathematical equations:

Gauss' law for electricity:

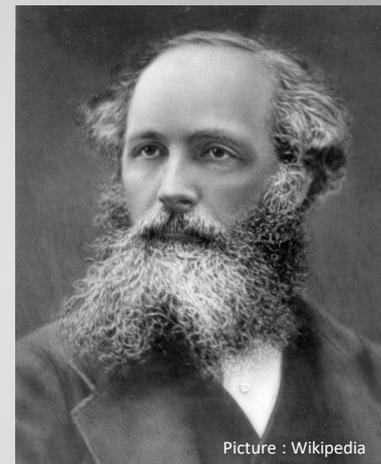
$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\oint_{\partial V} \vec{E} \cdot d\vec{A} = \frac{q}{\epsilon_0}$$

Gauss' law of flux conservation:

$$\nabla \cdot \vec{B} = 0$$

$$\oint_{\partial V} \vec{B} \cdot d\vec{A} = 0$$



Picture : Wikipedia

Faraday's law of induction:

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\oint_{\partial A} \vec{E} \cdot d\vec{s} = -\frac{d\Phi}{dt} = -\frac{d}{dt} \int_A \vec{B} \cdot d\vec{A}$$

Ampere's law:

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\oint_{\partial A} \vec{B} \cdot d\vec{s} = \int_A \mu_0 \vec{J} \cdot d\vec{A} + \frac{d}{dt} \int_A \mu_0 \epsilon_0 \vec{E} \cdot d\vec{A}$$



Maxwell's equations



Gauss' law for electricity:

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

Gauss' law of flux conservation:

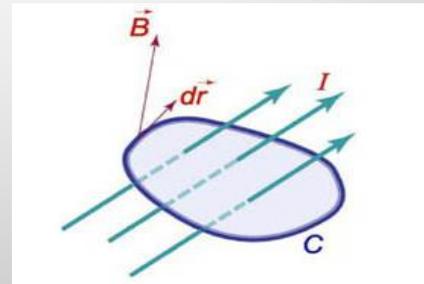
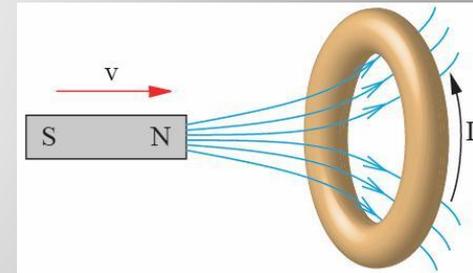
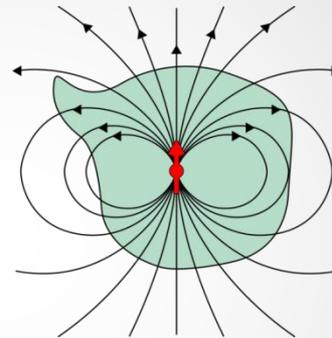
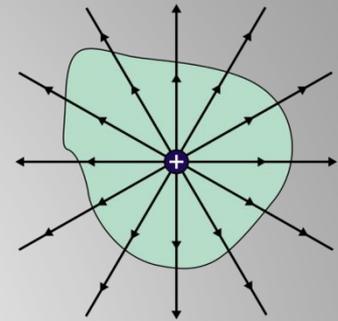
$$\nabla \cdot \vec{B} = 0$$

Faraday's law of induction:

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

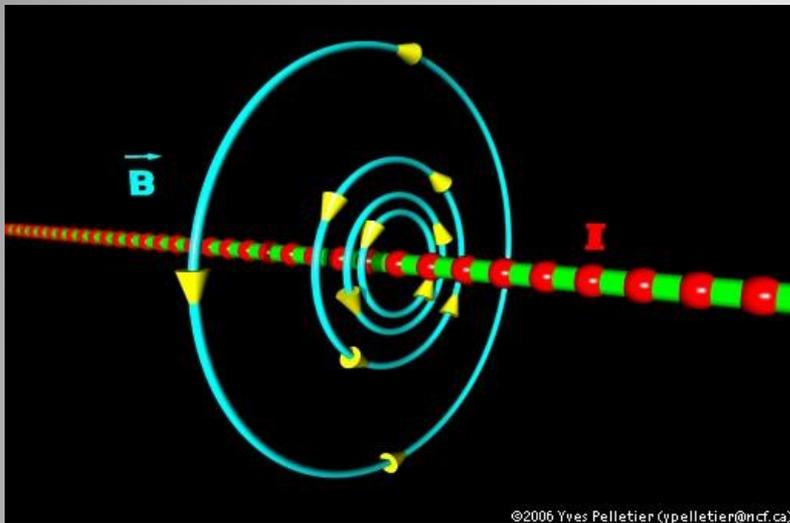
Ampere's law:

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$





Producing the field

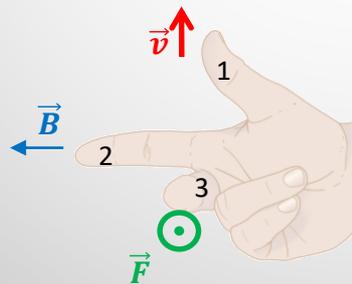
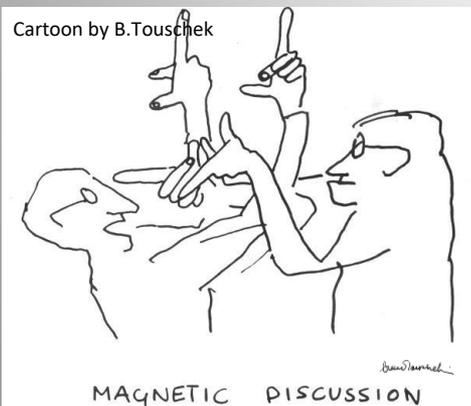


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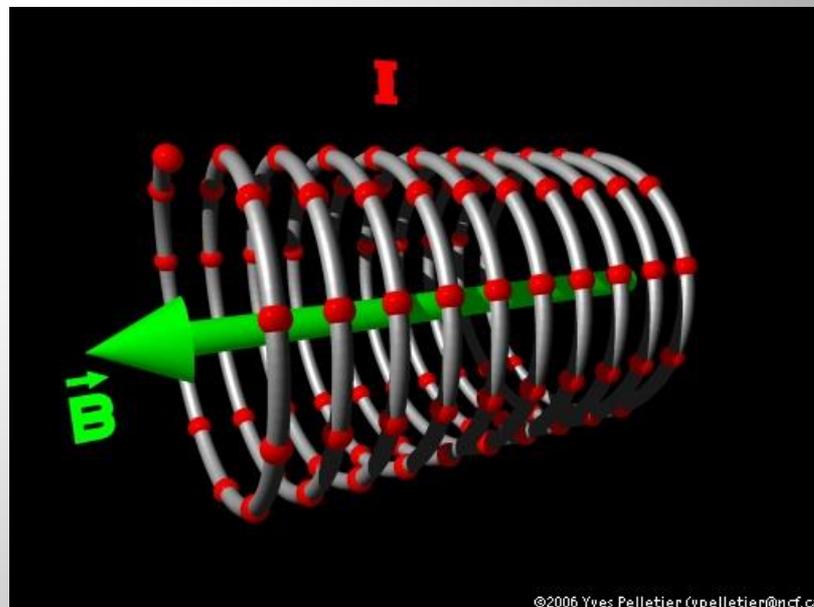
Maxwell & Ampere:

$$\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

„An electrical current is surrounded by a magnetic field“



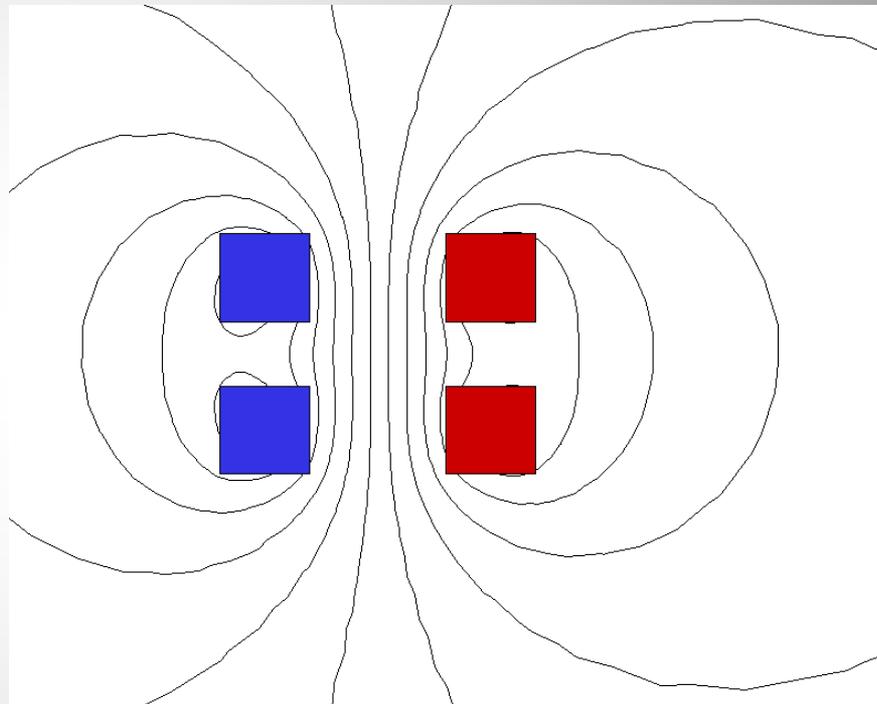
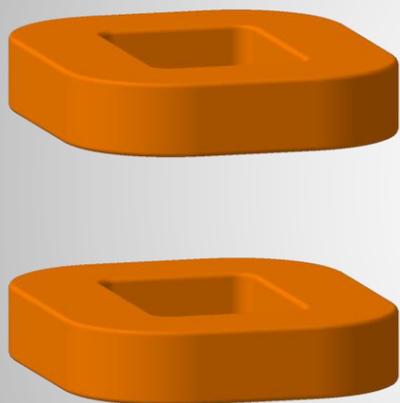
„Right hand rule“ applies



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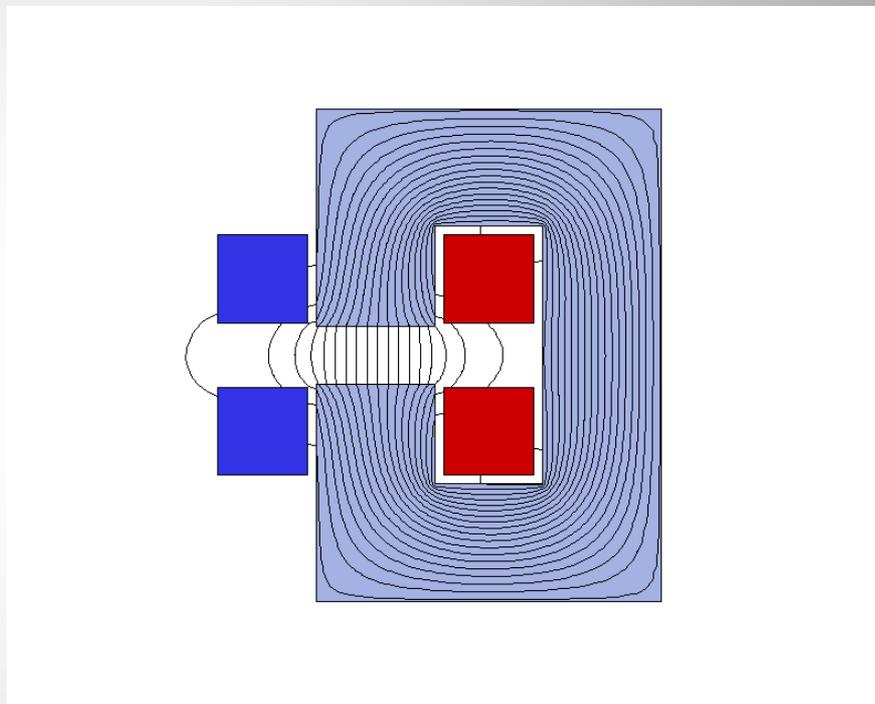
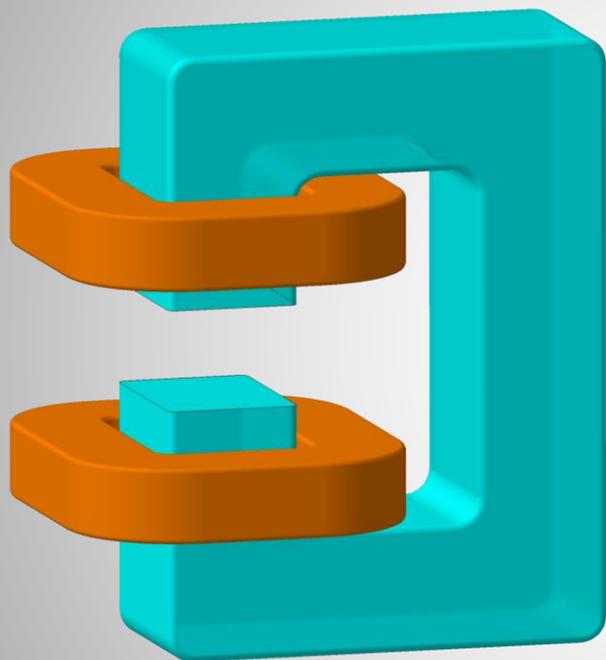
Magnetic circuit



Flux lines represent the magnetic field
Coil colors indicate the current direction



Magnetic circuit



Coils hold the electrical current which induces a magnetic effect

Iron enhance these effects and guides the magnetic flux

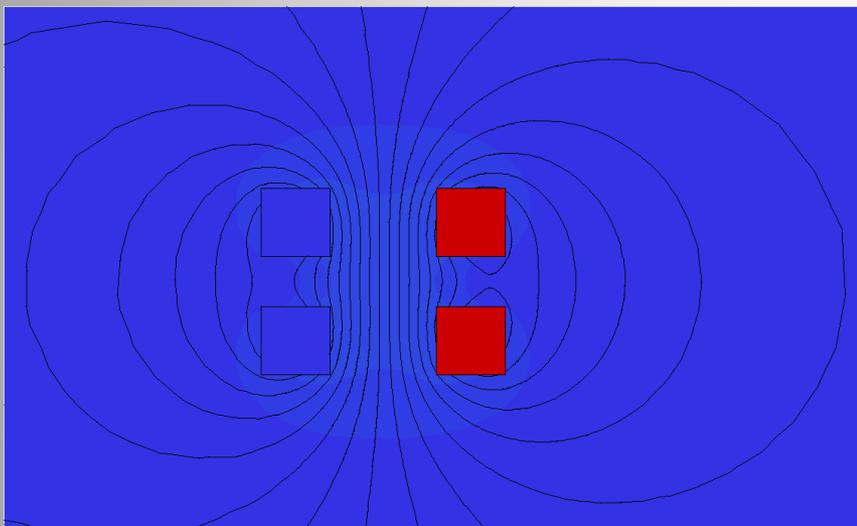
→ “iron-dominated magnet”



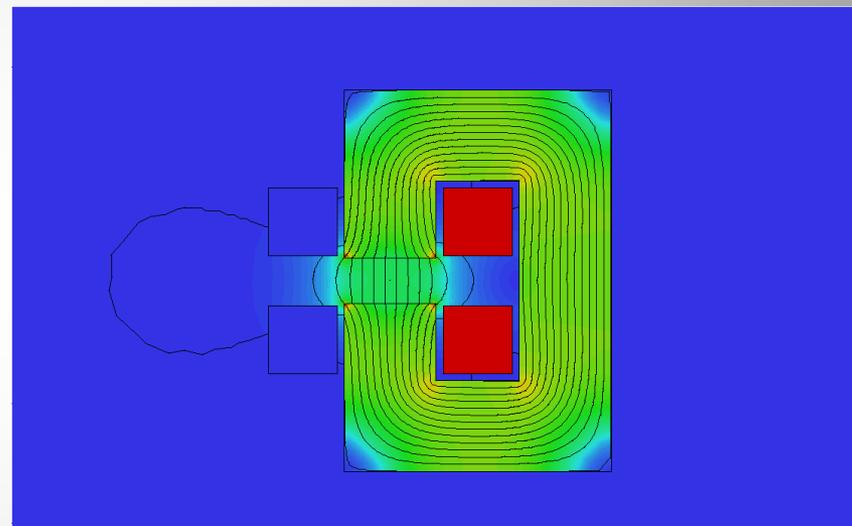
Magnetic circuit



$I = 32 \text{ kA}$
 $B_{\text{centre}} = 0.09 \text{ T}$



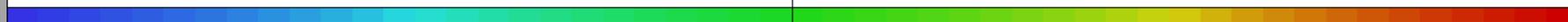
$I = 32 \text{ kA}$
 $B_{\text{centre}} = 0.80 \text{ T}$



Component: BMOD
 0.0

1.0

2.0



The presence of a magnetic circuit can increase the flux density in the magnet aperture by factors



Excitation current in a dipole



Ampere's law $\oint \vec{H} \cdot d\vec{l} = NI$ and $\vec{B} = \mu\vec{H}$

leads to
$$NI = \oint \frac{\vec{B}}{\mu} \cdot d\vec{l} = \int_{gap} \frac{\vec{B}}{\mu_{air}} \cdot d\vec{l} + \int_{yoke} \frac{\vec{B}}{\mu_{iron}} \cdot d\vec{l} = \frac{Bh}{\mu_{air}} + \frac{B\lambda}{\mu_{iron}}$$

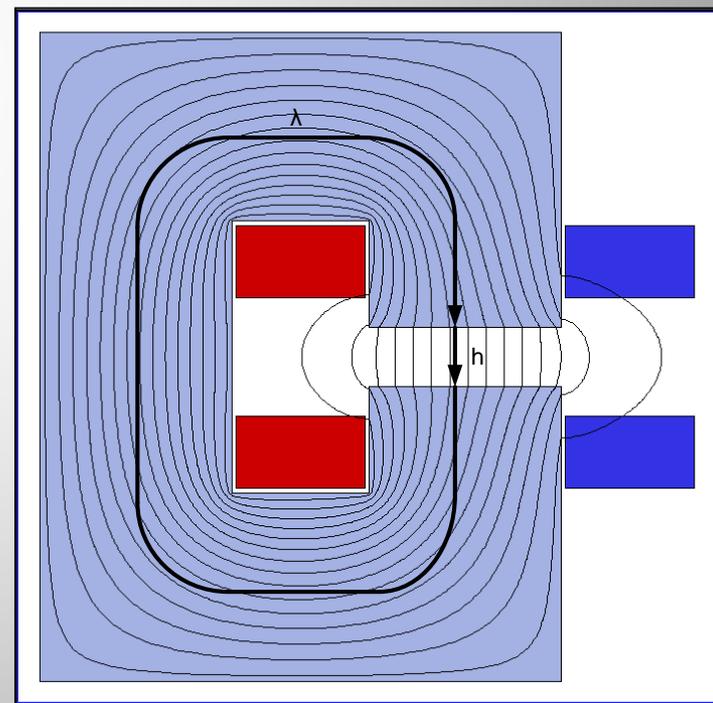
assuming, that B is constant along the path.

