

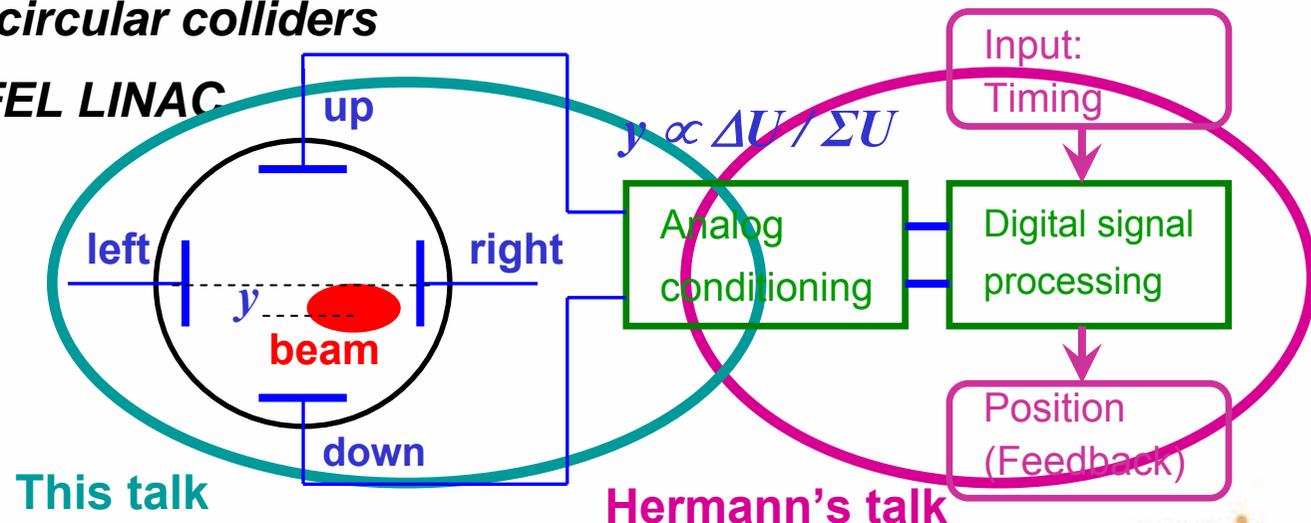
Beam Position Monitors: Detector Principle and Signal Estimation

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Outline:

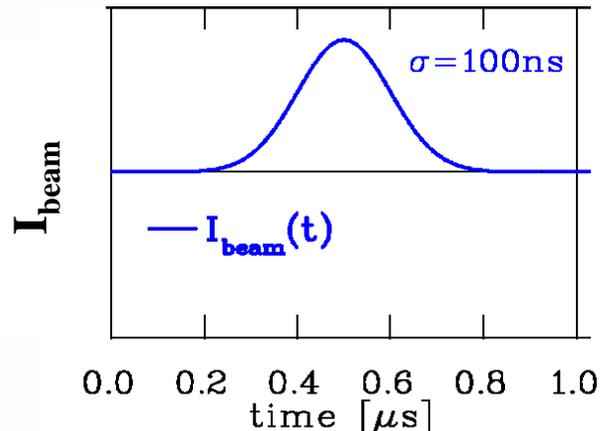
- **General discussion on BPM features and specification**
- **Sum signal estimation, example 'shoe box' BPM for proton synchrotron**
- **Differential signal estimation, example 'button' BPM for p-LINAC and e**
- **'Stripline' BPM for circular colliders**
- **'Cavity' BPMs for FEL LINAC**



Preface: Time Domain ↔ Frequency Domain



Time domain: Recording of a voltage as a function of time:



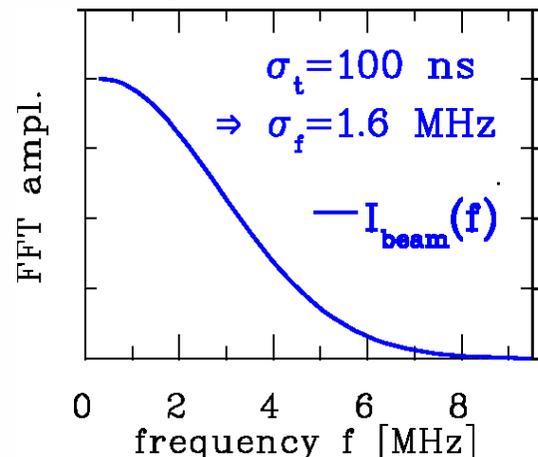
**Instrument:
Oscilloscope**



**Fourier
Transformation:**

$$\tilde{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt$$

Frequency domain: Displaying of a voltage as a function of frequency:



**Instrument:
Spectrum Analyzer
or Fourier Transformation of time domain data
Care: Contains amplitude *and* phase**

Usage of BPMs



A *Beam Position Monitor* is a non-destructive device for bunched beams

It has a low cut-off frequency i.e. dc-beam behavior can not be monitored

The abbreviation BPM and pick-up PU are synonyms

It delivers information about the transverse center of the beam

- ***Trajectory***: Position of an individual bunch within a transfer line or synchrotron
- ***Closed orbit***: central orbit averaged over a period much longer than a betatron oscillation
- ***Single bunch position*** → determination of parameters like tune, chromaticity, β -function
- Bunch position on a large time scale: bunch-by-bunch → turn-by-turn → averaged position
- Time evolution of a single bunch can be compared to ‘macro-particle tracking’ calculations
- Feedback: fast bunch-by-bunch damping *or* precise (and slow) closed orbit correction

Trajectory Measurement with BPMs

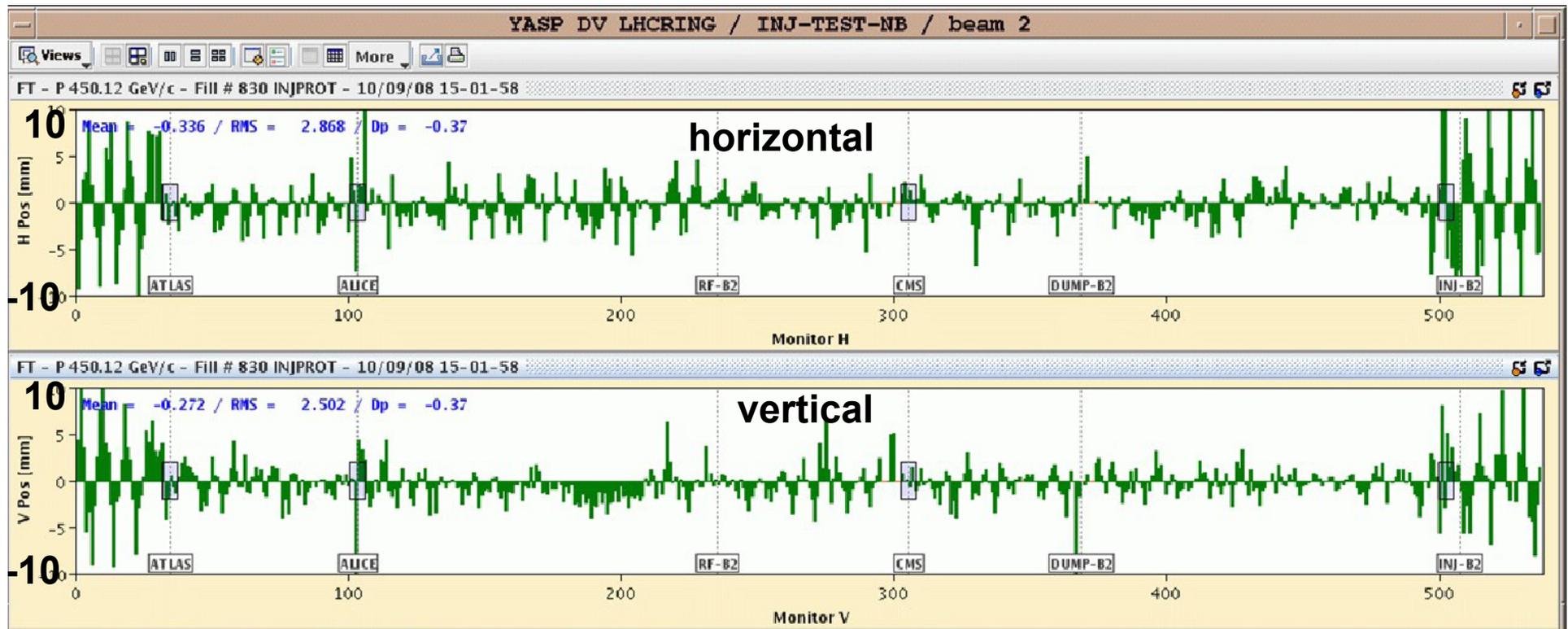


Trajectory:

The position delivered by an individual bunch within a transfer line or a synchrotron.

Main task: Control of matching (center and angle), first-turn diagnostics

Example: LHC injection 10/09/08 (y-axis: -10 → 10 mm, x-axis: monitor number 0 → 530)



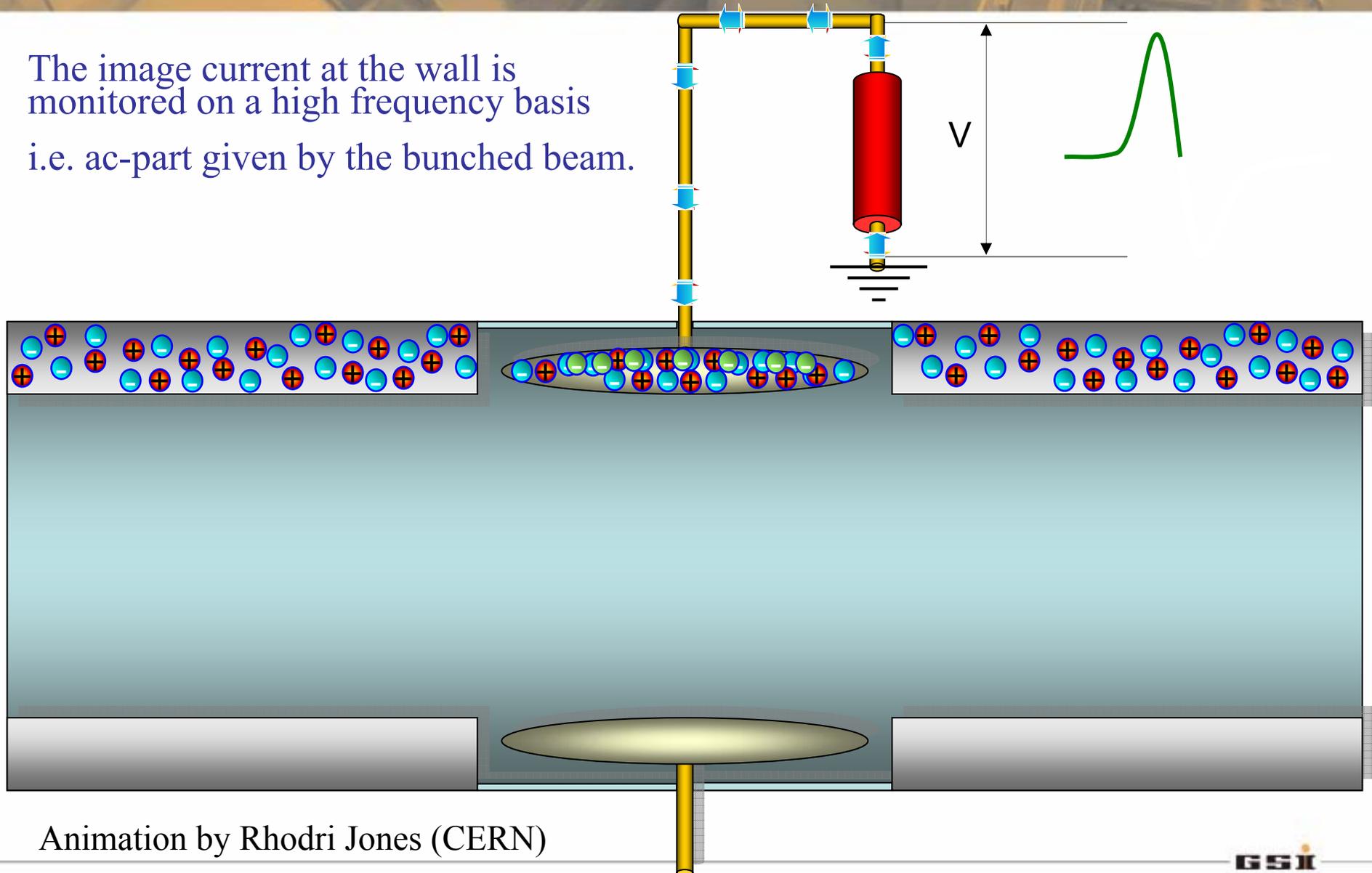
From R. Jones (CERN)



Principle of Signal Generation of capacitive BPMs



The image current at the wall is monitored on a high frequency basis i.e. ac-part given by the bunched beam.



Animation by Rhodri Jones (CERN)



What are the general demands for a proper choice of BPMs?

What are the basic properties to characterize a BPM?

What are adequate technical terms required for the BPM specification?

What are reasons for the choice of an appropriate type?

Characteristics for Position Measurement



Position sensitivity: Factor between beam position & signal quantity

defined as
$$S_x(x, y, f) = \frac{d}{dx} (\Delta U_x / \Sigma U_x) = [\%/mm]$$

Accuracy: Ability for position reading relative to a mechanical fix-point ('absolute position')

- influenced by mechanical tolerances and alignment accuracy and reproducibility
- by electronics: e.g. amplifier drifts, electronic interference, ADC granularity

Resolution: Ability to determine small displacement variation ('relative position')

- typically: **single bunch:** 10^{-3} of aperture $\approx 100 \mu m$
averaged: 10^{-5} of aperture $\approx 1 \mu m$, **goal:** 10 % of beam width $\Delta x \approx 0.1 \cdot \sigma$
- in most case much better than accuracy!
- electronics has to match the requirements e.g. bandwidth, ADC granularity...

