Beam dynamics basics in RF linacs

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- RF cavity
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Why RF linacs

<u>Goal of an accelerator</u> : Accelerate a wanted beam within the lower cost wanted : particle, energy, emittance, intensity, time structure cost : construction, operation

<u>Main competitors</u> : RF linacs, Synchrotrons, Cyclotrons...

<u>**RF** linacs</u> : Particles accelerated on a linear path with RF cavities.

<u>Advantages</u> : High current, high duty-cycle, low synchrotron radiation losses. <u>Drawbacks</u> : High room & cavities consumption, no synchrotron radiation damping

<u>Main use of linacs</u> : Low energy injectors, high intensity protons beam, high energy lepton colliders.

RF resonant cavity

Goal : Give kinetic energy to the beam

Basic principle

- Conductor enclosing a close volume,

- Maxwell equations + *Boundary conditions* allow possible electromagnetic field E_n/B_n configurations each oscillating with a given frequency f_n : a *resonant mode*. The field is a weighted superposition of these modes.

- The wanted (accelerating) mode is excited at the good frequency and position from a RF power supply through a power coupler,

- The phase of the electric field is adjusted to accelerate the beam.



RF resonant cavity

Transit time factor

Energy gain

Energy gained by a particle in a cavity :

$$\Delta W = \int qEz(s) \cdot \cos(\phi(s)) \cdot ds$$

with:
$$\phi(s) = \phi_0 + \omega \cdot t = \phi_0 + \frac{\omega}{c} \int_{s_0}^s \frac{ds}{\beta_z(s)}$$



$$\Delta W = q V_0 \cdot T \cdot \cos \phi_p$$

with :
$$V_0 = \int |Ez(s)| \cdot ds$$
 The cavity voltage
 ϕ_p The average phase
 $0 < T < 1$ Transit-time factor

Transit time factor Example 1 : The transit time factor in a one-cell cavity





Electric Field

- Field amplitude
- Field in the cavity with time
- Field seen by a non ... synchronous particle

Energy gain

$$\Delta W = qV_0 \cdot T\left(\overline{\beta}\right)$$

Transit time factor Example 1 : The transit time factor in a one-cell cavity

Medium fast particle : $T \cong 0.85$



Electric Field

- Field amplitude
- Field in the cavity with time
- Field seen by a non synchronous particle

Energy gain

 $\Delta W = qV_0 \cdot T(\overline{\beta})$

Transit time factor Example 1 : The transit time factor in a one-cell cavity

Slow particle : $T \cong 0.3$



Electric Field

- Field amplitude
- Field in the cavity with time
- Field seen by a non synchronous particle

Energy gain

 $\Delta W = qV_0 \cdot T(\overline{\beta})$

RF cavity shunt impedance

Cavity voltage
$$V_0$$
: $V_0 = \int \hat{E}_z(z) \cdot dz$

Dissipated power P_d : Mean power dissipated in conductor over one RF period

Shunt impedance **R** :

$$R = \frac{V_0^2}{2 \cdot P_d}$$

$$P_d = \frac{1}{2} \cdot V_0^2 / Z$$

RF resonant cavity

 ΔW_{max} : Maximum energy that can be gained by a particle in the cavity

 $\Delta W_{\text{max}} = qV_0 \cdot T$ **T**: Transit time factor

Effective shunt impedance :

$$ZT^2 = \frac{\Delta W_{\text{max}}^2}{2P_d}$$

RF resonant cavity Example of use of effective shunt impedance ZT²



The effective shunt impedance per unit length of the structures can been used to set the transition energy between sections.

RF Systems

Various types of cavity : Tanks

RFQ (low energy ~50 keV-7 MeV)



DTL (medium energy ~5-100 MeV)







Various types of cavity : Coupled cavity

CCDTL (medium energy ~5-100 MeV)







RF Systems

CCL (high energy ~80 MeV-2 GeV)





Various types of cavity : Superconducting

Spoke (medium energy ~20-100 MeV)



Elliptical (high energy ~100MeV- 2 GeV)







RF Systems



Linac design

The synchronous particle - Linac design

A linac is designed with a hypothetical *synchronous particle*. Its phase in a cavity is called the *synchronous phase* :

• The synchronous particle absolute phase ϕ_i and the velocity β_{si-1} being known at the entrance of cavity *i*, its RF phase ϕ_i is calculated to get the wanted synchronous phase ϕ_{si} .