If the iron is not saturated: $\frac{h}{\mu_{air}} \gg \frac{\lambda}{\mu_{iron}}$

then:
$$NI \approx \frac{Bh}{\mu_0}$$

$$P_{dip} = \rho NI j l_{avg}$$

- h : gap height [m]
- j : current density [A/m²]
- ρ : conductor resistivity [Ωm]
- l_{avg} : avg. length of coil [m]





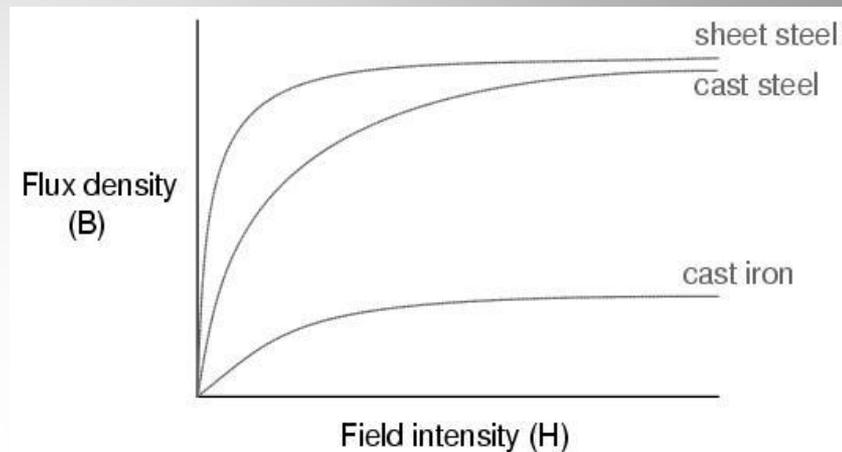
Permeability



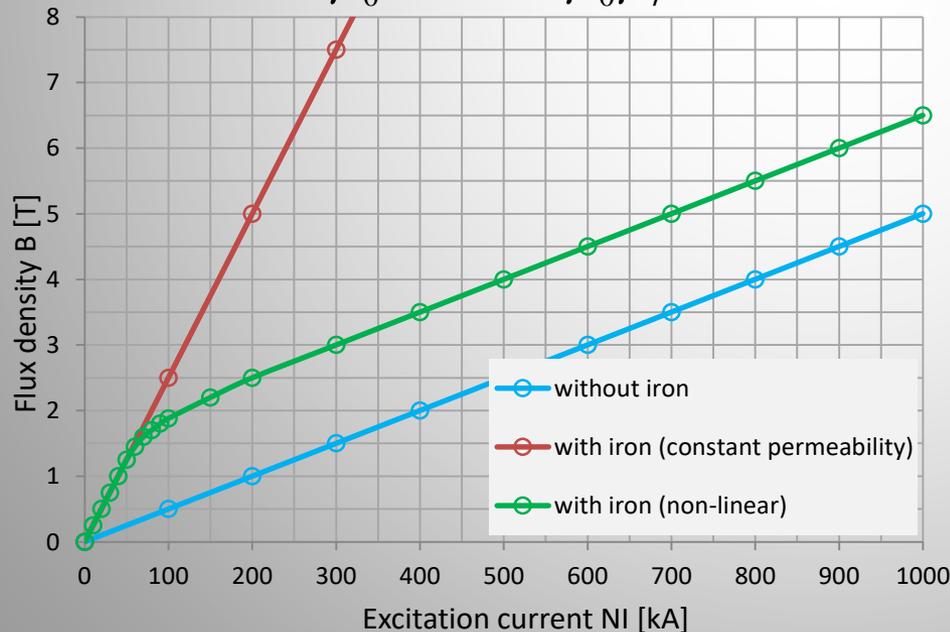
$$\vec{B} = \mu \vec{H}$$

$$\mu = \mu_0 \mu_r$$

Permeability: correlation between magnetic field strength H and magnetic flux density B



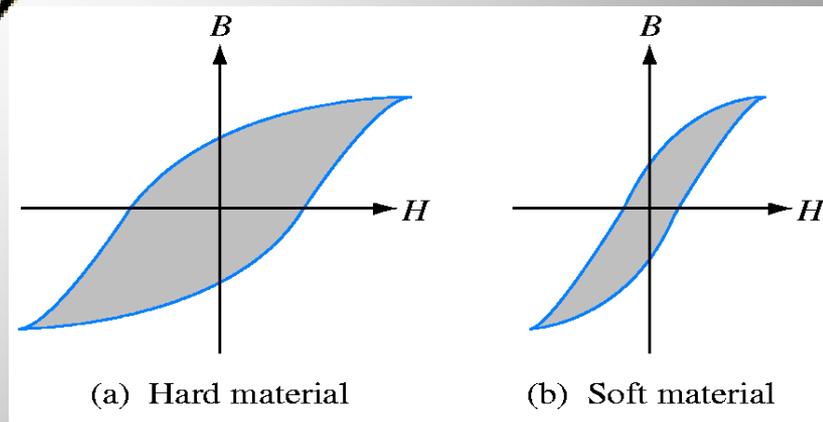
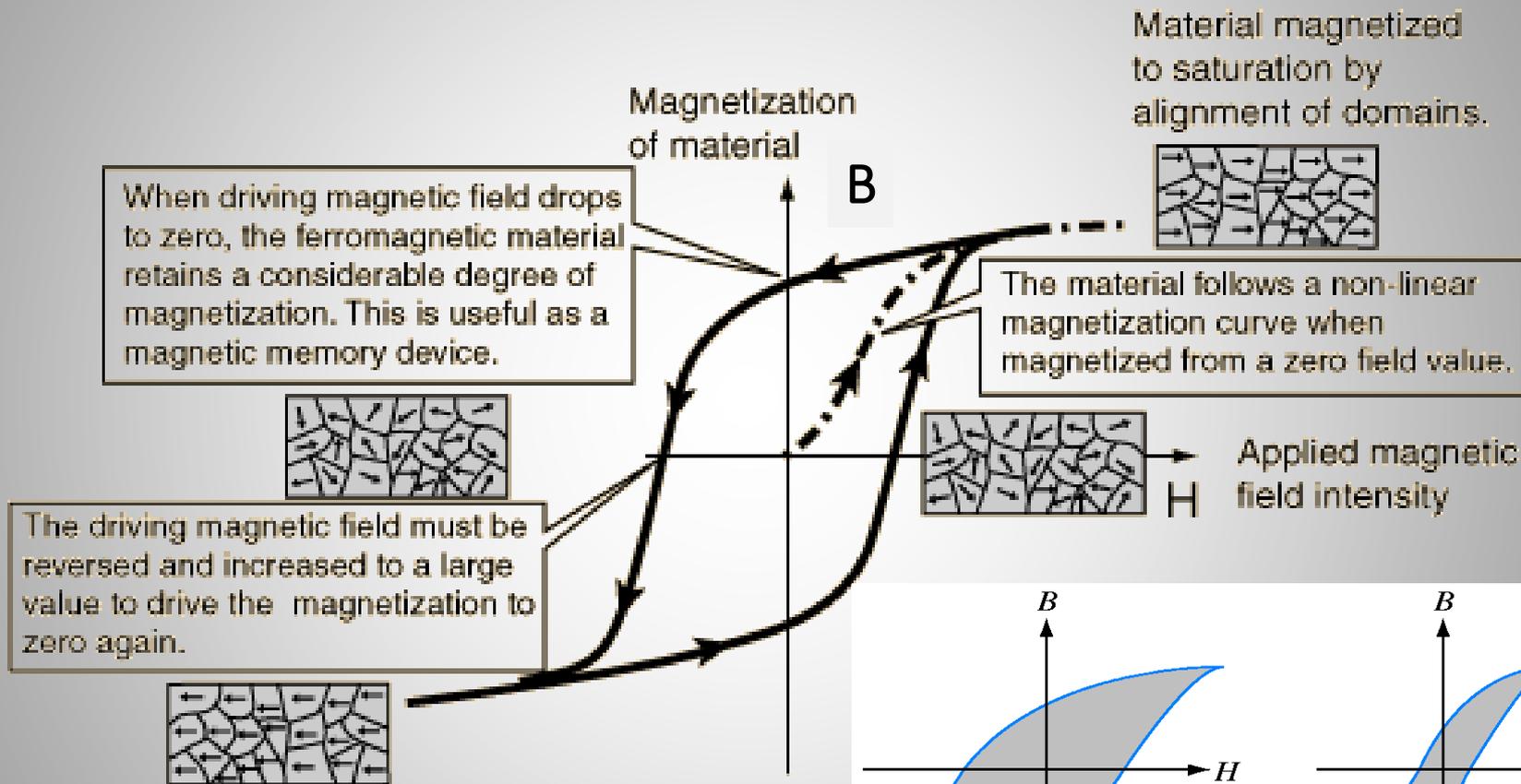
$$\vec{B} = \mu_0 \vec{H} + \vec{J} = \mu_0 \mu_r \vec{H}$$



Ferro-magnetic materials: high permeability ($\mu_r \gg 1$), but not constant

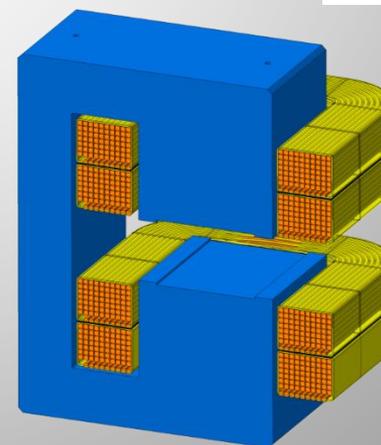
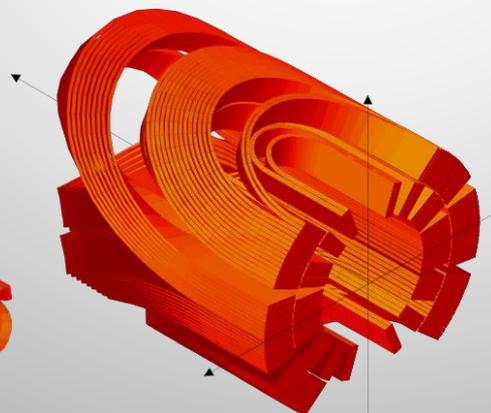
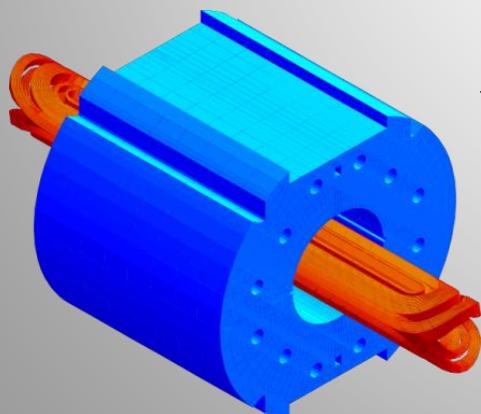
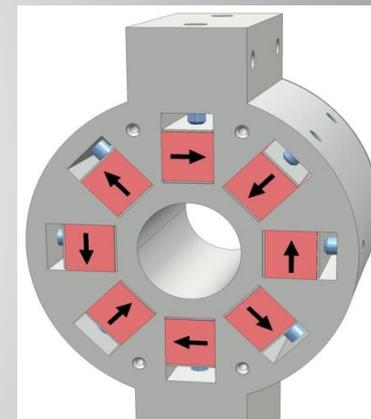
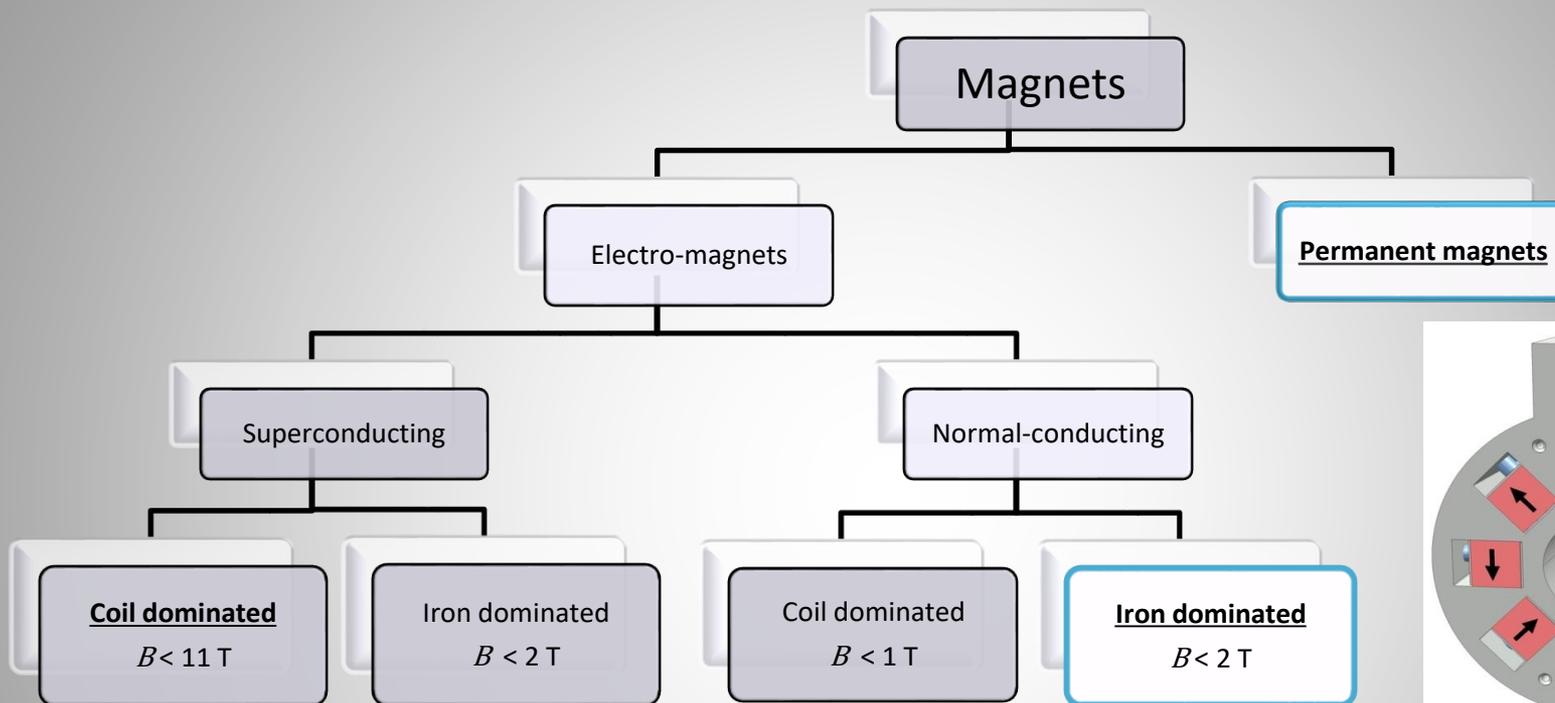


Hysteresis & Coercivity





Magnet technologies



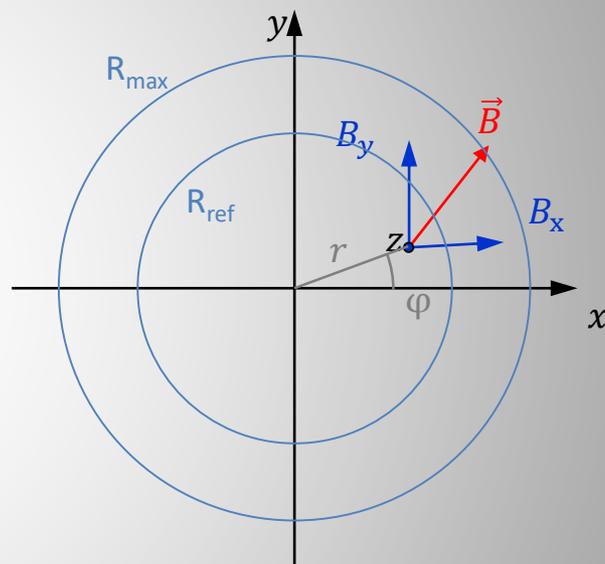
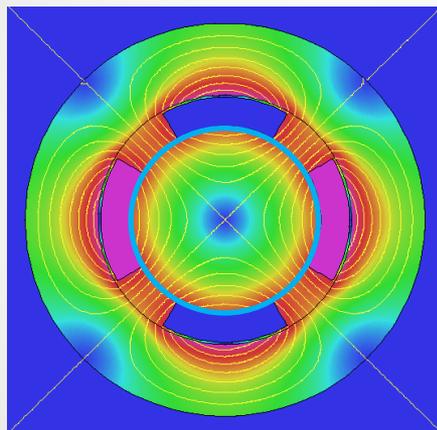
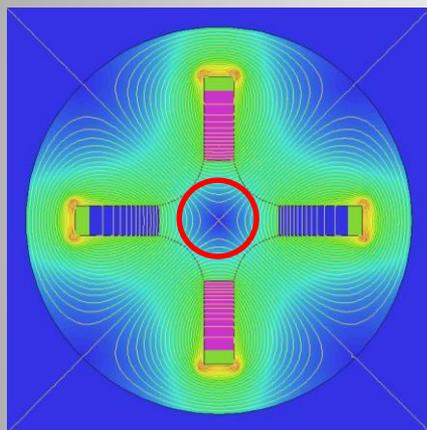


Field description



How can we conveniently describe the field in the aperture?

