

Beam Instrumentation CAS, Tuusula (Finland), 2-15 June 2018

Transverse Phase Space Emittance Diagnostics

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Accelerator Key Parameters

● light source: spectral brilliance

- measure for phase space density of photon flux

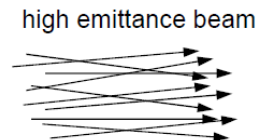
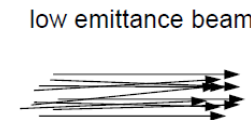
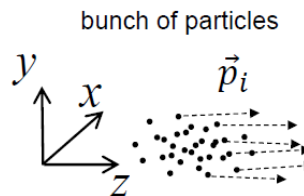
$$B = \frac{\text{Number of photons}}{[\text{sec}][\text{mm}^2][\text{mrad}^2][0.1\% \text{ bandwidth}]}$$

- user requirement: high brightness
 - lot of monochromatic photons on sample
- connection to machine parameters

$$B \propto \frac{N_\gamma}{\sigma_x \sigma_{x'} \sigma_z \sigma_{z'}} \propto \frac{I}{\varepsilon_x \varepsilon_z}$$

● requirements

- design of small emittance machine
 - proper choice of magnet lattice
- preserve small emittance
 - question of stability
 - require active feedback systems / careful design considerations



● collider: luminosity

- measure for the collider performance

$$\dot{N} = \mathcal{L} \cdot \sigma$$

relativistic invariant proportionality factor between cross section σ (property of interaction) and number of interactions per second

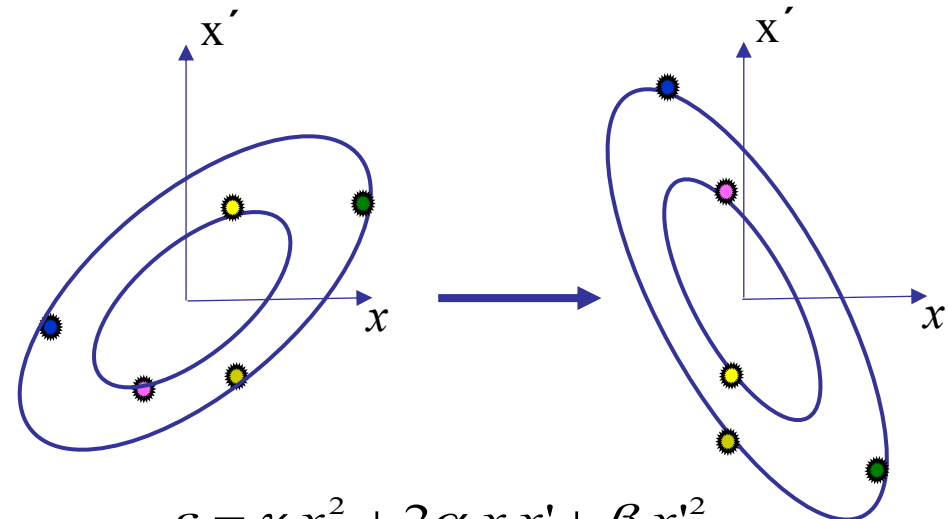
- user requirement: high luminosity
 - lot of interactions in reaction channel
- connection to machine parameters

$$\mathcal{L} = \frac{I_1 \cdot I_2}{\varepsilon}$$

for two identical beams with emittances $\varepsilon_x = \varepsilon_z = \varepsilon$

Transverse Emittance

- projection of phase space volume
 - separate horizontal, vertical and longitudinal plane
- accelerator key parameter
 - defines **luminosity** / **brilliance**
- linear forces
 - any particle moves on an ellipse in trace space (x, x')
 - ellipse rotates in magnets and shears along drifts
 - but area is preserved: **emittance**



$$\varepsilon = \gamma x^2 + 2\alpha x x' + \beta x'^2$$

(α, β, γ : Courant-Snyder or Twiss parameters)

- transformation along accelerator

- knowledge of the magnet structure (beam optics) → transformation from initial (i) to final (f) location

→ single particle transformation

$$\begin{pmatrix} x \\ x' \end{pmatrix}_f = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix} \cdot \begin{pmatrix} x \\ x' \end{pmatrix}_i$$

→ transformation of Courant-Snyder/Twiss parameters

$$\begin{pmatrix} \beta \\ \alpha \\ \gamma \end{pmatrix}_f = \begin{pmatrix} m_{11}^2 & -2m_{11}m_{12} & m_{12}^2 \\ -m_{11}m_{21} & 1 + m_{12}m_{21} & -m_{12}m_{22} \\ m_{21}^2 & -2m_{21}m_{22} & m_{22}^2 \end{pmatrix} \cdot \begin{pmatrix} \beta \\ \alpha \\ \gamma \end{pmatrix}_i$$

