

# Introduction to Beam Instrumentation

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# An accelerator can never be better than the instruments measuring its performance!

- A Beam Diagnostics and Instrumentation activity
  - Designs & builds
  - Maintains & improves

the diagnostic instruments that allow the observation of particle beams with the precision required to diagnose, tune, operate and improve an accelerator and its associated transfer lines.

- Beam Instrumentation combines the disciplines of:
  - accelerator physics
  - mechanical engineering
  - electronic engineering
  - software engineering.

In Short: A fascinating field of work



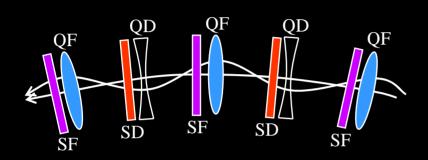
### Introduction

- What do we mean by beam instrumentation?
  - The "eyes" of the machine operators
    - i.e. the instruments that observe beam behaviour
- What beam parameters do we measure?
  - Beam Position
    - Horizontal and vertical throughout the accelerator
    - Corrected using orbit corrector magnets (dipoles)
  - Beam Intensity (& lifetime measurement for a storage ring/collider)
    - bunch-by-bunch charge and circulating current
  - Beam Loss
    - Especially important for superconducting machines
  - Beam profiles
    - Transverse and longitudinal distribution
  - Collision rate / Luminosity (for colliders)
    - Measure of how well the beams are overlapped at the collision point



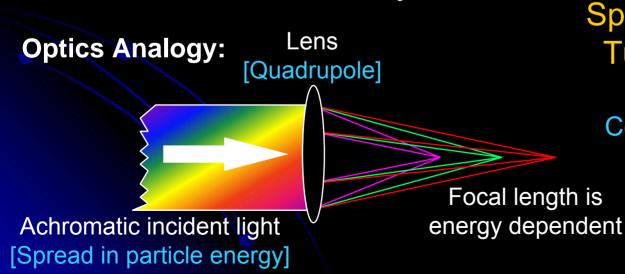
### More Measurements

Machine Tune



Characteristic Frequency
of the Magnet Lattice
Given by the strength of the
Quadrupole magnets

Machine Chromaticity



Spread in the Machine
Tune due to Particle
Energy Spread
Controlled by Sextupole
magnets

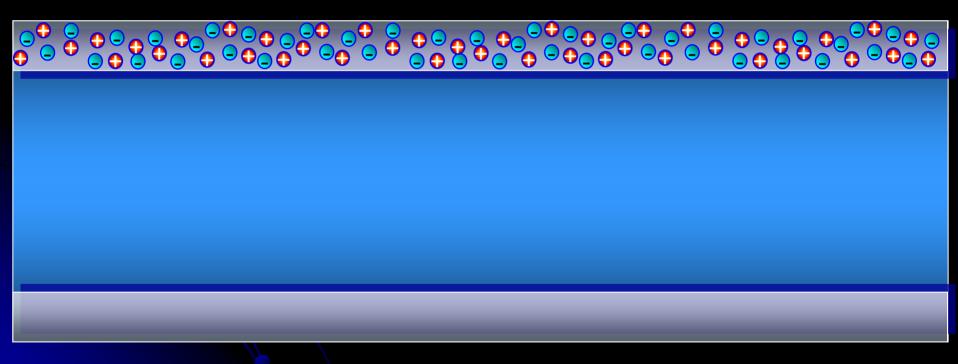


## The Typical Instruments

- Beam Position
  - electrostatic or electromagnetic pick-ups and related electronics
- Beam Intensity
  - beam current transformers
- Beam Profile
  - secondary emission grids and screens
  - wire scanners
  - synchrotron light monitors
  - ionisation and luminescence monitors
  - femtosecond diagnostics for ultra short bunches (afternoon course)
- Beam Loss
  - ionisation chambers or pin diodes
- Machine Tune and Chromaticity
  - in diagnostics section of tomorrow
- Luminosity
  - in diagnostics section of tomorrow