- at any point (in 2D) $z = x + iy = re^{i\varphi}$
- for any field configuration
- regardless of the magnet technology



Solution: multipole expansion, describing the field within a **circle of validity** with **scalar coefficients**

$$B_y(z) + iB_x(z) = \sum_{n=1}^{\infty} (B_n + iA_n) \left(\frac{z}{R_{ref}} \right)^{n-1}$$



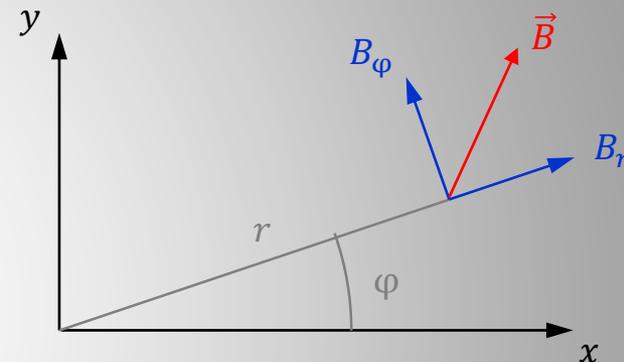
Field description



For radial and tangential components of the field the series contains sin and cos terms (Fourier decomposition):

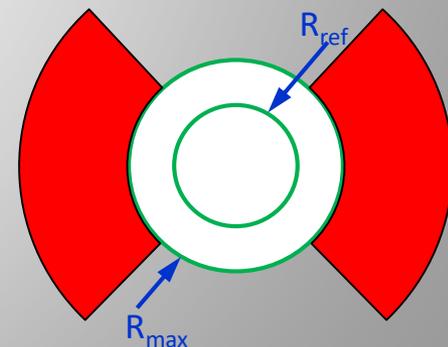
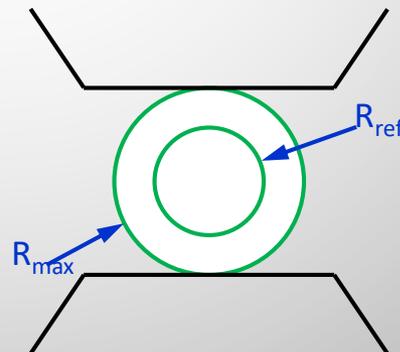
$$B_r(r, \varphi) = \sum_{n=1}^{\infty} \left(\frac{r}{R_{ref}} \right)^{n-1} [B_n \sin(n\varphi) + A_n \cos(n\varphi)]$$

$$B_\varphi(r, \varphi) = \sum_{n=1}^{\infty} \left(\frac{r}{R_{ref}} \right)^{n-1} [B_n \cos(n\varphi) - A_n \sin(n\varphi)]$$



This 2D decomposition holds only in a region of space:

- without magnetic materials ($\mu_r = 1$)
- without currents
- when B_z is constant



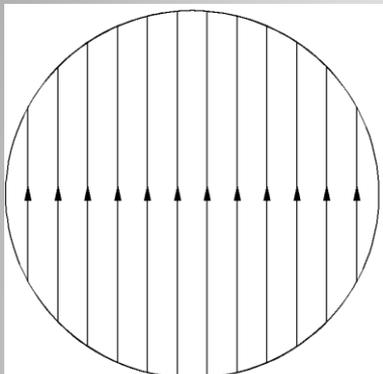


Field description

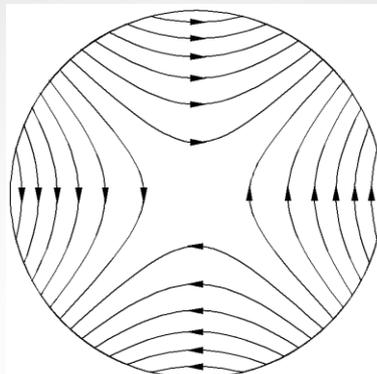


Each multipole term has a corresponding magnet type:

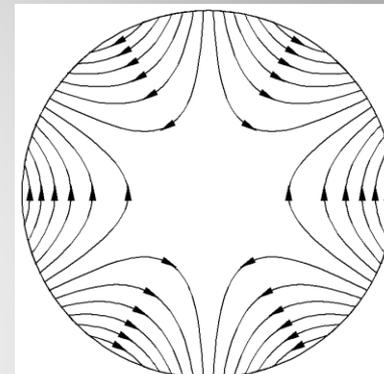
B_1 : normal dipole



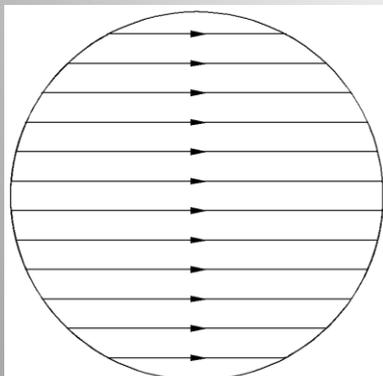
B_2 : normal quadrupole



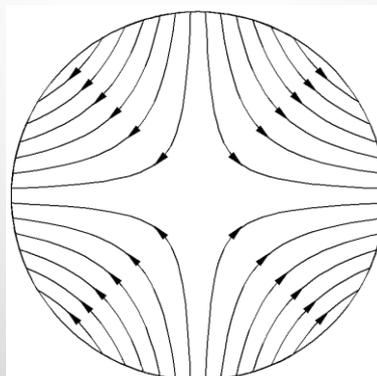
B_3 : normal sextupole



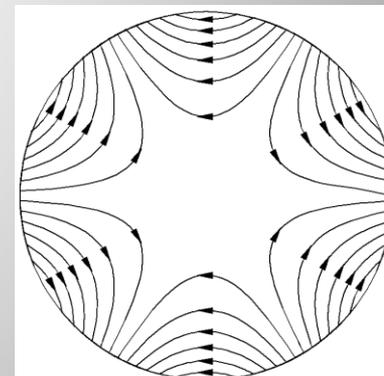
A_1 : skew dipole



A_2 : skew quadrupole



A_3 : skew sextupole



Vector equipotential lines are flux lines. \vec{B} is tangent point by point to the flux lines
Scalar equipotential lines are orthogonal to the vector equipotential lines. They define the boundary conditions for shaping the field (for iron-dominated magnets).



Field quality



Taking

$$B_y(z) + iB_x(z) = \sum_{n=1}^{\infty} (B_n + iA_n) \left(\frac{z}{R_{ref}} \right)^{n-1}$$

and introducing **dimensionless normalized multipole coefficients**

$$b_n = \frac{B_n}{B_N} 10^4 \quad \text{and} \quad a_n = \frac{A_n}{B_N} 10^4$$

with B_N being the fundamental field of a magnet: $B_{N(\text{dipole})} = B_1$; $B_{N(\text{quad})} = B_2$; ...

we can describe each magnet by its ideal fundamental field and higher order harmonic distortions:

$$B_y(z) + iB_x(z) = \frac{B_N}{10^4} \sum_{n=1}^{\infty} (b_n + ia_n) \left(\frac{z}{R_{ref}} \right)^{n-1}$$

Fundamental field

Harmonic distortions

$$F_d = \sum_{n=1; n \neq N}^K \sqrt{b_n^2 + a_n^2}$$

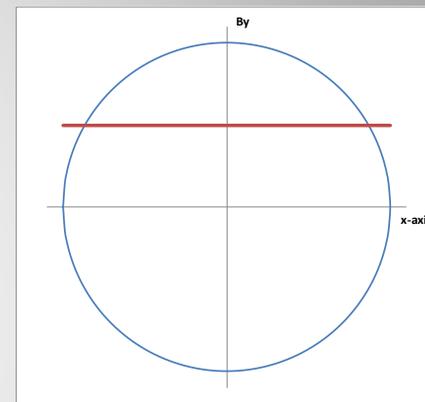
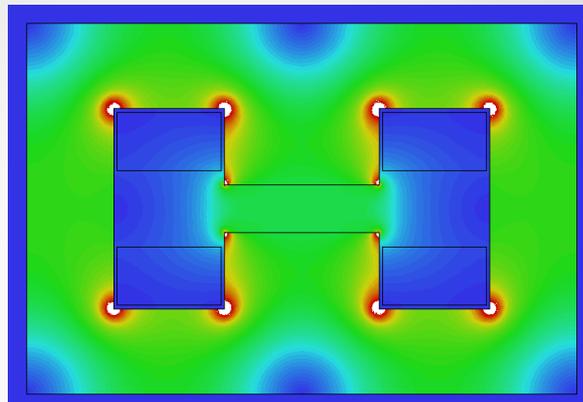
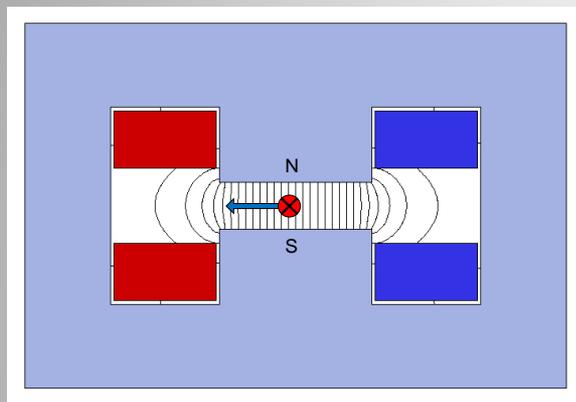
Harmonic distortion factor



Dipole



Purpose: bend or steer the particle beam



Equation for normal (non-skew) ideal (infinite) poles: $y = \pm h/2$

- Straight line ($h = \text{gap height}$)

Magnetic flux density: $B_x = 0$; $B_y = B_1 = \text{const.}$

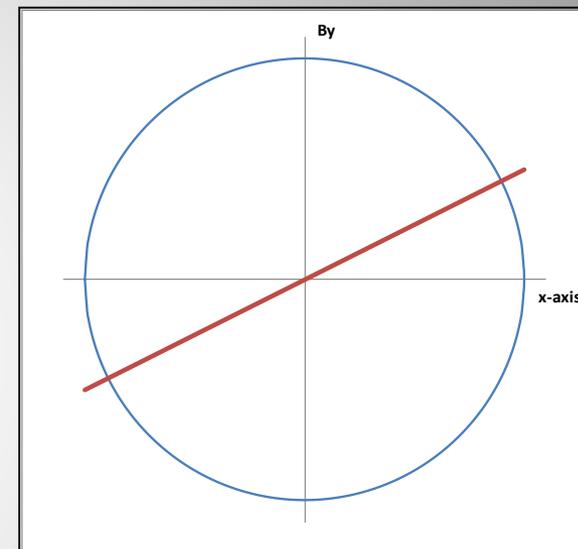
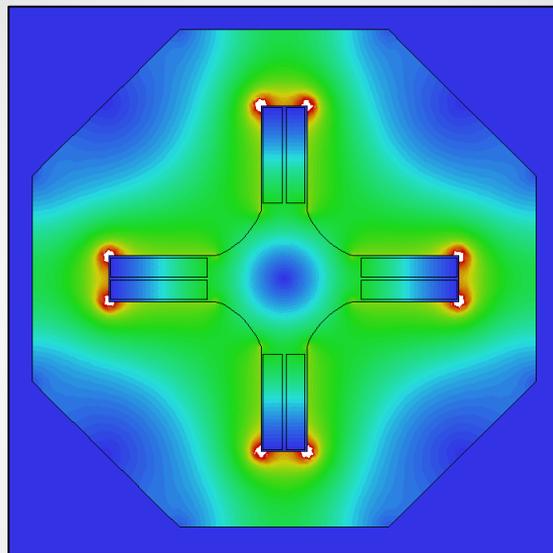
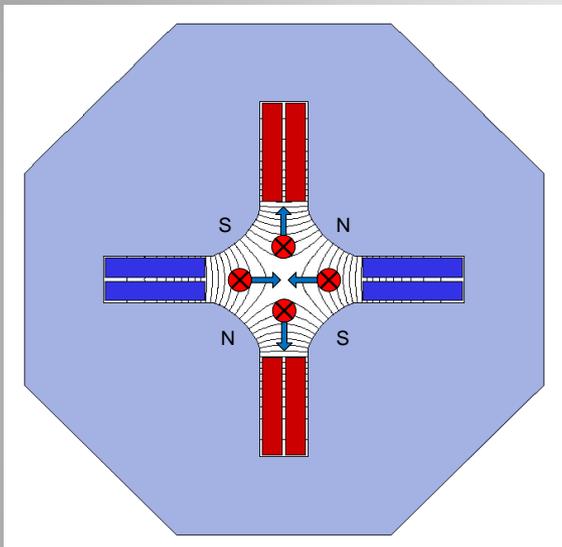
$$B_y(x) = \sum_{n=1}^{\infty} B_n \left(\frac{x}{R_{ref}} \right)^{n-1} = B_1 + B_2 \frac{x}{R_{ref}} + B_3 \left(\frac{x}{R_{ref}} \right)^2 + \dots$$



Quadrupole



Purpose: focusing the beam (horizontally focused beam is vertically defocused)



Equation for normal (non-skew) ideal (infinite) poles: $2xy = \pm r^2$

- Hyperbola ($r =$ aperture radius)

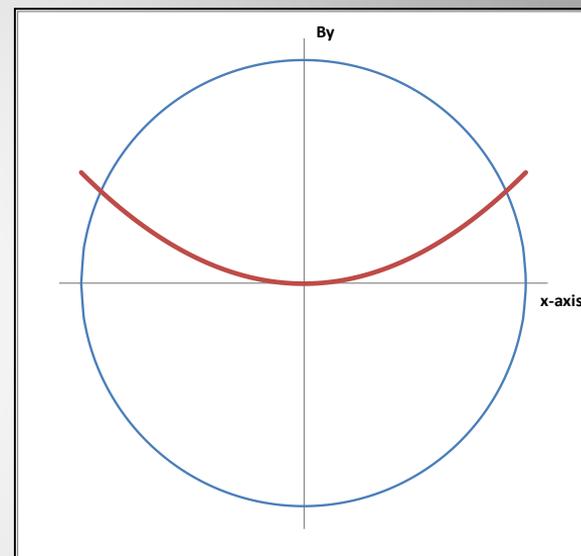
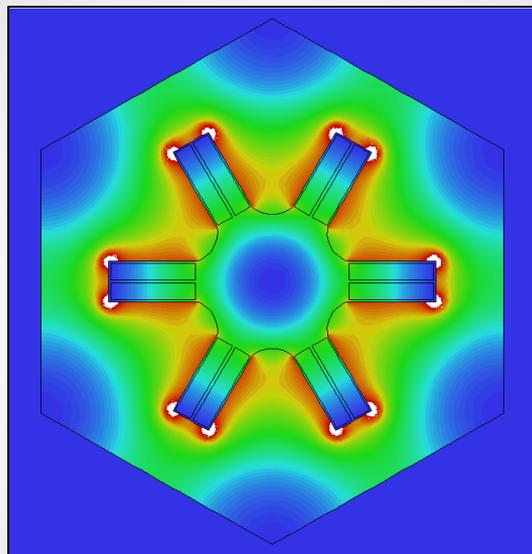
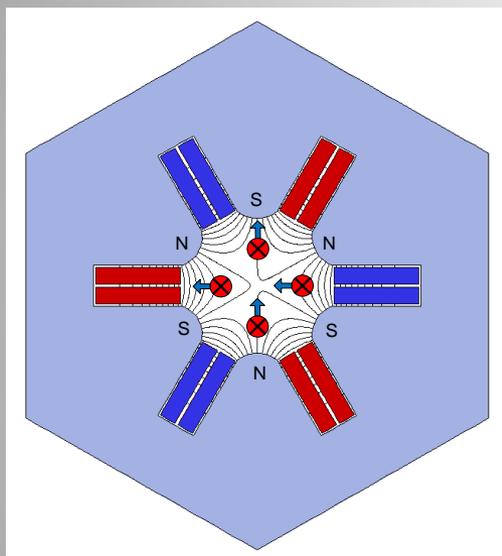
Magnetic flux density: $B_x = \frac{B_2}{R_{ref}} y$; $B_y = \frac{B_2}{R_{ref}} x$



Sextupole



Purpose: correct chromatic aberrations of 'off-momentum' particles

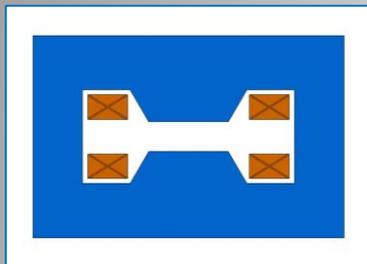


Equation for normal (non-skew) ideal (infinite) poles: $3x^2y - y^3 = \pm r^3$

Magnetic flux density: $B_x = \frac{B_3}{R_{ref}^2} xy$; $B_y = \frac{B_3}{R_{ref}^2} (x^2 - y^2)$



Conventional nc-magnet layout

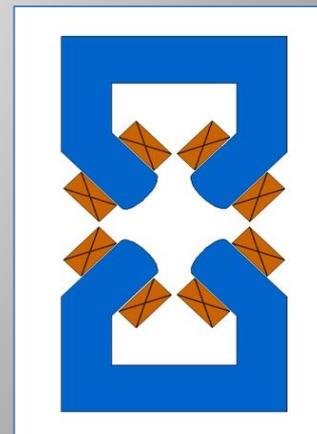
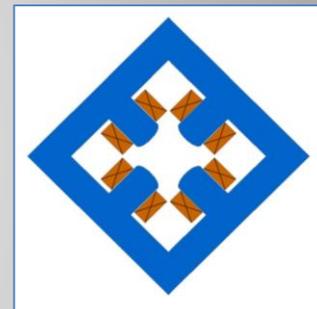
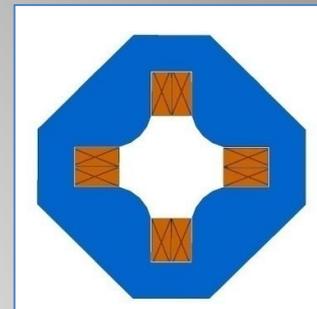
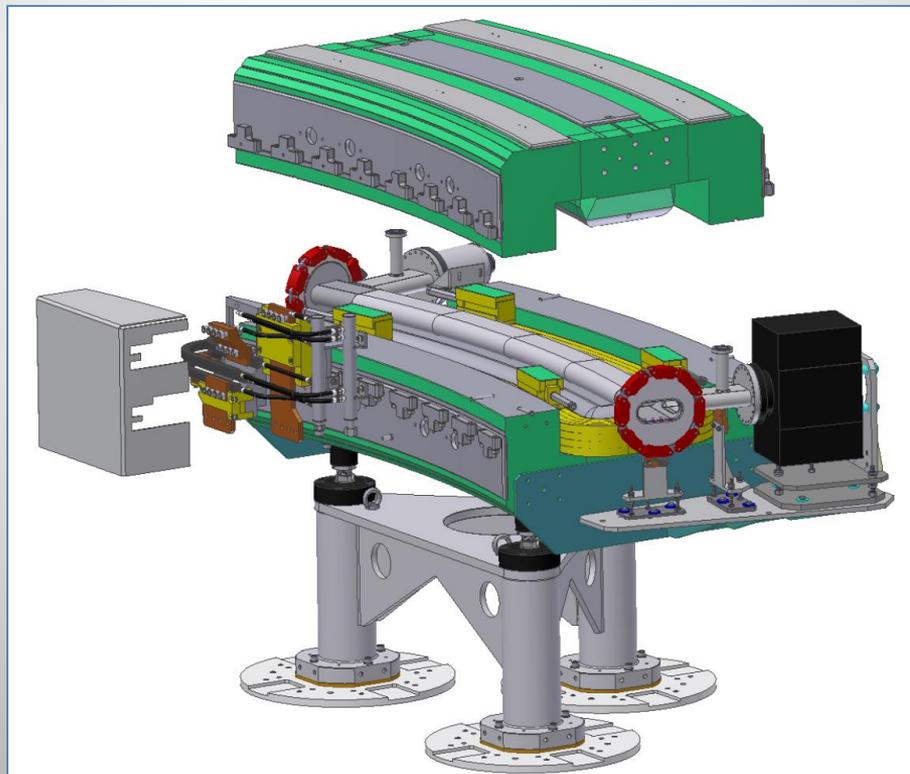
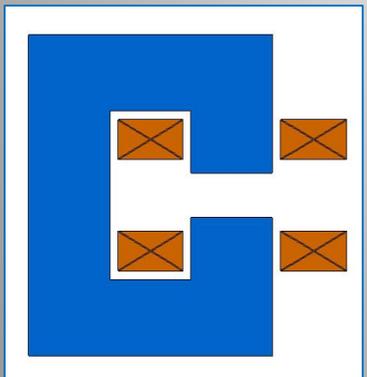
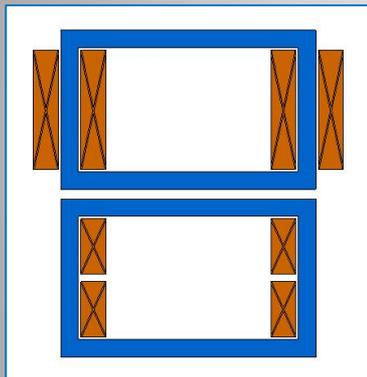