Transverse Emittance Ellipse

propagation along accelerator

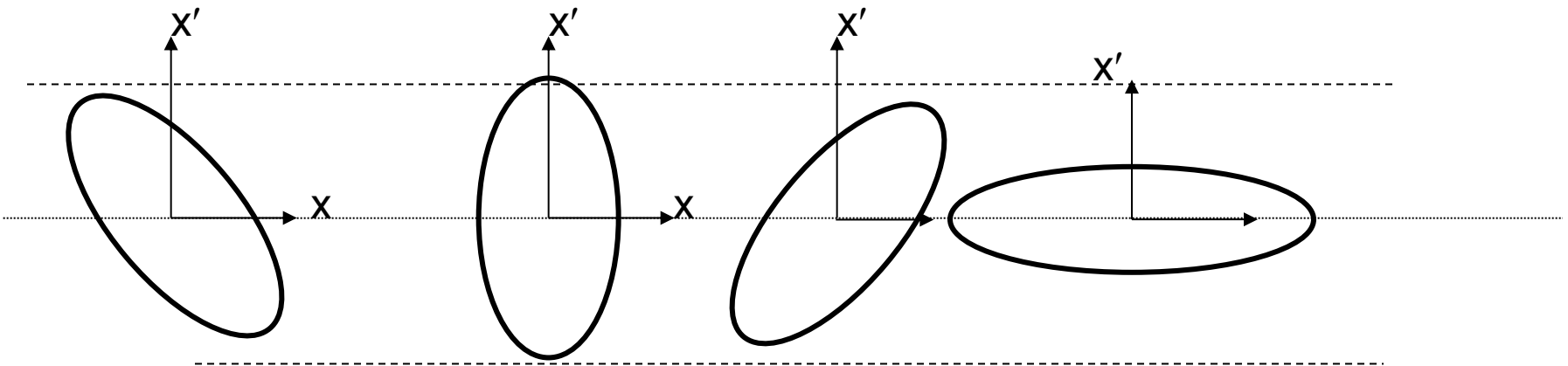
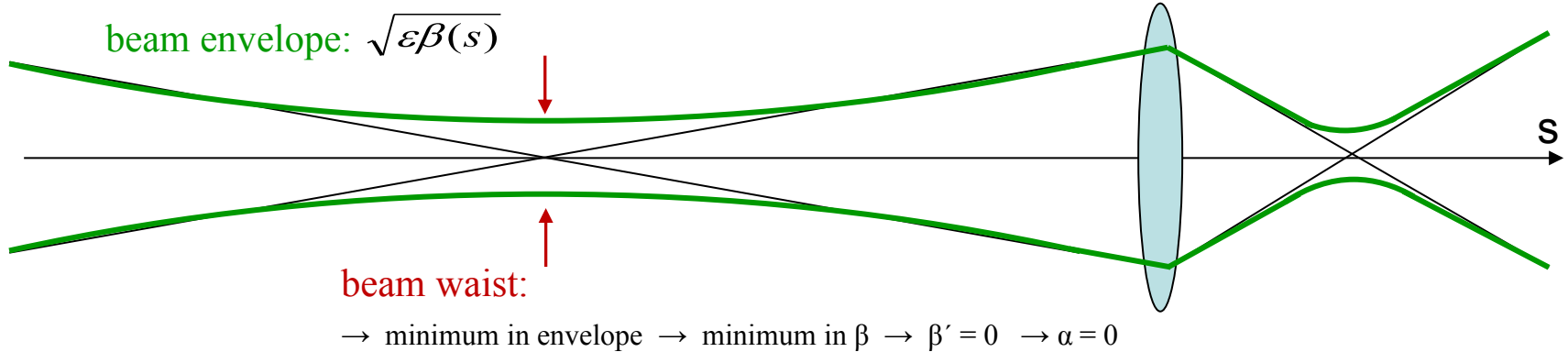
- change of ellipse shape and orientation → area is preserved

$$\alpha(s) = -\frac{\beta'(s)}{2}$$

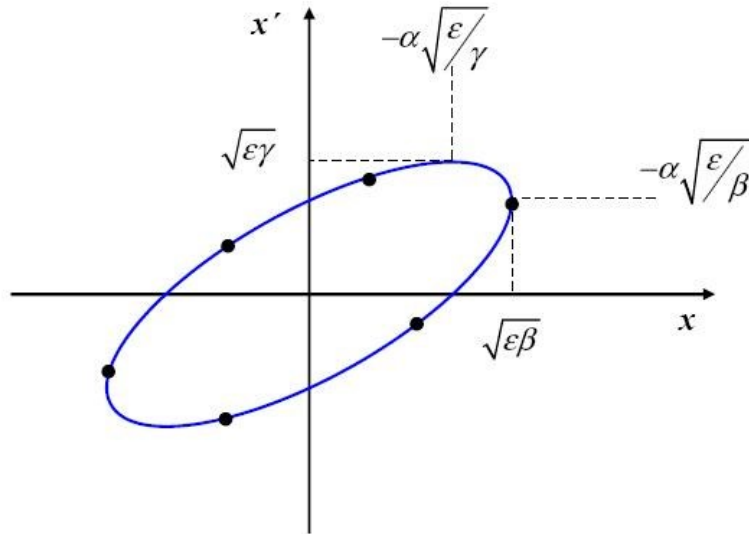
$$\gamma(s) = \frac{1 + \alpha^2(s)}{\beta(s)}$$

$$x(s) = \sqrt{\varepsilon\beta(s)} \cdot \cos[\Psi(s) + \Phi]$$

$$\varepsilon = \gamma(s) x(s)^2 + 2\alpha(s) x(s) x'(s) + \beta(s) x'(s)^2$$



Emittance and Beam Matrix



- via Twiss parameters

$$\varepsilon = \gamma x^2 + 2\alpha x x' + \beta x'^2$$

- statistical definition

P.M. Lapostolle, IEEE Trans. Nucl. Sci. NS-18, No.3 (1971) 1101

$$\varepsilon_{rms} = \sqrt{\langle x^2 \rangle \langle x'^2 \rangle - \langle x x' \rangle^2}$$

2nd moment of beam distribution $\rho(x)$

$$\langle x^2 \rangle = \frac{\int_{-\infty}^{\infty} dx x^2 \cdot \rho(x)}{\int_{-\infty}^{\infty} dx \rho(x)}$$

- ε_{rms} is measure of spread in phase space

- root-mean-square (rms) of distribution

$$\sigma_x = \langle x^2 \rangle^{1/2}$$

- ε_{rms} useful definition for non-linear beams

→ usually restriction to certain range

(c.f. 90% of particles instead of $[-\infty, +\infty]$)

- beam matrix

$$\Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix} = \begin{pmatrix} \langle x^2 \rangle & \langle x x' \rangle \\ \langle x x' \rangle & \langle x'^2 \rangle \end{pmatrix} = \varepsilon \begin{pmatrix} \beta & -\alpha \\ -\alpha & \gamma \end{pmatrix}$$

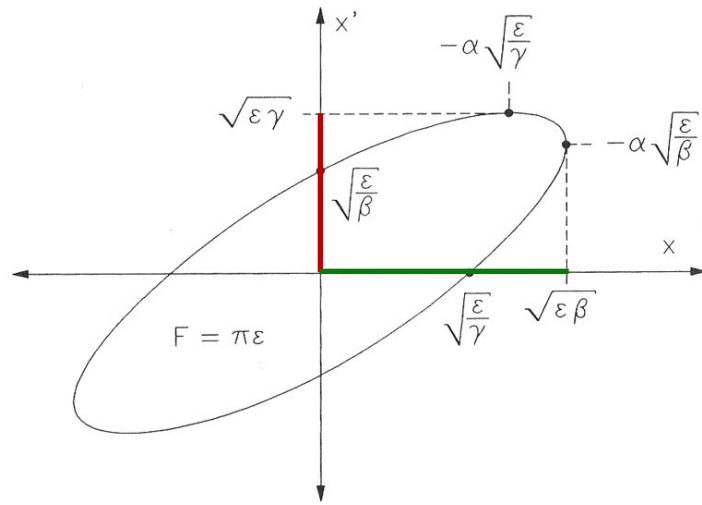
$$\varepsilon = \sqrt{\det \Sigma} = \sqrt{\Sigma_{11} \cdot \Sigma_{22} - \Sigma_{12}^2}$$

- transformation of beam matrix

$$\Sigma^1 = M \Sigma^0 M^T \quad M = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix}$$

Emittance Measurement: Principle

- emittance: projected area of transverse phase space volume
- not directly accessible for beam diagnostics