Bandwidth: Frequency range available for measurement

- has to be chosen with respect to required resolution via analog or digital filtering

Dynamic range: Range of beam currents the system has to respond

- position reading should not depend on input amplitude

Signal-to-noise: Ratio of wanted signal to unwanted background

- influenced by thermal and circuit noise, electronic interference
- can be matched by bandwidth limitation

Detection threshold=signal sensitivity: minimum beam current for measurement



Comparison of BPM Types (simplified)



Type	Usage	Precaution	Advantage	Disadvantage
Shoe-box	p-Synch.	Long bunches $f_{rf} < 10$ MHz	Very linear No x-y coupling Sensitive For broad beams	Complex mechanics Capacitive coupling between plates
Button	p-Linacs, all e ⁻ acc.	$f_{rf} > 10$ MHz	Simple mechanics	Non-linear, x-y coupling Possible signal deformation
Stipline	colliders p-Linacs all e ⁻ acc.	best for $\beta \approx 1$, short bunches	Directivity 'Clean' signals Large Signal	Complex 50 Ω matching Complex mechanics
Cavity	e ⁻ Linacs (e.g. FEL)	Short bunches Special appl.	Very sensitive	Very complex, high frequency

Remark: Other types are also some time used: e.g. wall current monitors, inductive antenna, BPMs with external resonator, slotted wave-guides for stochastic cooling etc.

Estimation of the Beam Spectrum



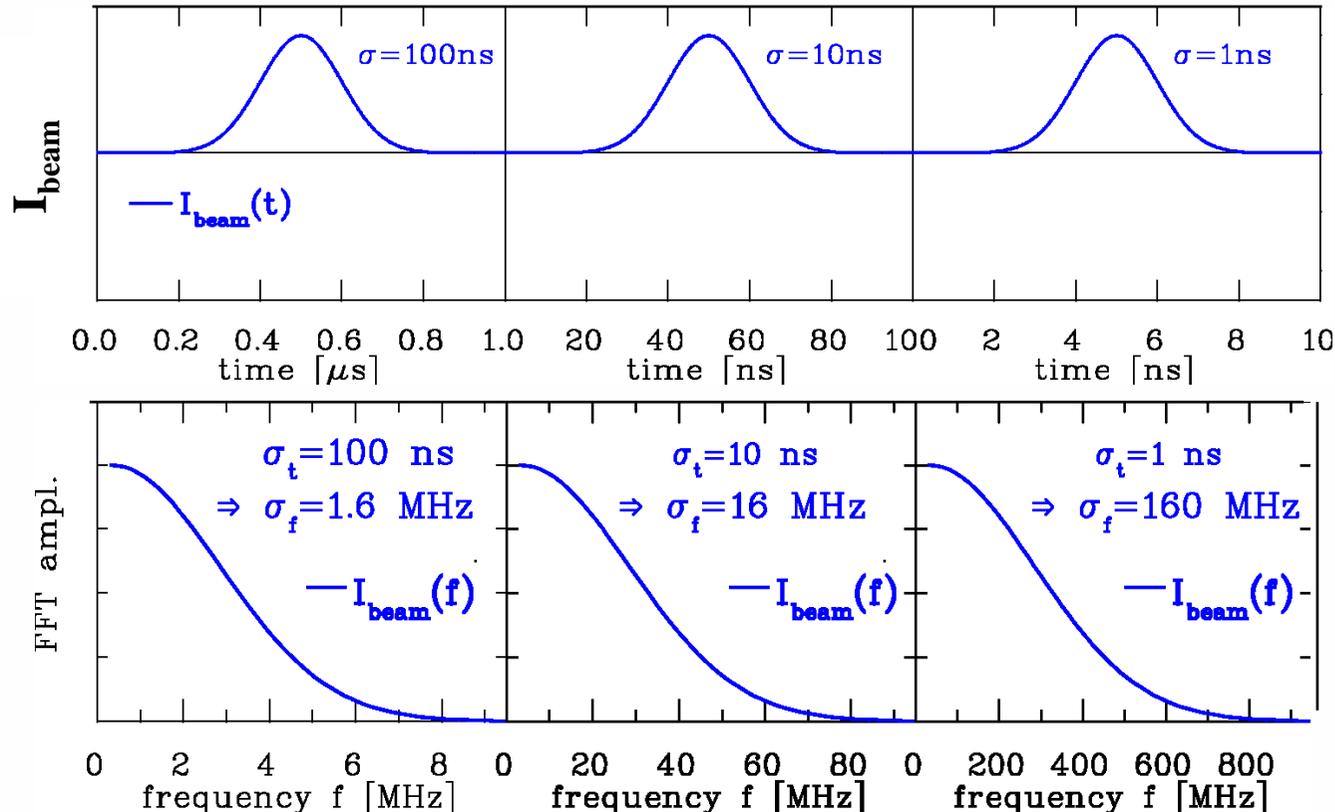
2.1.1 What is the spectral function of a single bunch?

Assume a single bunch of Gaussian width $\sigma_t=100$ ns passing a BPM.

Sketch the spectral beam current $I_{beam}(f)$ as a function of frequency!

What are the corresponding values for $\sigma_t=10$ ns and $\sigma_t=1$ ns?

Note: The Fourier transformation of a Gaussian with σ_t is a half Gaussian with $\sigma_f=1/(2\pi\sigma_t)$.



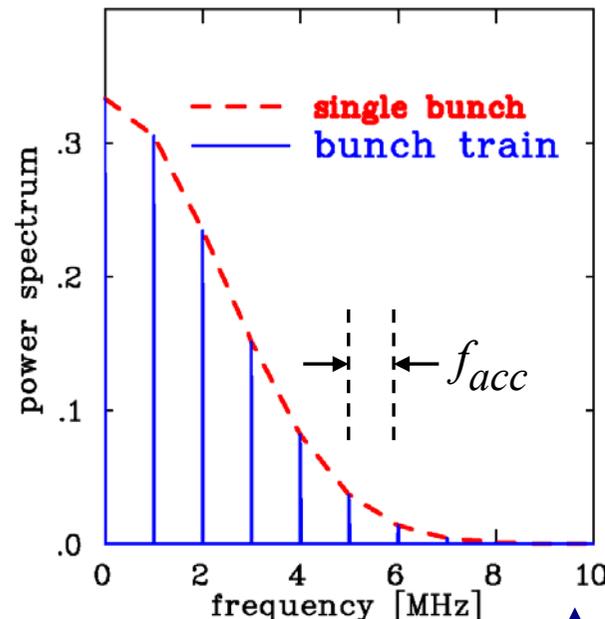
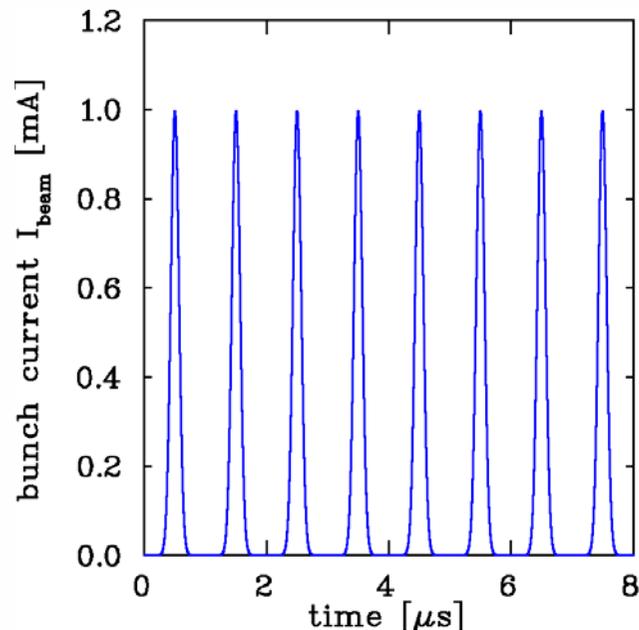
Estimation of the Beam Spectrum



2.1.2 What is the spectral function of a train of bunches?

Assume a train of bunches with $\sigma_t=100$ ns width and a repetition of $f_{acc}=1$ MHz.

Sketch the spectral beam current $I_{beam}(f)$ as a function of frequency!



The spectrum consists of line separated by f_{acc} .

The envelope is given by the single bunch.

Typical value for p-synch.:
most power below $\approx 10 \cdot f_{max}$.

f_{max}



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Shoe-box BPM for Proton or Ion Synchrotron

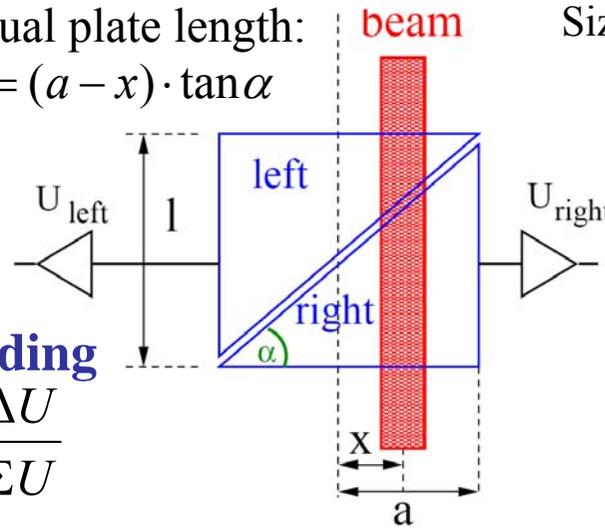


Frequency range: $1 \text{ MHz} < f_{rf} < 10 \text{ MHz} \Rightarrow \text{bunch-length} \gg \text{BPM-length}$.

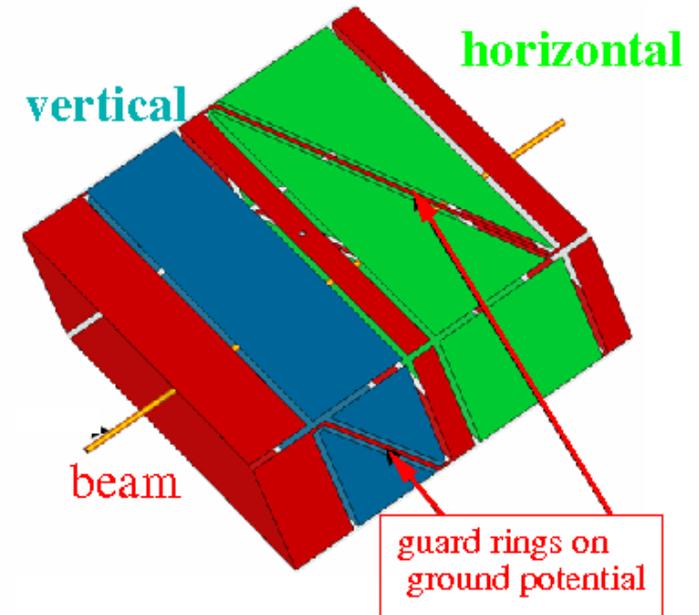
Signal is proportional to actual plate length:

$$l_{\text{right}} = (a + x) \cdot \tan \alpha, \quad l_{\text{left}} = (a - x) \cdot \tan \alpha$$

$$\Rightarrow x = a \cdot \frac{l_{\text{right}} - l_{\text{left}}}{l_{\text{right}} + l_{\text{left}}}$$

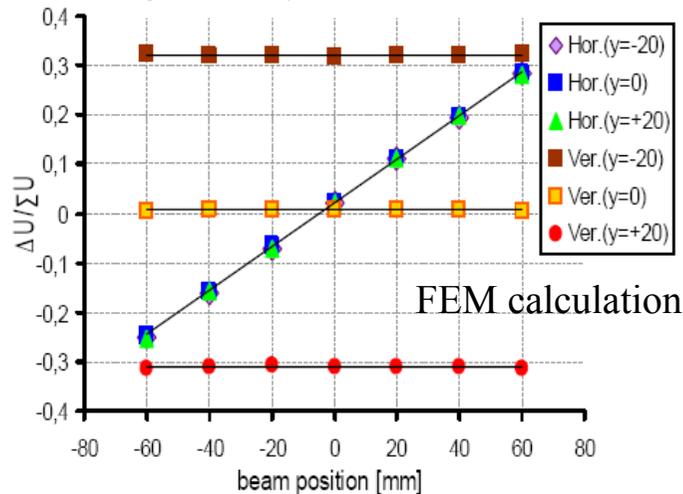


Size: 200x70 mm²



In ideal case: linear reading

$$x = a \cdot \frac{U_{\text{right}} - U_{\text{left}}}{U_{\text{right}} + U_{\text{left}}} \equiv a \cdot \frac{\Delta U}{\Sigma U}$$



Shoe-box BPM:

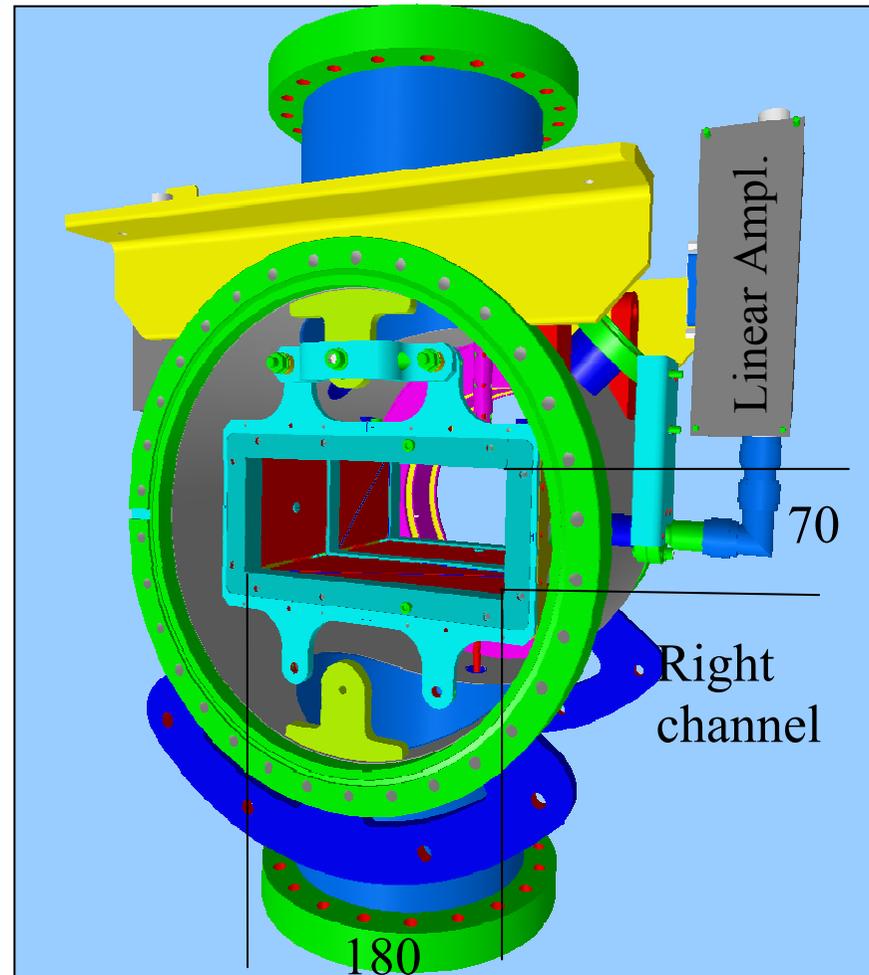
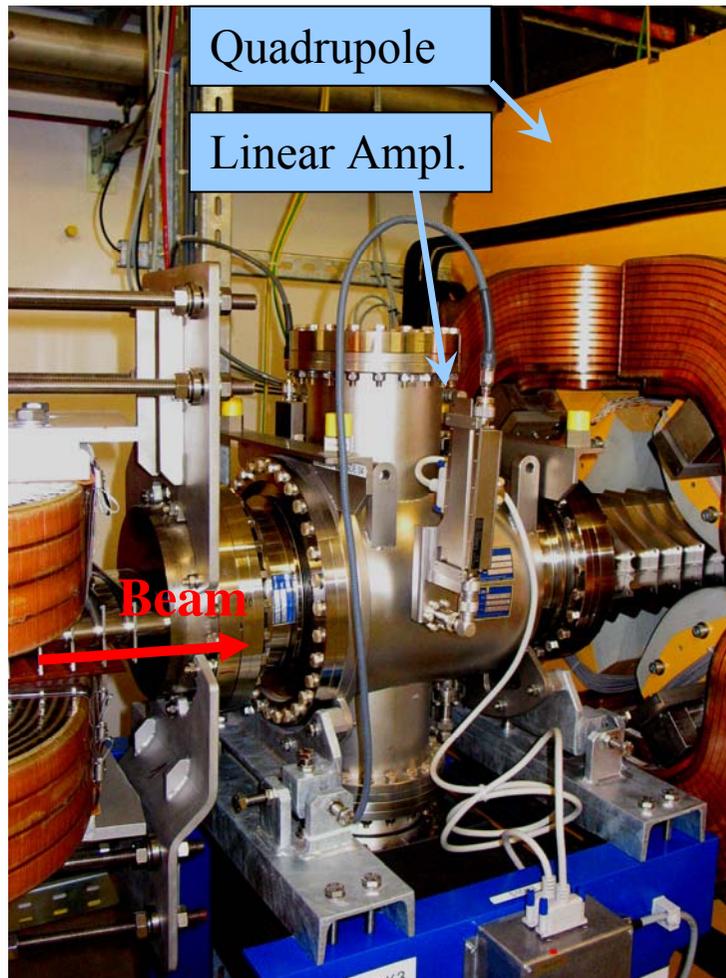
Advantage: Very linear, minor frequency dependence
i.e. position sensitivity \mathcal{S} is constant

Disadvantage: Large size, complex mechanics
high capacitance



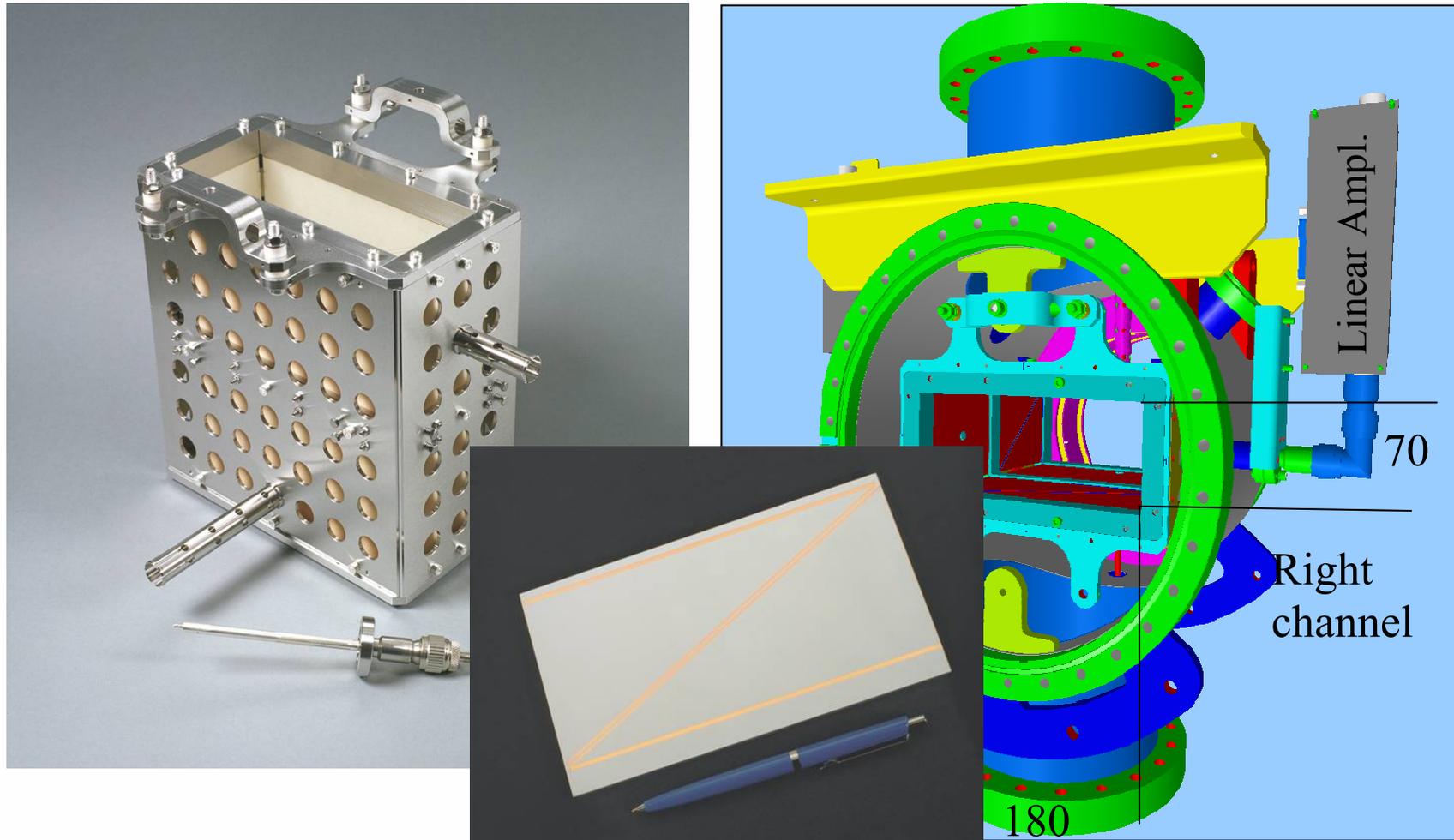
Technical Realization of Shoe-Box BPM

Technical realization at HIT synchrotron of 46 m length for 7 MeV/u \rightarrow 440 MeV/u
BPM clearance: 180x70 mm², standard beam pipe diameter: 200 mm.



Technical Realization of Shoe-Box BPM

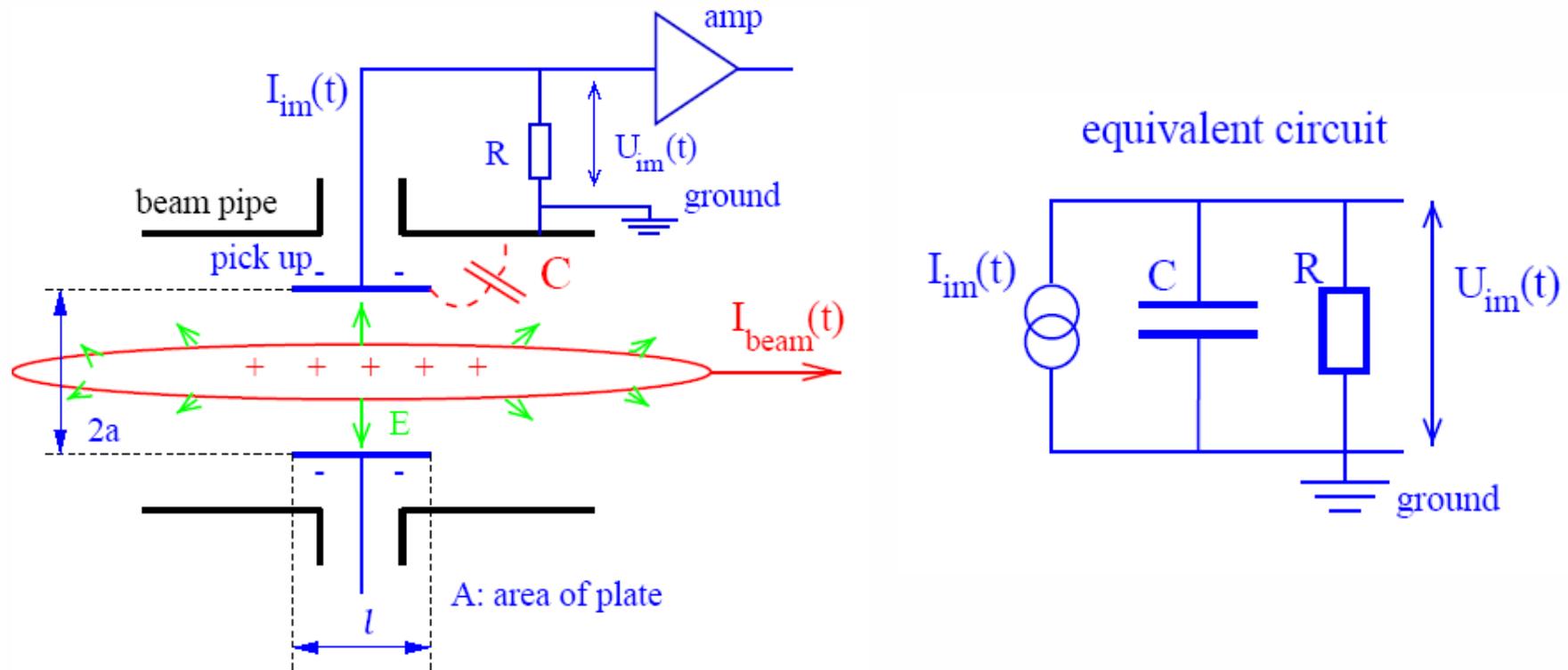
Technical realization at HIT synchrotron of 46 m length for 7 MeV/u \rightarrow 440 MeV/u
BPM clearance: 180x70 mm², standard beam pipe diameter: 200 mm.



Model for Signal Treatment of capacitive BPMs



The wall current is monitored by a plate or ring inserted in the beam pipe:



The image current I_{im} at the plate is given by the geometry and the capacitive coupling:

$$I_{im}(t) = \frac{dQ_{im}(t)}{dt} = \frac{A}{2\pi al} \cdot \frac{dQ_{beam}(t)}{dt} = \frac{A}{2\pi a} \cdot \frac{1}{\beta c} \cdot \frac{dI_{beam}(t)}{dt} = \frac{A}{2\pi a} \cdot \frac{1}{\beta c} \cdot i\omega I_{beam}(\omega)$$

Using a relation for Fourier transformation: $I_{beam} = I_0 e^{i\omega t} \Rightarrow dI_{beam}/dt = i\omega I_{beam}$.

Transfer Impedance for capacitive BPM



At a resistor R the voltage U_{im} from the image current is measured.

The transfer impedance Z_t is the ratio between voltage U_{im} and beam current I_{beam}

in *frequency domain*: $U_{sig}(\omega) = R \cdot I_{im}(\omega) = Z_t(\omega, \beta) \cdot I_{beam}(\omega)$.