Excitation coils carry the electrical current creating H

Iron yokes guide and enhance the magnetic flux

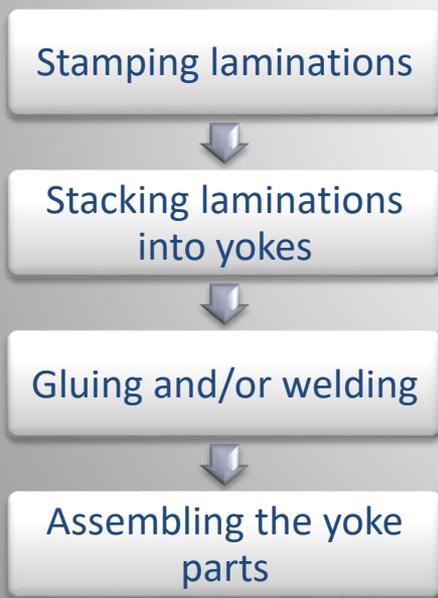
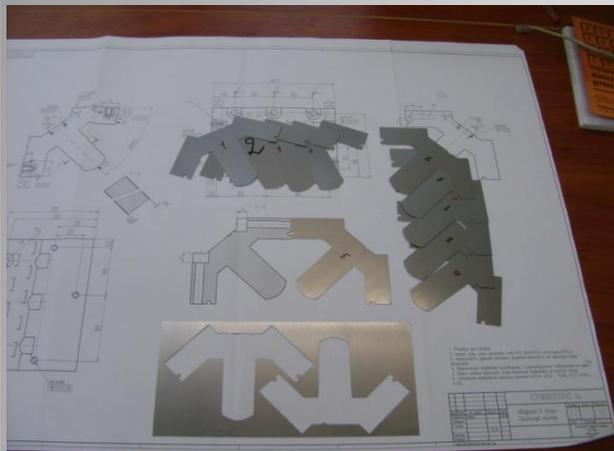
Iron poles shape the magnetic field in the aperture around the particle beam

Auxiliaries for cooling, interlock, safety, alignment, ...





Iron yoke



Advantages:

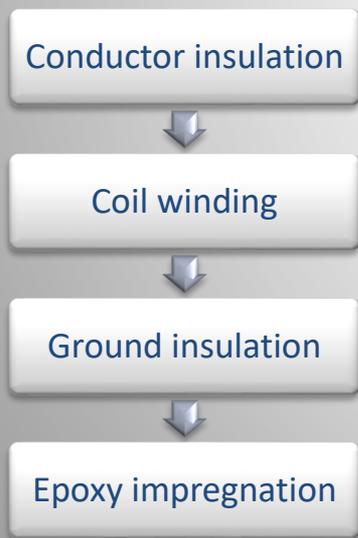
- Well established technology with plenty of experience
- Robust design
- Industrial methods for large series
- Different magnetic materials on the market
- Steel properties are adjustable within a certain range
- Good reproducibility

Limitations:

- Fields limited to 2 T (saturation)
- Field quality dependent on mechanics (machining, assembly)
- Small apertures more sensitive (small tolerances)
- dB/dt limited by eddy current effects
- Steel hysteresis requires magnetic cycling



Excitation coils



Advantages:

- Adjustable magnetic fields
- Well established technology
- Easy accessible and maintainable
- (Almost) no limit in dB/dt
- Conductor commercially available

Limitations:

- Power consumption (ohmic losses)
- Moderate current densities ($j < 10 \text{ A/mm}^2$)
- (Water) cooling required for $j > 2 \text{ A/mm}^2$
- Insulation lifetime (ionizing radiation)
- Reliability of cooling circuits (water leaks)
- Increase the magnet dimensions



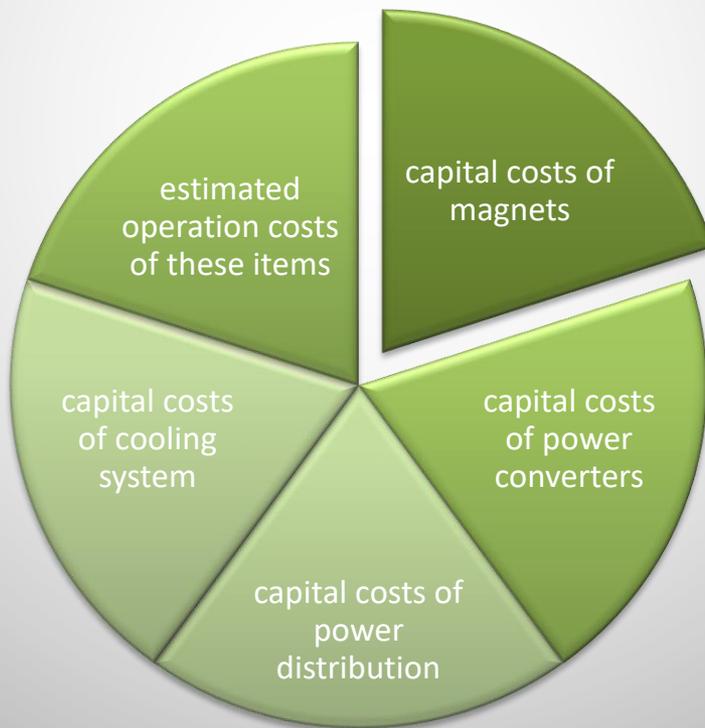
Cost optimization



Focus on economic design!

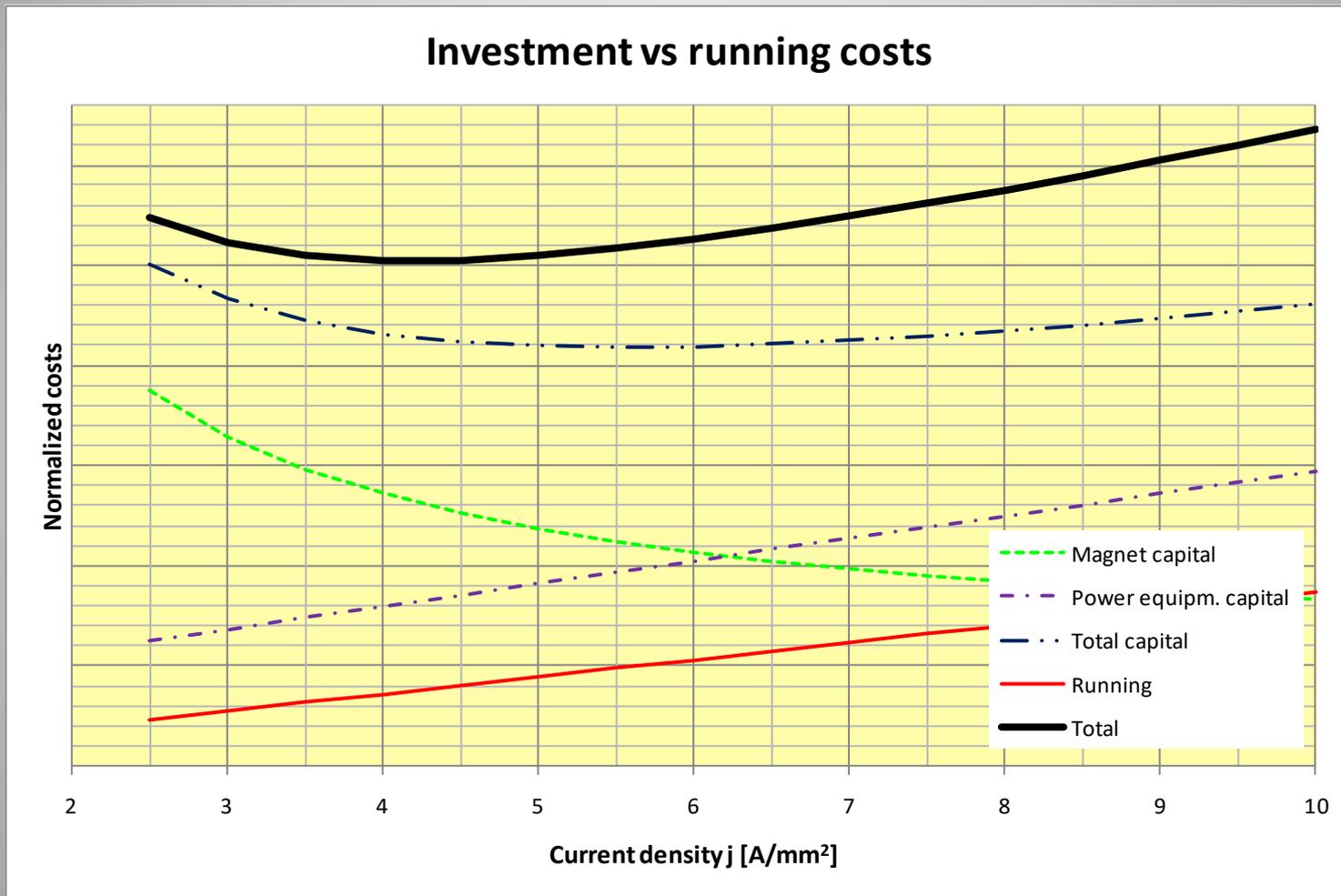
Design goal: Minimum total costs over projected magnet life time by optimization of capital (investment) costs against running costs (power consumption)

Total costs include:



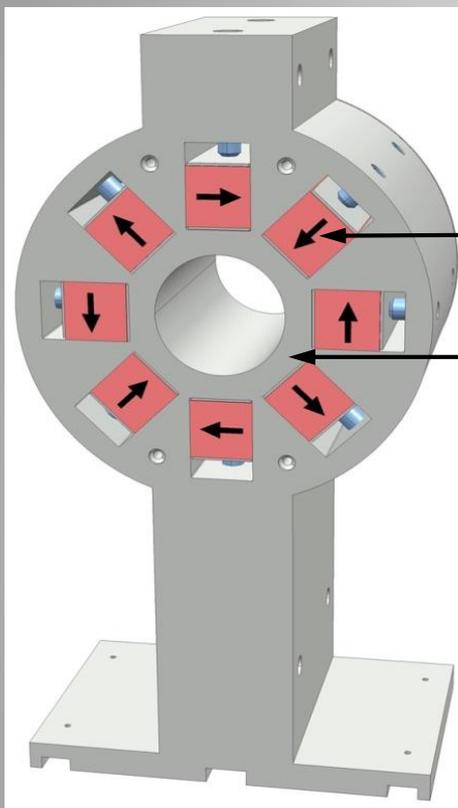


Cost optimization

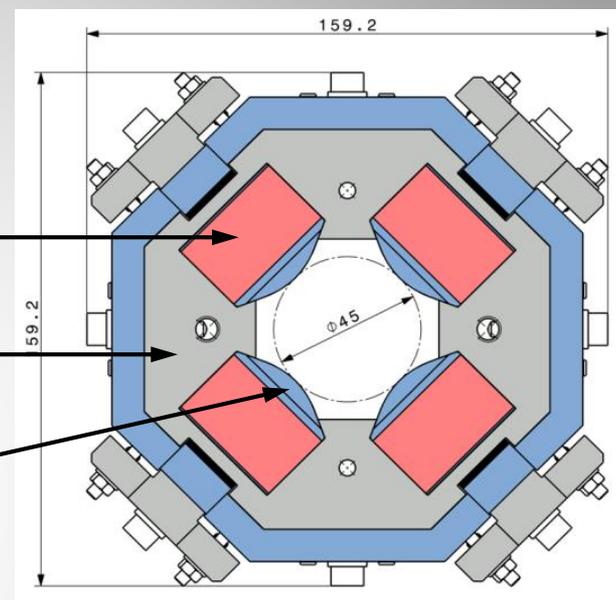




Conventional PM layout



- Permanent magnets
(e.g. $\text{Sm}_2\text{Co}_{17}$)
- Non-magnetic yoke
(e.g. austenitic steel 316LN)
- Magnetic poles
(e.g. low-carbon steel)



Advantages:

- No electrical power consumption
- No powering/cooling network required
- More compact for small magnets
- No coil heads / small fringe field
- Reliable: no risk of insulation failure or water leaks

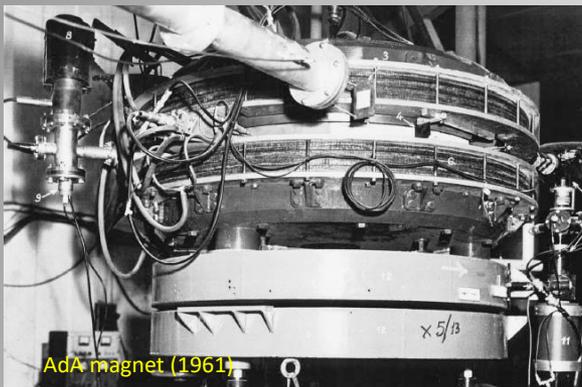
Limitations:

- Produce constant fields only
- Complex mechanics when tuneability required
- Risk of radiation damage (→ use of $\text{Sm}_2\text{Co}_{17}$)
- Sensible to ΔT (→ can be compensated)

$\text{Nd}_2\text{Fe}_{14}\text{B}$	SmCo_5 or $\text{Sm}_2\text{Co}_{17}$
Typical $B_r \approx 1.4$ T	Typical $B_r \approx 1.2$ T
Temp. coef. of $B_r = -0.11\%/^\circ\text{C}$	Temp. coef. of $B_r = -0.03\%/^\circ\text{C}$
Poor corrosion resistance	Good corrosion/radiation resistance



A few examples...



AdA magnet (1961)



ISR dipole (1971) – now in the MM lab



SPS dipoles before installation (1981)



SPS quadrupoles before installation (1981)



Discarded LEP dipole cores (2002)



LEP quadrupole (1989) – now in the MM lab



LHC Lambertson Septum (2008)



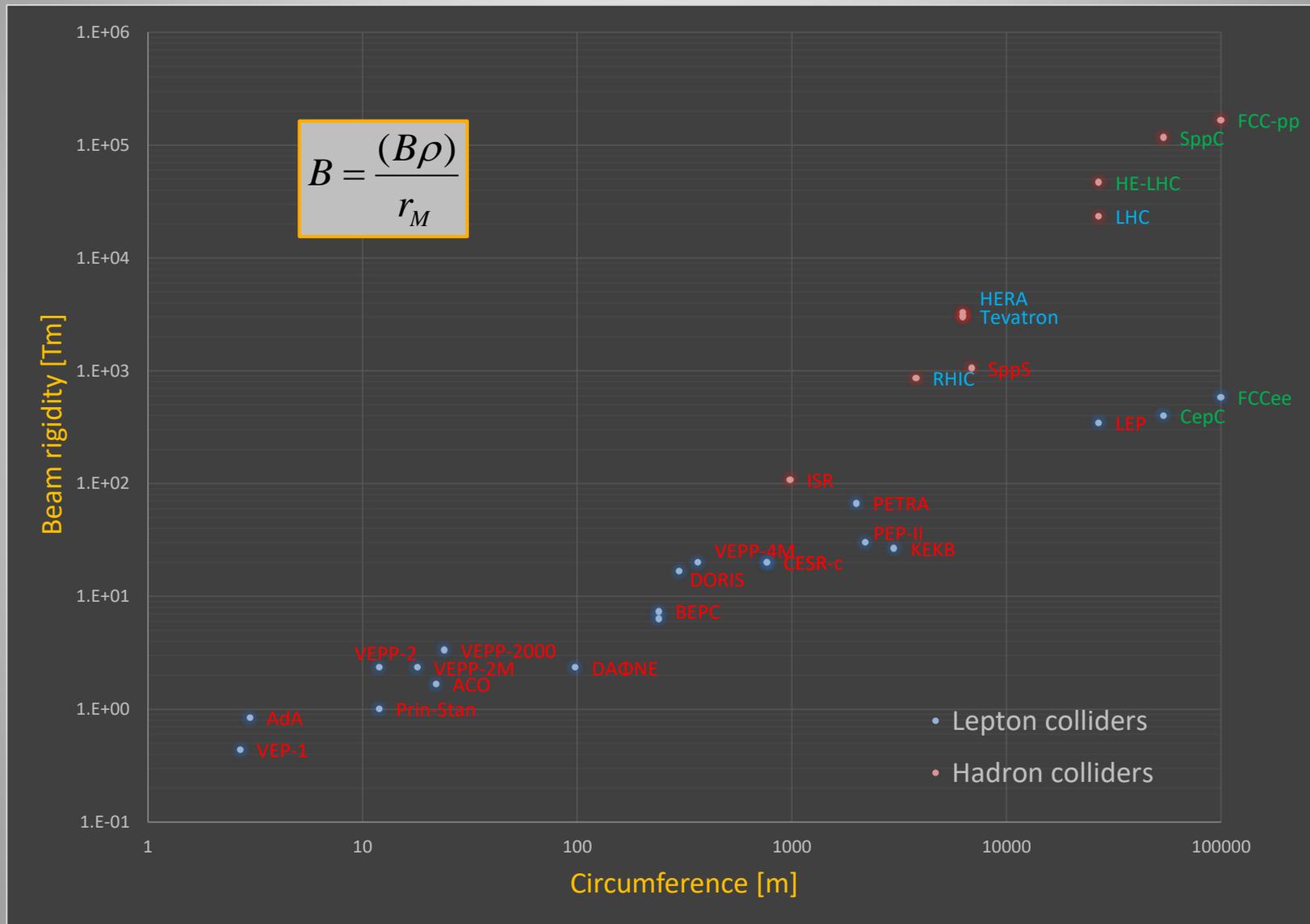
LHC twin aperture quadrupole (2008)



Future collider magnet (20xx)



Circular Colliders





Challenges of future colliders



Future collider projects bear a number of financial and technological challenges in general, but also in particular for magnets ...