- measured quantity

- ▶ beam size $\sqrt{\Sigma_{11}} = \sqrt{\langle x^2 \rangle} = \sqrt{\epsilon \beta}$
- ▶ beam divergence $\sqrt{\Sigma_{22}} = \sqrt{\langle x'^2 \rangle} = \sqrt{\epsilon \gamma}$

- ▶ divergence measurements seldom in use

→ restriction to profile measurements

- measurement schemes

- ▶ beam matrix based measurements

→ determination of beam matrix elements:

$$\epsilon = \sqrt{\det \Sigma} = \sqrt{\Sigma_{11} \cdot \Sigma_{22} - \Sigma_{12}^2}$$

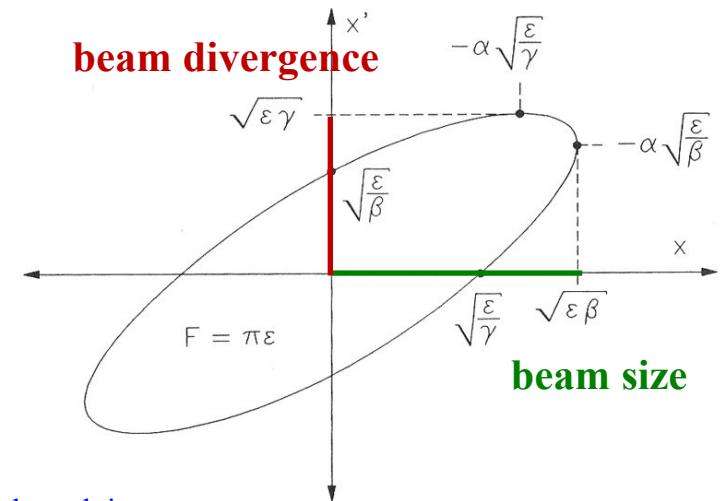
- ▶ mapping of phase space

→ restrict to (infinitesimal) element in space coordinate, convert angles x' in position

Circular Accelerators

emittance diagnostics in circular accelerators

- ▶ circular accelerator: periodic with circumference C_0
 - one-turn transport matrix: $M(s+C_0) = M(s)$
 - Twiss parameters $\alpha(s)$, $\beta(s)$, $\gamma(s)$ uniquely defined at each location in ring
- ▶ measurement at one location in ring sufficient to determine ϵ
 - measured quantity: beam profile / angular distribution



classification

- ▶ imaging
 - beam size
- ▶ interference
 - beam size
- ▶ projection
 - beam divergence

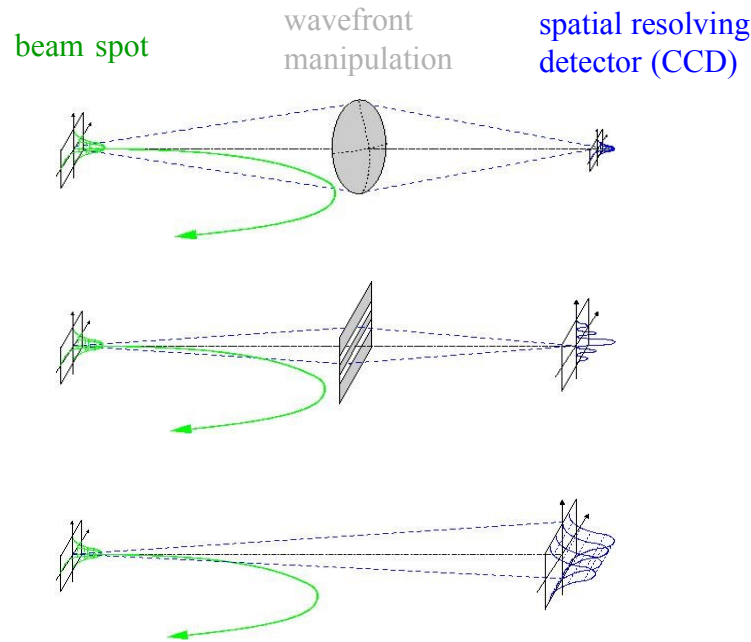
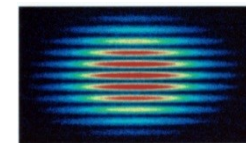
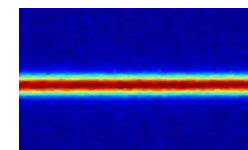


image size



interference pattern



angular distribution

Beam Matrix based Measurements

- starting point: beam matrix

$$\Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix} = \begin{pmatrix} \langle x^2 \rangle & \langle xx' \rangle \\ \langle xx' \rangle & \langle x'^2 \rangle \end{pmatrix} = \varepsilon \begin{pmatrix} \beta & -\alpha \\ -\alpha & \gamma \end{pmatrix}$$

- emittance determination

- measurement of 3 matrix elements Σ_{11} , Σ_{12} , Σ_{22}

$$\varepsilon = \sqrt{\det \Sigma} = \sqrt{\Sigma_{11} \cdot \Sigma_{22} - \Sigma_{12}^2}$$

- remember:** beam matrix Σ depends on location, i.e. $\Sigma(s)$

→ determination of matrix elements at same location required

- access to matrix elements

- profile monitor determines only $\sigma = \sqrt{\Sigma_{11}}$

- other matrix elements can be inferred from beam profiles taken under various transport conditions

→ knowledge of transport matrix M required

$$\Sigma^b = M \cdot \Sigma^a \cdot M^T \quad M = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix}$$

- measurement of at least 3 profiles for 3 matrix elements

$$\Sigma_{11}^a$$

$$\Sigma_{11}^b = m_{11}^2 \cdot \Sigma_{11}^a + 2m_{11}m_{12} \cdot \Sigma_{12}^a + m_{12}^2 \cdot \Sigma_{22}^a$$

$$\Sigma_{11}^c = \overline{m_{11}}^2 \cdot \Sigma_{11}^a + 2\overline{m_{11}}\overline{m_{12}} \cdot \Sigma_{12}^a + \overline{m_{12}}^2 \cdot \Sigma_{22}^a$$

- measurement:** profiles

$$\sigma^{a,b,c} = \sqrt{\Sigma_{11}^{a,b,c}}$$

- known:** transport optics

$$M, \overline{M}$$

- deduced:** matrix elements

$$\Sigma_{11}^a, \Sigma_{12}^a, \Sigma_{22}^a$$

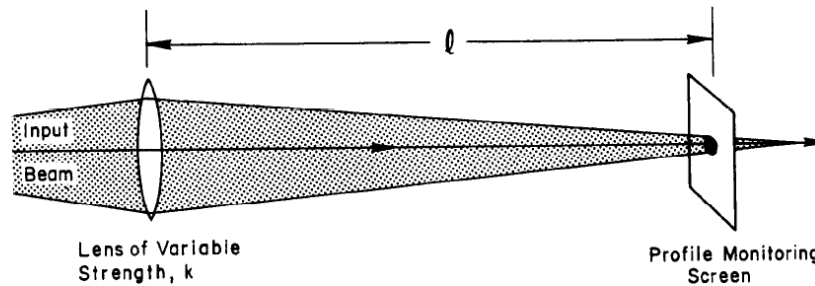
→ more than 3 profile measurements favourable, data subjected to least-square analysis