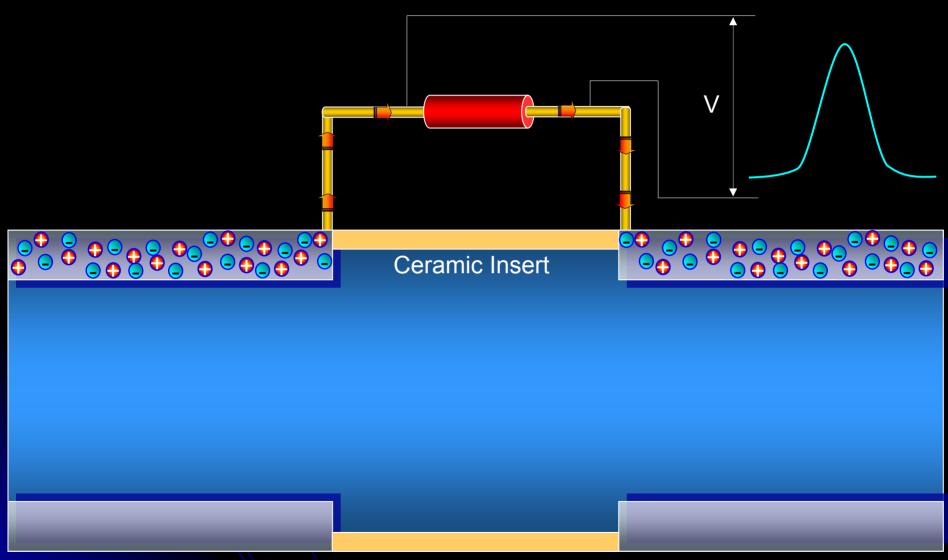


## Measuring Beam Position - The Principle



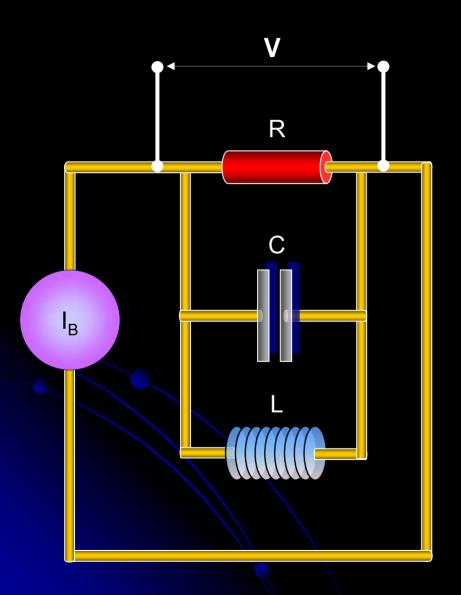


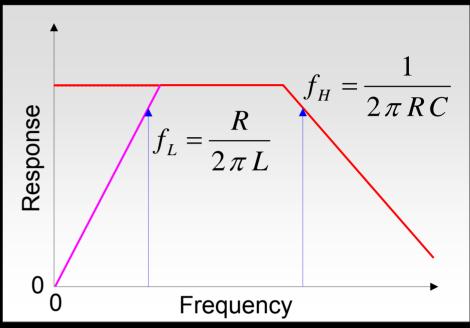
## Wall Current Monitor – The Principle

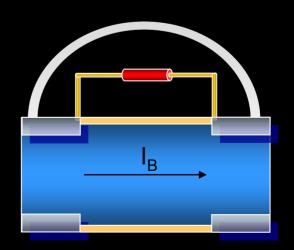




## Wall Current Monitor - Beam Response

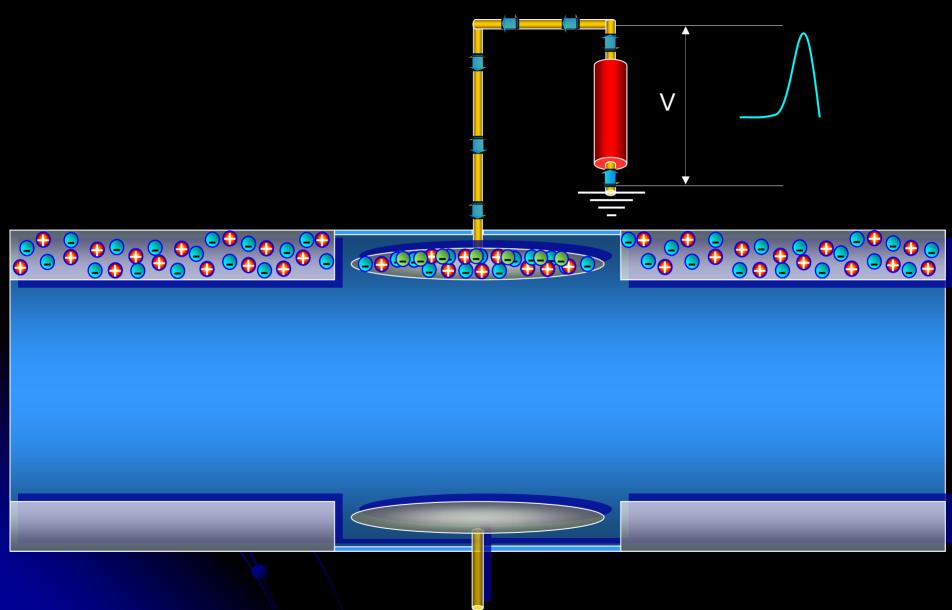






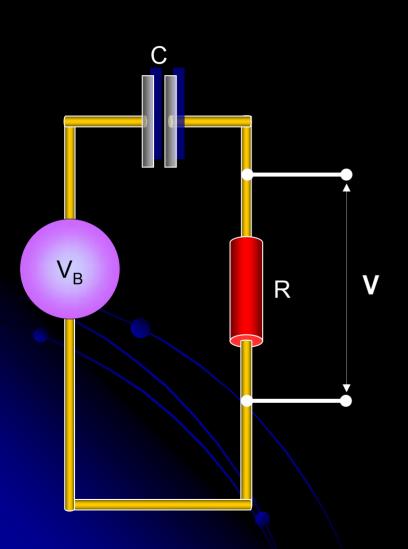


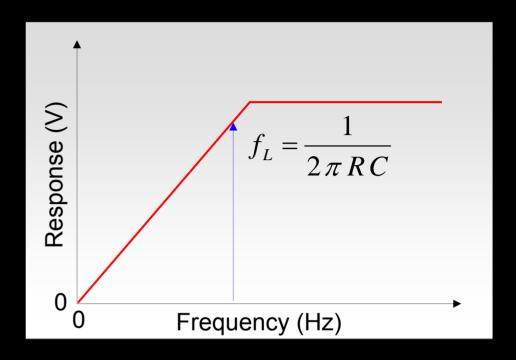
## **Electrostatic Monitor – The Principle**

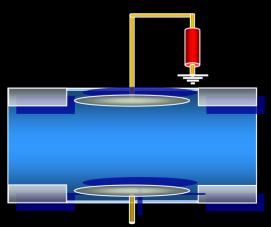




## Electrostatic Monitor – Beam Response



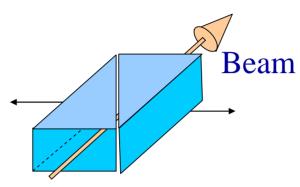


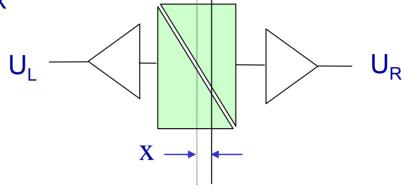




## Electrostatic Pick-up - Shoebox

Linear cut through a shoebox





Linear Response across the aperture

$$x \propto \frac{U_L - U_R}{U_L + U_R} = \frac{\Delta}{\Sigma}$$



Same principle applied to a cylindrical pick-up

- The cuts can be made by photo-chemical or mechanical means
  - Here done with a sand-blasting device



## Electrostatic Pick-up - Button

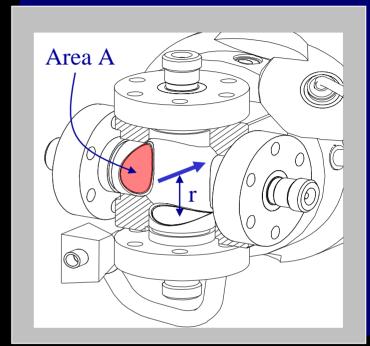
- Variant of electrostatic PU
- ✓ Low cost ⇒ most popular
- × Non-linear
  - requires correction algorithm when beam is off-centre

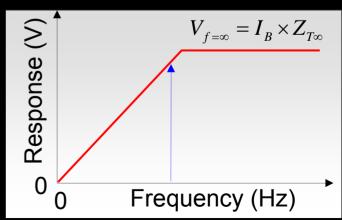
Transfer Impedance:

$$Z_{T\infty} = \frac{A}{(2\pi r) \times c \times C_e}$$

Low frequency cut-off:

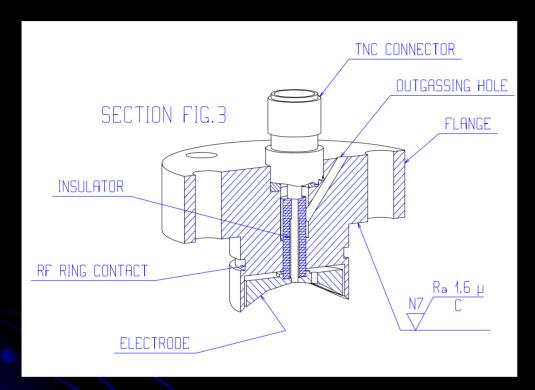
$$f_L = \frac{1}{2\pi RC}$$







# What does a real (LHC) electrostatic button monitor look like?



$$Z_{T\infty} = \frac{A}{(2\pi r) \times c \times C_e} = \frac{\pi \times (12mm)^2}{(2\pi \times 24.5mm) \times c \times (8pF)} = 1.2\Omega$$

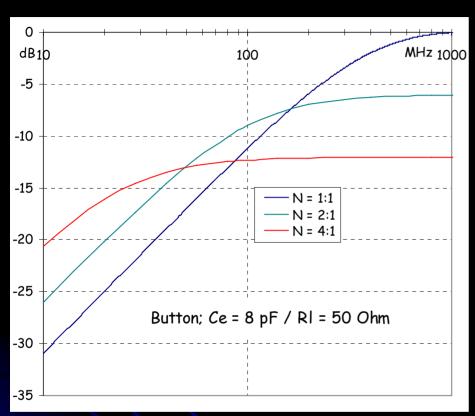
$$f_L = \frac{1}{2\pi RC} = \frac{1}{2\pi \times 50\Omega \times 8pF} = 400MHz$$

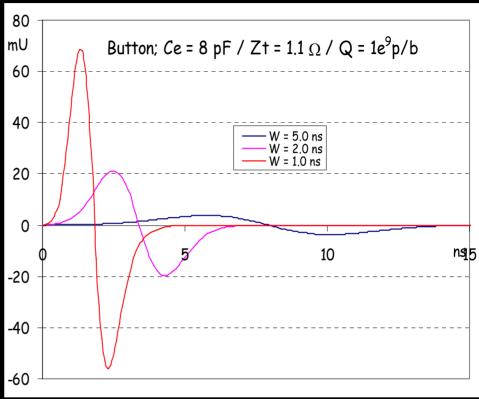






## **Button Frequency & Time Response**





### Frequency domain:

 Impedance transformers improve the low frequency levels at the expense of the high frequency