Capacitive coupling: $I_{im}(\omega) = \frac{A}{2\pi a} \cdot \frac{1}{\beta c} \cdot i\omega I_{beam}(\omega)$

Capacitive BPM:

- The pick-up capacitance C :
plate \leftrightarrow vacuum-pipe and cable.
- The amplifier with input resistor R .
- The beam is a high-impedance current source:

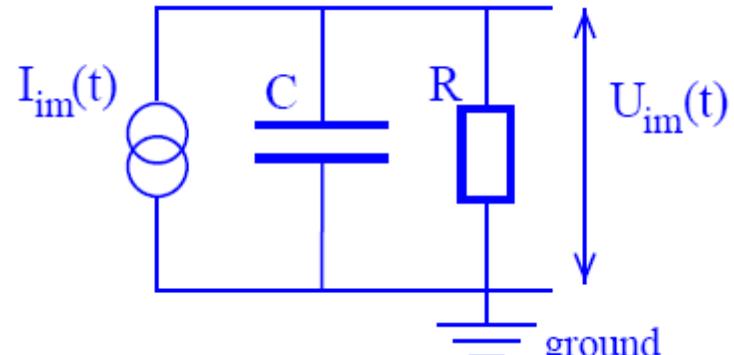
$$U_{sig} = \frac{R}{1 + i\omega RC} \cdot I_{im}$$

$$= \frac{A}{2\pi a} \cdot \frac{1}{\beta c} \cdot \frac{1}{C} \cdot \frac{i\omega RC}{1 + i\omega RC} \cdot I_{beam}$$

$\equiv Z_t(\omega, \beta) \cdot I_{beam} \Rightarrow$ this is a **high-pass** with $\omega_{cut} = 1/(RC) \Leftrightarrow f_{cut} = 1/(2\pi RC)$:

Amplitude: $|Z_t(f)| = \frac{A}{2\pi a} \cdot \frac{1}{\beta c} \cdot \frac{1}{C} \cdot \frac{f / f_{cut}}{\sqrt{1 + f^2 / f_{cut}^2}}$ **Phase:** $\varphi(f) = \arctan(f_{cut} / f)$

equivalent circuit



$$\frac{1}{Z} = \frac{1}{R} + i\omega C \Leftrightarrow Z = \frac{R}{1 + i\omega RC}$$

Estimation Voltage Spectrum for Shoe-box BPM



What is the spectral function of a bunched beam seen by the capacitive BPM?

2.2.1 Calculate the cut-off frequency $f_{cut} = 1/(2\pi RC)$ for $R=50 \Omega$ (for voltage measurement) and $C=100 \text{ pF}$ (capacitance BPM-Plates-wall, cable etc.)!

Sketch the transfer impedance $Z_t(f)$ as a function of frequency! (high-pass characteristic)

The cut-off frequency is

$$f_{cut} = 1/(2\pi RC) = 32 \text{ MHz.}$$

$Z_t(f)$ is described by a first order high-pass:

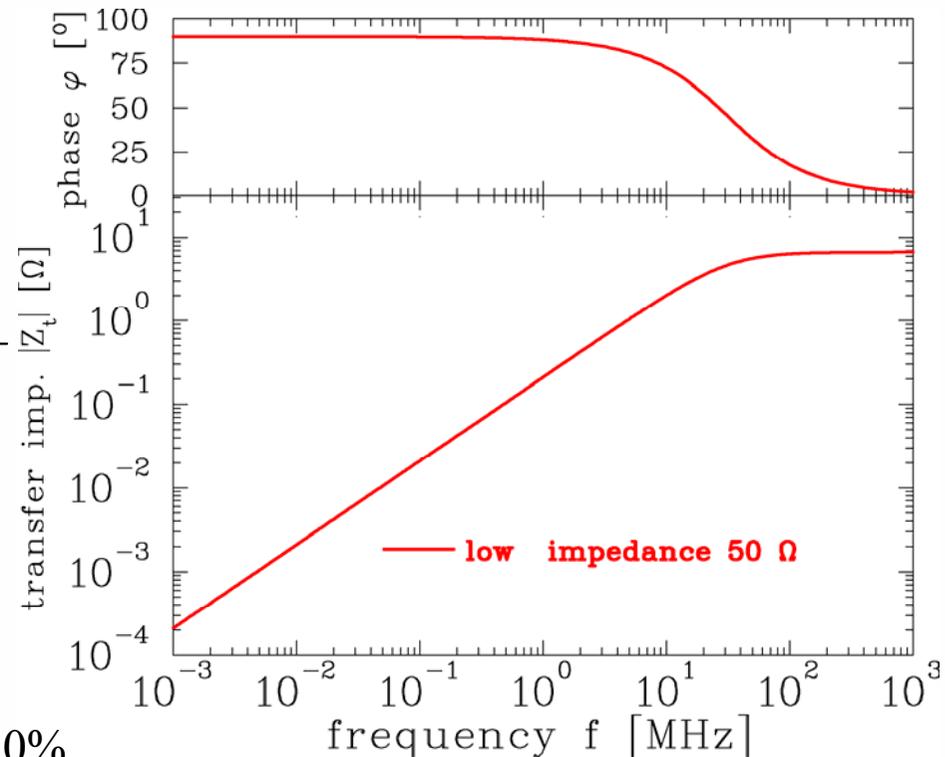
$$|Z_t(f)| = \frac{A}{2\pi a} \cdot \frac{1}{\beta c} \cdot \frac{1}{C} \cdot \frac{f / f_{cut}}{\sqrt{1 + f^2 / f_{cut}^2}}$$

↑
geometry

↑
capacitance

↑
high-pass

$$|Z_t(f > f_{cut})| = 7 \Omega \text{ for a 10 cm long cylinder, } \beta = 50\%$$



Estimation Voltage Spectrum for Shoe-box BPM

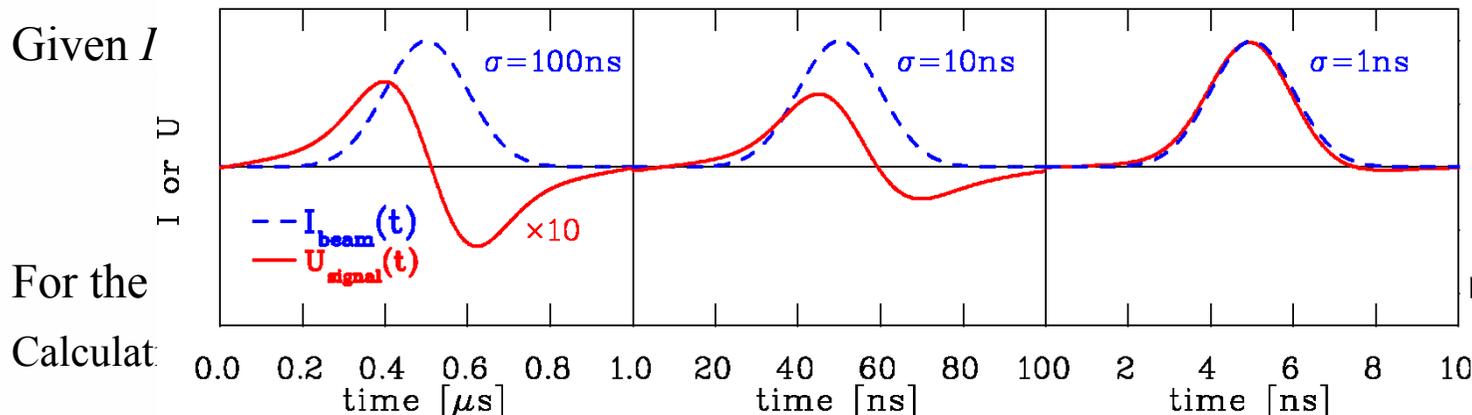
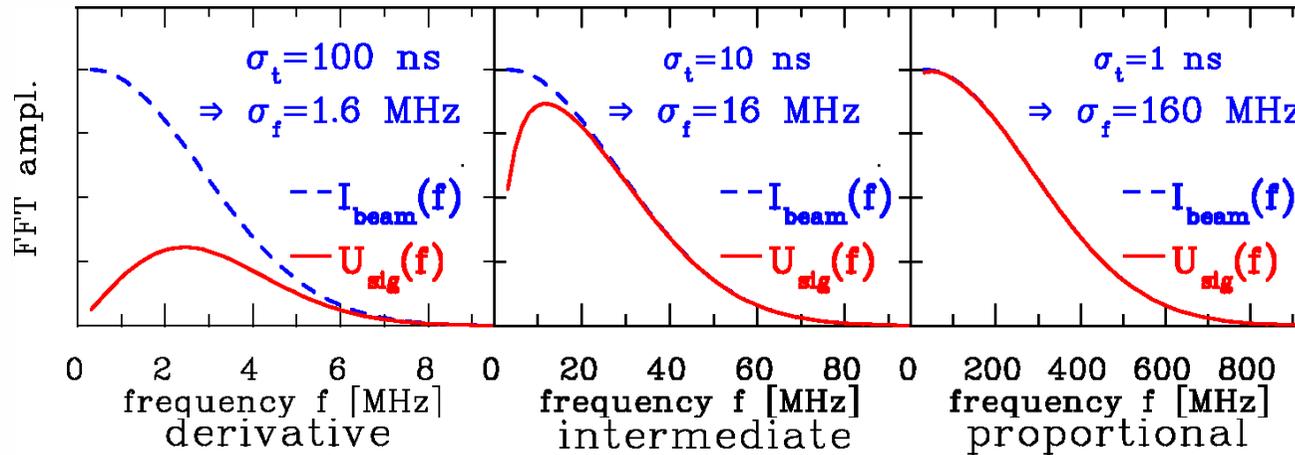


2.2.2 What is the voltage spectrum for the case of a **single** bunch with

$\sigma_t=100$ ns, $\sigma_t=10$ ns and $\sigma_t=1$ ns as discussed above with $f_{cut}=1/(2\pi RC)=32$ MHz ?

What type of math. algorithm is used for the calculation of the time dependent $U_{signal}(t)$?

Sketch the time dependent voltage $U_{signal}(t)$ for these cases !



adding $\varphi(f)$

Numerical Value of $U_{signal}(t)$ with $1M\Omega$ Termination



2.2.4 Sometimes a high impedance termination with $R=1\text{ M}\Omega$ is used for shoe-box BPMs.

What is the cut-off frequency $f_{cut}=1/(2\pi RC)$ in this case ($C=100\text{ pF}$) ?

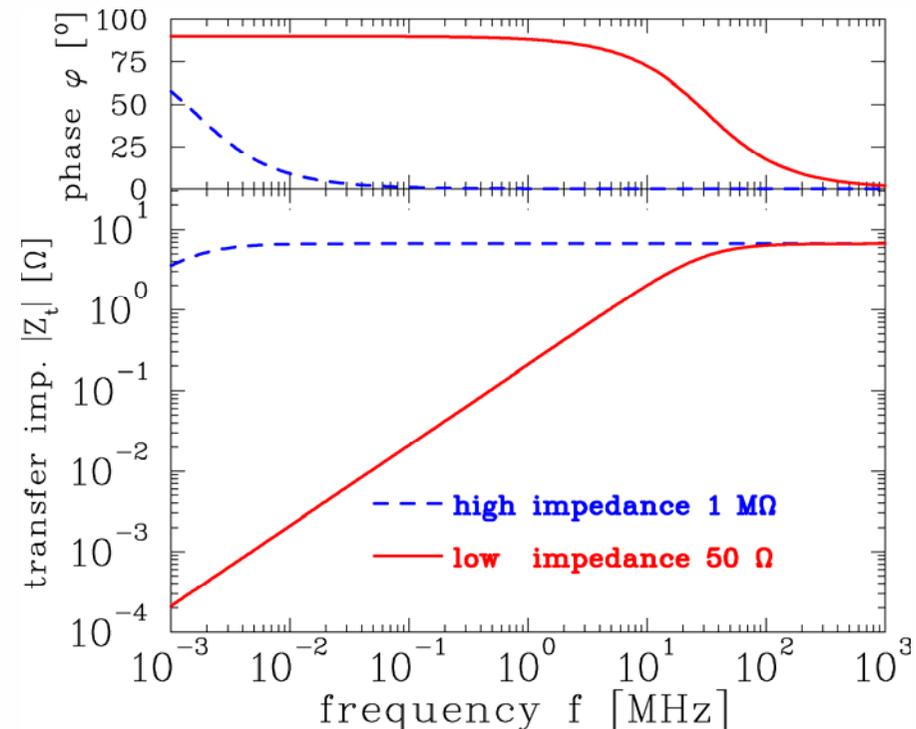
Sketch and discuss the signal voltage for the case of a bunch train with $\sigma_t=100\text{ ns}$!

What might be reasons for this choice?