Beam Matrix based Measurements

„quadrupole scan“ method

› use of variable quadrupole strengths

→ change quadrupole settings and measure beam size in profile monitor located downstream



M_{quad} ($f = 1/k$) M_{drift} (drift space)

quadrupole transfer matrix

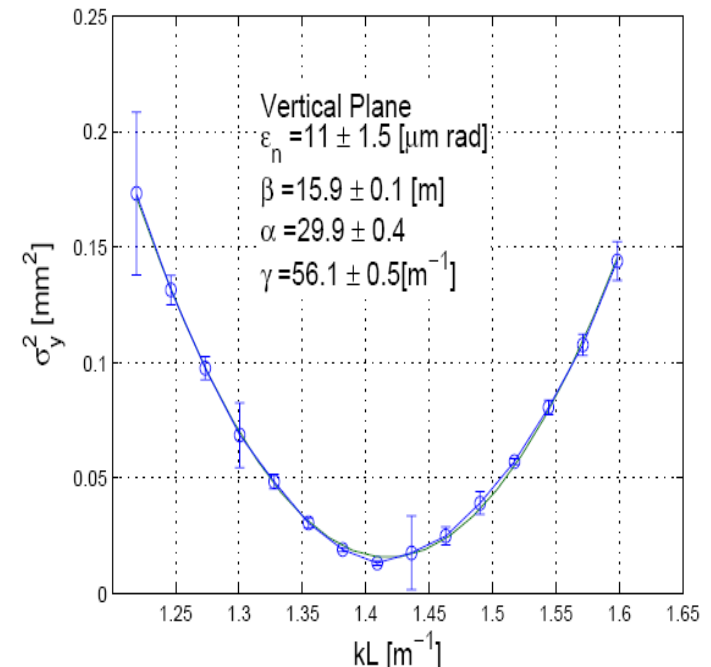
$$M_{quad} = \begin{pmatrix} 1 & 0 \\ \pm 1/f & 1 \end{pmatrix}$$

drift space transfer matrix

$$M_{drift} = \begin{pmatrix} 1 & l \\ 0 & 1 \end{pmatrix}$$

$$\rightarrow M = M_{drift} M_{quad}$$

› Σ_{II} depends quadratically on quadrupole field strength



Beam Matrix based Measurements

- „multi profile monitor“ method

- fixed particle beam optics
 - measure beam sizes using multiple profile monitors at different locations

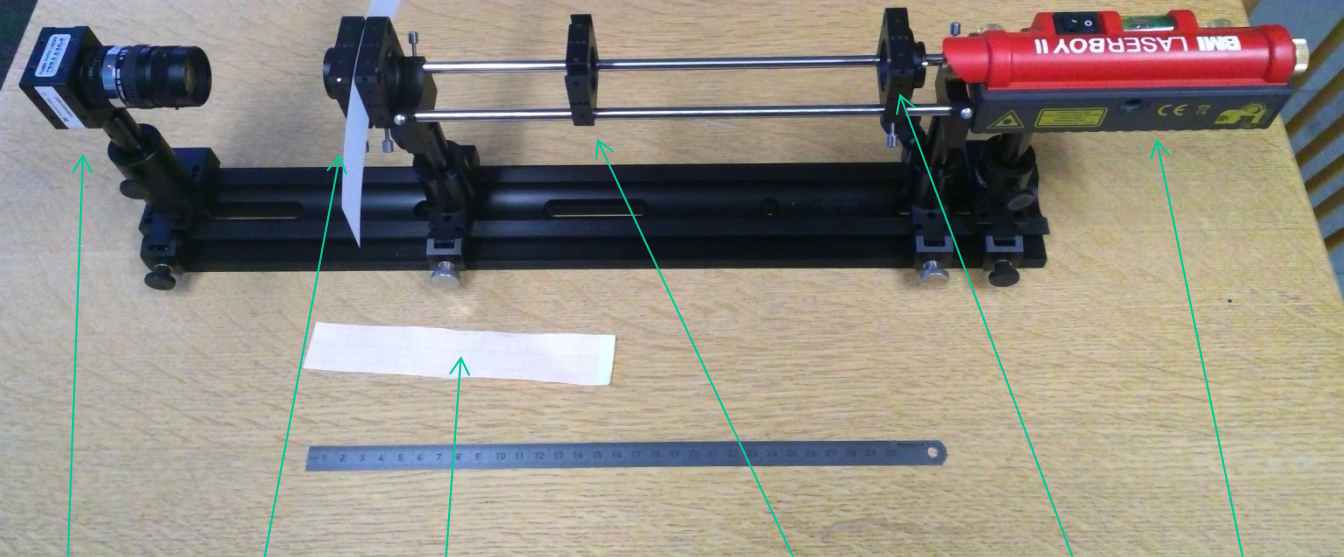
- example:
 - emittance measurement
 - setup at FLASH injector (DESY)
 - courtesy: K. Honkavaara (DESY)



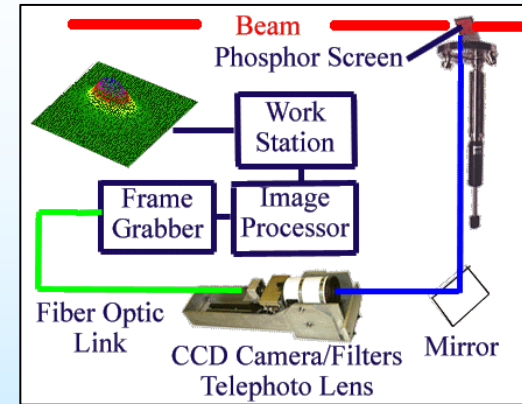
- task

- beam profile measurement

Introduction



Camera Screen Calibration Screen Moveable Lens Aperture Laser



By moving the lens one can take pictures from the camera in the focus (not preferred due to limited resolution of the optic system) and on other positions. The distance of the lens to various screen positions can be measured by a simple ruler*. The camera is connected to a Computer where the readout software is installed. The pictures (.jpg) can be saved and can be loaded into a free software called “ImageJ” where a profile of an area can be displayed and the cursor position and the value is displayed (8 bit). The σ of the profile have to be found for each screen (camera) position and the emittance have to be calculated.