• The new velocity β_{si} of the particle can be calculated from : $\Delta W_i = qV_0T \cdot \cos \phi_s$

① if the phase difference between cavities *i* and *i*+1 is given, the distance D_i between them is adjusted to get the wanted synchronous phase ϕ_s in cavity *i*+1.

② if the distance D_i between cavities *i* and *i*+1 is set, the RF phase ϕ_{i+1} of cavity *i*+1 is calculated to get the wanted synchronous phase ϕ_s in it.

RF phase	ϕ_{i-1}	ϕ_i	ϕ_{i+1}	
Particle velocity	β_{si}		β_{si}	
Distances			$\overrightarrow{D_i}$	
Cavity number	i-1	i	<i>i</i> +1	

Synchronism condition :

 $\phi_{i+1} - \phi_i + 2\pi n = \omega \cdot \frac{D_i}{\beta_i c}$

① Linac with coupled cavities

Linac design

Coupled cavities have the same phase. Distances between them are adjusted for synchronism.



② Linac with independently phased cavities

Linac design

The distance between the cavities is given. Cavities are phased to accelerate a given particle.



Choice of the synchronous phase

Acceleration condition : The field should accelerate the particle



$$\Delta W > 0 \implies \qquad qV_0 > 0: \ \phi_p \in [-90^\circ, 90^\circ]$$
$$qV_0 T \cdot \cos \phi_p > 0 \qquad qV_0 < 0: \ \phi_p \in [90^\circ, 270^\circ]$$

Linac design

Stability condition : Late particles should gain more energy that early ones $\frac{d\Delta W}{d\phi_p} > 0 \implies qV_0T \cdot \sin\phi_p < 0 \qquad \qquad qV_0 > 0: \ \phi_p \in [-180^\circ, 0^\circ]$ $qV_0 < 0: \ \phi_p \in [0^\circ, 180^\circ]$

$$qV_0 > 0: \ \phi_p \in [-90^\circ, 0^\circ]$$
$$qV_0 < 0: \ \phi_p \in [90^\circ, 180^\circ]$$



Beam dynamics

General equations of motion

$$\frac{d\vec{p}}{dt} = q \cdot \left(\vec{v} \times \vec{B} + \vec{E}\right) = \vec{F}$$

+
$$p_w = \beta_w \gamma \cdot mc$$

+ $dt = ds/\beta_z c$

 $\beta_w c$ is the particle velocity along *w* direction γ is the particle reduced energy, *q* and *m* its charge and rest mass. *x* and *y* are transverse directions, *s* is the abscissa along longitudinal direction *z*, *x*' and *y*' are called the particle slopes.

$$\begin{cases} \frac{d\gamma\beta_x}{ds} = \frac{F_x}{mc^2\beta_z} = \frac{d\gamma\beta_z x'}{ds} \\ \frac{d\gamma\beta_y}{ds} = \frac{F_y}{mc^2\beta_z} = \frac{d\gamma\beta_z y'}{ds} \\ \frac{d\gamma\beta_z}{ds} = \frac{F_z}{mc^2\beta_z} \end{cases}$$

$$x'' + \frac{d\gamma\beta_z/ds}{\gamma\beta_z}x' = \frac{F_x}{mc^2\gamma\beta_z^2}$$

These equations are <u>non linear</u>, <u>coupled</u> and <u>damped</u>. Each element (cavity, quadrupole ...) contributes to the force.

A few words on longitudinal coordinates

Beam dynamics

• If the beam is described at a given time t (useful for space-charge calculation and time-varying fields), particles are generally represented by their position z in the bunch and their velocity z' relative to the synchronous particle :

$$\begin{cases} z(t) = s(t) - s_s(t) \\ z'(t) = \frac{\beta_z(t) - \beta_s(t)}{\beta_s(t)} = \frac{v_z - v_s}{v_s} = \frac{p_z - p_s}{p_s} \end{cases}$$

• If the beam is described at a given abscissa *s* (easier for transport into elements), particles are generally represented by their phase φ in the bunch and their kinetic energy *w* relative to the synchronous particle :

$$\begin{cases} \varphi(s) = \phi(s) - \phi_s(s) \\ w(s) = W(s) - W_s(s) \end{cases}$$

One remarks that kinetic energy is not only a longitudinal particle property but it is often assumed as being totally longitudinal (paraxial approximation).