The cut-off frequency is

$$f_{cut}=1/(2\pi RC)=1.6\text{ kHz}$$

\Rightarrow the proportional shape is recorded



Numerical Value of $U_{signal}(t)$ with $1M\Omega$ Termination



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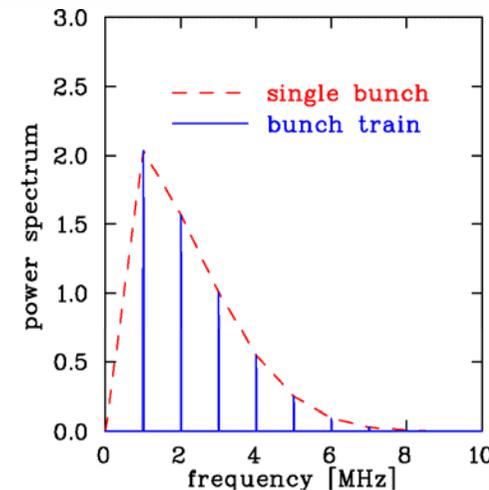
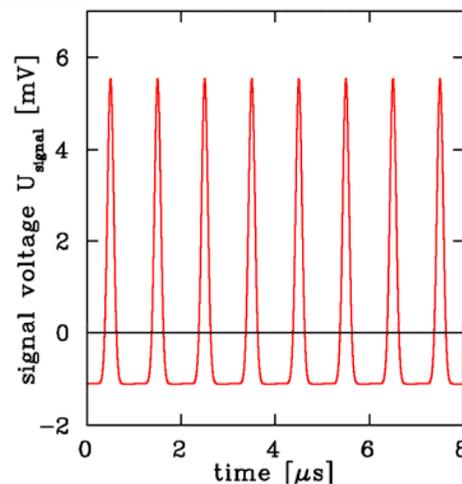
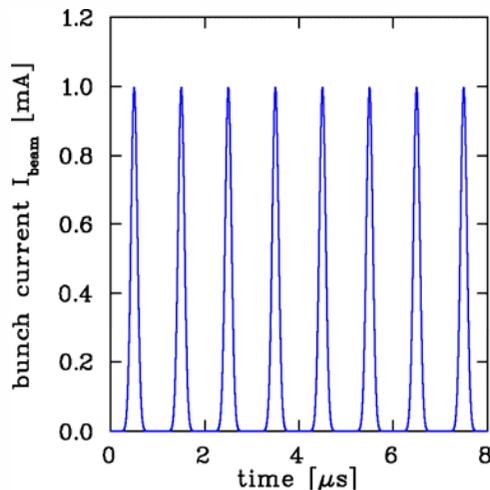
\Rightarrow the proportional shape is recorded

Signal strength for long bunches is $U_{signal}=Z_t(f>f_{cut}) \cdot I_{beam}$

A baseline shift occur i.e. no dc-transmission

Reason for this choice: larger signal *independent* on bunch length

However: larger thermal noise due to $U_{eff}=(4kB \cdot T \cdot \Delta f \cdot R)^{1/2}$





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Button BPM for short Bunches

LINACs, e-synchrotrons: $100 \text{ MHz} < f_{rf} < 3 \text{ GHz} \rightarrow$ bunch length \approx BPM length

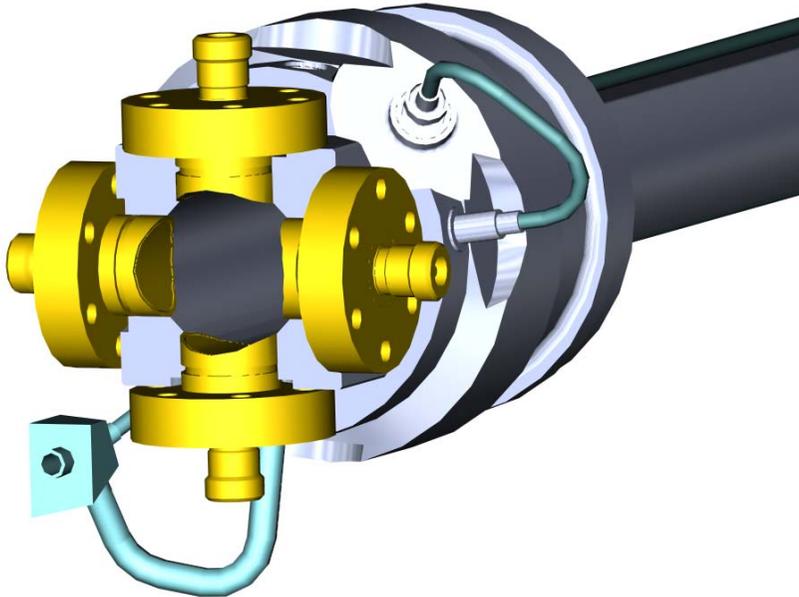
$\rightarrow 50 \Omega$ signal path to prevent reflections

$$\text{Button BPM with } 50 \Omega \Rightarrow U_{sig}(t) = R \cdot \frac{A}{2\pi a} \cdot \frac{1}{\beta c} \cdot \frac{dI_{beam}}{dt}$$

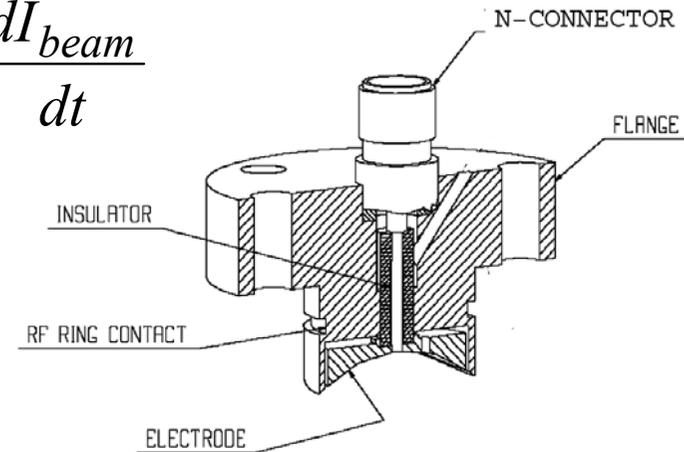
Example: LHC-type inside cryostat:

$\varnothing 24 \text{ mm}$, half aperture $a=25 \text{ mm}$, $C=8 \text{ pF}$

$\Rightarrow f_{cut}=400 \text{ MHz}$, $Z_t = 1.3 \Omega$ above f_{cut}



From C. Boccad (CERN)

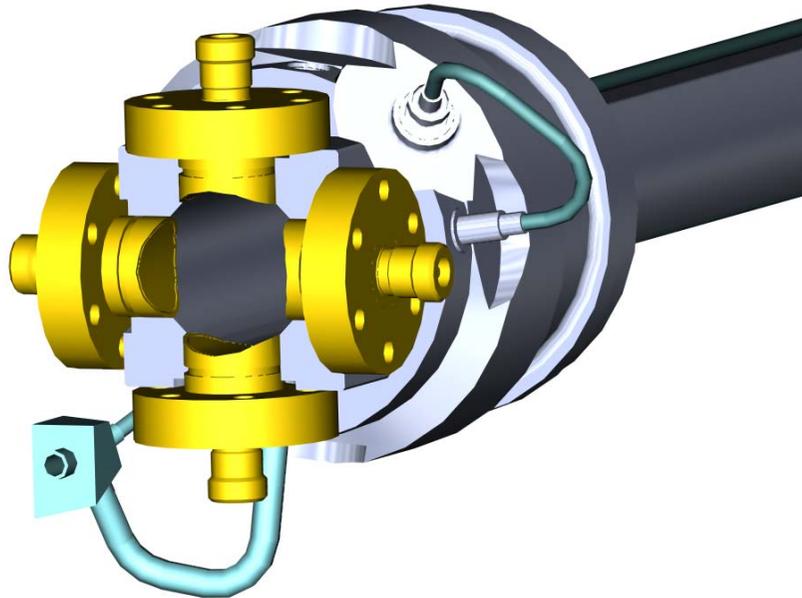
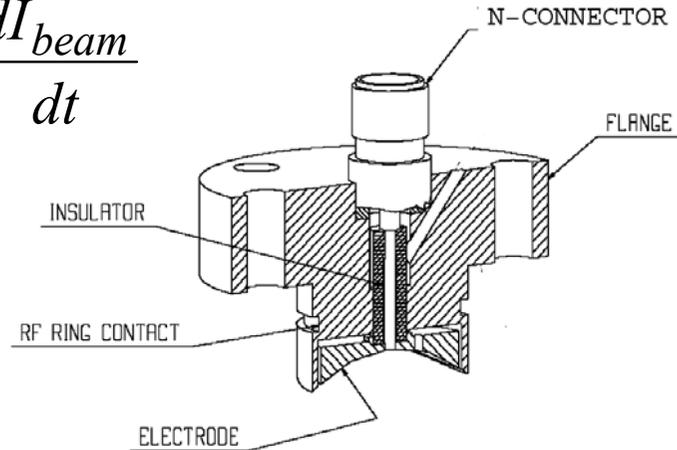


Button BPM for short Bunches

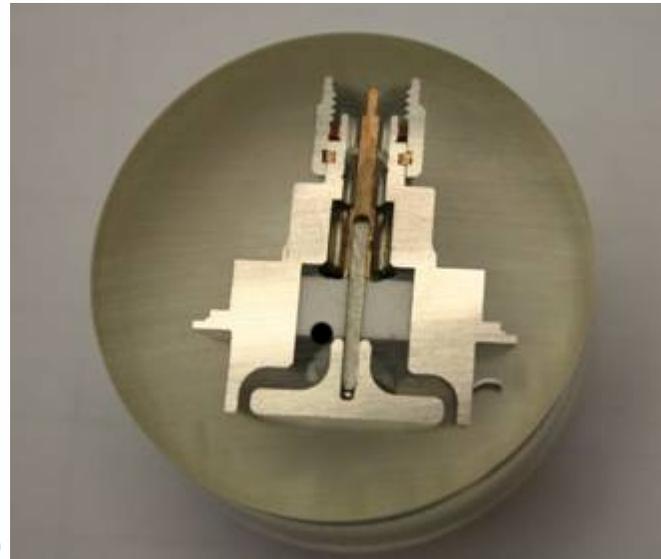
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 $\Rightarrow f_{cut}=400 \text{ MHz}$, $Z_t = 1.3 \Omega$ above f_{cut}



From C. Boccard (CERN)



From K. Wittenburg (DESY)



2-dim Model for Button BPM



‘Proximity effect’: larger signal for closer plate

Ideal 2-dim model: Cylindrical pipe → image current density via ‘image charge method’ for ‘pensile’ beam:

$$j_{im}(\phi) = \frac{I_{beam}}{2\pi a} \cdot \left(\frac{a^2 - r^2}{a^2 + r^2 - 2ar \cdot \cos(\phi - \theta)} \right)$$

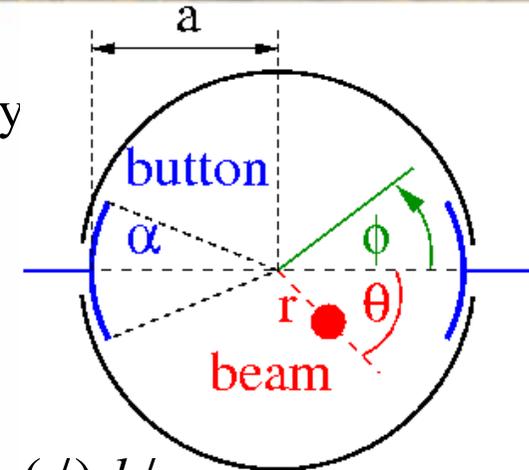
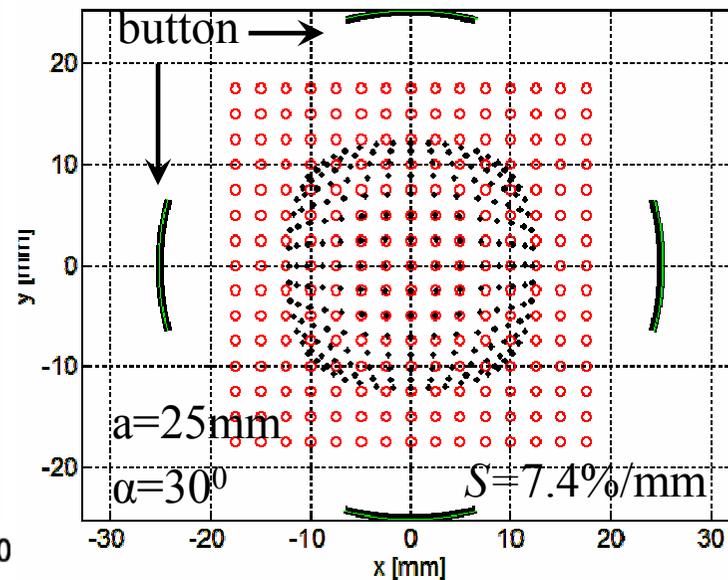
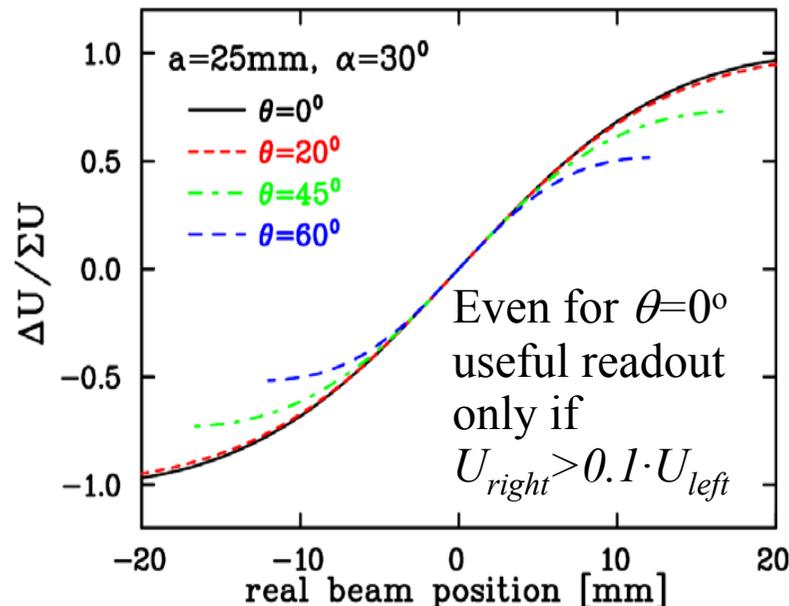


Image current: Integration of finite BPM size: $I_{im} = a \cdot \int_{-\alpha/2}^{\alpha/2} j_{im}(\phi) d\phi$



Position map:

Beam position

& result

using $\Delta U/\Sigma U$

⇒ non-linear $S(x,y)$

⇒ beam size dependent

Estimation of Signal Voltage for Button BPM

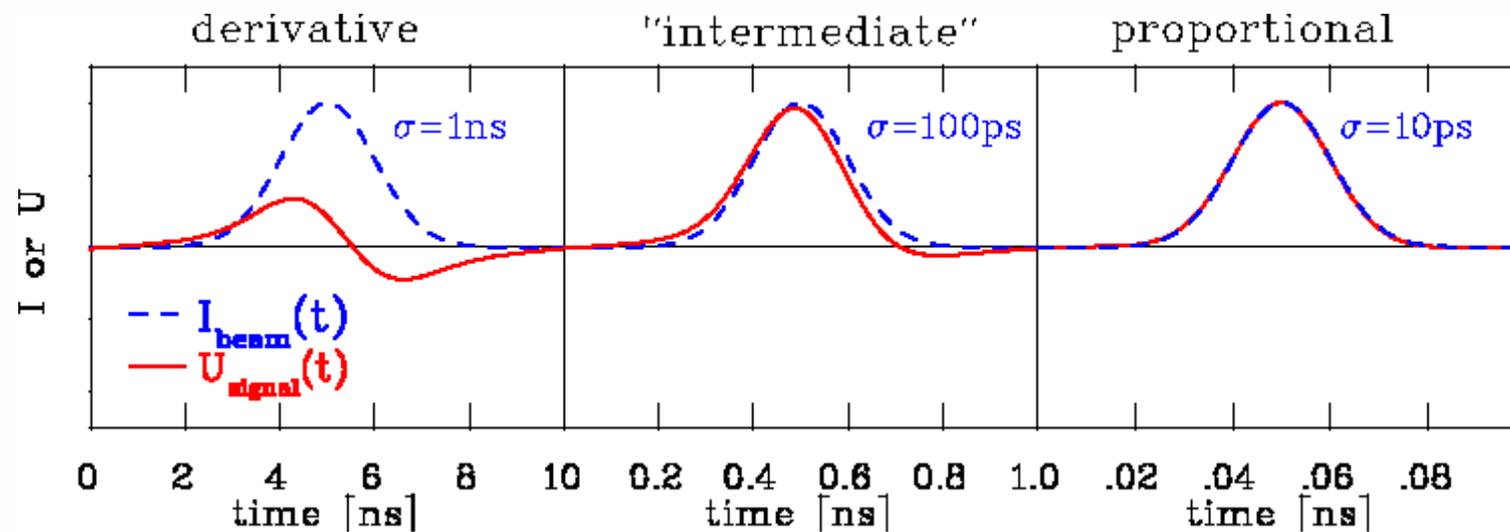


2.3.1 What is the signal voltage shape for a single bunch of $\sigma_t=1$ ns, $\sigma_t=100$ ps and $\sigma_t=10$ ps?
 Sketch the time dependent voltage $U_{\text{signal}}(t)$ for these cases !
 Assume a termination of $R=50 \Omega$ and a capacitance $C=5$ pF.

The cut-off frequency is $f_{\text{cut}}=1/(2\pi RC)=640$ MHz.

For $\sigma_t=1$ ns $\Rightarrow \sigma_f=1/2\pi\sigma_t=160$ MHz i.e. main component below $f_{\text{cut}} \Rightarrow$ derivative

For $\sigma_t=10$ ps $\Rightarrow \sigma_f=1/2\pi\sigma_t=16$ GHz i.e. main component above $f_{\text{cut}} \Rightarrow$ proportional



Numerical Value of Signal Voltage for Button BPM



2.3.2 Calculate the signal voltage $U_{signal}(t)$ for the cases $\sigma_t=1$ ns, $\sigma_t=100$ ps and $\sigma_t=10$ ps?

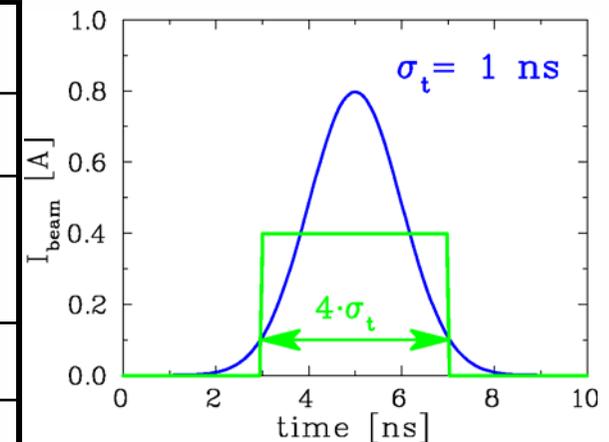
Assume $N=10^{10}$ electrons per bunch and transfer impedance $|Z_t(f > f_{cut})|=1 \Omega$.

Use a boxcar like bunch shape of width $4 \cdot \sigma$, $e = 1.6 \cdot 10^{-19}$ C, $v_{beam} = c$.

Discuss briefly possible problems for short bunch observations!

For $N=10^{10}$ electron within *boxcar-like* bunch shape of $6\sigma_t$ the beam current is: $I_{beam} = eN/6\sigma_t$

Bunch length σ_t [ps]	1000	100	10
Current I_{beam} [A]	0.4	4	40
Signal U_{signal} [V]	0.4	4	40
	due to $f > f_{cut} \approx 0.2$ V		
Bunch length σ_l [cm]	30	3	0.3
Spectrum width σ_f [GHz]	0.16	1.6	16



If one assumes a *Gaussian bunch shape*: Maximum voltage ≈ 2 larger than the average value.

\Rightarrow e.g. $U_{signal} = 80$ V for $\sigma_t=10$ ps !

If the bunch length is comparable to button size \rightarrow signal propagation must be considered

Technical item: Bandwidth of feed-through typically below ≈ 3 GHz.

Difference Voltage for position Measurement



2.3.3 The beam position is obtained via $x = I/S \cdot (U_{right} - U_{left}) / (U_{right} + U_{left})$ (linear processing)

S is the position sensitivity with a typical value of $S = 10 \text{ \%/mm}$ (at the BPM center).

What is the precision of the voltage reading for the detection of 10 \mu m offset ?

What is the related numerical value of $\Delta U = (U_{right} - U_{left})$ for a single bunch of $\sigma_t = 1 \text{ ns}$?

Thermal noise $U_{eff} = (4k_B \cdot T \cdot \Delta f \cdot R)^{1/2}$ contributes to any signal, $k_B = 1.4 \cdot 10^{-23} \text{ J/K}$.

Calculate the thermal noise for $\Delta f = 1 \text{ GHz}$ and $T = 300 \text{ K}$!

What is the beam current for a S-to-N of 2:1? What is a strategy for enlarged resolution?

Due to $S = 10 \text{ \%/mm}$ an 10 \mu m offset transforms to ratio $\Delta U / \Sigma U = 0.1 \text{ \%$

For the case of $\Sigma U = 400 \text{ mV}$ it is $\Delta U = 10^{-3} \cdot \Sigma U = 400 \text{ \mu V}$ only

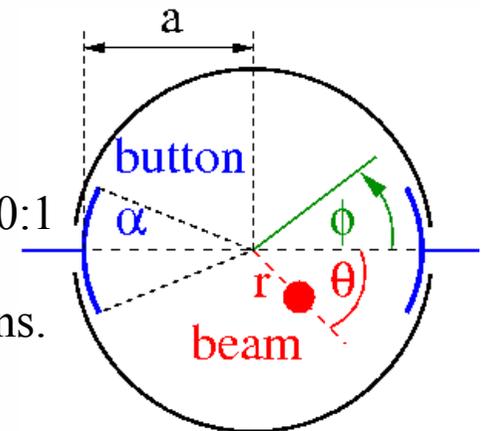
The thermal noise for $\Delta f = 1 \text{ GHz}$ is $U_{eff} = 30 \text{ \mu V} \rightarrow \text{S-to-N} = \Delta U / U_{eff} \approx 10:1$

For a S-to-N=2:1 a current of $I_{beam} = 50 \text{ \mu A}$ is required i.e. $N = 10^9$ electrons.

Realistic value: Amplifier has at least 3 times higher noise.

The main improvement is gained by a restriction of bandwidth Δf , down to kHz.

Correspondingly the time resolution of any position variation decreases!

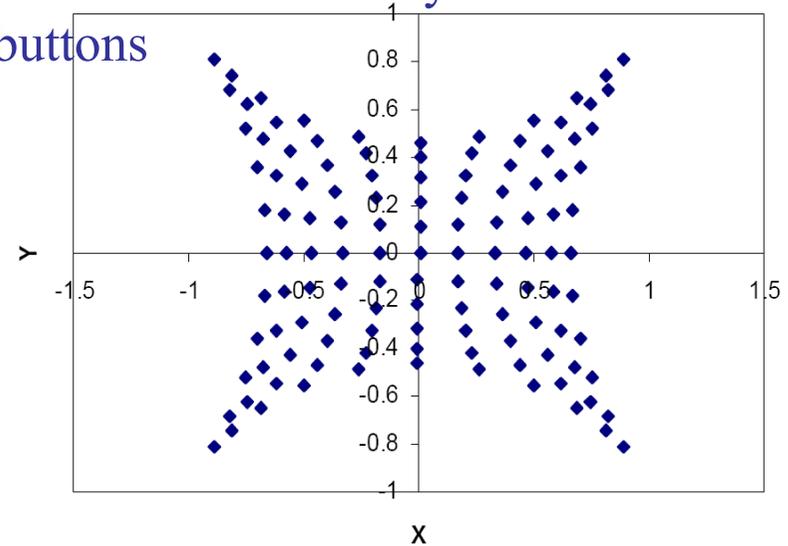
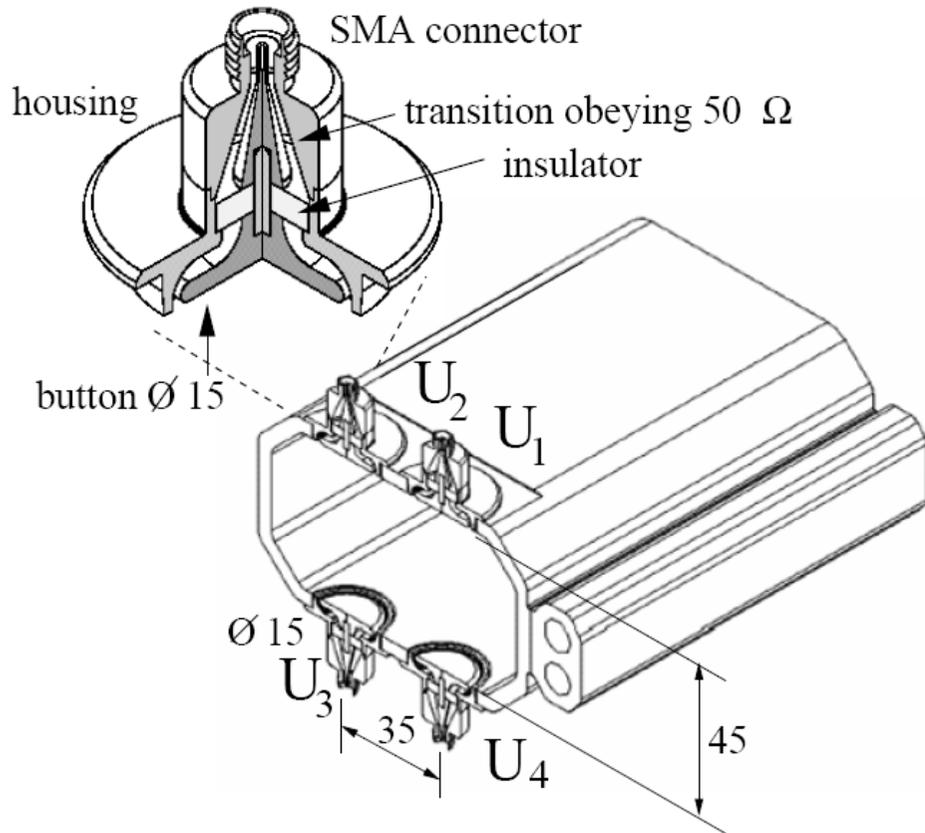


Button BPM at Synchrotron Light Sources



Due to synchrotron radiation, the button insulation might be destroyed
 ⇒ buttons only in vertical plane possible ⇒ increased non-linearity

Optimization: horizontal distance and size of buttons



- Beam position swept with 2 mm steps
- Non-linear sensitivity and hor.-vert. coupling
- At center $S_x = 8.5\%/mm$ in this case

$$\text{horizontal : } x = \frac{1}{S_x} \cdot \frac{(U_2 + U_4) - (U_1 + U_3)}{U_1 + U_2 + U_3 + U_4}$$

$$\text{vertical : } y = \frac{1}{S_y} \cdot \frac{(U_1 + U_2) - (U_3 + U_4)}{U_1 + U_2 + U_3 + U_4}$$

From S. Varnasseri, SESAME, DIPAC 2005





Outline:

- *General discussion on BPM features and specification*
- *Sum signal estimation, example 'shoe box' BPM for proton synchrotron*
- *Differential signal estimation, example 'button' BPM for p-LINAC and e⁻*
- ***Stripline BPM for circular colliders***
- *Cavity BPMs for FEL LINAC*