Large scale machines:

Investment cost: material, production, transport, installation

Operation costs: low power consumption & cooling

Reliability & availability: see presentation *M. Zerlauth*

Logistics: installation, maintenance & service distribution

High energy beams and intensities:

Ionizing radiation impact on materials and electronics

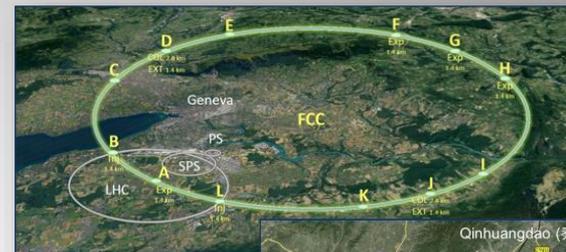
Hadron colliders:

High magnetic fields: SC magnets, see presentation *L. Bottura*

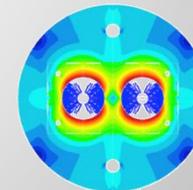
Lepton colliders: (circular & linear)

Alignment & stabilization: see presentation *D. Missiaen*

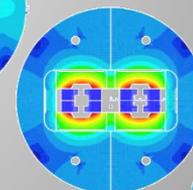
Compact design & small apertures



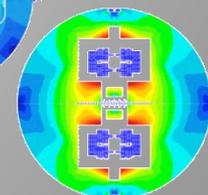
Cos-theta



Blocks

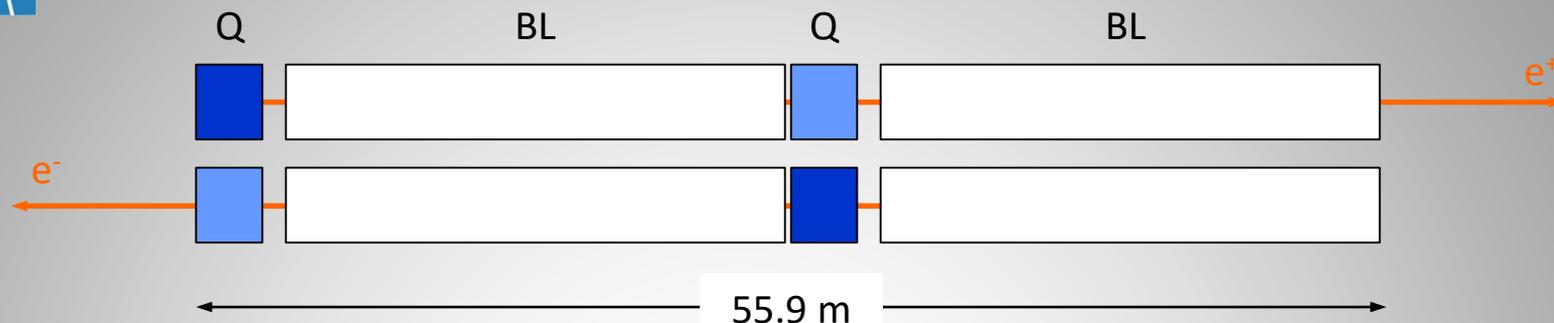


Common coils

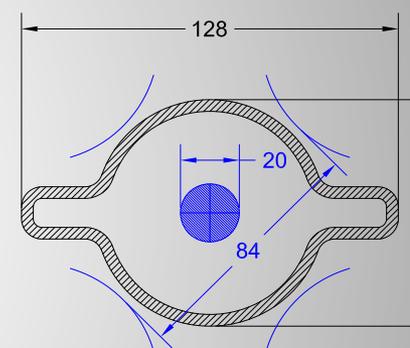
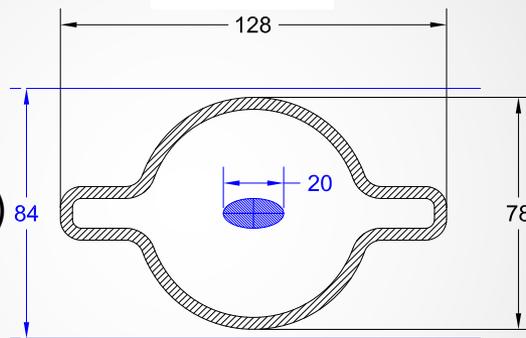




Magnet system for FCC-ee



- Double collider
- Counter-rotating e+ / e- beams
- DC operation with top-up injection
- 1450 FODO cells (each 55.9 m long)
- Tuneability $\pm 1\%$
- Low-field magnets



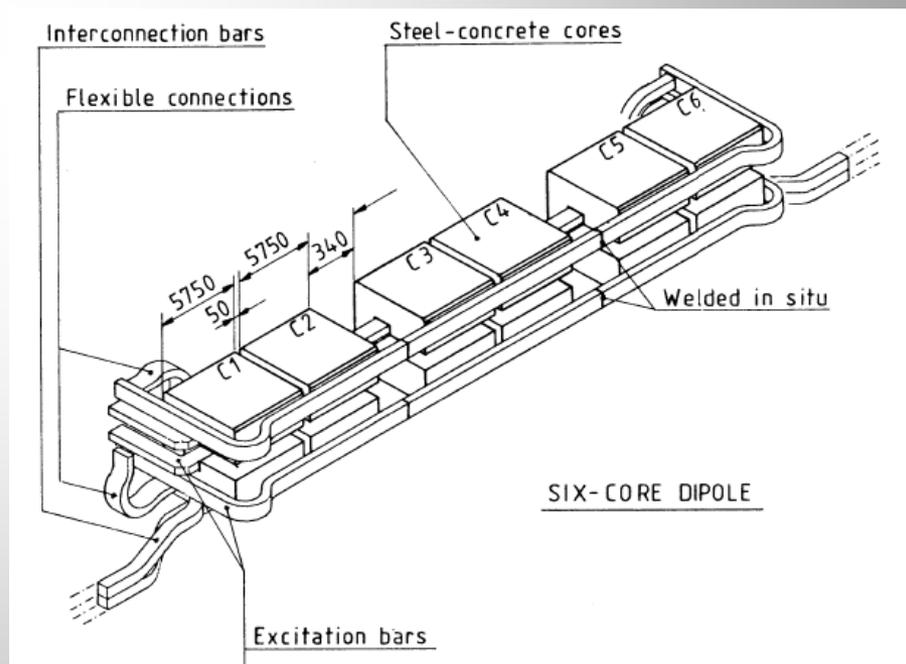
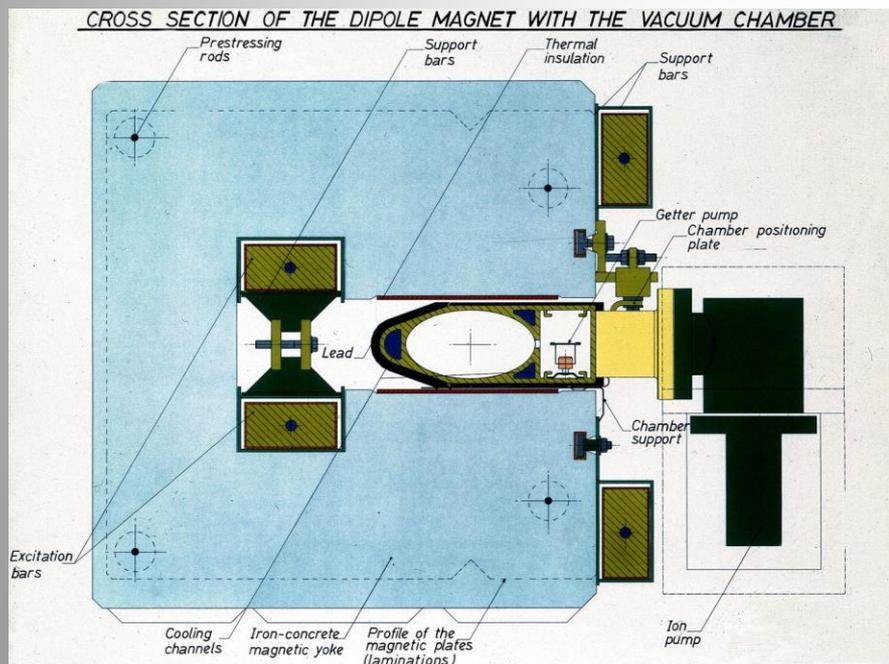
Parameter	Bending magnets	Quadrupole magnets
Quantity (per ring)	2900	1450 + 1450
Magnetic length	23.94 (21.94) m	3.1 m
Aperture	128 mm x 84 mm	R = 42 mm
Inter-beam distance	300 mm	300 mm
Field / max. gradient at 175 GeV	54.3 mT	9.9 T/m
Goof field region	± 10 mm horizontal	R = 10 mm
Field quality	$< 10^{-4}$	$< 10^{-4}$



Recap: LEP dipoles



- Cycled field: 22 mT (20 GeV injection) to 108 mT (100 GeV)
- 5.75 m long 'diluted' magnet cores: 30% Fe / 70% concrete
- Four water cooled aluminium excitation bars
- Max. current: 4.5 kA

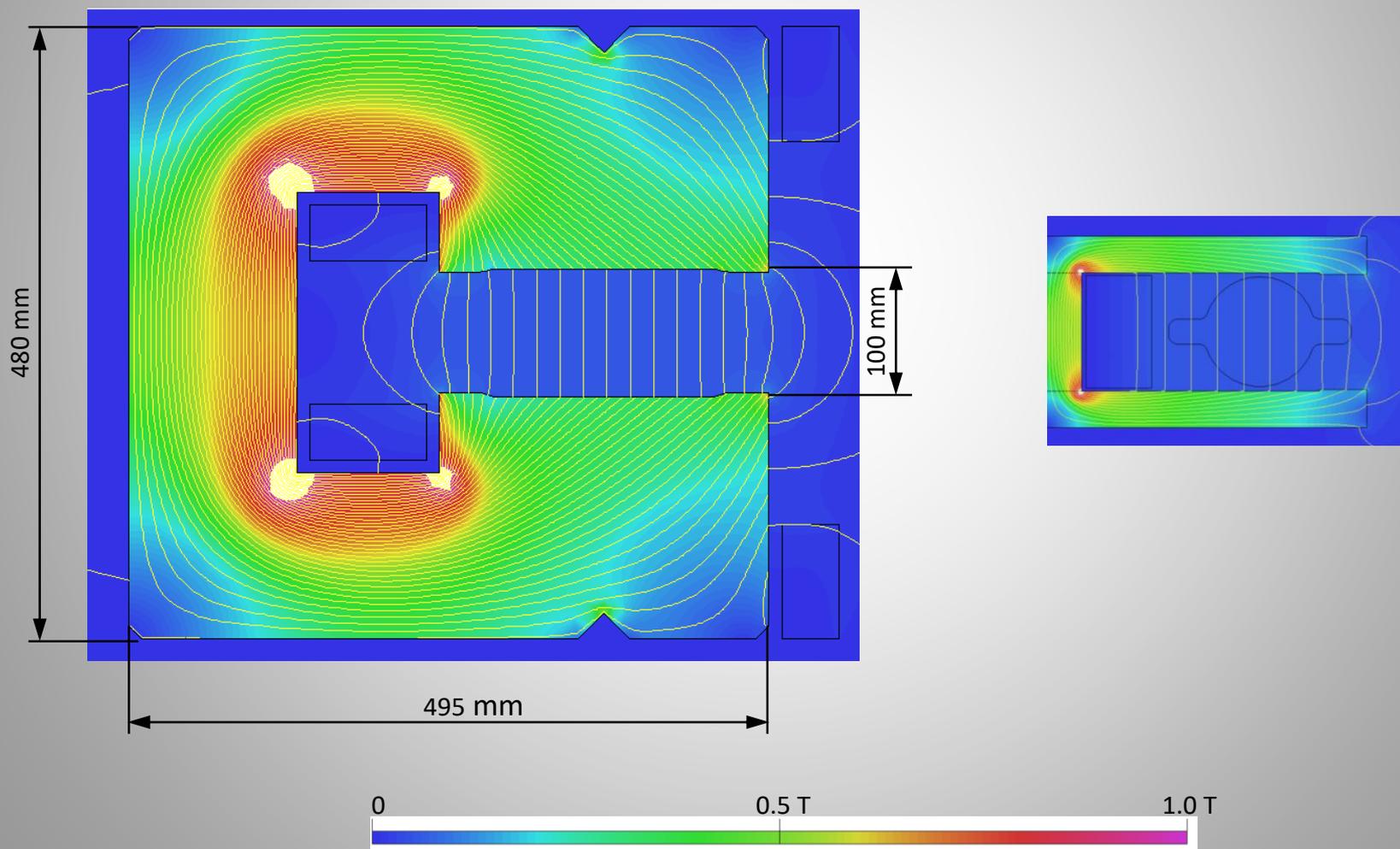




Recap: LEP dipoles

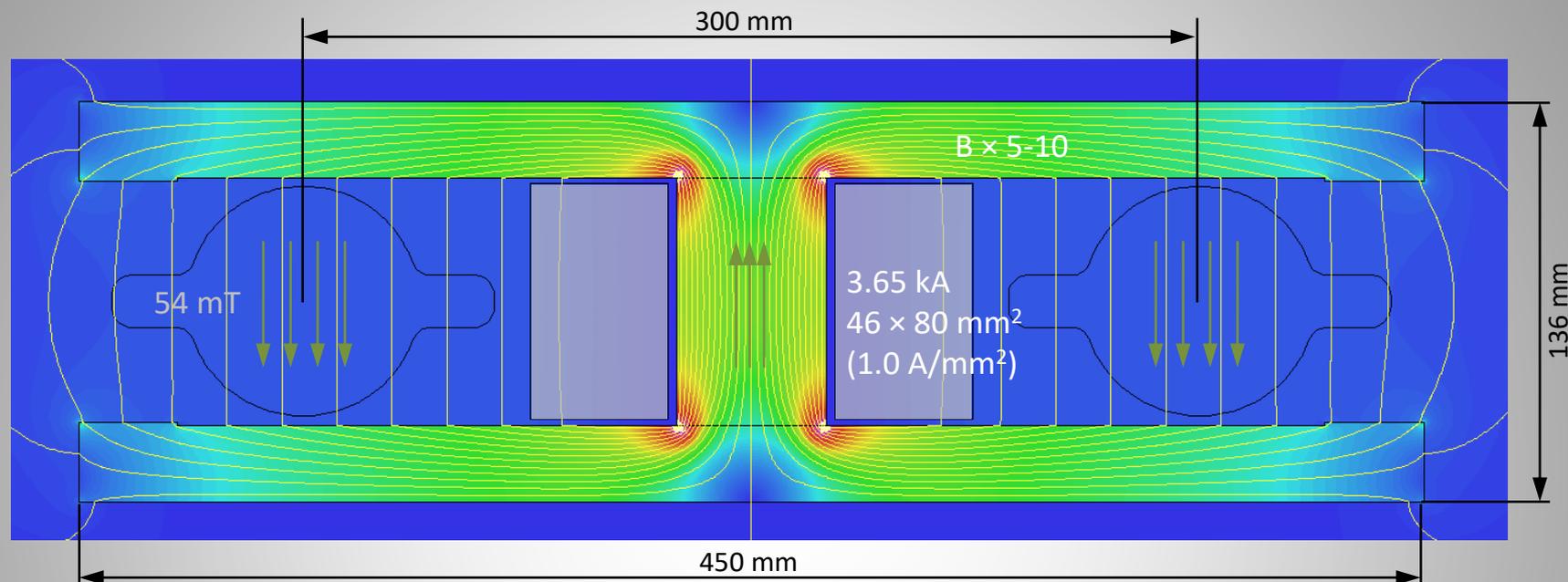


Using the LEP diluted dipoles for FCC-ee at 54 mT...