### • Time domain:

- Differentiated pulse
- Exponential dependence of amplitude on bunch length

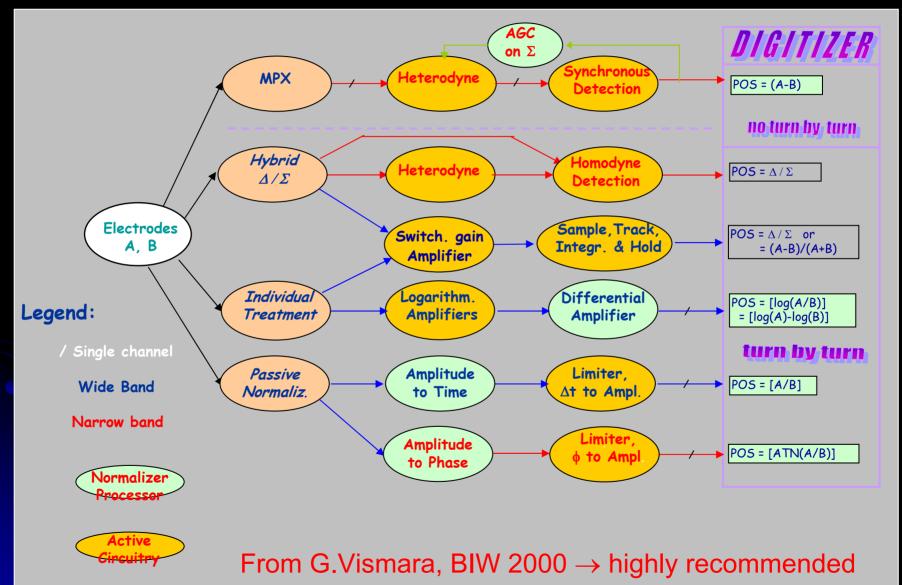


# Criteria for Electronics Choice - so called "Processor Electronics"

- Accuracy
  - mechanical and electromagnetic errors
  - electronic components
- Resolution
- Stability over time
- Sensitivity and Dynamic Range
- Acquisition Time
  - measurement time
  - repetition time
- Linearity
  - aperture & intensity
- Radiation tolerance

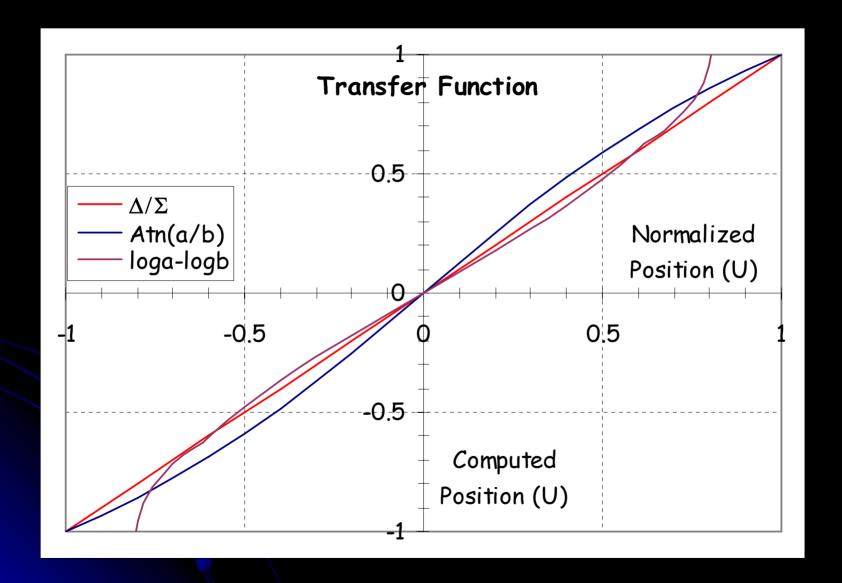


## **Processing System Families**



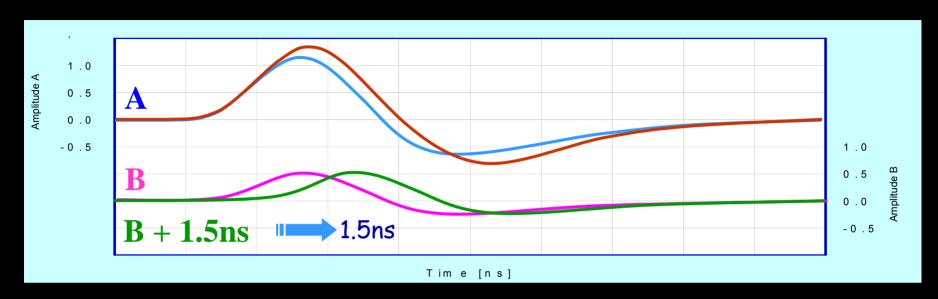


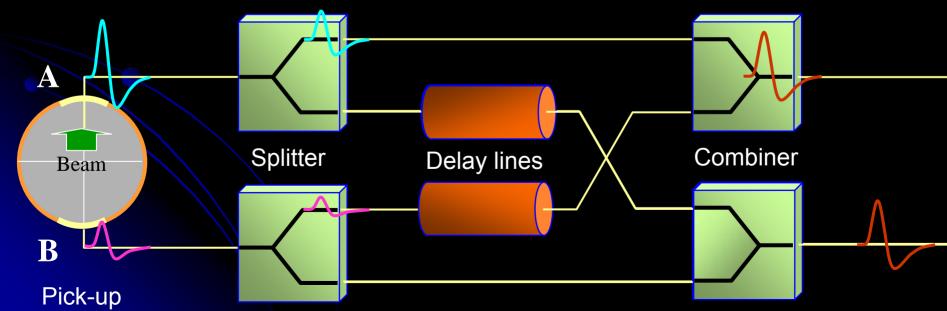
# **LINEARITY Comparison**





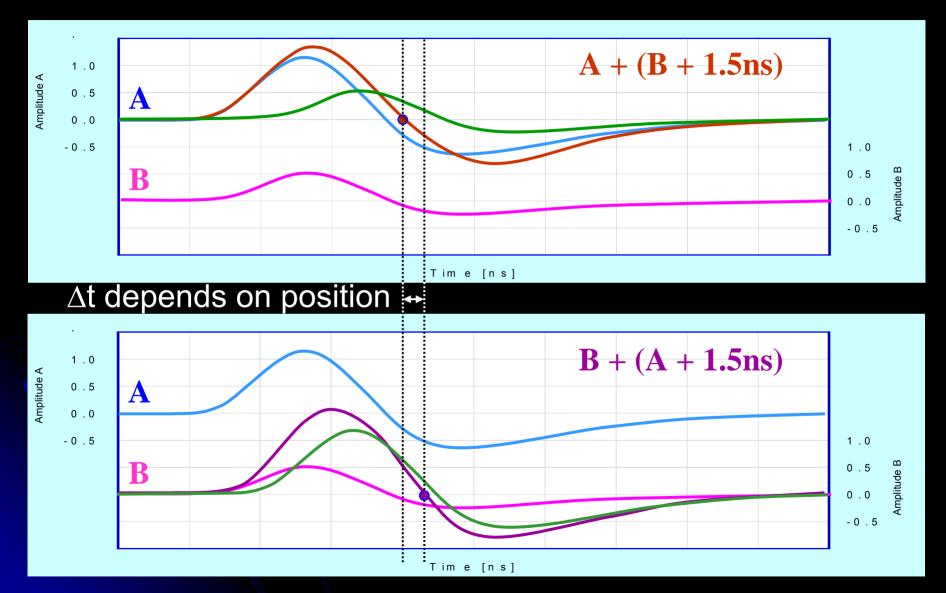
## **Amplitude to Time Normalisation**







## **Amplitude to Time Normalisation**





# BPM Acquisition Electronics Amplitude to Time Normaliser

#### Advantages

- Fast normalisation (< 25ns)</li>
  - bunch to bunch measurement
- Signal dynamic independent of the number of bunches
  - Input dynamic range ~45 dB
  - No need for gain selection
- Reduced number of channels
  - normalisation at the front-end
- ~10 dB compression of the position dynamic due to the recombination of signals
- Independent of external timing
- Time encoding allows fibre optic transmission to be used