*** Move the lens to simulate different screen positions**

Parameters

● CCD

› Phytec USB-CAM 051H

| | | | | |
|------------------------|--|------------------------------|---------------------|------------------------------|
| Resolution | 2592 x 1944 (5 MPix), 2048 x 1536 (3,1MPix), 1600 x 1200 (2MPix), 1280 x 960 (1,2MPix) 1024 x 768 (0,8MPix), 640 x 480 (VGA) | | | |
| Model | USB-CAM-051H | USB-CAM-151H | USB-CAM-052H | USB-CAM-152H |
| color / monochrom | monochrom | | color | |
| Sensor Format | 1/2,5" | | | |
| Image Sensor | Aptina MT9P031, CMOS | | | |
| Pixel Size | 2,2 µm x 2,2 µm | | | |
| Color format | Y8 | RGB32, RGGB (Raw) | | |
| Lens Holder | C / CS – Mount | | | |
| fps | 6 fps to 52 fps | | | |
| Dynamic Range | 8 bit | | | |
| Shutter | Rolling | | | |
| Light sensitivity | 1,4 V/lux-sec | | | |
| Interface | USB 2.0 High Speed | | | |
| Exposure time | 1/10.000 s to 30 s | | | |
| Gain | 0 dB to 18 dB | | | |
| White Balance | - | -6 dB bis +6 dB | | |
| Power supply | 4,5 V bis 5,5V DC | | | |
| Power Consumption | Circa 250 mA bei 5V | | | |
| Feature (optional) | - | ext. Trigger, Digital-Output | - | ext. Trigger, Digital-Output |
| Temperature range | -5°C bis +45°C | | | |
| Dimensions (B x L x H) | 36 mm x 36 mm x 25 mm | | | |
| Fixing | 1/4" and M6x8 on all sides | | | |
| Weight | 70 g | | | |
| Connection | USB Mini-B | | | |
| Feature- Connection | - | Hirose HR10A-7R-4P | - | Hirose HR10A-7R-4P |

● screen

› material: white paper

● grid target

› spacing: 1 mm

● Laser: LaserBoyII

BMI Bayerische Laserboy II Wasserwaage 649 015

Allgemeine Informationen

| | |
|--------------------|----------------|
| Artikelnummer | ET1117000 |
| EAN | 4007368050049 |
| Hersteller | BMI Bayerische |
| Hersteller-ArtNr | 649 015 |
| Hersteller-Typ | 649 015 |
| Verpackungseinheit | 1 Stück |
| Artikelklasse | Messlaser |



Technische Informationen

| | |
|--------------------------|-----|
| Länge der Signalstrecke | 30m |
| Laserklasse | |
| Sichtbare Signalstrecke | |
| Rotierende Signalstrecke | |

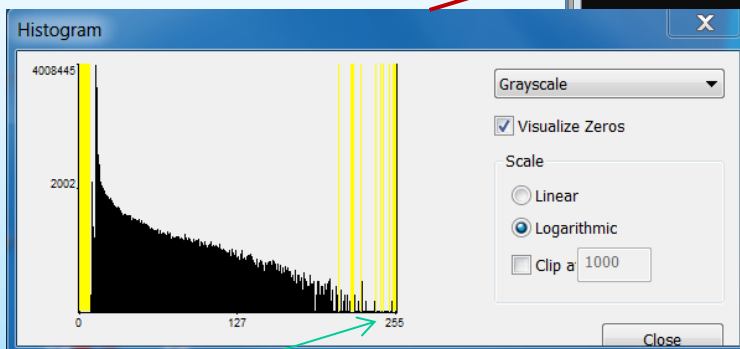
BMI Bayerische Laserboy II Wasserwaage 649 015 Länge der Signalstrecke 30m, Laserklasse 2, Sichtbare Signalstrecke,

CCD Readout: Introduction

● readout program

PHYTEC Vision Demo 2.2

▶ histogram of grey values



Device Properties - USB-CAM-051H

Exposure Partial scan Special

Gain 4 Auto

Exposure 1/139 sec Auto

Auto Reference 43

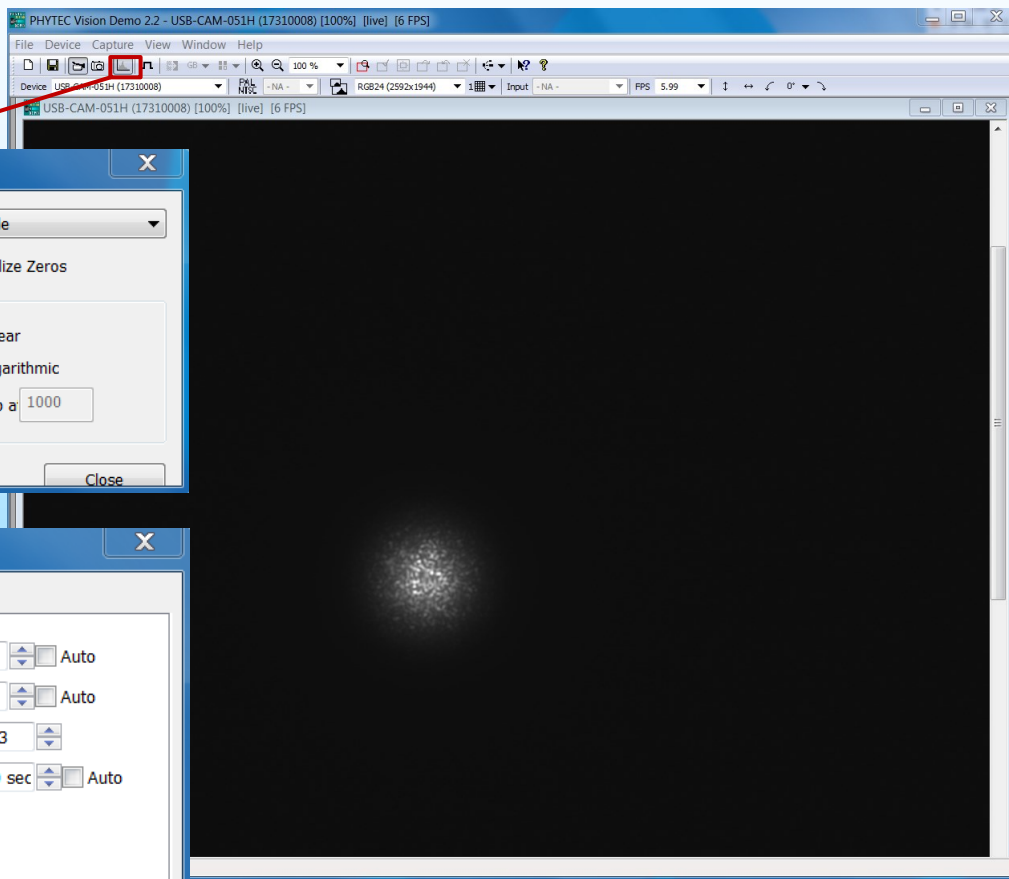
Auto Max Value 30.000 sec Auto

Help Update Default OK

Check
always:
Do not
saturate
(255)