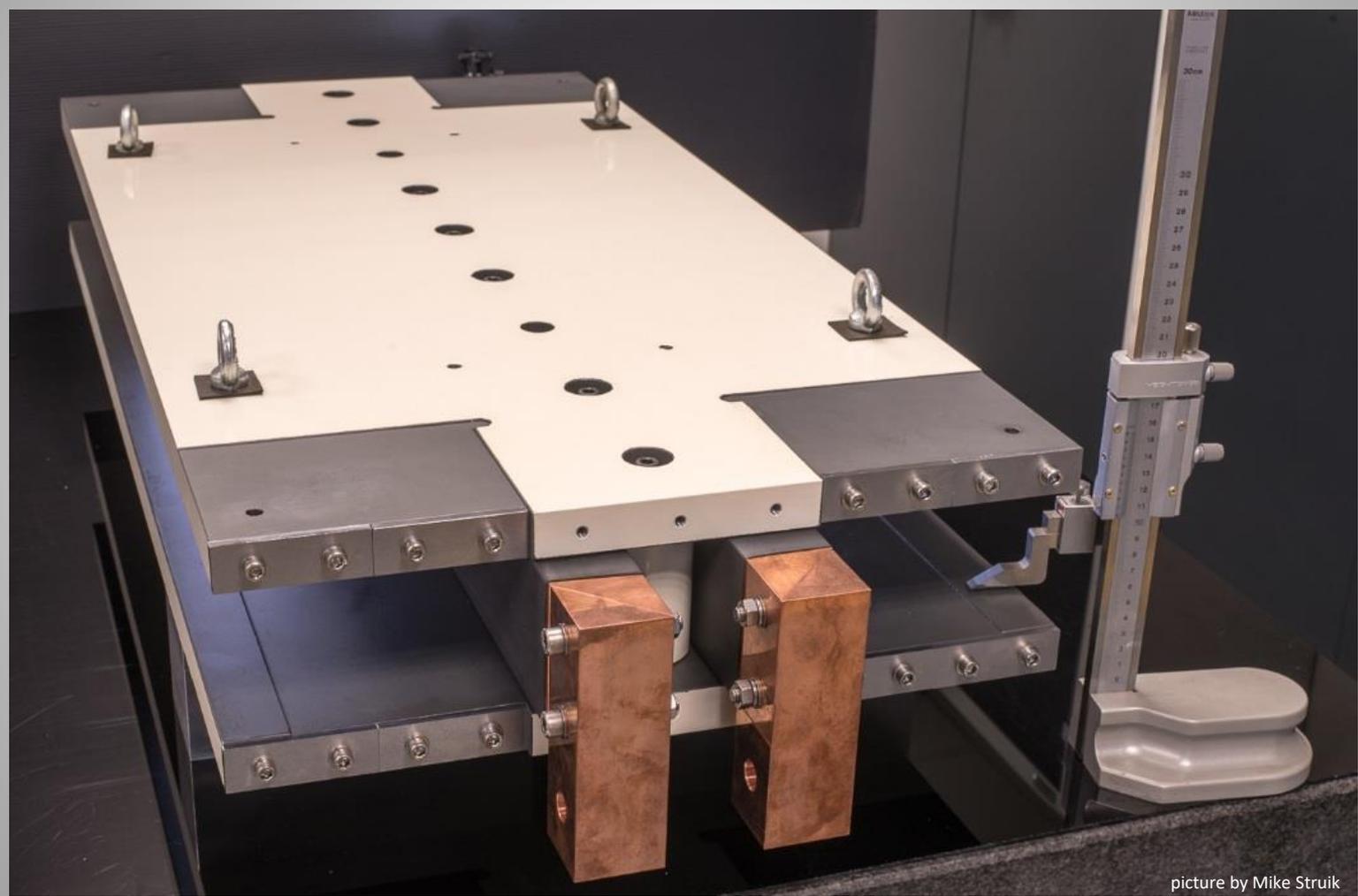
FCC-ee Twin dipole design



- **Energy saving:** Ampere-turns recycled → **50% power consumption** (16 MW)
- **Cost saving:** 50% less units to manufacture, transport, install, align
- **Simple:** few components
 - Simple yoke design: thick laminations (5-6 mm) without **dilution** (easier recycling)
 - Simple coil layout: low coil manufacturing costs
- **Compact:** small dimensions, less material
 - Yoke: 200 kg/m → total 13500 t (low carbon) steel
 - Coil: 1-turn conductor busbar, 20 kg/m → total 1650 t hollow Al conductor
- **Reliable:** no coil inter-turn insulation needed
- **Flexible:** can be easily adapted for a combined-function design



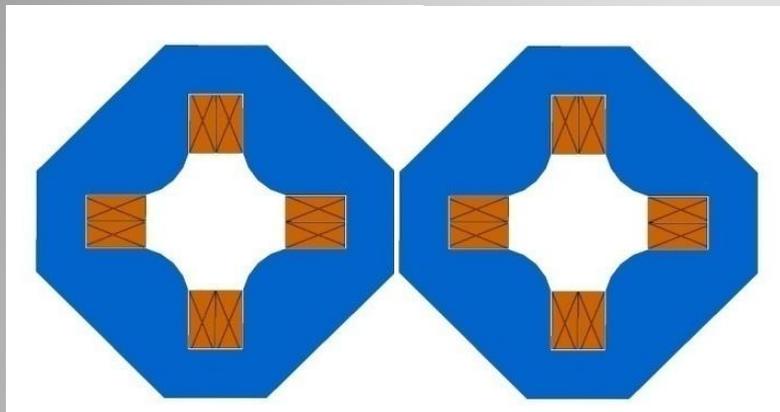
FCC-ee Twin dipole prototype



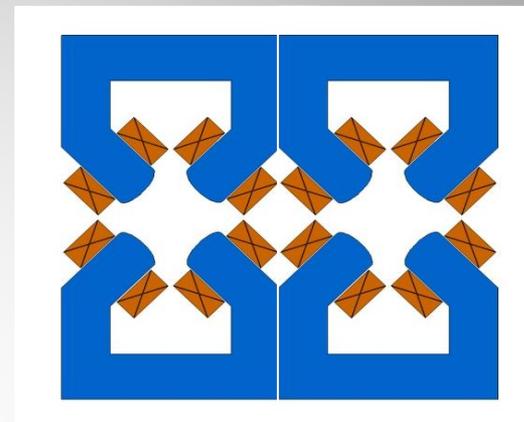
picture by Mike Struik



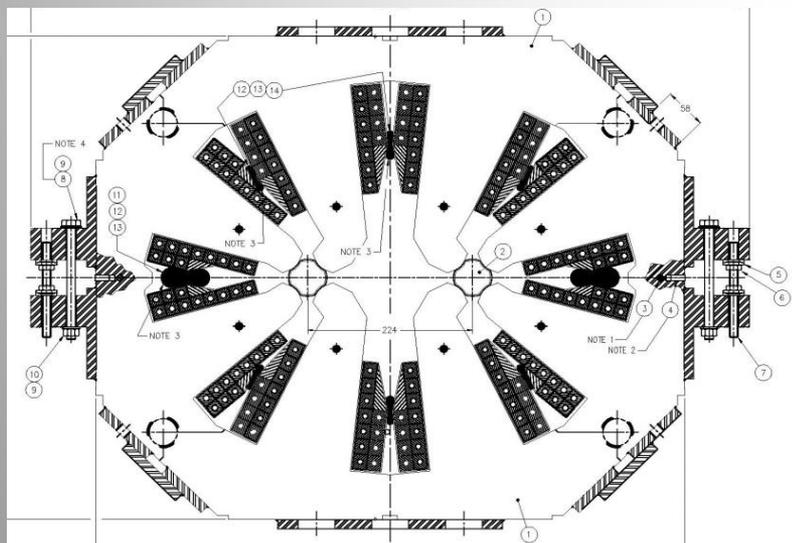
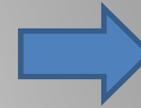
Recap: LHC twin-aperture quad



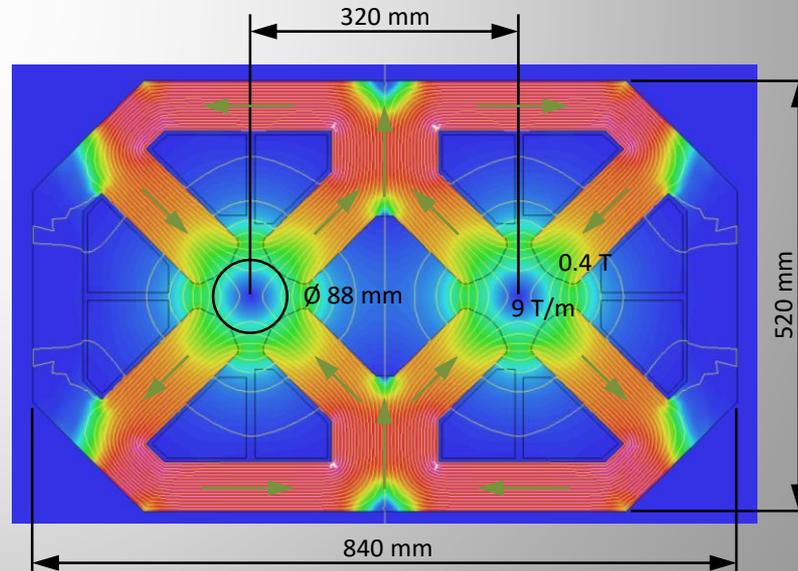
Two-beam layout with separated quadrupoles



Reduced inter-beam distance with Collins quadrupoles



LHC twin-aperture quadrupole MQW with common yoke:

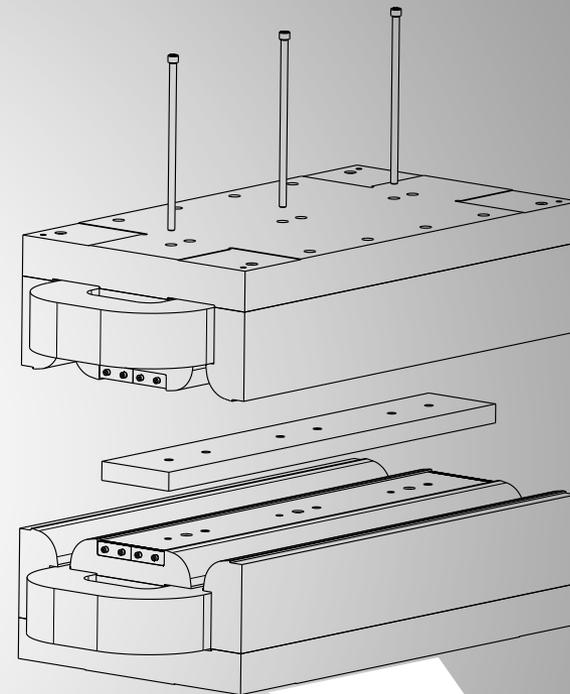
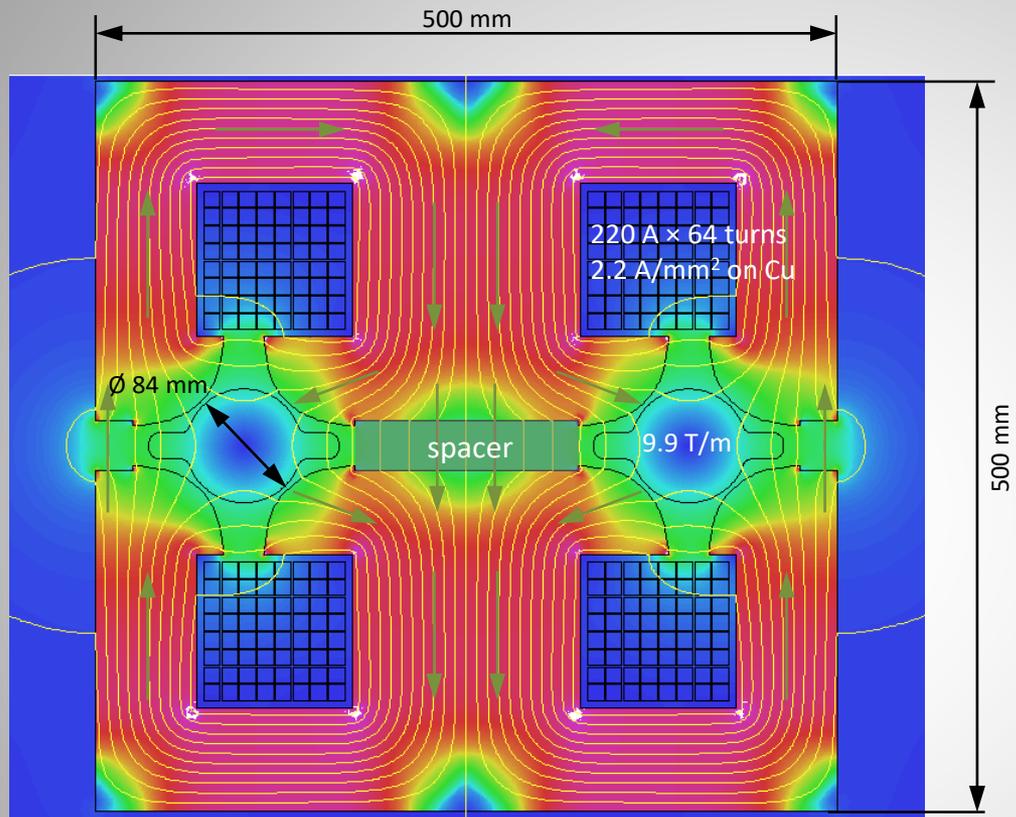


MQW design adopted for FCC-ee

25% power saving (for the same current density) but with constrained F/D polarity



FCC-ee Twin quadrupole design



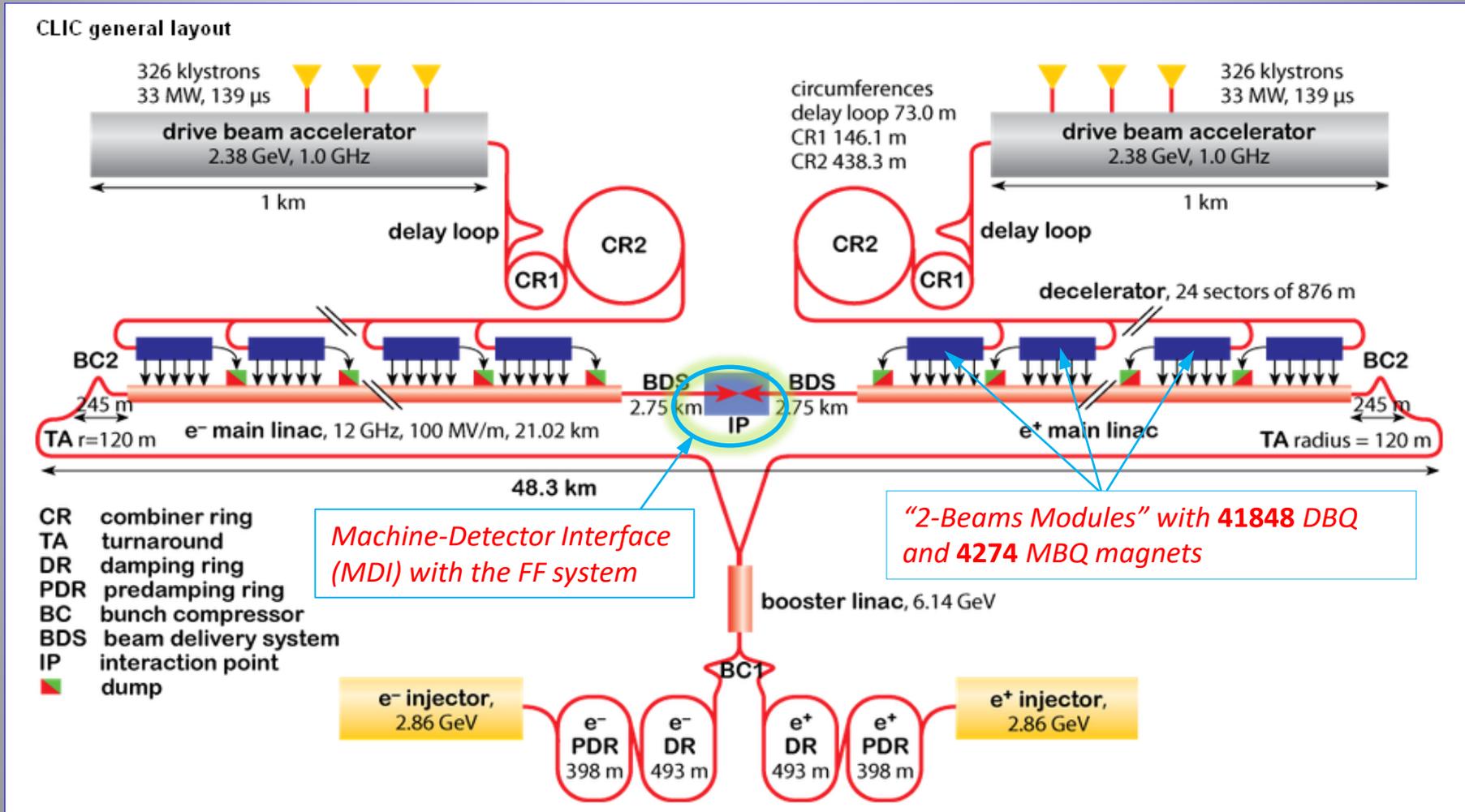
- **Energy saving:** 50% savings in ampere-turns and power consumption (25 MW)
- **Cost saving:** 50% less units to manufacture, transport, install, align
- **Compact:** small dimensions, less material
- **Reliable:** coils are far from the midplane radiation
- **Flexible:** compatible with individual trims on the apertures (typically 5%)



CLIC

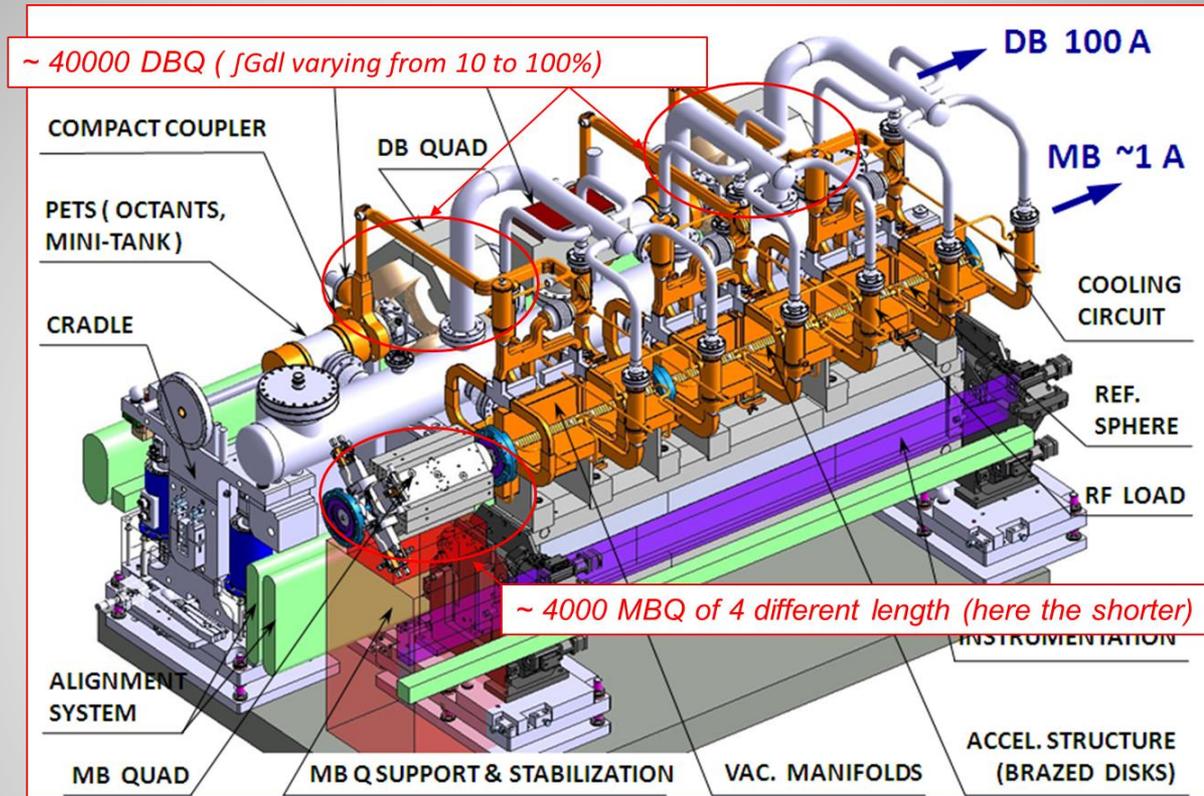


... more than 65000 magnets of more than 100 types!