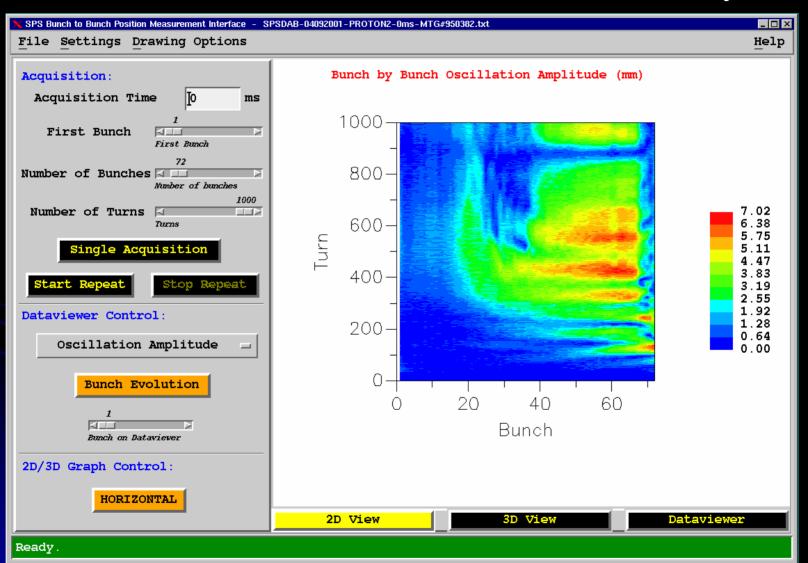
#### Limitations

- Currently reserved for beams with empty RF buckets between bunches e.g.
  - LHC 400MHz RF but 25ns spacing
  - 1 bunch every 10 buckets filled
- Tight time adjustment required
- No Intensity information
- Propagation delay stability and switching time uncertainty are the limiting performance factors



## What one can do with such a System

Used in the CERN-SPS for electron cloud & instability studies.



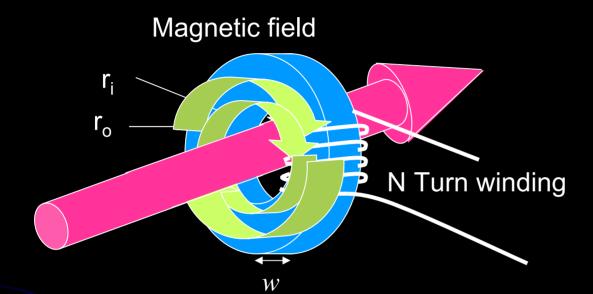


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- Machine Tunes and Chromacitities
  - in diagnostics section of tomorrow
- Luminosity
  - in diagnostics section of tomorrow



## **Current Transformers**



Fields are very low

Capture magnetic field lines with cores of high relative permeability

(CoFe based amorphous alloy Vitrovac:  $\mu_r = 10^5$ )

#### Beam current

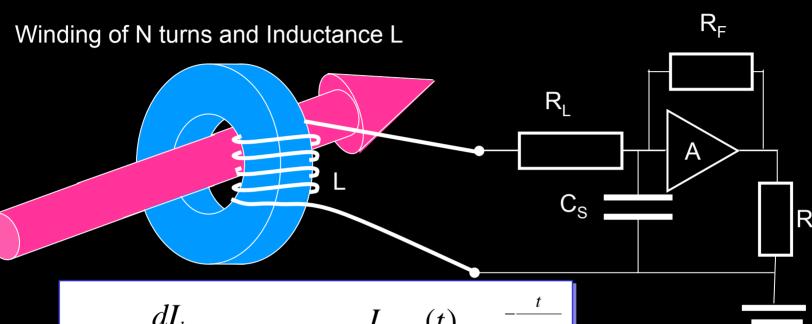
$$I_{Beam} = \frac{e N_q}{t} = \frac{e N_q \beta c}{w}$$

#### **Transformer Inductance**

$$L = \frac{\mu_0 \ \mu_r}{2\pi} w N^2 \ln \frac{r_0}{r_1}$$

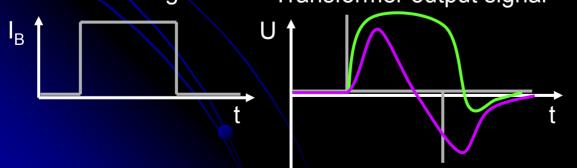


## The Active AC transformer



$$U = L \frac{dI_{beam}}{dt} \qquad U(t) = \frac{I_{beam}(t)}{N} R e^{-\frac{t}{\tau_{droop}}}$$