▶ CCD control parameters

→ Device → Properties



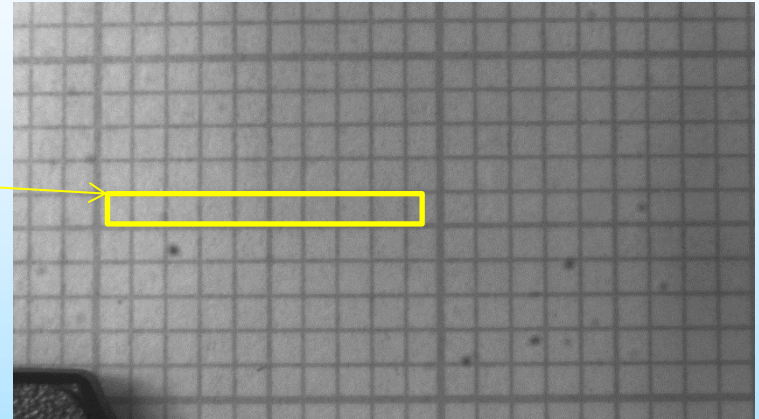
Your tasks in green frames

Check:
Do not
saturate
(255)

Calibration

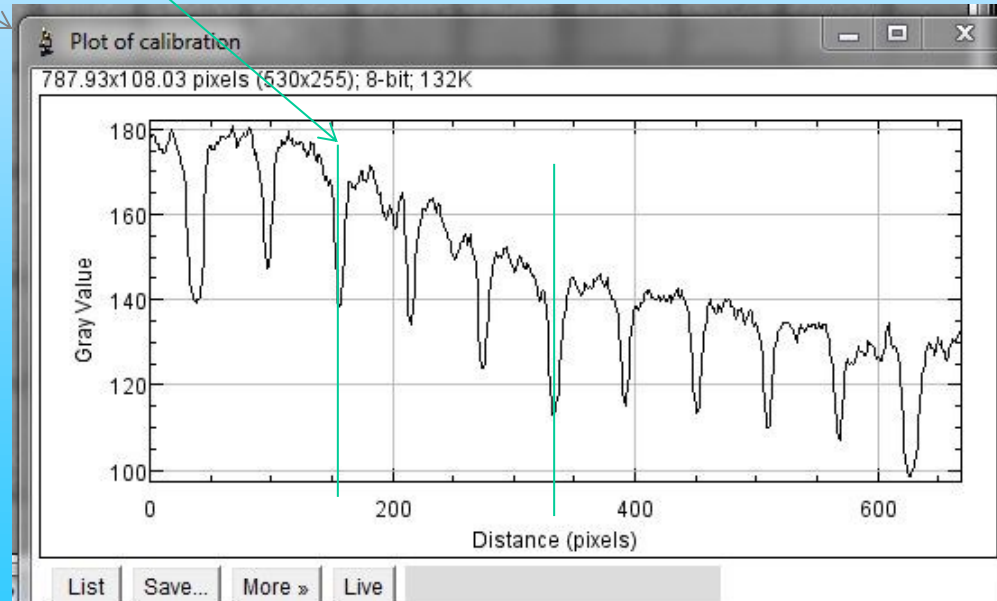
Use mm-grid to calibrate the readout setup.

Select ROI (where beam image will appear), plot profile, use cursor and enter measurement into pre-prepared Excel sheet “Laser emittance.xlsx”



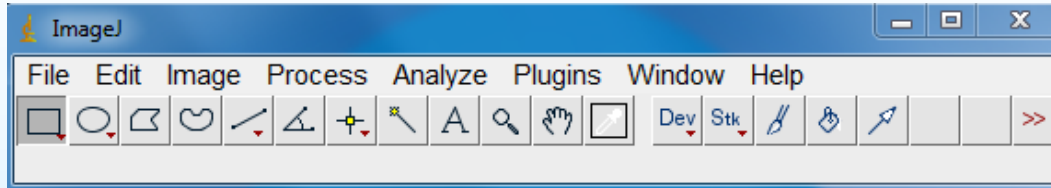
| Calibration | | | |
|---------------|---------|-------------|----------|
| Line-distance | | | |
| [mm] | pixel 1 | pixel 2 | |
| 3 | 66 | 401 | |
| [meter] | | Cal. Result | |
| 3.00E-03 => | | 111.6667 | pixel/mm |

All yellow cells will be calculated automatically



ImageJ: Introduction

- press icon → access to start panel

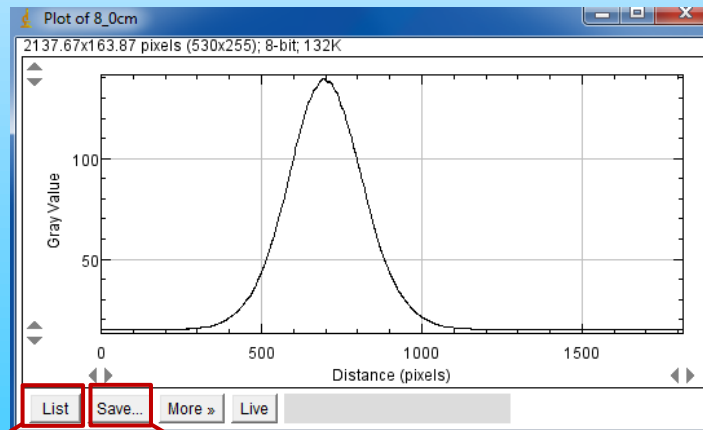


- load image file → File → Open (Shortcut: Ctrl + O)

- select ROI: in start panel: select left button (below "File"), usually already pre-selected
then with left mouse button: draw rectangular ROI



- plot horizontal projection → Analyze → Plot Profile (Shortcut: Ctrl + k)

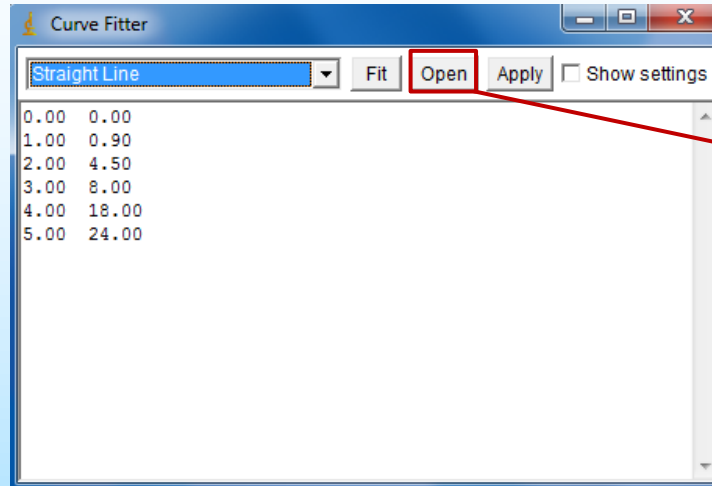


- save data → list data points → save data as .csv file (required for profile fitting)