MBQ for the «2-Beams Module»



MBQ challenges:

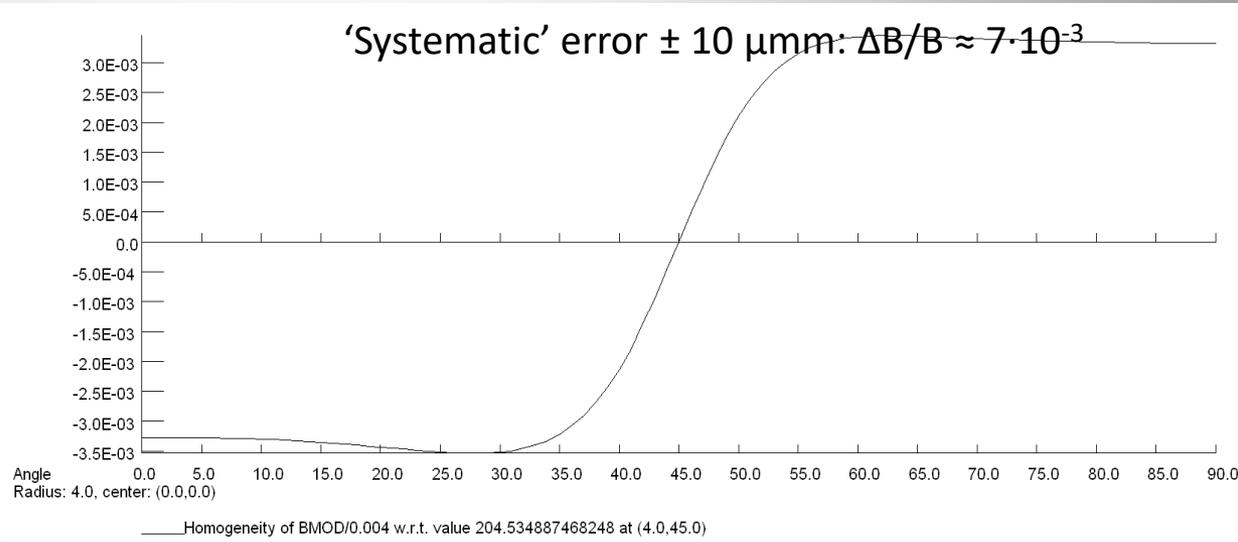
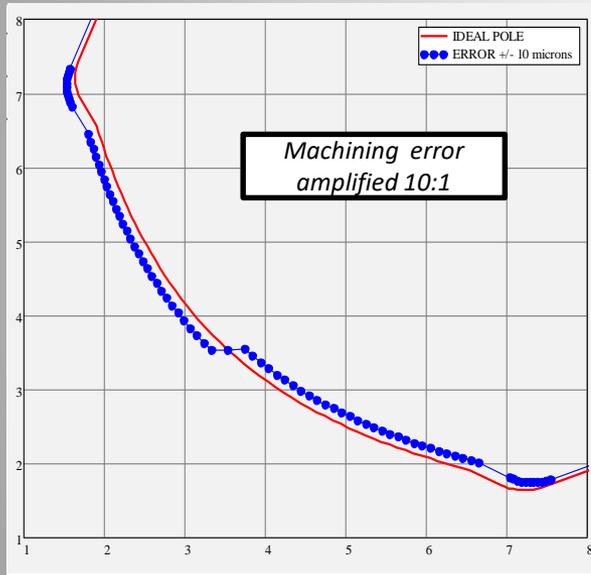
- Limited space: longitudinal and transversal
- Limited mass and maximum rigidity: individual stabilization in the nm range
- Large quantity (< 4000): requires simple design and industrial techniques for production, assembly and testing at reasonable costs
- **Performance:** good field quality within a small aperture



Sensitivity analysis I



Main challenge: 200 T/m within 10^{-4} and a small aperture (\varnothing 10 mm)



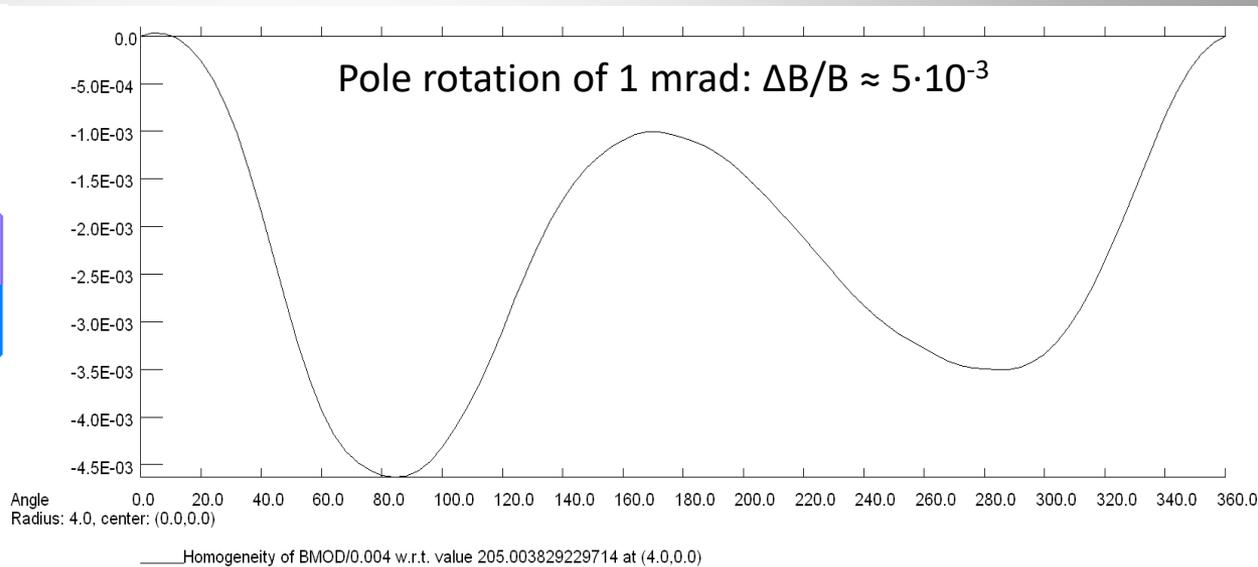
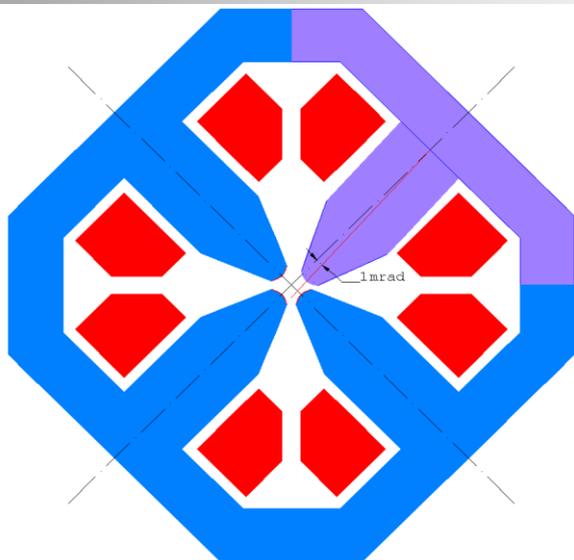
Impact of pole profile errors on the field homogeneity: Perfect magnet $\Delta B/B \approx 6 \cdot 10^{-5}$



Sensitivity analysis II



Impact of assembly errors on the field homogeneity: Perfect magnet $\Delta B/B \approx 6 \cdot 10^{-5}$

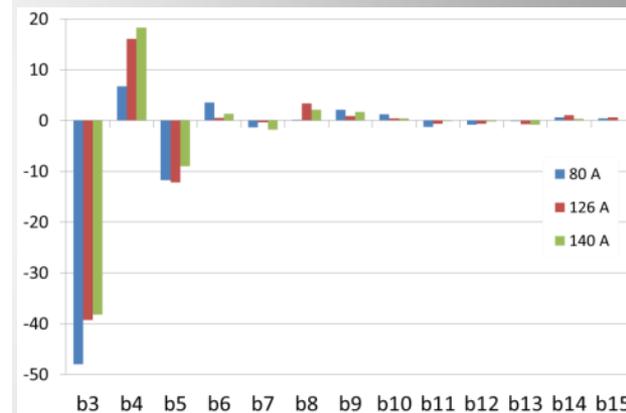
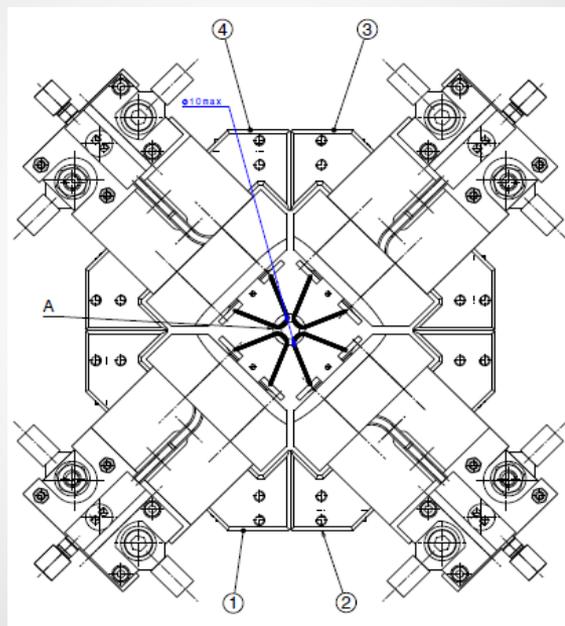
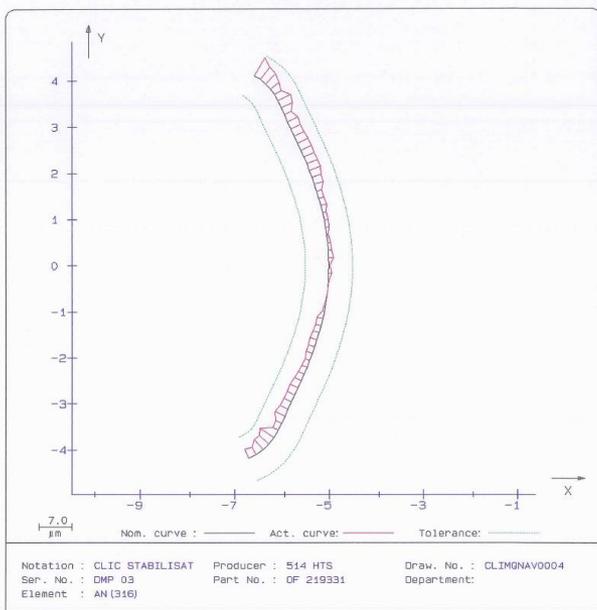




MBQ Prototype



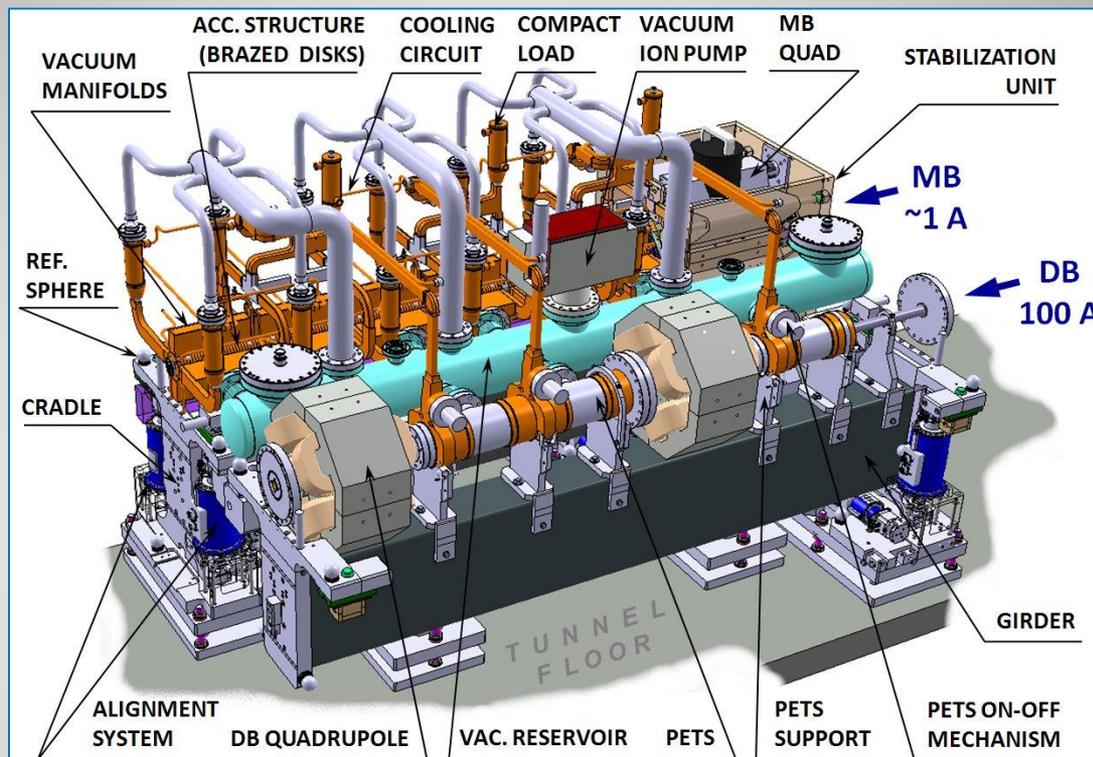
- Main challenge: 200 T/m within 10^{-4} and a small aperture (\varnothing 10 mm)
- 4 magnet types with different length between 420 mm and 1920 mm
- 3 short and 1 long prototype to study machining precision, assembly tolerances, mechanical stabilization, field quality and magnetic measurement techniques



- Short prototype obtained machining precision ($\pm 7\mu\text{m}$) with “standard” industrial techniques (fine grinding) on all the critical surfaces → can this result also be achieved for the long(er) types?
- Alignment and assembly of the 4 quadrants within a cylindricity of 13 μm has been achieved
- Are there alternatives techniques to improve the precision and achieve the required field quality?
- How can we develop **precise, fast, robust** machining and assembly methods aiming towards industrial production?



DBQ for the «2-Beams Module»



DBQ challenges:

- Tight alignment tolerance: no active stabilization and beam feedback alignment
- Very large series: requires simple design and industrial techniques for production, assembly, testing and installation at reasonable costs
- Performance: wide $\int Gdl$ variation from 7% - 120%
- **Reliability**: large number of magnets requires short MTTR and long MTBF
- **Power consumption**: minimize cooling power and heat load to the tunnel

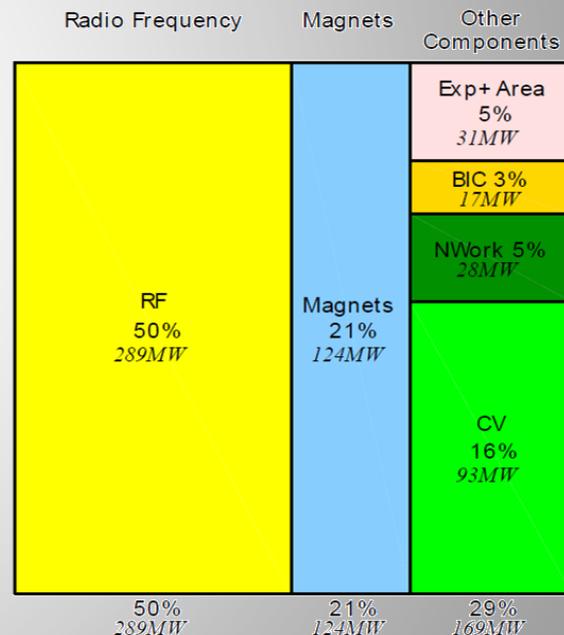
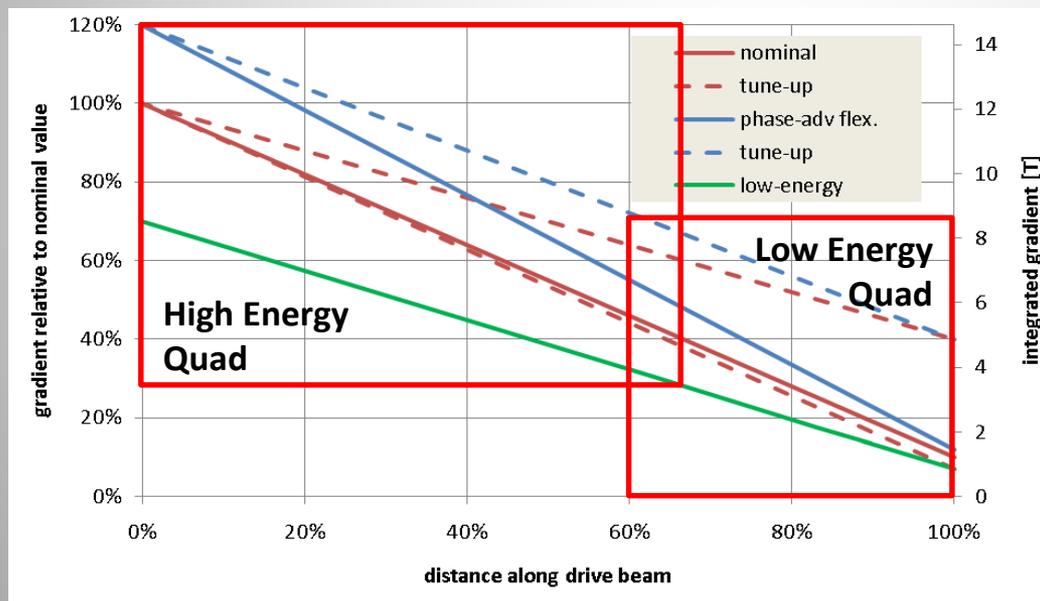


DB Quadrupole



Normal conducting systems on CLIC will result in high electrical power consumption and running costs:

- CLIC estimated to draw >580 MW (compared to 90 MW for LHC)
- 124 MW projected for nc electro-magnets
- 32 MW (> 25%) for DB quadrupoles (20 MW) and DB dipoles (12 MW)

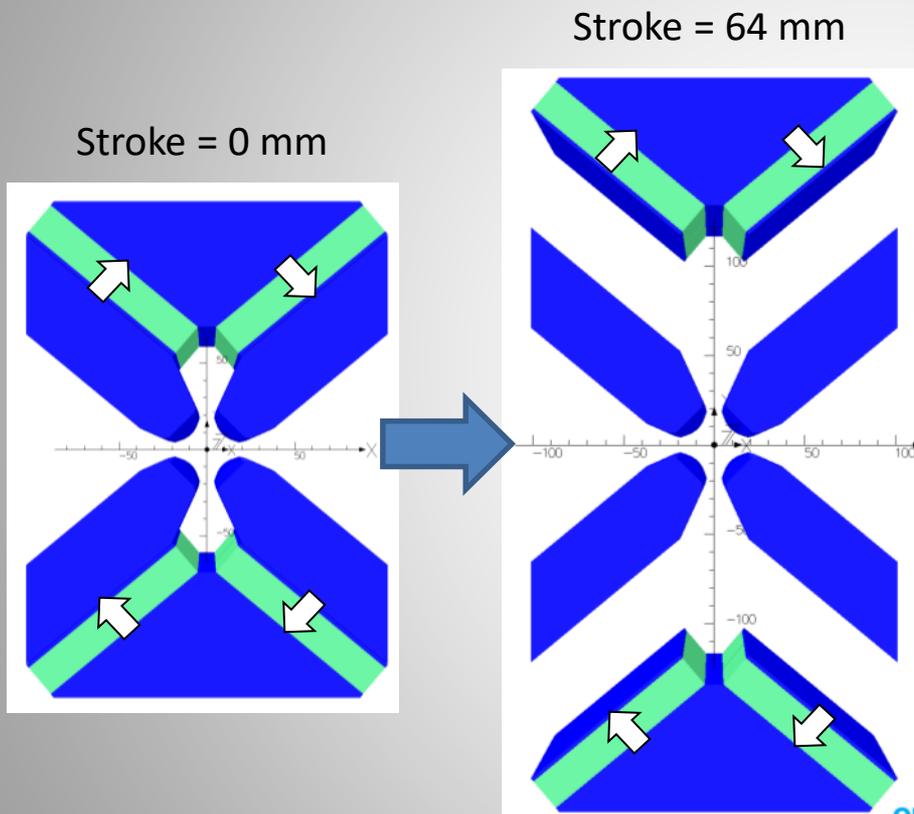


Can we use permanent magnets to save power?