Beam signal Transformer output signal

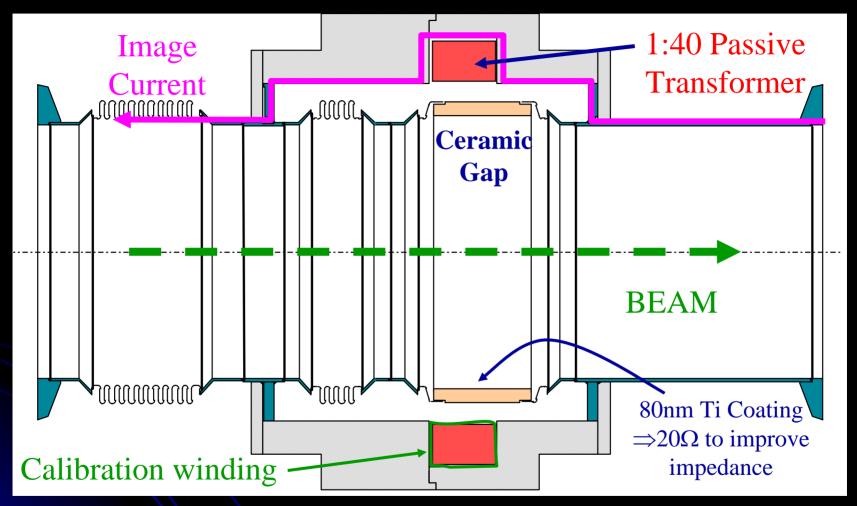


$$\tau_{rise} = \sqrt{L_s C_s}$$

$$\tau_{droop} = \frac{L}{\frac{R_f}{A} + R_L} \approx \frac{L}{R_L}$$



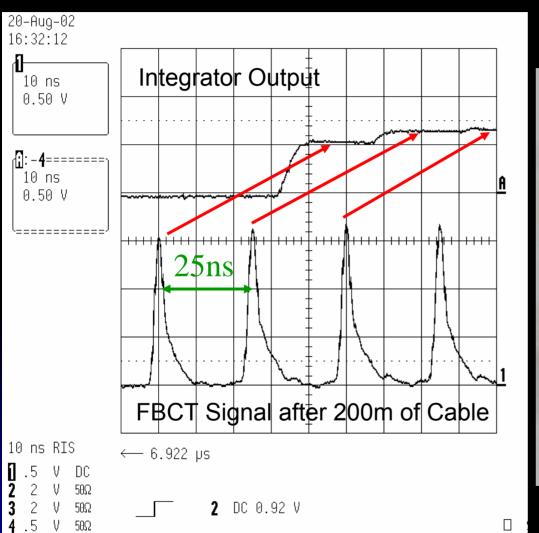
## Fast Beam Current Transformer



- 500MHz Bandwidth
- Low droop (< 0.2%/μs)</li>



## **Acquisition Electronics**

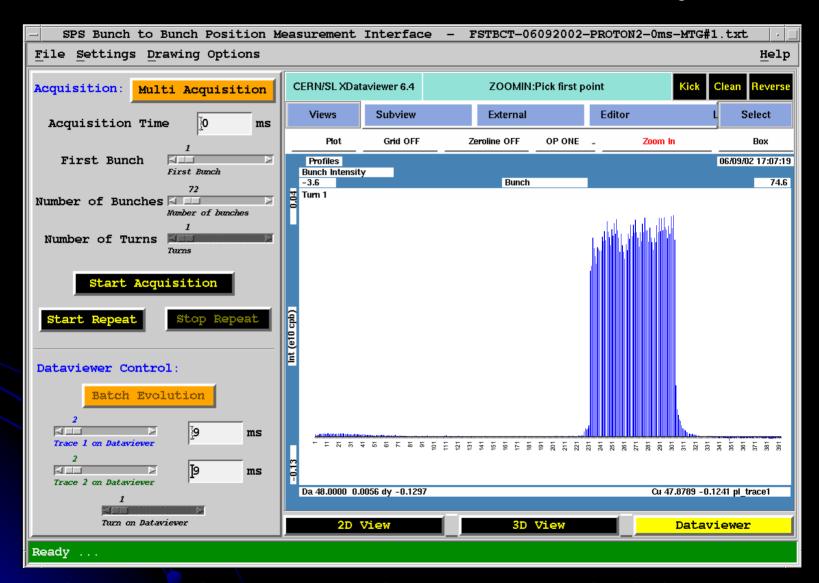




Data taken on LHC type beams at the CERN-SPS



## What one can do with such a System

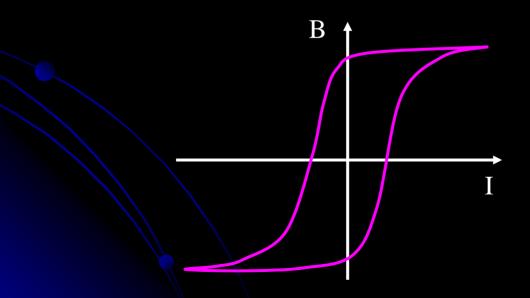


Bad RF Capture of a single LHC Batch in the SPS (72 bunches)



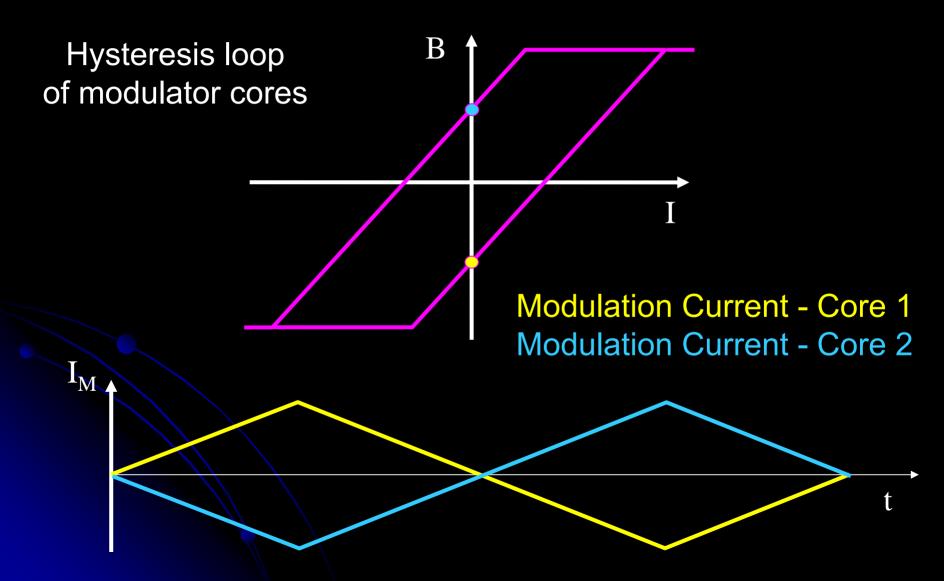
## The DC current transformer

- AC current transformer can be extended to very long droop times but not to DC
- DC current measurement is required in storage rings
- To do this:
  - Take advantage of non-linear magnetisation curve
  - Apply a modulation frequency to 2 identical cores