ImageJ: Introduction

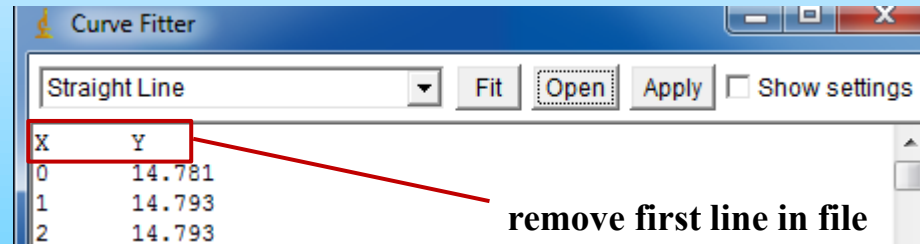
● profile fitting → Analyze → Tools → Curve Fitting...

▶ load profile data:



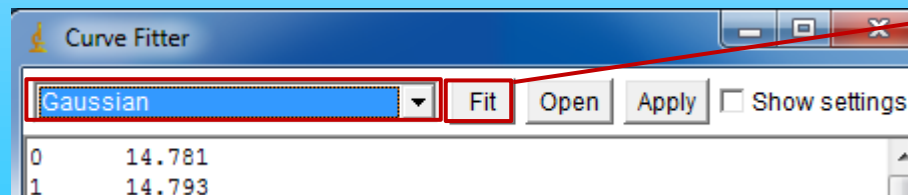
load .csv data file

▶ delete bad data:



remove first line in file

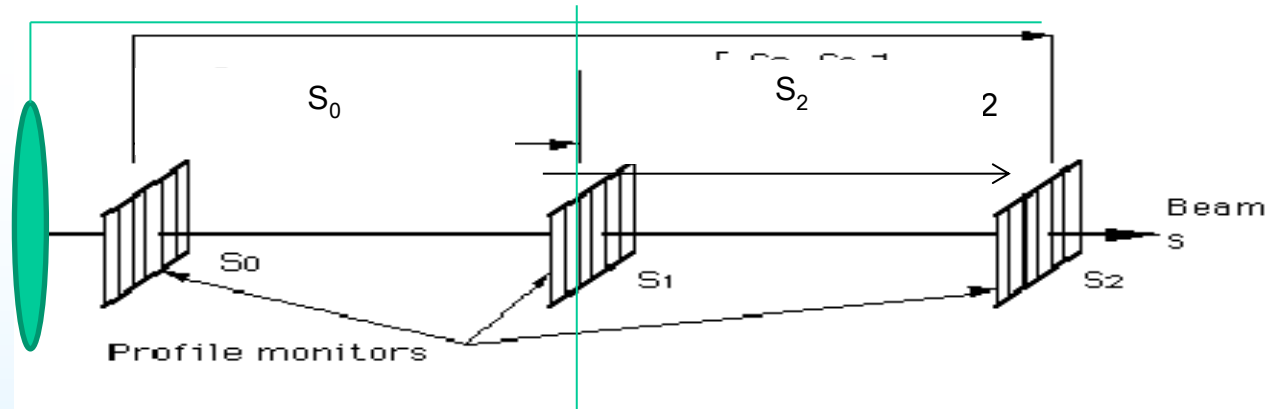
▶ select fit function:



fit profile data

$$y = a + (b - a) \cdot e^{-\frac{(x-c)^2}{2d^2}}$$

Take profiles at 3 different distances lens-screen. Move lense to simulate 3 positions.



Hint1: Make the distances equal, set $s_1 = 0, s_2 = -s_0$
Hint 2: Avoid position at waist (why?)

$S_1=0$

Check: Do not saturate (255)

$$\sigma = \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{pmatrix} = \begin{pmatrix} \sigma_y^2 & \sigma_{yy'} \\ \sigma_{yy'} & \sigma_y'^2 \end{pmatrix} = \epsilon_{rms} \begin{pmatrix} \beta & -\alpha \\ -\alpha & \gamma \end{pmatrix} = \sigma \text{ matrix}$$

$$\epsilon_{rms} = \sqrt{\det \sigma} = \sqrt{\sigma_{11}\sigma_{22} - \sigma_{12}^2}$$

$$\sigma_{y \text{ measured}}^2 = M_{11}^2 \sigma_{11} + 2M_{11} M_{12} \sigma_{12} + M_{12}^2 \sigma_{22}$$

No optical elements => $M = \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix}$

$$\sigma^2(S1)_{\text{measured}} = \sigma_{11} + 2s_1 \sigma_{12} + s_1^2 \sigma_{22}$$

$$\sigma^2(S0)_{\text{measured}} = \sigma_{11} + 2s_0 \sigma_{12} + s_0^2 \sigma_{22}$$

$$\sigma^2(S2)_{\text{measured}} = \sigma_{11} + 2s_2 \sigma_{12} + s_2^2 \sigma_{22}$$