Beam dynamics

 $t = \frac{\phi}{\omega_{rf}}$

Longitudinal motion (1)

- At a given abscissa, a particle arrives at a given time :
- It has a given kinetic energy : $W = (\gamma 1) \cdot mc^2$
- The evolution of these variables is given by :

$$\begin{cases} \frac{dW(s)}{ds} = qE_z(s) \cdot \cos(\phi(s) - \phi_{rf}) \\ \frac{d\phi(s)}{ds} = \frac{2\pi}{\beta(s)\lambda_{rf}} \end{cases}$$
 n.b. Joel Leduff is using sinus

• The linac is designed with a *synchronous particle*, for which the phase law in the cavities has been fixed by the designer : $\phi_s(s)$.

• Beam particles are referred to this synchronous particle :

$$\begin{cases} \varphi(s) = \phi(s) - \phi_s(s) \\ w(s) = W(s) - W_s(s) \end{cases}$$

Beam dynamics

Longitudinal motion (2)

• The evolution of these variables is given by :

$$\frac{d\varphi}{ds} = \frac{2\pi}{\lambda_{rf}} \left(\frac{1}{\beta} - \frac{1}{\beta_s} \right)$$

$$\frac{dw}{ds} = qE_z(s) \cdot \left(\cos(\phi(s) - \phi_{rf}) - \cos(\phi_s(s) - \phi_{rf}) \right)$$

• Giving finally :

$$\begin{cases} \frac{d\varphi}{ds} = -2\pi \cdot \frac{w}{(\beta_s \gamma_s)^3 \cdot mc^2 \cdot \lambda} = \frac{\partial H_{\phi w}}{\partial w} \\ \frac{dw}{ds} = -q \cdot E_z(s) \cdot \left(\cos(\phi_s - \phi_{rf}) \cdot (1 - \cos\varphi) + \sin(\phi_s - \phi_{rf}) \cdot \sin\varphi\right) = -\frac{\partial H_{\phi w}}{\partial \varphi} \end{cases}$$

• $H_{\varphi\varphi}$ is the motion hamiltonian given by :

$$H_{\varphi w} = -\frac{2\pi}{(\beta_s \gamma_s)^3 \cdot mc^2 \cdot \lambda} \cdot \frac{w^2}{2} - q \cdot E_z(s) \cdot \left(\sin(\phi_s - \phi_{rf})) \cdot (\cos\varphi - 1) + \cos(\phi_s - \phi_{rf}) \cdot (\sin\varphi - \varphi)\right)$$

• Particles follow curves for which $H_{\varphi W}$ =Cst.

Longitudinal motion linearisation

Beam dynamics

- The longitudinal motion can be linearised assuming : $\varphi \ll 1$
- In these conditions :

$$\begin{cases} \frac{d\varphi}{ds} = -2\pi \cdot \frac{w}{(\beta_s \gamma_s)^3 \cdot mc^2 \cdot \lambda} = \frac{\partial H_{\phi w,l}}{\partial w} \\ \frac{dw}{ds} = -q \cdot E_z(s) \cdot \sin(\phi_s - \phi_{rf}) \cdot \varphi = -\frac{\partial H_{\phi w,l}}{\partial \varphi} \end{cases}$$

• $H_{\varphi \omega,l}$ is the motion hamiltonian given by :

$$H_{\varphi w,l} = -\frac{2\pi}{\left(\beta_s \gamma_s\right)^3 \cdot mc^2 \cdot \lambda} \cdot \frac{w^2}{2} + q \cdot E_z(s) \cdot \sin\left(\phi_s - \phi_{rf}\right) \cdot \frac{\varphi^2}{2}$$

• Particles follow curves for which H_{φ_W} =Cste, which are ellipses.

Longitudinal motion - No acceleration $(\phi_s = -90^\circ)$

• Let's assume that $H_{\varphi w}$ is not a function of s ($E_z = Cst$; $\beta_s \gamma_s = Cst$).



Beam dynamics

Longitudinal motion - φ_s =-30° - With $\beta_s \gamma_s$ change

• Let's assume that $H_{\varphi w}$ is not a function of s ($E_z = \text{Cst}$; $\beta_s \gamma_s \neq \text{Cst}$).