Stripline BPM: General Idea

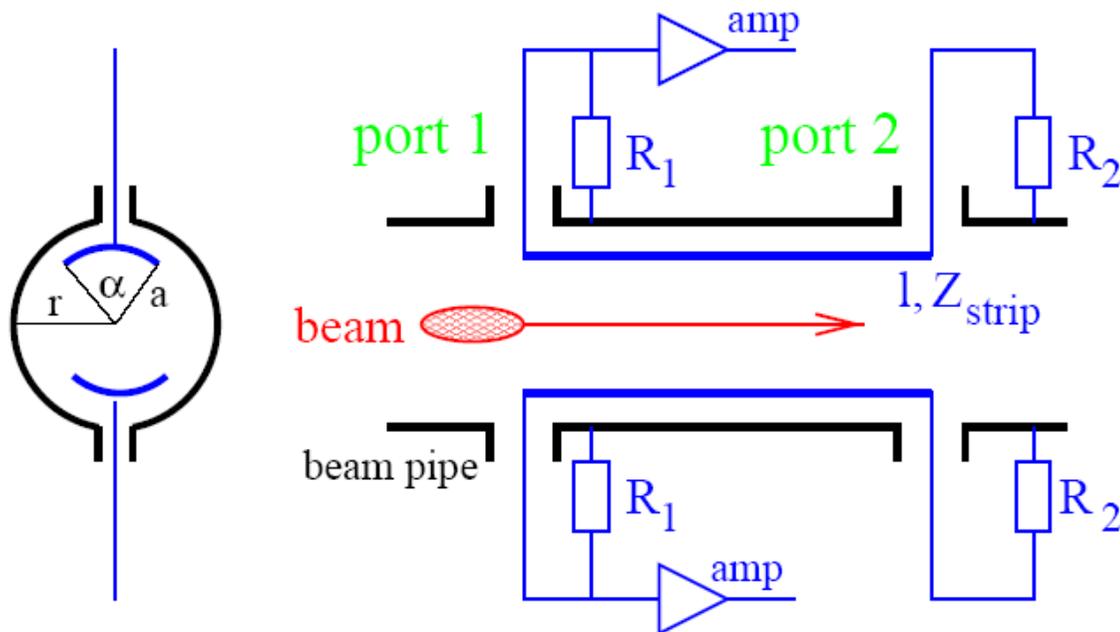


For short bunches, the *capacitive* button deforms the signal

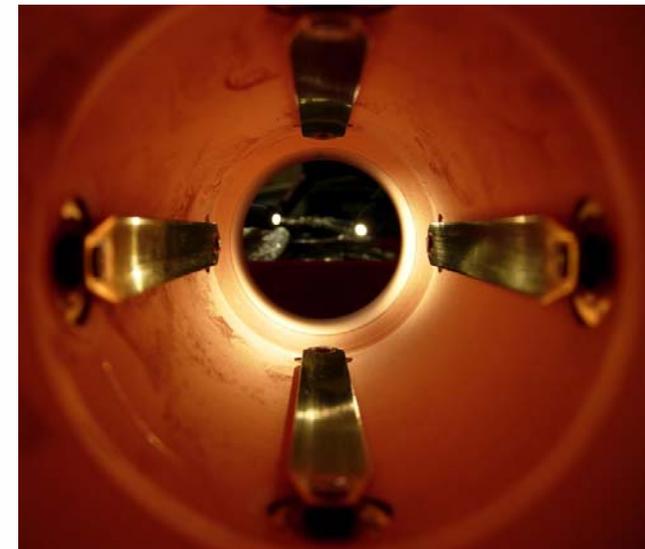
→ Relativistic beam $\beta \approx 1 \Rightarrow$ field of bunches nearly TEM wave

→ Bunch's electro-magnetic field induces a **traveling pulse** at the strips

→ Assumption: Bunch shorter than BPM, $Z_{strip} = R_1 = R_2 = 50 \Omega$ and $v_{beam} = c_{strip}$.



LHC stripline BPM, $l=12$ cm



From C. Boccard, CERN

Stripline BPM: General Idea



For relativistic beam with $\beta \approx 1$ and short bunches:

→ Bunch's electro-magnetic field induces a **traveling pulse** at the strip

→ **Assumption:** $l_{bunch} \ll l$, $Z_{strip} = R_1 = R_2 = 50 \Omega$ and $v_{beam} = c_{strip}$

Signal treatment at upstream port 1:

$t=0$: Beam induced charges at **port 1**:

→ half to R_1 , half toward **port 2**

$t=l/c$: Beam induced charges at **port 2**:

→ half to R_2 , **but** due to different sign, it cancels with the signal from **port 1**

→ half signal reflected

$t=2 \cdot l/c$: reflected signal reaches **port 1**

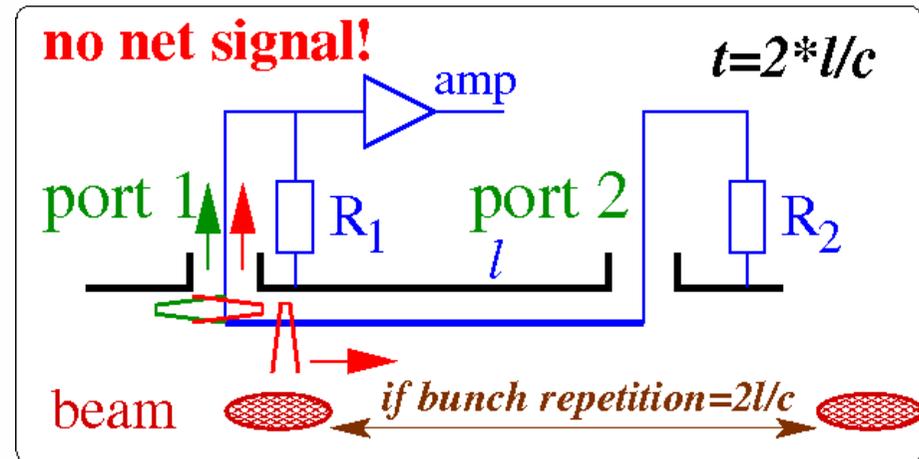
$$\Rightarrow U_1(t) = \frac{1}{2} \cdot \frac{\alpha}{2\pi} \cdot Z_{strip} (I_{beam}(t) - I_{beam}(t - 2l/c))$$

If beam repetition time equals $2 \cdot l/c$: reflected preceding port 2 signal cancels the new one:

→ no net signal at **port 1**

Signal at downstream port 2: Beam induced charges cancels with traveling charge from port 1

⇒ Signal depends direction ⇔ directional coupler: e.g. can distinguish between e^- and e^+ in collider



Signal Voltage for stripline BPM



3.2 Sketch the signal voltage of a stripline BPM for a single bunch with $\sigma_t=100$ ps !

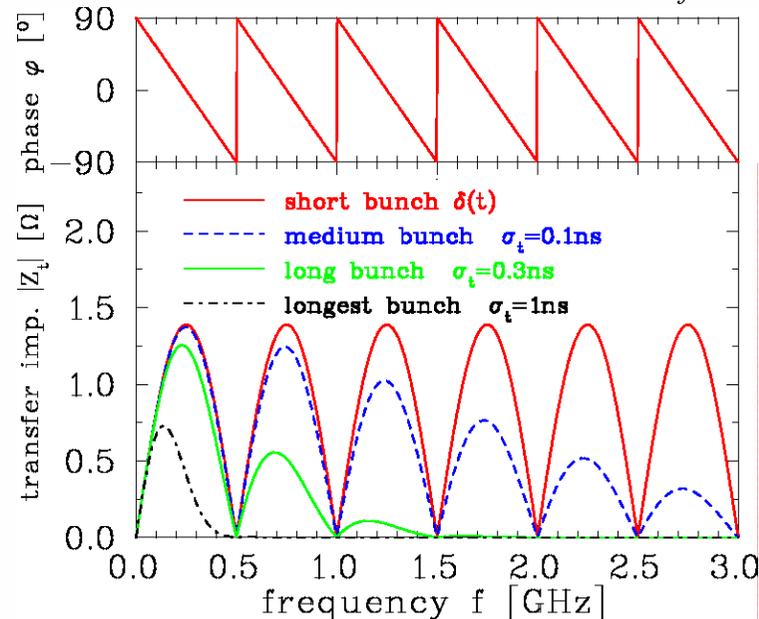
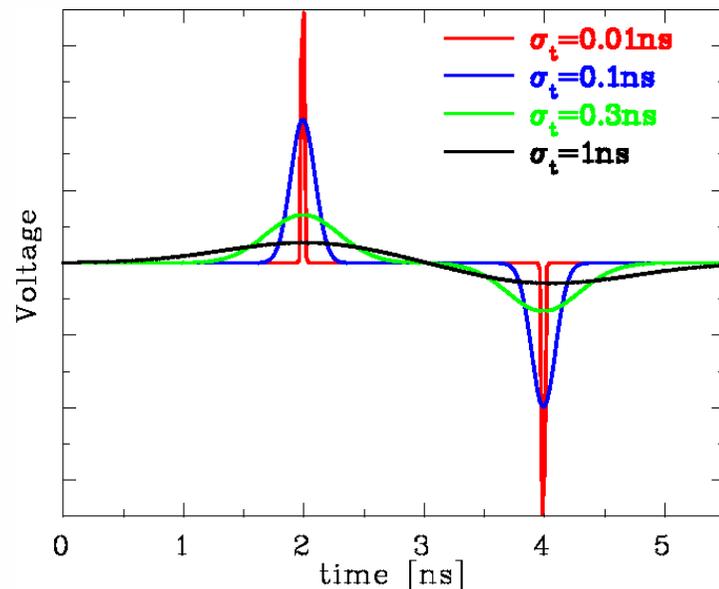
Use the following parameter: Strip length $l=30$ cm, transfer imp. $Z_t=1.5 \Omega$ at its maximum.

Sketch the transfer impedance!

How is the signal shape and transfer impedance modified for longer bunches ?

The bunch length $\sigma_t=100$ ps is short compared to the transit time $2l/c \Rightarrow$ no overlap

The shape of $Z_t(f)$ are comps with minima at $n \cdot c/2l$ with a envelop given by $\sigma_f=1/2\pi\sigma_t$.



Short bunches: Z_t is periodic, for long bunches ($\sigma_t > 0.3$ ns) overlapping occur, Z_t max. not reached



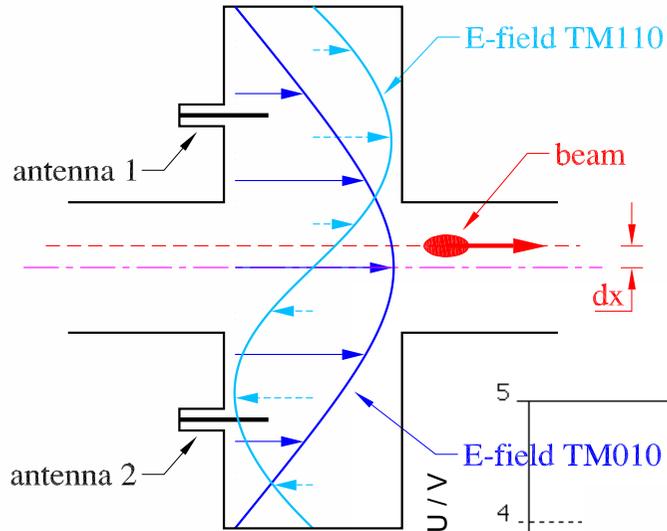
Outline:

- *General discussion on BPM features and specification*
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- **Cavity BPMs for FEL LINAC**

Cavity BPM: Principle



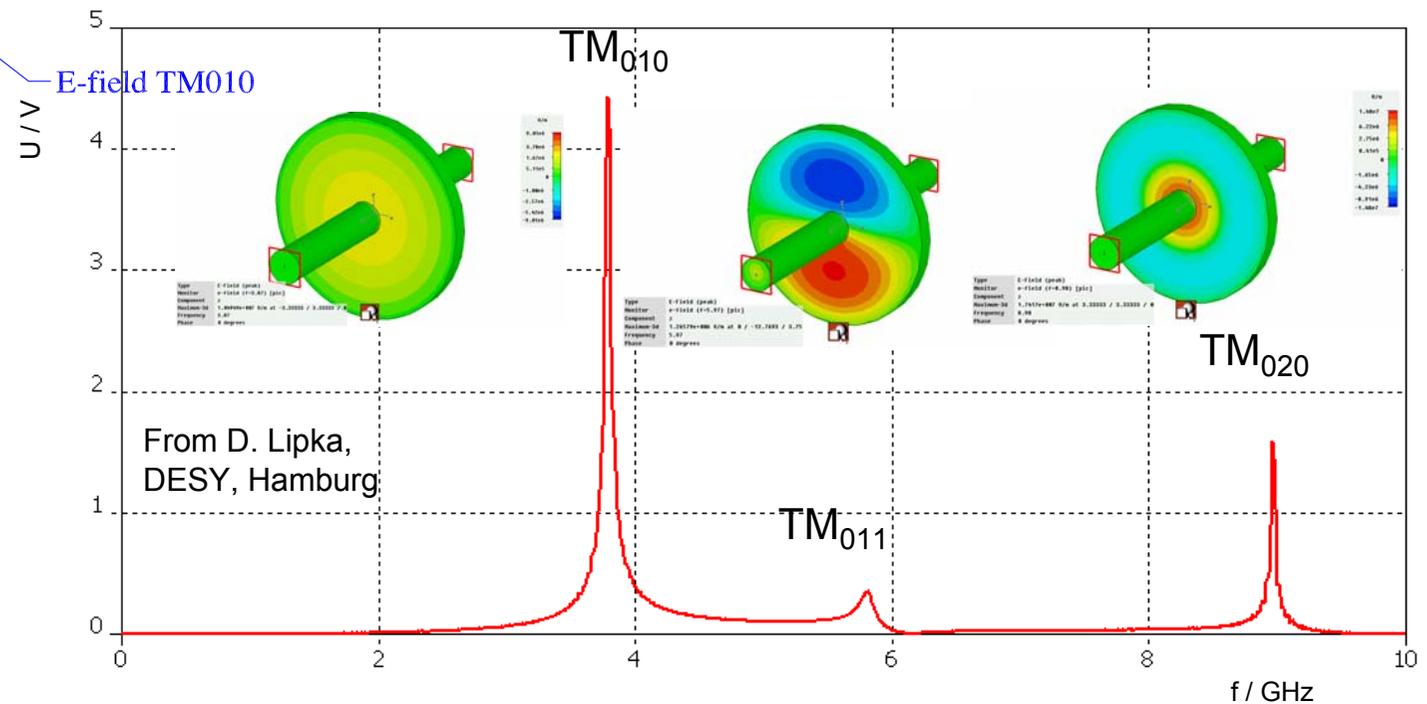
High resolution on μs time scale can be achieved by excitation of a dipole mode:



For pill box the resonator modes given by geometry:

- monopole TM_{010} with f_{010}
 - maximum at beam center \Rightarrow strong excitation
- Dipole mode TM_{011} with f_{011}
 - minimum at center \Rightarrow excitation by beam offset
 - \Rightarrow Detection of dipole mode amplitude

Application:
small e^- beams
(ILC, X-FEL...)