How can we deal with the wide gradient variation from 7% - 120%?



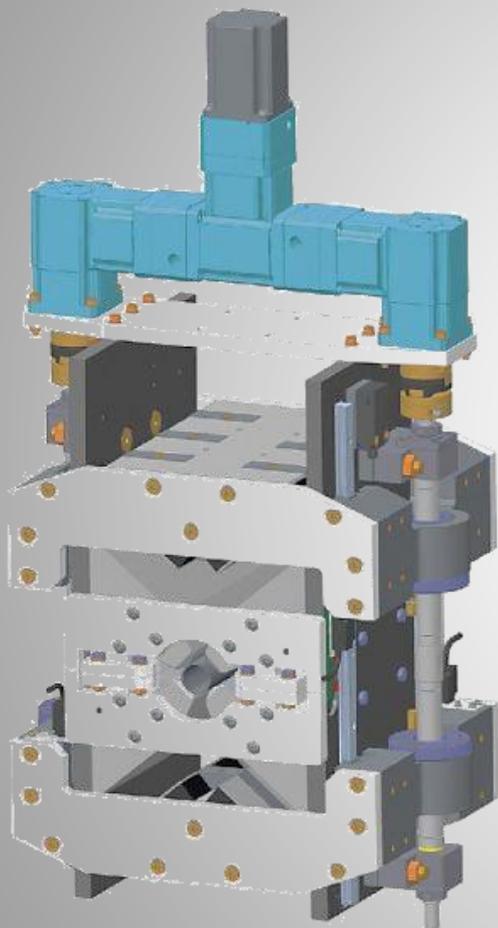
High-Energy DB quadrupole



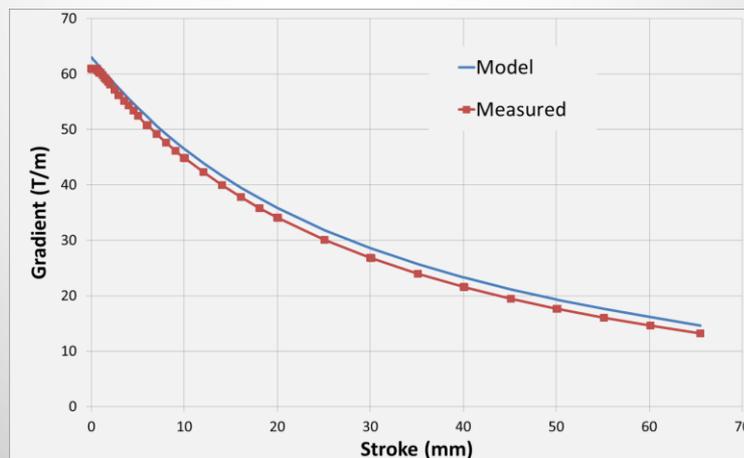
- NdFeB magnets (VACODYM 764 TP)
- $B_r = 1.37 \text{ T}$
- Max. gradient = 60.4 T/m (0 mm stroke)
- Min. gradient = 15.0 T/m (64 mm stroke)
- 30% - 120% of nom. gradient
- Aperture $\varnothing = 27.2 \text{ mm}$
- GFR $\varnothing = 23 \text{ mm}$
- Field quality = $\pm 0.1\%$



High-Energy DB quadrupole



- Single axis motion with one motor and two ballscrews
- Maximum force per side: 16.4 kN (reduced by 10 when stroke = 64 mm)
- PM blocks bonded and strapped to steel bridge piece, protective steel plate also bonded



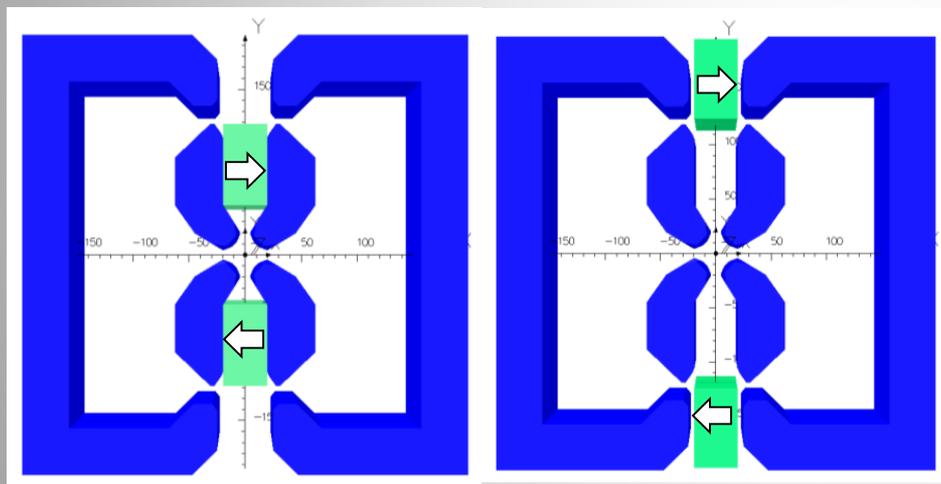


Low-Energy DB quadrupole



Stroke = 0 mm

Stroke = 75 mm



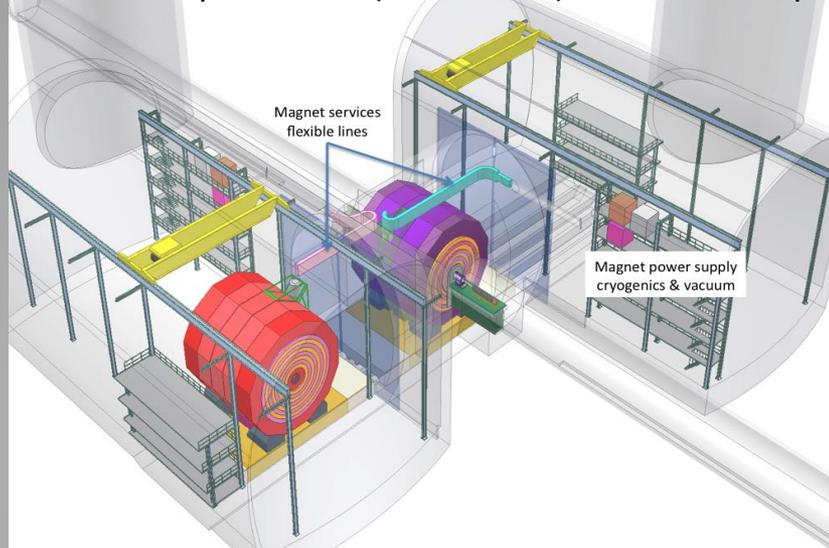
- NdFeB magnets (VACODYM 764 TP)
- $B_r = 1.37$ T
- Max. gradient = 43.4 T/m (0 mm stroke)
- Min. gradient = 3.5T/m (75 mm stroke)
- 7% - 70% of nom. gradient
- Aperture $\varnothing = 27.2$ mm
- GFR $\varnothing = 23$ mm
- Field quality = $\pm 0.1\%$
- Maximum force only 0.7 kN per side



CLIC Final Focusing



CLIC two-experiments (ILD and SiD) “roll-in” concept

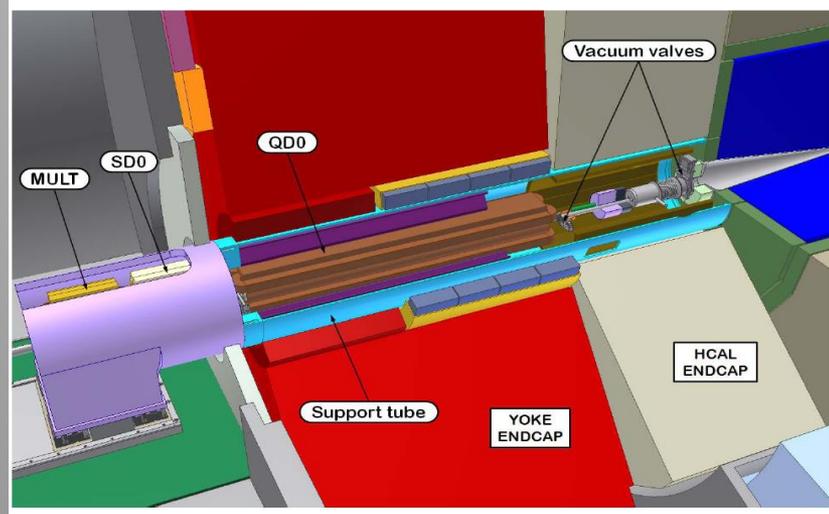


Nominal requirements & boundary conditions for the QD0:

- Gradient: highest possible towards **575 T/m**
- Total Length: 2.73 m
- Aperture radius: **4.125 mm**
- Field Quality: better than 10^{-3}
- **Tunability**: -20% minimum

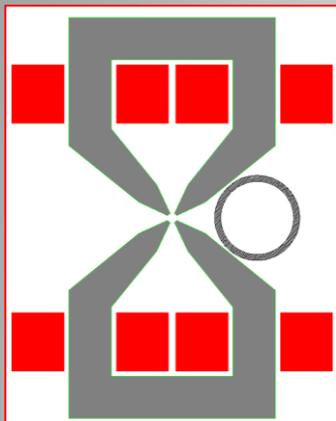
Geometric and other boundary conditions:

- Stabilization: similar to MBQ magnets, the QD0 needs to be actively stabilized in the nm range
- Minimize weight and vibration sources
- Alignment budget: 10 μm
- Compactness: magnet inside Detector Solenoid

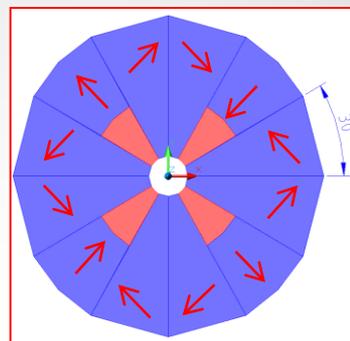
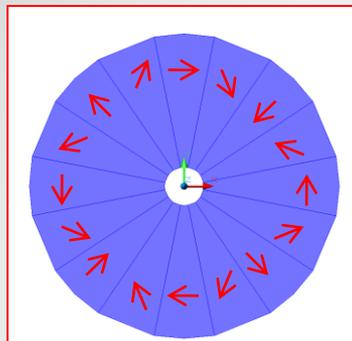




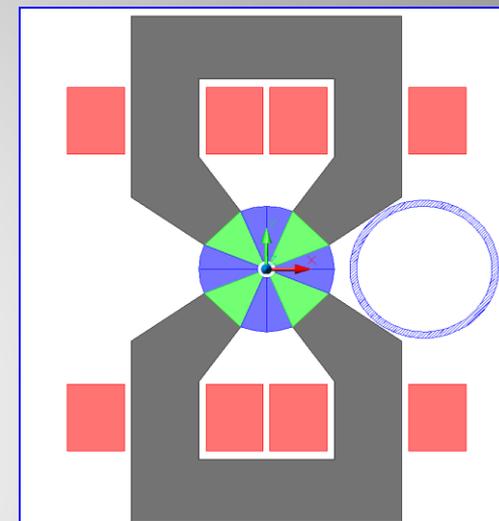
CLIC Final Focusing



Pure EM design

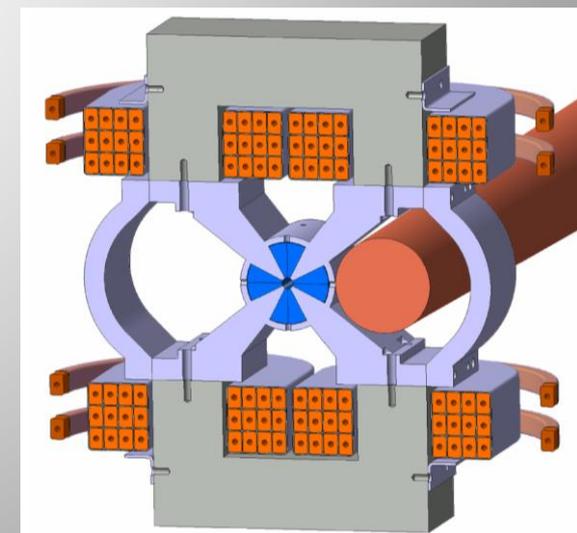


Pure Halbach and "super-strong" design



Hybrid design

Configuration	G [T/m] for r = 4.125 mm (2D calculation)	
	Sm ₂ Co ₁₇	Nd ₂ Fe ₁₄ B
Pure EM	0 - 310 (Steel1010);	0 - 365 (Permendur*)
"Pure Halbach"	409	540
"Super Strong"	550	615
"Hybrid"	145 - 550 (531**)	175 - 615 (599**)

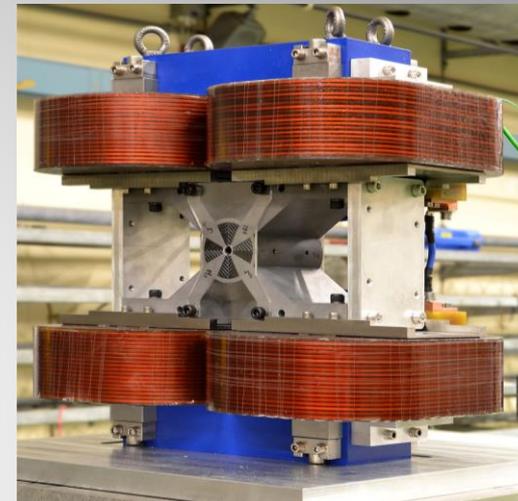
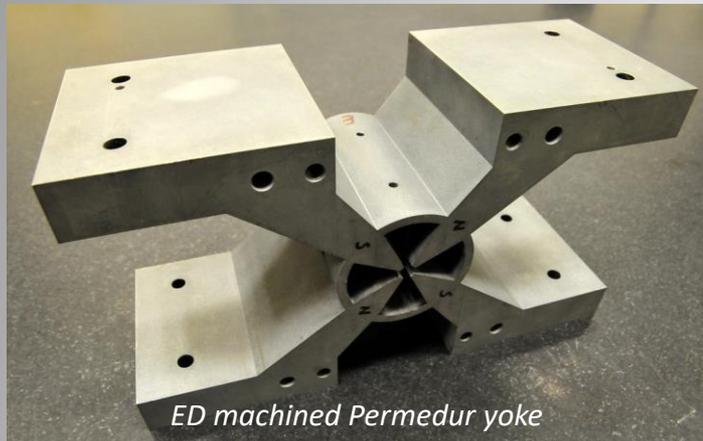


*) Permendur is a Fe-Co alloy (50%-50%) with a high magnetic flux saturation

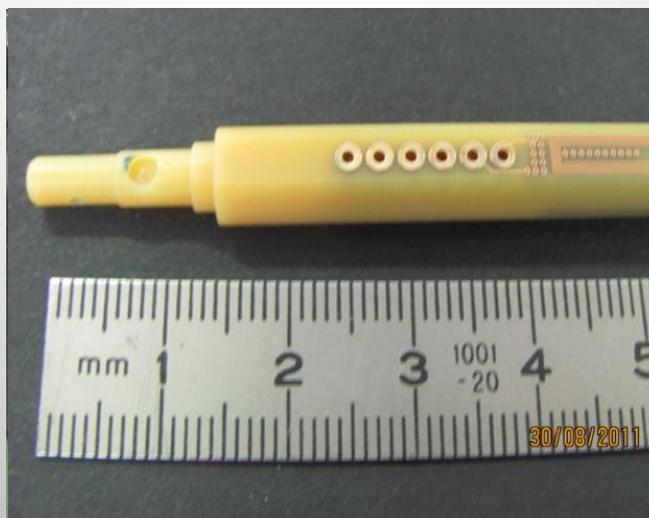
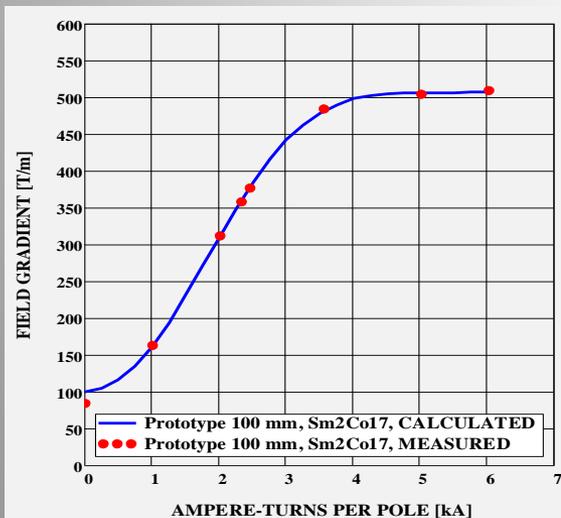
**) the "ring" decreases slightly the gradient (by 15-20 T/m) but improves assembly precision for the PM



CLIC Final Focusing



What comes next...? A super-ferric solution?





Summary



Main challenges for future collider magnets are:

- Strong fields
- Small apertures
- Power consumption and related operation costs
- Advanced stability
- High reliability

Conventional magnet concepts have clear **limitations** which we need to overcome with new innovative concepts in:

- Magnet design
- Magnetic materials
- Manufacturing techniques
- Test and measurement methods

Promising **alternative concepts**:

- Twin-aperture low-field magnets offering a second aperture “for free”
- Tuneable permanent magnets becoming a reality, merging the versatility of electromagnets with savings in operating costs and infrastructure
- Hybrid magnets combining the benefits of two worlds: economics from PM and flexibility of EM

Nevertheless: there is a lot of challenging and interesting work ahead of us to develop these ideas further or to come up with superior concepts ...