Particle motion in linear periodic force

Beam dynamics

In the highest simplification level, the particle motion along direction $w(x, y \text{ or } \varphi)$ can be considered : <u>undamped</u>, <u>uncoupled</u>, <u>linear</u>, and <u>periodic</u>.

$$w'' + \frac{\partial \beta_z / ds}{\partial \beta_z} w' - \frac{F_w(w, \psi, \omega)}{mc^2 \gamma \beta_z^2} = 0$$

Hill equation : $\frac{d^2 w}{ds^2} + k_w(s) \cdot w = 0$ $k_w(s+S) = k_w(s)$
Giving : $w(s) = \sqrt{\varepsilon_0 \beta_{wm}(s)} \cdot \cos(\mu(s) + \mu_0)$
with : μ_0 and ε_0 constant, $\mu(s) = \mu_0 + \int_{s_0}^s \frac{ds}{\beta_{wm}(s)}$, and : $\beta_{wm}(s+S) = \beta_{wm}(s)$

In the (w, w') phase-space, the particle is moving on an ellipse of equation :

$$\gamma_{wm}(s) \cdot w^2 + 2\alpha_{wm}(s) \cdot ww' + \beta_{wm}(s) \cdot w'^2 = A^2$$

with : $\alpha_{wm}(s) = -\frac{1}{2} \frac{d\beta_{wm}}{ds}$ and $\gamma_{wm}(s) = \frac{1 + \alpha_{wm}(s)^2}{\beta_{wm}(s)}$ Channel Courant-Snyder parameters.



Beam dynamics RMS dimensions and Beam Twiss parameters

The rms dimensions of the beam are defined statistically as followed :

rms size :

$$\widetilde{w} = \sqrt{\left\langle \left(w - \left\langle w \right\rangle\right)^2 \right\rangle}$$
$$\widetilde{w}' = \sqrt{\left\langle \left(w' - \left\langle w' \right\rangle\right)^2 \right\rangle}$$
$$\approx : \quad \widetilde{\varepsilon} = \sqrt{\widetilde{w}^2 \cdot \widetilde{w}'^2 - \left\langle \left(w - \left\langle w \right\rangle\right)}.$$

rms slope :

rms emittance : $\widetilde{\varepsilon}_{w} = \sqrt{\widetilde{w}^{2} \cdot \widetilde{w}^{\prime 2}} - \langle (w - \langle w \rangle) \cdot (w^{\prime} - \langle w^{\prime} \rangle) \rangle^{2}$

The <u>beam</u> Twiss parameters are then :



Beam matching

The beam is matched when :

 $\beta_w = \beta_{wm}$

 $\alpha_w = \alpha_{wm}$

$$\gamma_w = \gamma_{wm}$$

- Matched beam
- Bigger input beam
- ••••• Smaller input beam
- Phase-space scanned by the mismatched beams



Beam dynamics

50% mismatched beam

Beam matching (2)

The matching is done between sections by changing focusing force with quadrupoles (transverse) and cavities (longitudinal).

Calculations are made with « envelope codes » where the beam is modelled by its rms dimensions. This type of code calculates automatically the focusing strength that matches the beam.



Beam dynamics

Mismatched Beam

Mismatching :

Emittance growth & Halo formation through :

- non linear forces (external or space-charge),
- resonance of some particle motion with core oscillation (space-charge).



Beam dynamics

Non-linear forces

When the confinement force is non linear (multipole, <u>longitudinal</u>, <u>space-charge</u>), the particle phase advance depends on the oscillation amplitude A :

$$\sigma = \sigma(A)$$

$$\frac{d^2w}{ds^2} + k_w(s, w) \cdot w = 0$$

This phenomenon is known as the <u>tune spread</u>.

Particle do not rotate at the same speed in the phase-space : possible filamentation



Summary

- Linacs are competitive for low energy, high current, high duty cycle beams or very very high energy light-particles (e⁺-e⁻) colliders.
- Acceleration and longitudinal confinement is done with RF resonant cavities, transverse confinement with quadrupoles (except at very low energy).
- Cavities are pieces of metal (Cu or Nb) whose shape is optimised to accelerate the particles at the RF frequency with the higher efficiency (ZT² as high as possible) and the lower cost.
- RF phases in cavities are adjusted with respect to a synchronous particle to accelerate the beam and keep it bunched (synchronous phase choice).
- There exists a matched beam at input of each periodic structure
- Forces are linearised to calculate the beam matching to the structure.
- non linear forces have to be taken into account to quantified the effect of the errors on the emittance growth (loss of luminosity or halo formation).