From D. Lipka,
DESY, Hamburg

Cavity BPM: Example of Realization



Basic consideration for detection of eigen-frequency amplitudes:

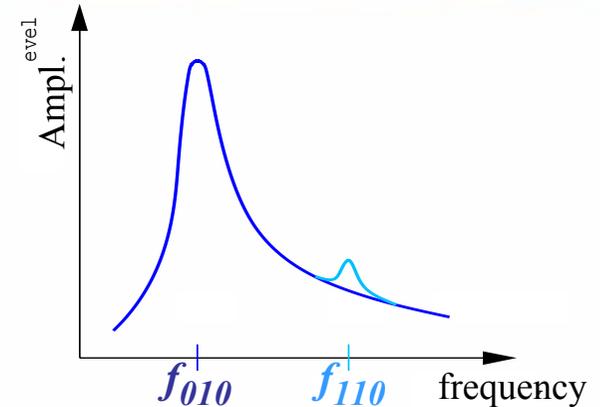
Dipole mode f_{110} separated from monopole mode

due to finite quality factor $Q \Rightarrow \Delta f = f/Q$

➤ Frequency $f_{110} \approx 1 \dots 10$ GHz

➤ Waveguide house the antennas

Task: suppression of TM_{010} mono-pole mode



FNAL realization:

Cavity: \varnothing 113 mm

Gap 15 mm

Mono. $f_{010} = 1.1$ GHz

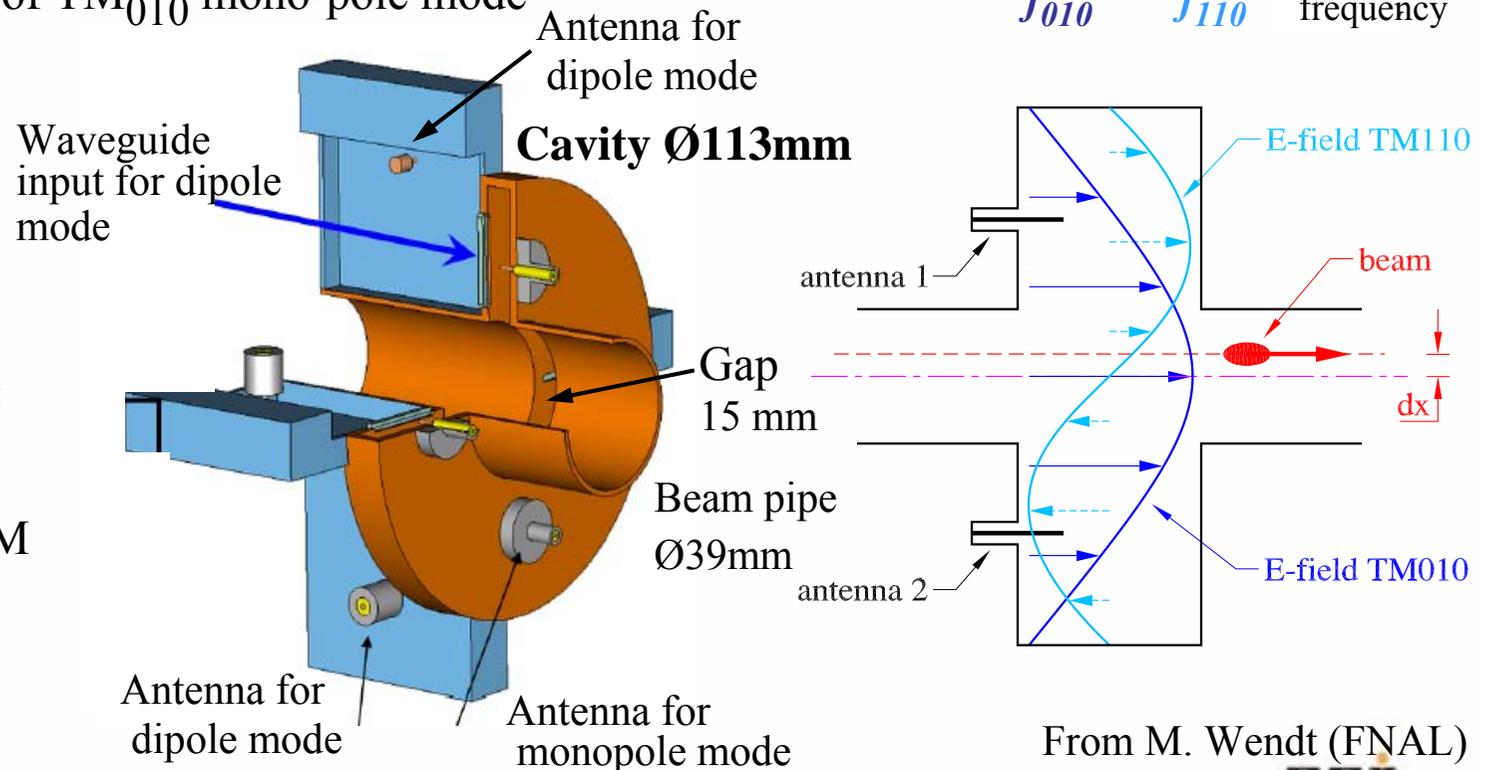
Dipole. $f_{110} = 1.5$ GHz

$Q_{load} \approx 600$

With comparable BPM

\Rightarrow **0.1 μ m resolution**

within 1 μ s



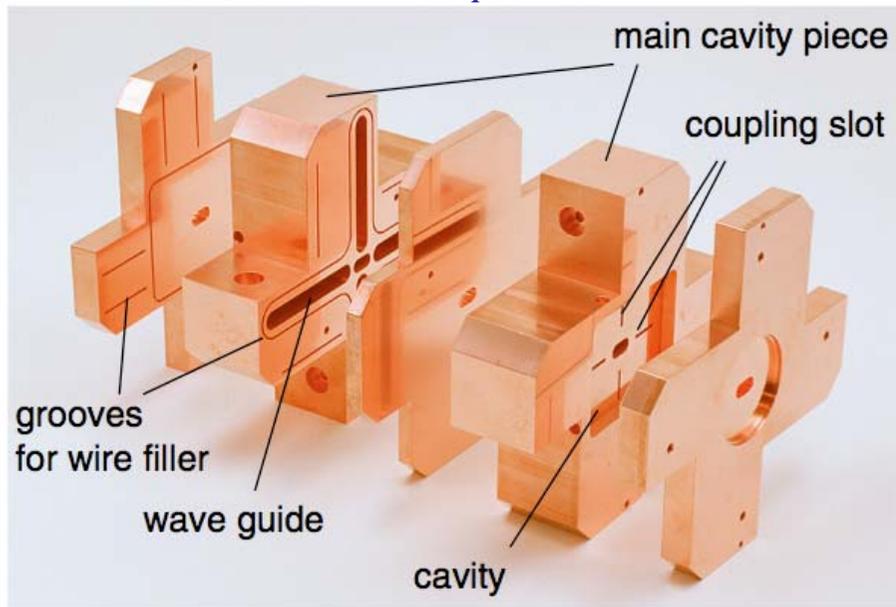
From M. Wendt (FNAL)



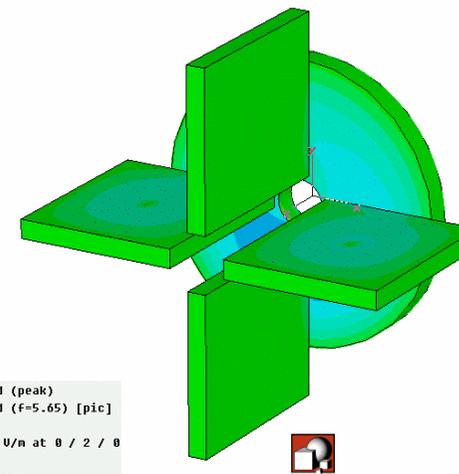
Cavity BPM: Suppression of monopole Mode

Suppression of mono-pole mode: waveguide that couple only to dipole-mode

due to $f_{mono} < f_{cut} < f_{dipole}$



Dipole-pole mode



Courtesy of D. Lipka,
DESY, Hamburg

Courtesy of D. Lipka and Y. Honda

Prototype BPM for ILC Final Focus

- Required resolution of 2nm (yes nano!) in a 6×12mm diameter beam pipe
- Achieved World Record (so far!) resolution of 8.7nm at ATF2 (KEK, Japan)

Signal Voltage for stripline BPM



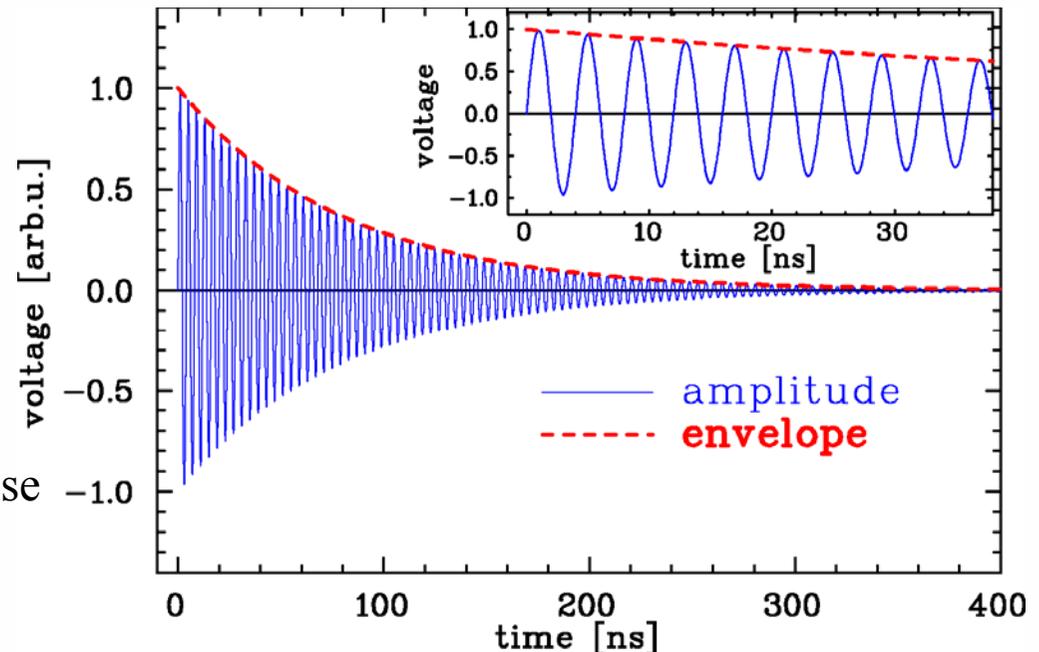
3.3 Sketch the signal voltage of a cavity BPM for a single bunch with $\sigma_t=100$ ps !

Use the following parameter: Resonance frequency $f=4$ GHz, quality factor $Q_L=1000$.

What influences the choice for the value of Q_L ?

The excited oscillation is described by $U_{signal}(t) = U_0 \cdot e^{-2\pi f/2Q_L t} \cdot \sin(2\pi f \cdot t)$.
For the given quality factor Q_L the damping time is $\tau=2Q_L/2\pi f \approx 80$ ns .

Large Q_L : larger integrated signal
larger position sensitivity
Small Q_L : Faster reaction to acceding pulse
broadband
→ better excited by bunch.



Signal Voltage for stripline BPM



3.4 Discuss briefly the reasons for an appropriate choice of shoebox button, stripline and cavity types !

➤ **Shoobox:** for low frequencies (proton synchrotron)

Linear position reading, no beam-size dependence

➤ **Button:** BPMs are easier to produce and have simpler processing scheme.

➤ **Stripline:** BPMs have lower signal deformation and offer directivity for colliders
i.e. counter-propagating beams within one beam pipe.

➤ **Cavity:** BPMs have much higher single pass resolution.

Comparison of BPM Types (simplified)



Type	Usage	Precaution	Advantage	Disadvantage
Shoe-box	p-Synch.	Long bunches $f_{rf} < 10$ MHz	Very linear No x-y coupling Sensitive For broad beams	Complex mechanics Capacitive coupling between plates
Button	p-Linacs, all e ⁻ acc.	$f_{rf} > 10$ MHz	Simple mechanics	Non-linear, x-y coupling Possible signal deformation
Stipline	colliders p-Linacs all e ⁻ acc.	best for $\beta \approx 1$, short bunches	Directivity 'Clean' signals Large Signal	Complex 50 Ω matching Complex mechanics
Cavity	e ⁻ Linacs (e.g. FEL)	Short bunches Special appl.	Very sensitive	Very complex, high frequency

Remark: Other types are also some time used: e.g. wall current monitors, inductive antenna, BPMs with external resonator, slotted wave-guides for stochastic cooling etc.

Thank you for your attention!