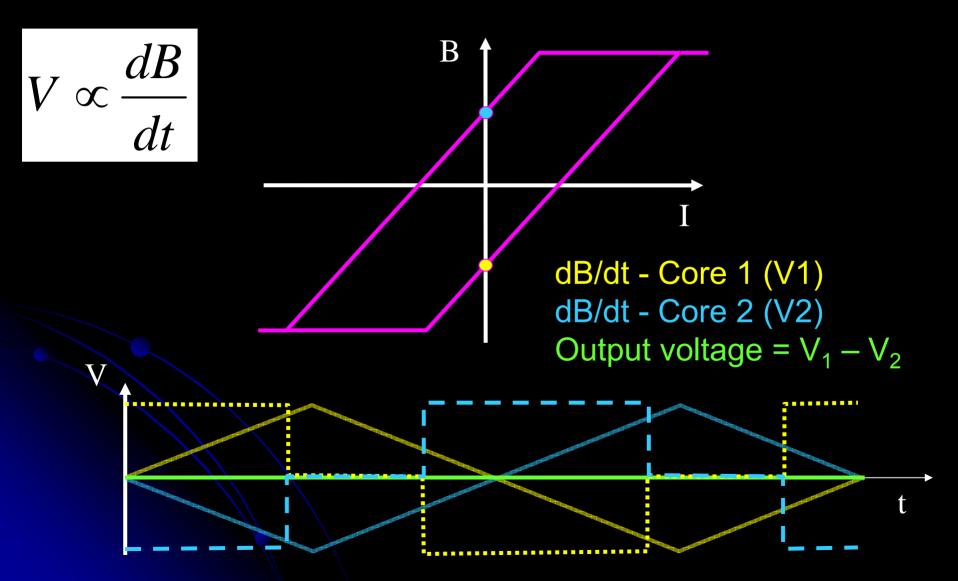


# DCCT Principle - Case 1: no beam



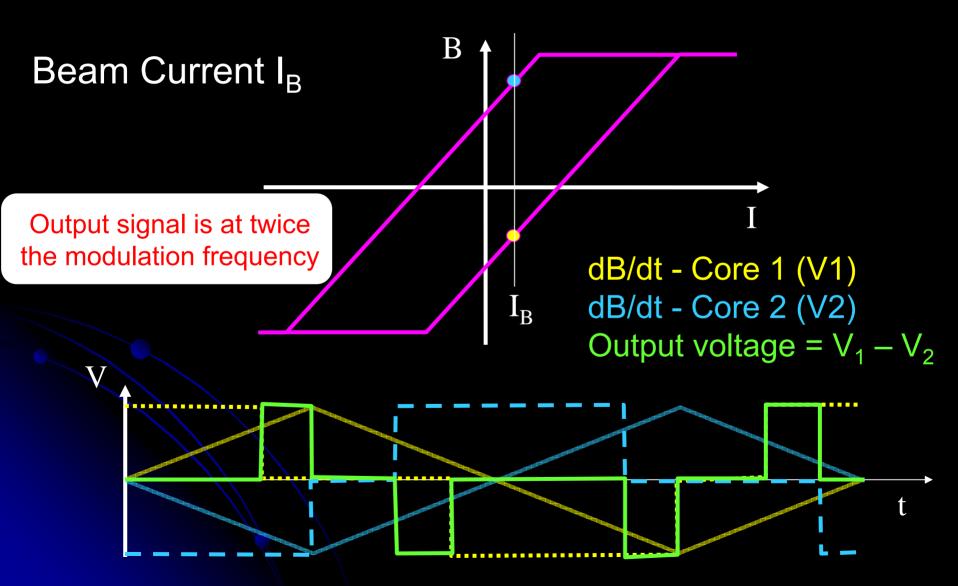


## DCCT Principle - Case 1: no beam



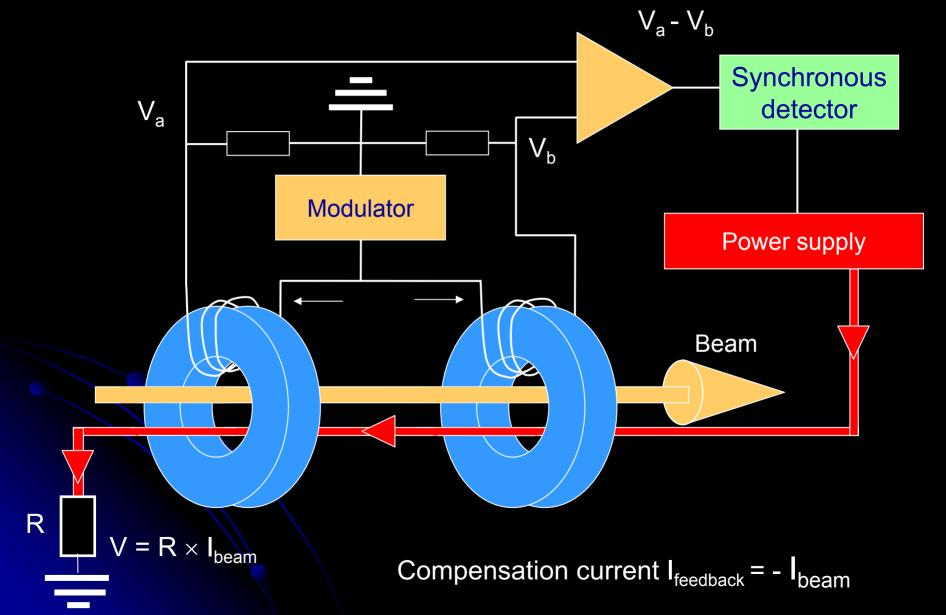


# DCCT Principle - Case 2: with beam





## **Zero Flux DCCT Schematic**





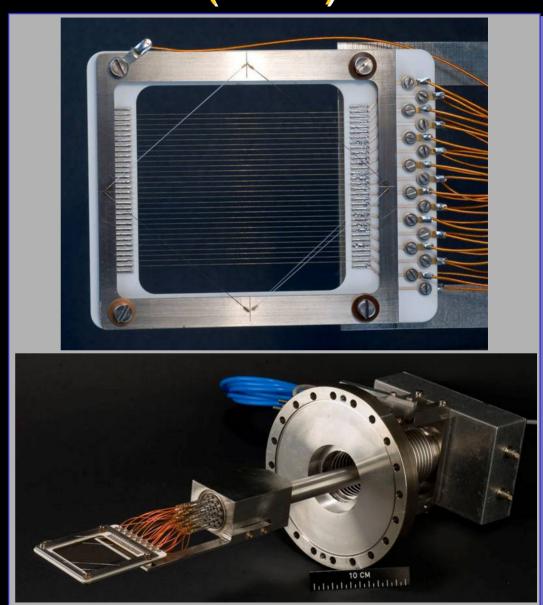
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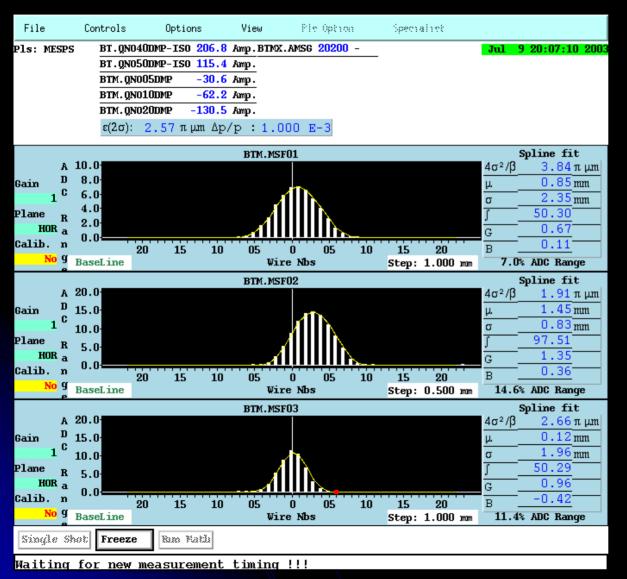
## Secondary Emission (SEM) Grids

- When the beam passes through secondary electrons are ejected from the wires
- The current flowing back onto the wires is measured
- The liberated electrons are removed using a polarisation voltage
- One amplifier/ADC chain is used for each wire





## Profiles from SEM grids

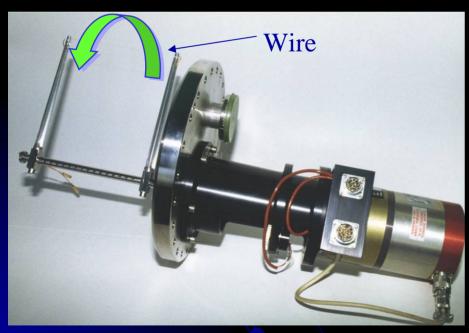


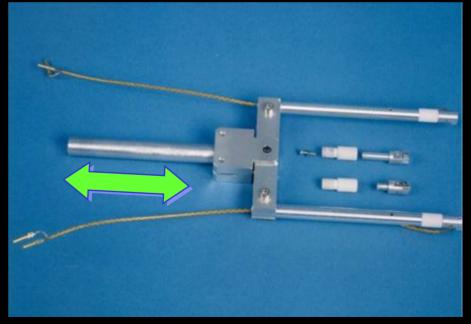
- Charge density
   measured from each
   wire gives a projection
   of the beam profile in
   either horizontal or
   vertical plane
- Resolution is given by distance between wires
- Used only in transfer lines as heating is too great for circulating beams



### Wire Scanners

- For circulating beams a thin wire is moved across the beam
  - has to move fast to avoid excessive heating of the wire
- Detection
  - secondary particle shower detected outside the vacuum chamber using a scintillator/photo-multiplier assembly
  - Secondary emission current detected as for SEM grids
  - Correlating wire position with detected signal gives the beam profile



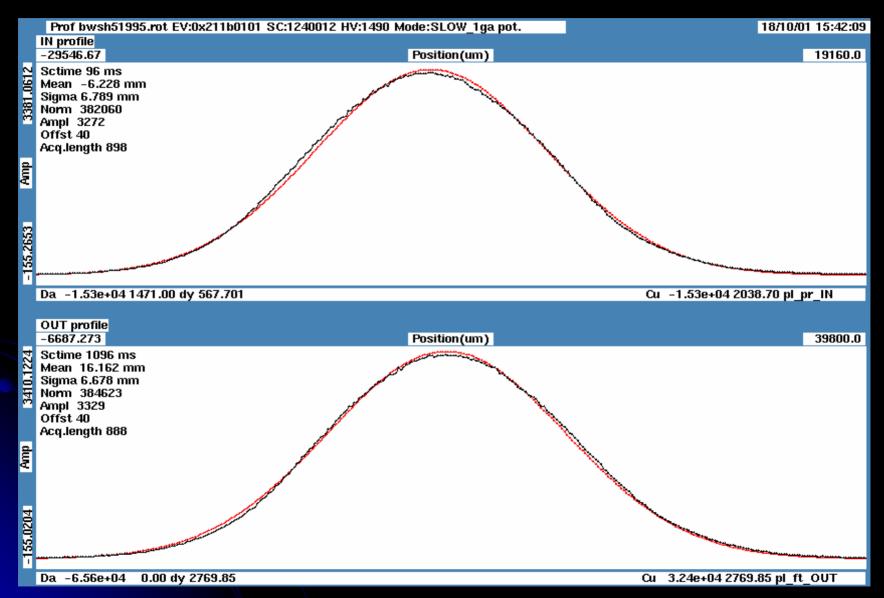


Rotative wire scanner

Linear wire scanner



# **Measurement Results**





### Beam Profile Monitoring using Screens

- Screen Types
  - Luminescence Screens
    - destructive (thick) but work during setting-up with low intensities
  - Optical Transition Radiation (OTR) screens
    - much less destructive (thin) but require higher intensity