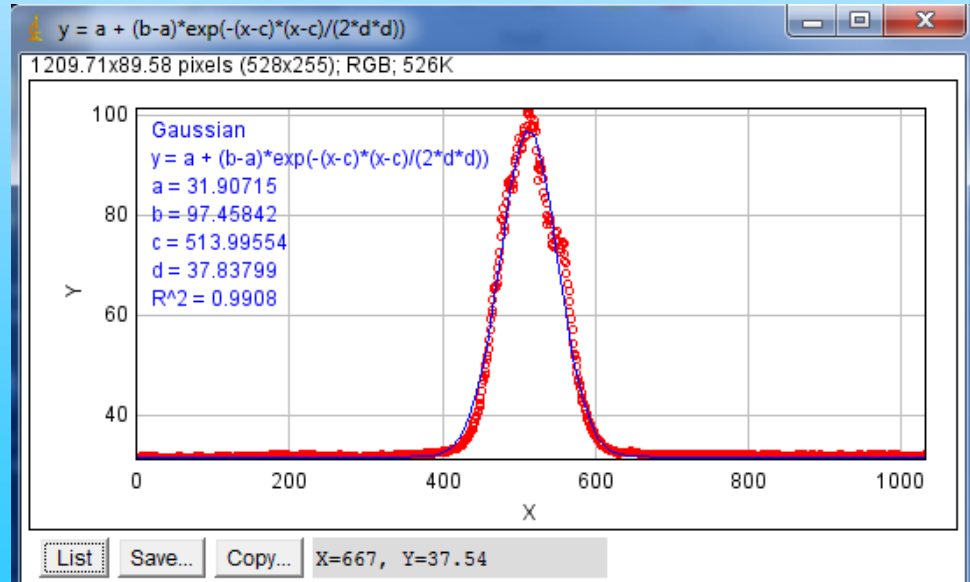
with

$$\sigma_{11} = \sigma_y^2(0) = \sigma^2(S0)$$

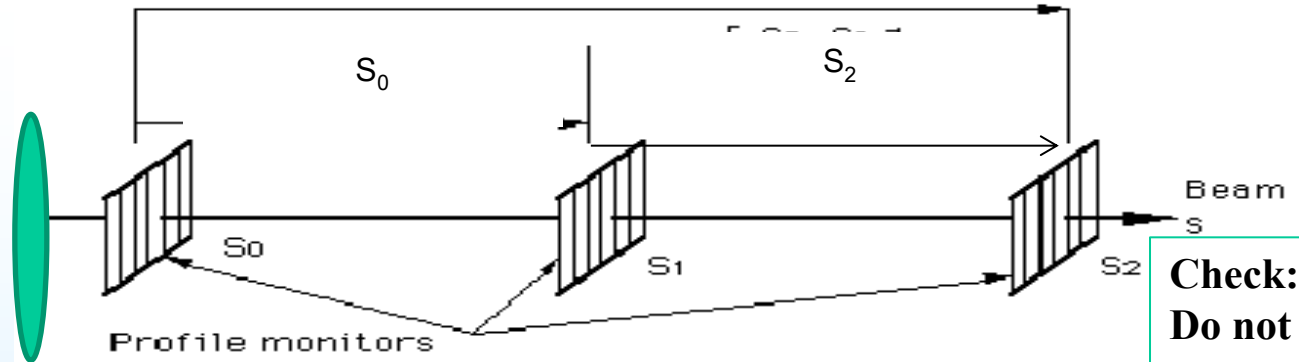
$$\sigma_{12} = \frac{\sigma_y^2(+s) - \sigma_y^2(-s)}{4s} = \sigma^2(+s)$$

$$\sigma_{22} = \frac{\sigma_y^2(+s) - 2 \cdot \sigma_y^2(0) + \sigma_y^2(-s)}{2 \cdot s^2} = \sigma^2(-s)$$

Adjust the aperture so that the image looks quite gaussian at its larges size!



Take profiles at 3 different distances lens-screen.

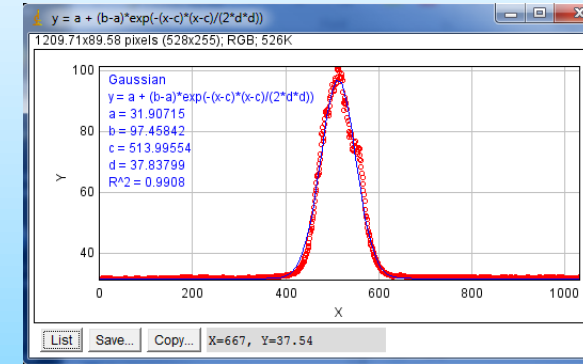


Check: Do not saturate (255)

Make the distances equal, set $s_1 = 0$, $s_2 = -s_0$

Enter the screen positions $+s$, 0 , $-s$ and the measured σ from fits (in pixel) at $+s$, 0 and $-s$ into the Excel sheet:

| | Position[m] | L [m] | sigma [p] | sigma(s) [m] | |
|------|-----------------|----------|--------------|--------------|---------------------------------|
| | METER!!! | | PIXEL | | |
| $+s$ | 1.00E-02 | 1.00E-02 | 37.8 | 3.38E-04 | Take FWHM/2.36 if not Gaussian! |
| 0 | 2.00E-02 | 1.00E-02 | 33.5 | 2.99E-04 | Take FWHM/2.36 if not Gaussian! |
| $-s$ | 3.00E-02 | | 30.2 | 2.70E-04 | Take FWHM/2.36 if not Gaussian! |



| | | |
|------------|----------|-------------------------------|
| distance s | [meter] | |
| s= | 1.00E-02 | (s equal between 3 positions) |
| sigma 11 | 8.95E-08 | Emitt*2 2.38E-12 |
| sigma 12 | 1.03E-06 | Emittance: 1.5415E-06 |
| sigma 22 | 3.84E-05 | |

should not be negativ! ←
 expected Emittance: around $1 \cdot 10E-6$ [m rad]
 (often the unit is written in [π mm mrad] while π indicates that s is the area of an ellipse)
 Unfortunately it depends sometimes from one pixel in sigma only in this experiment

↑
 Like Criegee: Trick: **Three screens at $-s$, 0 , $+s$** with $s=L$

$$\sigma_{11} = \sigma_y^2(0)$$

$$\sigma_{12} = \frac{\sigma_y^2(+s) - \sigma_y^2(-s)}{4s}$$

$$\sigma_{22} = \frac{\sigma_y^2(+s) - 2 \cdot \sigma^2(0) + \sigma_y^2(-s)}{2 \cdot s^2}$$

$$\epsilon_{rms} = \sqrt{\det \sigma} = \sqrt{\sigma_{11}\sigma_{22} - \sigma_{12}^2}$$

$$\left. \begin{aligned} \hat{x}_2^2 &= \epsilon\beta_2 - 2L \cdot \epsilon\alpha_2 + L^2 \cdot \epsilon\gamma_2 \\ \hat{x}_1^2 &= \epsilon\beta_2 \\ \hat{x}_3^2 &= \epsilon\beta_2 + 2L \cdot \epsilon\alpha_2 + L^2 \cdot \epsilon\gamma_2 \end{aligned} \right\} \text{with the solution } \left\{ \begin{aligned} \epsilon\beta_2 &= \hat{x}_2^2 \\ \epsilon\alpha_2 &= (\hat{x}_3^2 - \hat{x}_1^2)/(4L) \\ \epsilon\gamma_2 &= (\hat{x}_1^2 - 2\hat{x}_2^2 + \hat{x}_3^2)/(2L^2) \\ \epsilon^2 &= \epsilon\beta_2 \cdot \epsilon\gamma_2 - (\epsilon\alpha_2)^2 \end{aligned} \right.$$

The emittance is calculated by the formulas.
 Since the Laser is not gaussian, vary a little(!) the fitted widths. Note how sensitive the emittance behave.
 => Need of **good resolution** and **good fits**.