Sensitivities measured with protons with previous screen holder, normalised for  $7 \text{ px/}\sigma$ 



Type	Material	Activator	Sensitivity
Luminesc.	CsI	Tl	6 10 <sup>5</sup>
"	$Al_2O_3$	0.5%Cr	3 107
**	Glass	Ce	3 109
**	Quartz	none	6 10 <sup>9</sup>
OTR [bwd]	Al		2 1010
44	Ti		2 1011
44	С		2 1012

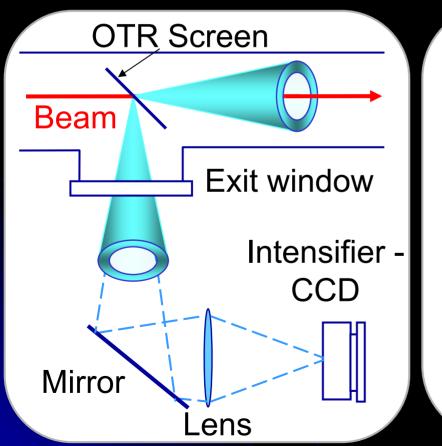
Luminesc. GSI	P43: Gd,O, S	Tb	2 107
	2		

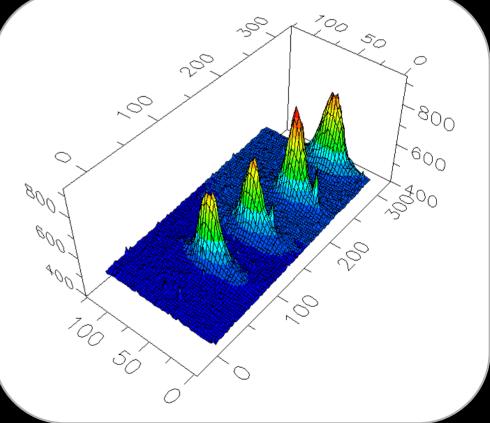




# OTR – The Principle

- Radiation emitted when a charged particle beam goes through the interface of 2 media with different dielectric constants
  - surface phenomenon allows the use of very thin screens (~10mm)







# Beam Profile Monitoring using Screens

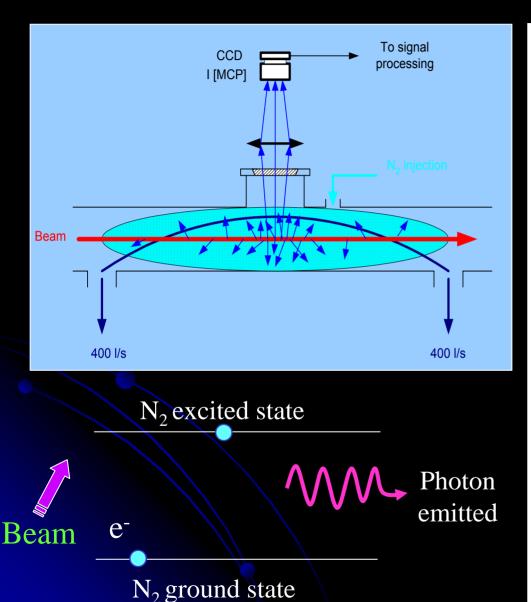
- Usual configuration
  - Combine several screens in one housing e.g.
    - Al<sub>2</sub>O<sub>3</sub> luminescent screen for setting-up with low intensity
    - Thin (~10um) Ti OTR screen for high intensity measurements
    - Carbon OTR screen for very high intensity operation

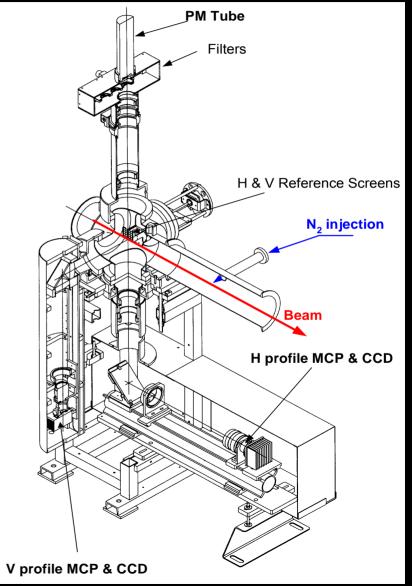


- Advantages compared to SEM grids
  - allows analogue camera or CCD acquisition
  - gives two dimensional information
  - high resolution: ~ 400 x 300 = 120'000 pixels for a standard CCD
  - more economical
    - Simpler mechanics & readout electronics
  - Time resolution depends on choice of image capture device
    - From CCD in video mode at 50Hz to Streak camera in the GHz range



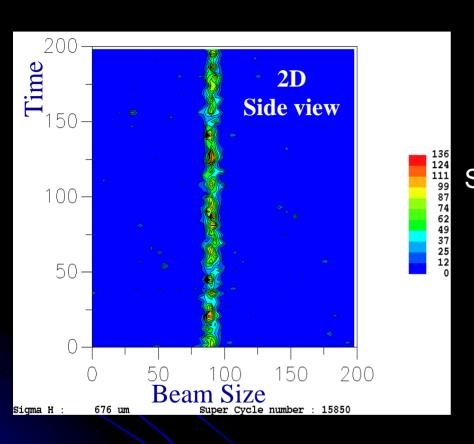
# **Luminescence Profile Monitor**





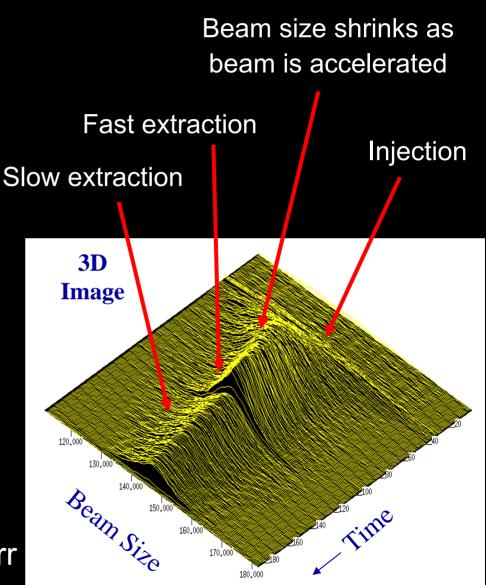


#### **Luminescence Profile Monitor**



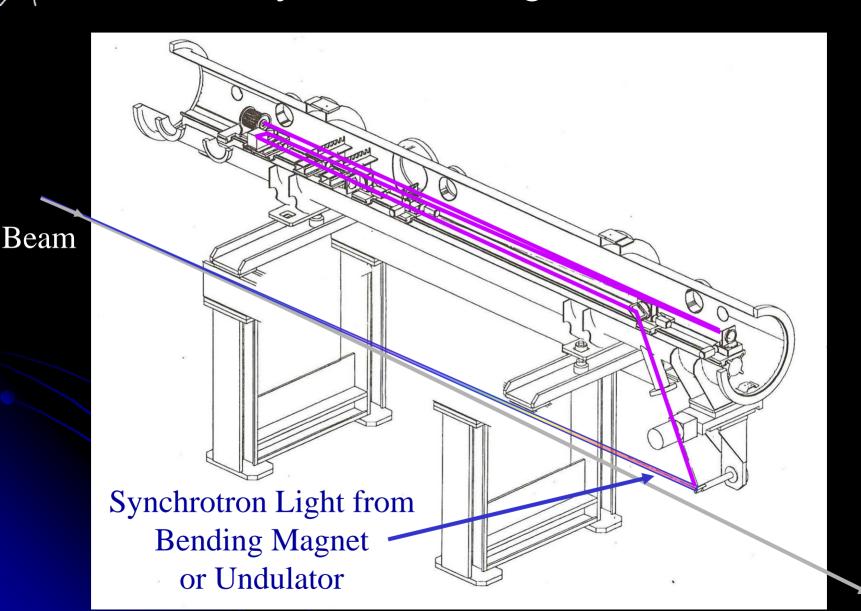


- Profile Collected every 20ms
- Local Pressure at ~5×10-7 Torr





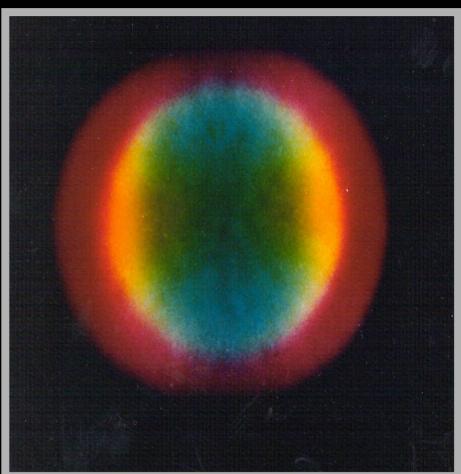
# The Synchrotron Light Monitor





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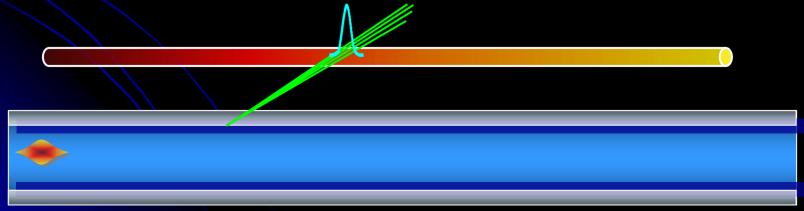
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#### **Beam Loss Detectors**

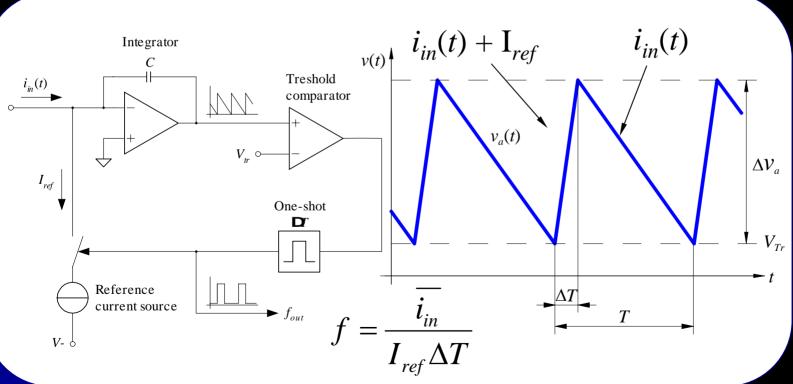
- Role of a BLM system:
  - 1. Protect the machine from damage
  - Dump the beam to avoid magnet quenches (for SC magnets)
  - 3. Diagnostic tool to improve the performance of the accelerator
- Common types of monitor
  - Long ionisation chamber (charge detection)
    - Up to several km of gas filled hollow coaxial cables
    - Position sensitivity achieved by comparing direct & reflected pulse
      - e.g. SLAC 8m position resolution (30ns) over 3.5km cable length
    - Dynamic range of up to 10<sup>4</sup>





# **Beam Loss Detectors**

- Common types of monitor (cont)
  - Short ionisation chamber (charge detection)
    - Typically gas filled with many metallic electrodes and kV bias
    - Speed limited by ion collection time tens of microseconds
    - Dynamic range of up to 10<sup>8</sup>



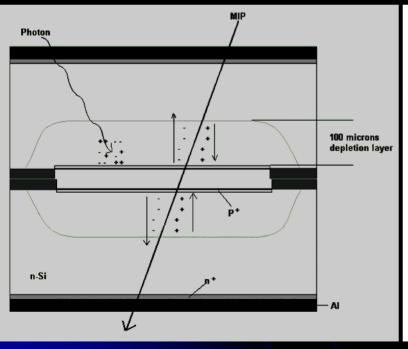


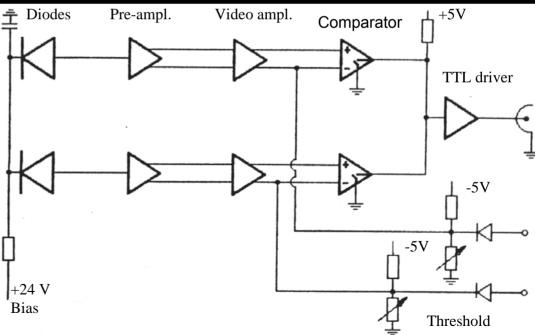


### **Beam Loss Detectors**

- Common types of monitor (cont)
  - PIN photodiode (count detection)
    - Detect MIP crossing photodiodes
    - Count rate proportional to beam loss
    - Speed limited by integration time
    - Dynamic range of up to 10<sup>9</sup>

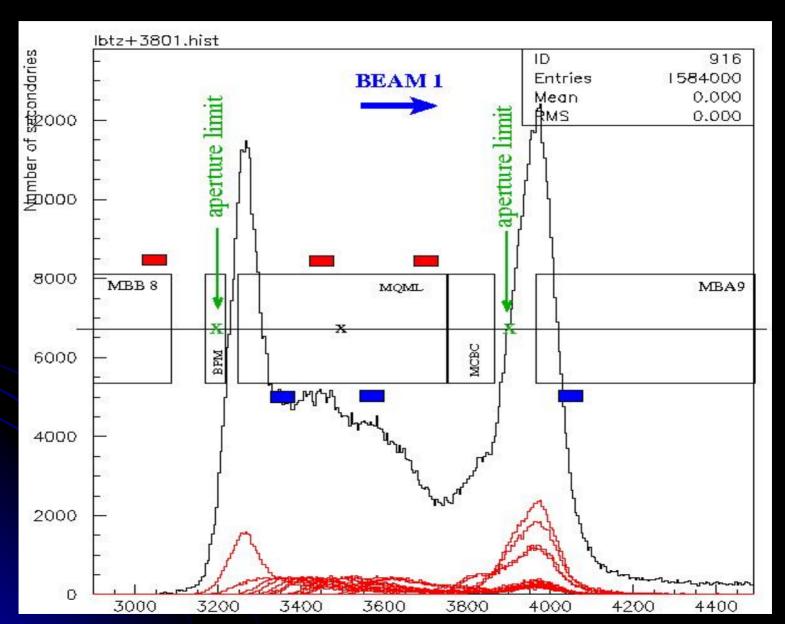








#### **BLM Threshold Level Estimation**





# Summary

We have seen a wide variety of instruments using many different technologies

Tomorrow you will see how to use these instruments to run and optimise accelerators

Accelerator Beam Diagnostics